

Pattern Recognition. Overview

Pooran Singh Negi

University Of Denver

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Outline

Pattern
Recognition.
Overview

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Negi

Generative
model for
discrete data

Concept learning
How to emulate
this behavior in
a machine

- 1 Generative model for discrete data
 - Concept learning
 - How to emulate this behavior in a machine

Bayesian concept learning

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- Typical machine learning model require both positive and negative example
- Human learning abilities(only positive examples, small sample)

Example of concept learning. Number game

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- Teacher Choose some arithmetic concept C e.g. **prime number, multiple of 4**
- Student is given some positive example drawn at random from C in the range $[1 \cdots 100]$.
- Student is asked whether new example $x_{test} \in C$.

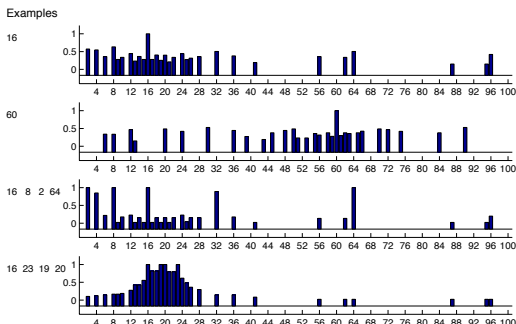
Empirical predictive distribution

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Empirical predictive distribution averaged over 8 humans. First, second. third and fourth row **posterior predictive distribution** $p(x|\mathcal{D})$ **after seeing** $\mathcal{D} = \{16\}$, $\{60\}$, $\{16, 8, 2, 64\}$ and $\{16, 23, 19, 20\}$.

Hypothesis Space

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Consider possible hypothesis \mathcal{H}

- Even number
- odd number
- power of 2
- power of 2, plus 37
- power of 2 except 32

The subset of \mathcal{H} consistent with data is called version space.
After seeing some example, some rule $h \in \mathcal{H}$ is consistent with samples. How to combine them to predict $x_{test} \in \mathcal{C}$.

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- Likelihood function. Size principle.
Let assume example of sampled uniformly form the extension of concept. Then probability of sampling N examples from h is

$$p(h|\mathcal{D}) = \left[\frac{1}{\text{size}(h)} \right]^N$$

Model favors simplest(smallest) hypothesis consistent with the data(**Occam's razor**)

- Prior. Intuition

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Overview

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■ Prior.

- Intuition.
- Helps in bringing background knowledge to the problem.
- Also helps in learning from small sample size.

Let $\mathcal{D} = \{16, 8, 2, 64\}$. Given this data
 $p(\mathcal{D} | h' = \text{power of two except } 32)$ is more likely than
 $p(\mathcal{D} | h' = \text{power of } 2)$, although unnatural.

Which prior we should choose?

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Posterior

$$p(h|\mathcal{D}) = \frac{p(\mathcal{D}|h)p(h)}{\sum_{h' \in \mathcal{H}} p(\mathcal{D}|h')p(h')}$$

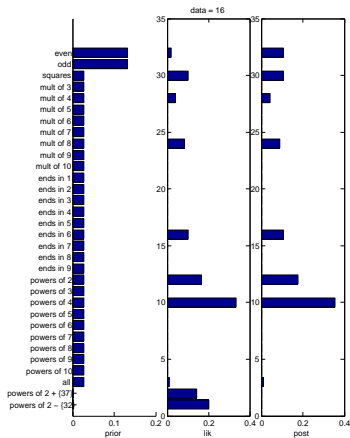
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Recognition.
Overview

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How to emulate
this behavior in
a machine



Prior, likelihood and posterior for $\mathcal{D} = \{16\}$

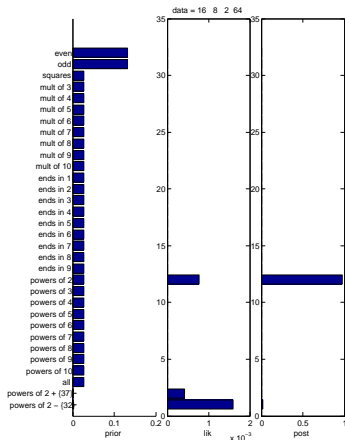
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Overview

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Concept learning
How to emulate
this behavior in
a machine



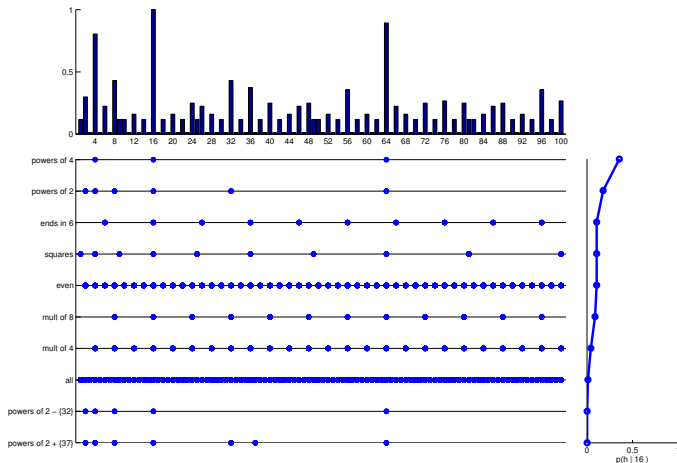
Prior, likelihood and posterior for $\mathcal{D} = \{16, 8, 2, 64\}$

When we have enough data posterior become peaked on single concept, called MAP (Maximum a posteriori estimate) estimate.

$$\begin{aligned}\hat{h}^{MAP} &= \operatorname{argmax}_h p(h|\mathcal{D}) \\ &= \operatorname{argmax}_h p((D)|h)p(h) \\ &= \operatorname{argmax}_h [\log p(\mathcal{D}|h) + \log p(h)]\end{aligned}$$

Posterior predictive distribution

Bayes model averaging $p(x_{new} \in C|\mathcal{D}) = \sum_h p(y = 1|x_{new})p(h|\mathcal{D})$



Posterior over hypothesis and corresponding predictive distribution

after seeing $\mathcal{D} = \{16\}$

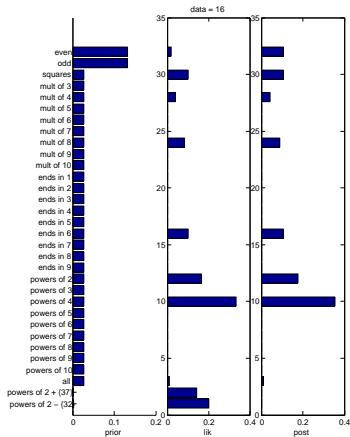
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Pattern
Recognition.
Overview

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Concept learning
How to emulate
this behavior in
a machine



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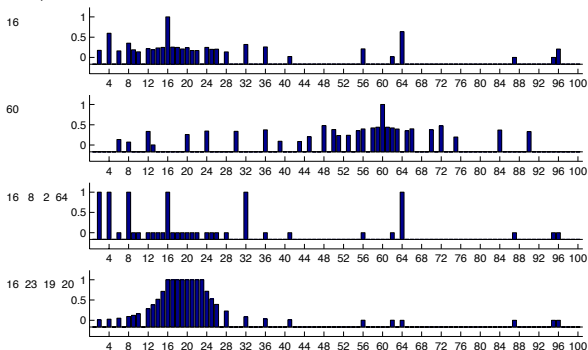
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Overview

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Concept learning
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Examples



Predictive distribution for the model using full hypothesis space. Compare this to human experiment at the beginning.

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this behavior in
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Thank you!