Contents

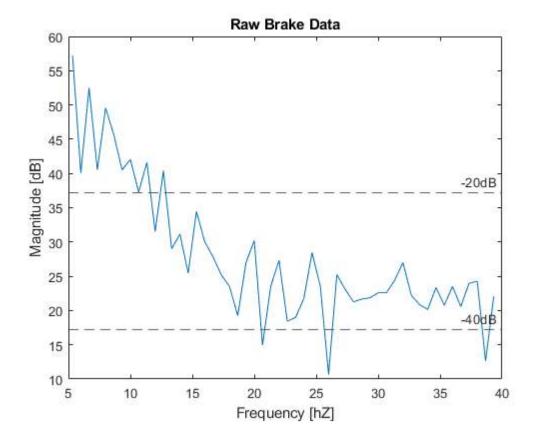
- part 1
- part 2
- part 3
- part 4
- part 5

part 1

```
brake_data = readmatrix("40p_1000ms.csv");
```

part 2

```
t = brake_data(:, 1) ./ fs;
norm_brake_data = normalize(brake_data(:, 2), 'range', [0, 1]);
x = fft(norm_brake_data);
x = x(1:numel(x)/2); "removing" negative frequencies by /2
f = fs * linspace(0, pi, numel(x)) / (2 * pi); % normalize fs to w range
fMaskLow = f >= 5; % only care about signals >= 5 hZ
x = x(fMaskLow);
f = f(fMaskLow);
dB = 20 * log10(abs(x));
fMaskHigh = f <= 40; % signals <= 40 hZ
f = f(fMaskHigh);
dB = dB(fMaskHigh);
% plot raw dft
figure;
plot(f, dB)
title("Raw Brake Data");
yline(max(dB) - 20, '--', '-20dB');
yline(max(dB) - 40, '--', '-40dB');
xlabel('Frequency [hZ]');
ylabel('Magnitude [dB]');
```



part 3

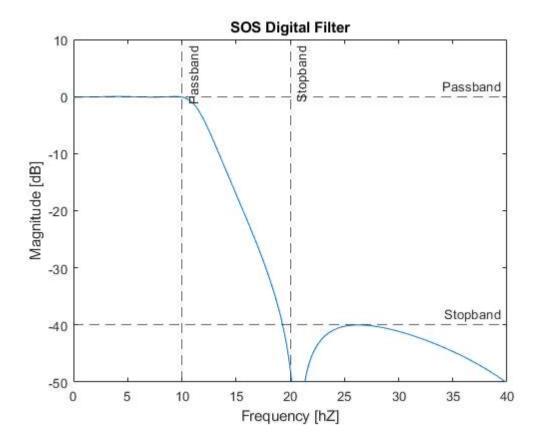
```
Wp = 10 / fn; % ~10 Hz goes below max - 20dB
Ws = 20 / fn; % ~20 Hz goes below max - 40dB
Rp = 0.1; % passband ripple
Rs = 40; % stopband ripple
% thus corner frequencies = 10 Hz, 20 Hz

[n, Wn] = ellipord(Wp, Ws, Rp, Rs);
[z, p, k] = ellip(n, Rp, Rs, Wp);
```

part 4

```
[sos, gain] = zp2sos(z, p, k); % get sos digital filter
sos_range = linspace(0, Ws * fn + 20, 1e3); % plot up to fstop + 20
sos_response = gain * freqz(sos, sos_range, fs);
sos_response_dB = 20 * log10(abs(sos_response));

% plot filter
figure;
plot(sos_range, sos_response_dB);
xline(Wp * fn, '--', 'Passband');
xline(Ws * fn, '--', 'Stopband');
yline(-Rp, '--', 'Passband');
yline(-Rs, '--', 'Stopband');
title("SOS Digital Filter");
xlabel('Frequency [hZ]');
ylabel('Magnitude [dB]');
ylim([-50, 10]);
```



part 5

```
S = gain * sosfilt(sos, norm_brake_data);

% plot raw data
figure;
plot(t, norm_brake_data);
title("Raw Data");
xlabel("Time [s]");

% plot filtered data
figure;
plot(t, S);
ylim([0, 1]);
yline(0.33, '--', 'DC Bias'); %is this the correct DC bias?
title("Filtered Data");
xlabel("Time [s]");
```

