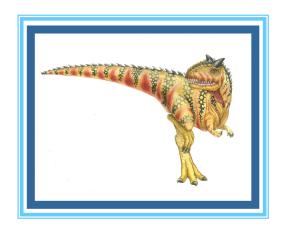
Operating System Lecture-02





Chapter 1: Introduction

- What Operating Systems Do
- Computer-System Organization
- Computer-System Architecture
- Operating-System Structure
- Operating-System Operations
- Process Management
- Memory Management
- Storage Management
- Protection and Security
- Kernel Data Structures
- Computing Environments
- Open-Source Operating Systems





Objectives

- To describe the basic organization of computer systems
- To provide a grand tour of the major components of operating systems
- To give an overview of the many types of computing environments
- To explore several open-source operating systems





I/O Structure

- After I/O starts, control returns to user program only upon I/O completion
 - Wait instruction idles the CPU until the next interrupt
 - Wait loop (contention for memory access)
 - At most one I/O request is outstanding at a time, no simultaneous I/O processing
- After I/O starts, control returns to user program without waiting for I/O completion
 - System call request to the OS to allow user to wait for I/O completion
 - Device-status table contains entry for each I/O device indicating its type, address, and state
 - OS indexes into I/O device table to determine device status and to modify table entry to include interrupt





Storage Structure

- Main memory only large storage media that the CPU can access directly
 - Random access
 - Typically volatile
- Secondary storage extension of main memory that provides large nonvolatile storage capacity
- Hard disks rigid metal or glass platters covered with magnetic recording material
 - Disk surface is logically divided into tracks, which are subdivided into sectors
 - The disk controller determines the logical interaction between the device and the computer
- Solid-state disks faster than hard disks, nonvolatile
 - Various technologies
 - Becoming more popular





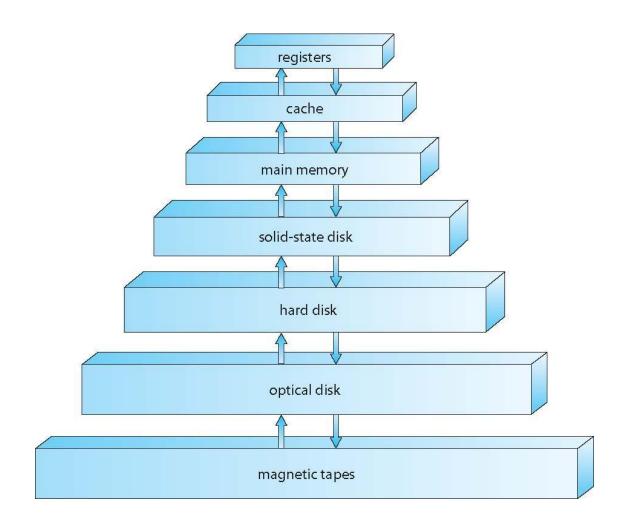
Storage Hierarchy

- Storage systems organized in hierarchy
 - Speed
 - Cost
 - Volatility
- Caching copying information into faster storage system; main memory can be viewed as a cache for secondary storage
- Device Driver for each device controller to manage I/O
 - Provides uniform interface between controller and kernel





Storage-Device Hierarchy







Caching

- Important principle, performed at many levels in a computer (in hardware, operating system, software)
- Information in use copied from slower to faster storage temporarily
- Faster storage (cache) checked first to determine if information is there
 - If it is, information used directly from the cache (fast)
 - If not, data copied to cache and used there
- Cache smaller than storage being cached
 - Cache management important design problem
 - Cache size and replacement policy

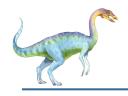




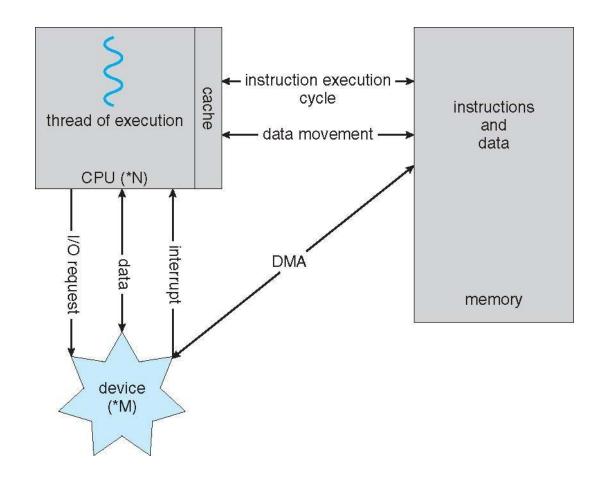
Direct Memory Access Structure

- Used for high-speed I/O devices able to transmit information at close to memory speeds
- Device controller transfers blocks of data from buffer storage directly to main memory without CPU intervention
- Only one interrupt is generated per block, rather than the one interrupt per byte



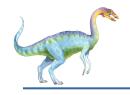


How a Modern Computer Works



A von Neumann architecture





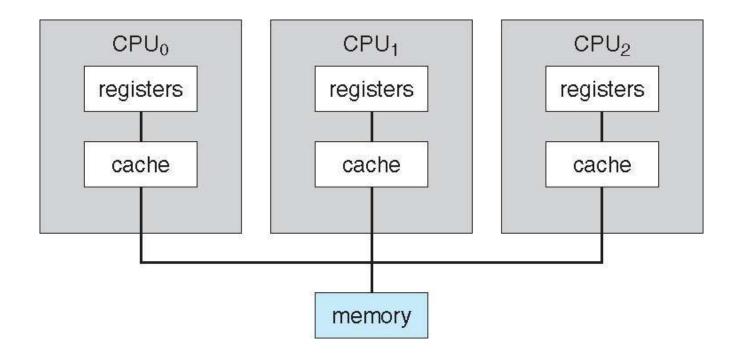
Computer-System Architecture

- Most systems use a single general-purpose processor
 - Most systems have special-purpose processors as well
- Multiprocessors systems growing in use and importance
 - Also known as parallel systems, tightly-coupled systems
 - Advantages include:
 - 1. Increased throughput
 - 2. Economy of scale
 - 3. Increased reliability graceful degradation or fault tolerance
 - Two types:
 - Asymmetric Multiprocessing each processor is assigned a specie task.
 - 2. Symmetric Multiprocessing each processor performs all tasks





Symmetric Multiprocessing Architecture

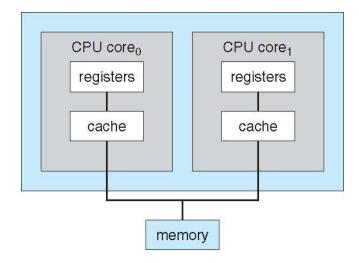






A Dual-Core Design

- Multi-chip and multicore
- Systems containing all chips
 - Chassis containing multiple separate systems







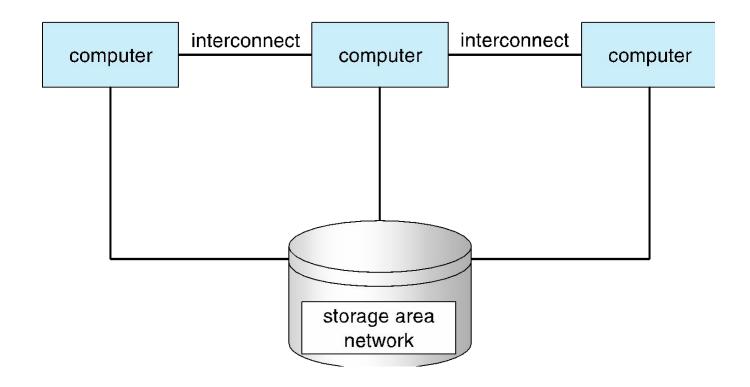
Clustered Systems

- Like multiprocessor systems, but multiple systems working together
 - Usually sharing storage via a storage-area network (SAN)
 - Provides a high-availability service which survives failures
 - 4 Asymmetric clustering has one machine in hot-standby mode
 - 4 Symmetric clustering has multiple nodes running applications, monitoring each other
 - Some clusters are for high-performance computing (HPC)
 - 4 Applications must be written to use parallelization
 - Some have distributed lock manager (DLM) to avoid conflicting operations





Clustered Systems







Operating System Structure

- Multiprogramming (Batch system) needed for efficiency
 - Single user cannot keep CPU and I/O devices busy at all times
 - Multiprogramming organizes jobs (code and data) so CPU always has one to execute
 - A subset of total jobs in system is kept in memory
 - One job selected and run via job scheduling
 - When it has to wait (for I/O for example), OS switches to another job
- Timesharing (multitasking) is logical extension in which CPU switches jobs so frequently that users can interact with each job while it is running, creating interactive computing
 - Response time should be < 1 second
 - Each user has at least one program executing in memory process

 - If processes don't fit in memory, swapping moves them in and out to run
 - Virtual memory allows execution of processes not completely in memory





Operating-System Operations

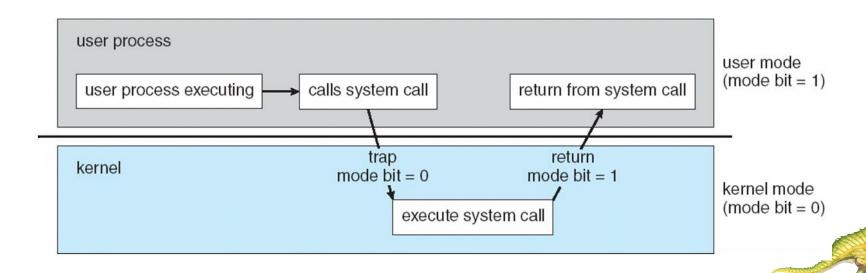
- Dual-mode operation allows OS to protect itself and other system components
 - User mode and kernel mode
 - Mode bit provided by hardware
 - 4 Provides ability to distinguish when system is running user code or kernel code
 - 4 Some instructions designated as **privileged**, only executable in kernel mode
 - 4 System call changes mode to kernel, return from call resets it to user
- Increasingly CPUs support multi-mode operations
 - i.e. virtual machine manager (VMM) mode for guest VMs





Transition from User to Kernel Mode

- Timer to prevent infinite loop / process hogging resources
 - Timer is set to interrupt the computer after some time period
 - Keep a counter that is decremented by the physical clock.
 - Operating system set the counter (privileged instruction)
 - When counter zero generate an interrupt
 - Set up before scheduling process to regain control or terminate program that exceeds allotted time





Process Management

- A process is a program in execution. It is a unit of work within the system. Program is a passive entity, process is an active entity.
- Process needs resources to accomplish its task
 - CPU, memory, I/O, files
 - Initialization data
- Process termination requires reclaim of any reusable resources
- Single-threaded process has one program counter specifying location of next instruction to execute
 - Process executes instructions sequentially, one at a time, until completion
- Multi-threaded process has one program counter per thread
- Typically system has many processes, some user, some operating system running concurrently on one or more CPUs
 - Concurrency by multiplexing the CPUs among the processes / threads



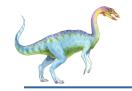


Process Management Activities

The operating system is responsible for the following activities in connection with process management:

- Creating and deleting both user and system processes
- Suspending and resuming processes
- Providing mechanisms for process synchronization
- Providing mechanisms for process communication
- Providing mechanisms for deadlock handling





Memory Management

- To execute a program all (or part) of the instructions must be in memory
- All (or part) of the data that is needed by the program must be in memory.
- Memory management determines what is in memory and when
 - Optimizing CPU utilization and computer response to users
- Memory management activities
 - Keeping track of which parts of memory are currently being used and by whom
 - Deciding which processes (or parts thereof) and data to move into and out of memory
 - Allocating and deallocating memory space as needed





Storage Management

- OS provides uniform, logical view of information storage
 - Abstracts physical properties to logical storage unit file
 - Each medium is controlled by device (i.e., disk drive, tape drive)
 - 4 Varying properties include access speed, capacity, data-transfer rate, access method (sequential or random)
- File-System management
 - Files usually organized into directories
 - Access control on most systems to determine who can access what
 - OS activities include
 - 4 Creating and deleting files and directories
 - 4 Primitives to manipulate files and directories
 - 4 Mapping files onto secondary storage
 - 4 Backup files onto stable (non-volatile) storage media





Mass-Storage Management

- Usually disks used to store data that does not fit in main memory or data that must be kept for a "long" period of time
- Proper management is of central importance
- Entire speed of computer operation hinges on disk subsystem and its algorithms
- OS activities
 - Free-space management
 - Storage allocation
 - Disk scheduling
- Some storage need not be fast
 - Tertiary storage includes optical storage, magnetic tape
 - Still must be managed by OS or applications
 - Varies between WORM (write-once, read-many-times) and RW (read-write)



Performance of Various Levels of Storage (Assignment)

Level	1	2	3	4	5
Name	registers	cache	main memory	solid state disk	magnetic disk
Typical size	< 1 KB	< 16MB	< 64GB	< 1 TB	< 10 TB
Implementation technology	custom memory with multiple ports CMOS	on-chip or off-chip CMOS SRAM	CMOS SRAM	flash memory	magnetic disk
Access time (ns)	0.25 - 0.5	0.5 - 25	80 - 250	25,000 - 50,000	5,000,000
Bandwidth (MB/sec)	20,000 - 100,000	5,000 - 10,000	1,000 - 5,000	500	20 - 150
Managed by	compiler	hardware	operating system	operating system	operating system
Backed by	cache	main memory	disk	disk	disk or tape

Movement between levels of storage hierarchy can be explicit or implicit

