

# Data Structures and Algorithms

## Chapter 9

# Priority Queues

- Each element in a queue is associated with a *key*.
- When an element is removed, an element with a *minimal* (or *maximal*) *key* is removed.
- Usually keys are numbers.
- Objects can be used as keys as far as there is a total ordering among those objects.

# Priority Queues

## ADT

- `insert( $k$ ,  $v$ )`: Create an entry with key  $k$  and value  $v$  in the priority queue.
- `min( )`: Returns (but does not remove) an entry ( $k$ ,  $v$ ) with the minimum key. Returns null if the priority queue is empty.
- `removeMin( )`: Removes and returns an entry ( $k$ ,  $v$ ) with the minimum key. Returns null if the priority queue is empty.
- `size( )`: Returns the number of entries in the priority queue.
- `isEmpty( )`: Returns true if the priority queue is empty. Returns false, otherwise.

# Priority Queues

## ADT

- Illustration

Method	Return Value	Priority Queue Contents
insert(17, A)		{(17, A)}
insert(4, P)		{(4, P) , (17, A)}
insert(15, X)		{(4, P) , (15, X), (17, A)}
size( )	3	{(4, P) , (15, X), (17, A)}
isEmpty( )	false	{(4, P) , (15, X), (17, A)}
min( )	(4, P)	{(4, P) , (15, X), (17, A)}
removeMin( )	(4, P)	{(15, X), (17, A)}
removeMin( )	(15, X)	{(17, A)}
removeMin( )	(17, A)	{ }
removeMin( )	null	{ }
size( )	0	{ }
isEmpty( )	true	{ }

# Priority Queues

## Implementation

- An element in a priority queue has *key* and *value*.
- *Entry* interface is used to store a key-value pair.

```
1 public interface Entry<K,V> {  
2     K getKey();  
3     V getValue();  
4 }
```

# Priority Queues

## Implementation

- *PriorityQueue* interface

```
1 public interface PriorityQueue<K,V> {  
2     int size();  
3     boolean isEmpty();  
4     Entry<K,V> insert(K key, V value) throws  
                                     IllegalArgumentException;  
5     Entry<K,V> min();  
6     Entry<K,V> removeMin();  
7 }
```

# Priority Queues

## Implementation

- Keys must have *total ordering*.
- Total ordering: there is a linear ordering among all keys.
- Total ordering of a comparison rule,  $\rho$ , satisfies the following properties:
  - Comparability property:  $k_1 \rho k_2$  or  $k_2 \rho k_1$ .
  - Antisymmetric property: If  $k_1 \rho k_2$  and  $k_2 \rho k_1$ , then  $k_1 = k_2$ .
  - Transitive property: If  $k_1 \rho k_2$  and  $k_2 \rho k_3$ , then  $k_1 \rho k_3$ .
- If keys have total ordering, *minimal key* is well defined
- $key_{min}$  is a key such that:  $key_{min} \rho k$ , for all  $k$
- Note: it will be easy to understand if you replace  $\rho$  with  $\leq$  (or any other familiar relation)

# Priority Queues

## Implementation

- Two ways to compare objects in Java
  - *compareTo* and *compare*
- *compareTo* is defined in *java.util.Comparable* interface.
- A class must override and implement the *compareTo* method.
- *Ordering* defined in the *compareTo* method is called *natural ordering*.
- Usage: *a.compareTo(b)* returns
  - a negative number, if  $a < b$
  - zero, if  $a = b$
  - a positive number, if  $a > b$
- Many Java classes implemented *Comparable* interface.



# Priority Queues

## Implementation

- *compare* is defined in *java.util.Comparator* interface.
- Use this to compare not by natural ordering
- Need to write a separate customized comparator
- Example: To compare strings by length (natural ordering is lexicographic ordering).
- First, write a customized comparator method

```
1 public class StringLengthComparator implements Comparator<String> {  
2     public int compare(String a, String b){  
3         if (a.length() < b.length()) return -1;  
4         else if (a.length() == b.length()) return 0;  
5         else return 1;  
6     }  
7 }
```

# Priority Queues

## Implementation

- Then, use it as follows:

```
8  public class ComparatorTest {
9      public static void main(String[] args) {
10          StringLengthComparator c = new StringLengthComparator();
11          String s1 = "tiger";
12          String s2 = "sugar";
13          String s3 = "coffee";
14          String s4 = "cat";
15          System.out.println("Compare s1 and s2: " + c.compare(s1, s2)); // 0
16          System.out.println("Compare s1 and s3: " + c.compare(s1, s3)); // -1
17          System.out.println("Compare s1 and s4: " + c.compare(s1, s4)); // 1
27      }
28 }
```

# Priority Queues

## AbstractPriorityQueue Base Class

- Provides common features for different concrete implementations.
- An entry in a queue is implemented as *PQEntry*:

```
1  protected static class PQEntry<K,V> implements Entry<K,V> {  
2      private K k; // key  
3      private V v; // value  
4      public PQEntry(K key, V value) {  
5          k = key;  
6          v = value;  
7      }  
8      public K getKey() { return k; }  
9      public V getValue() { return v; }  
10     protected void setKey(K key) { k = key; }  
11     protected void setValue(V value) { v = value; }  
12 }
```

# Priority Queues

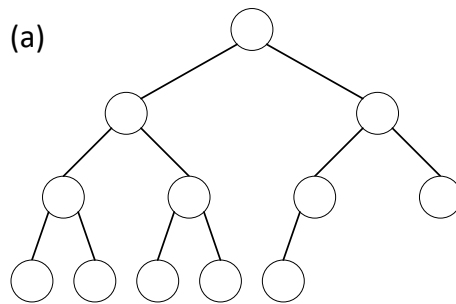
## Implementing Using a Heap

- Implementation with an unsorted list
- Implementation with a sorted list
- We will focus on implementation with *heap*.
- *Heap* is a binary tree with the following properties:
  - *Heap-order property*: In a heap  $T$ , for every position  $p$ , except the root, the key stored at  $p$  is greater than or equal to the key stored at  $p$ 's parent. (*minimum-oriented heap*)
  - *Complete binary tree property*: A heap is a complete binary tree.

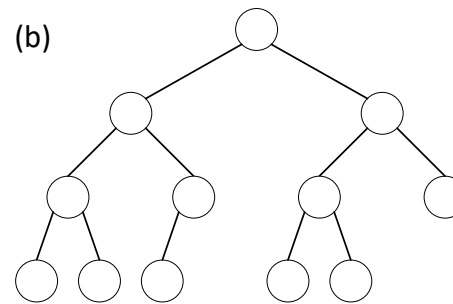
# Priority Queues

## Implementing Using a Heap

- Complete binary tree
  - Levels  $0, 1, \dots, h - 1$  of  $T$  have the maximal number of nodes (in other words, level  $i$  has  $2^i$  nodes, where  $0 \leq i \leq h - 1$ ), and
  - Nodes at level  $h$  are in the leftmost possible positions at that level.



yes

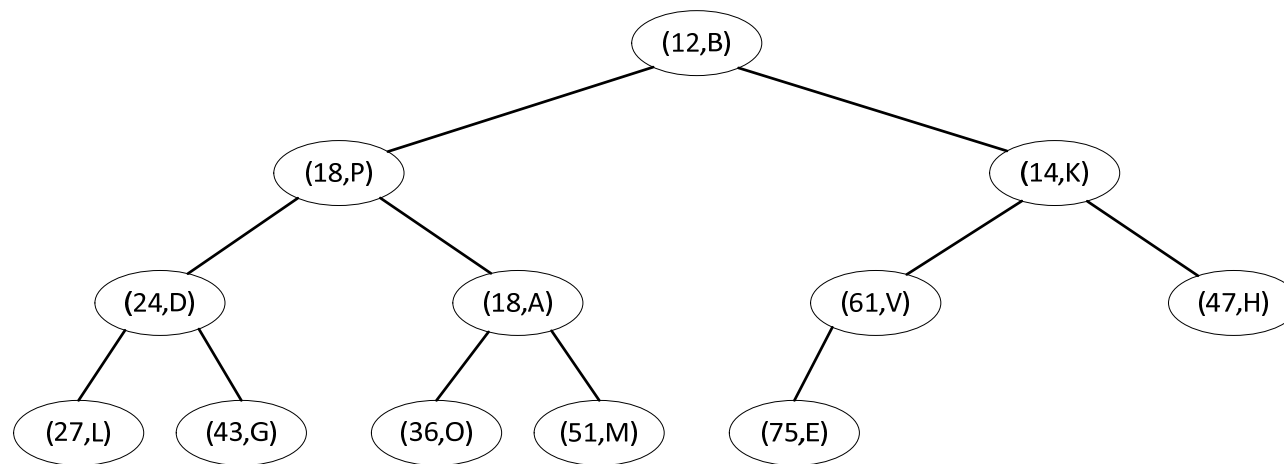


no

# Priority Queues

## Implementing Using a Heap

- Priority queue implemented using a heap example:



- Height of a heap with  $n$  entries is  $h = \lfloor \log n \rfloor$

# Priority Queues

## Implementing Using a Heap

- Adding an entry to a heap
  - Step 1: Add new entry at the “end” of the heap
  - Step 2: Reorganize the heap (because adding new entry may violate the heap-order property)
- Reorganization is done by *up-heap bubbling*.

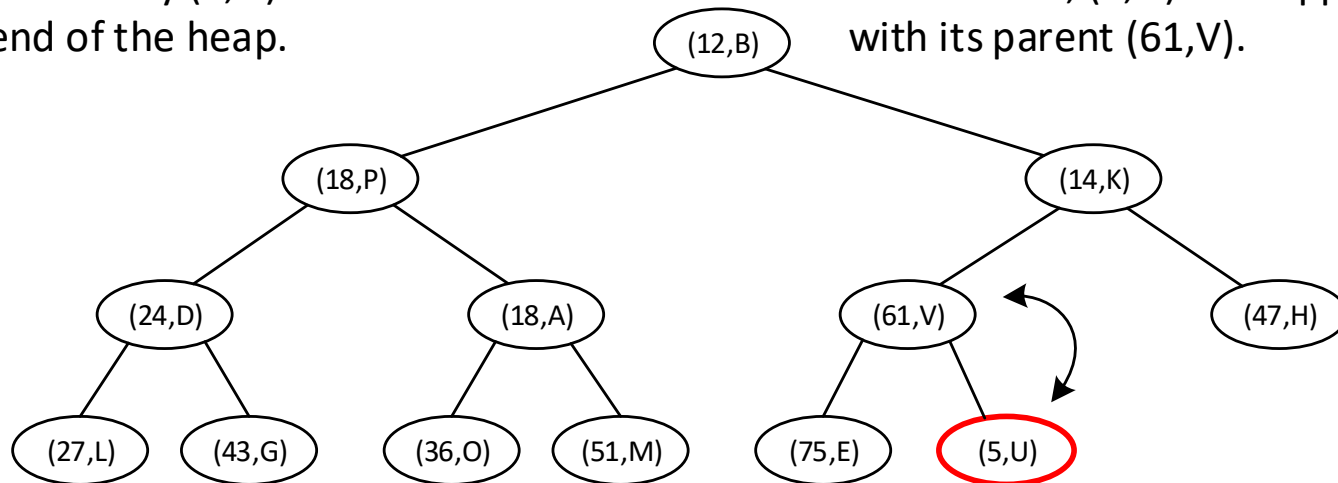
# Priority Queues

## Implementing Using a Heap

- Illustration

New entry (5,U) is added to the end of the heap.

Since  $5 < 61$ , (5,U) is swapped with its parent (61,V).



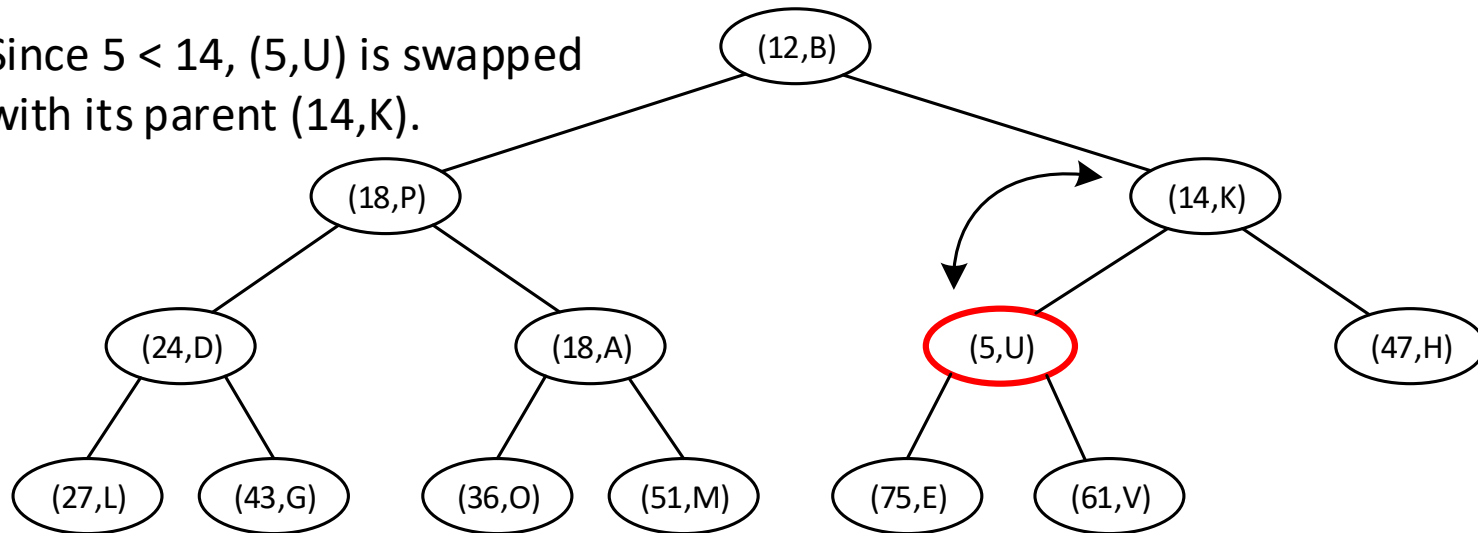


# Priority Queues

## Implementing Using a Heap

- Illustration

Since  $5 < 14$ , (5,U) is swapped with its parent (14,K).

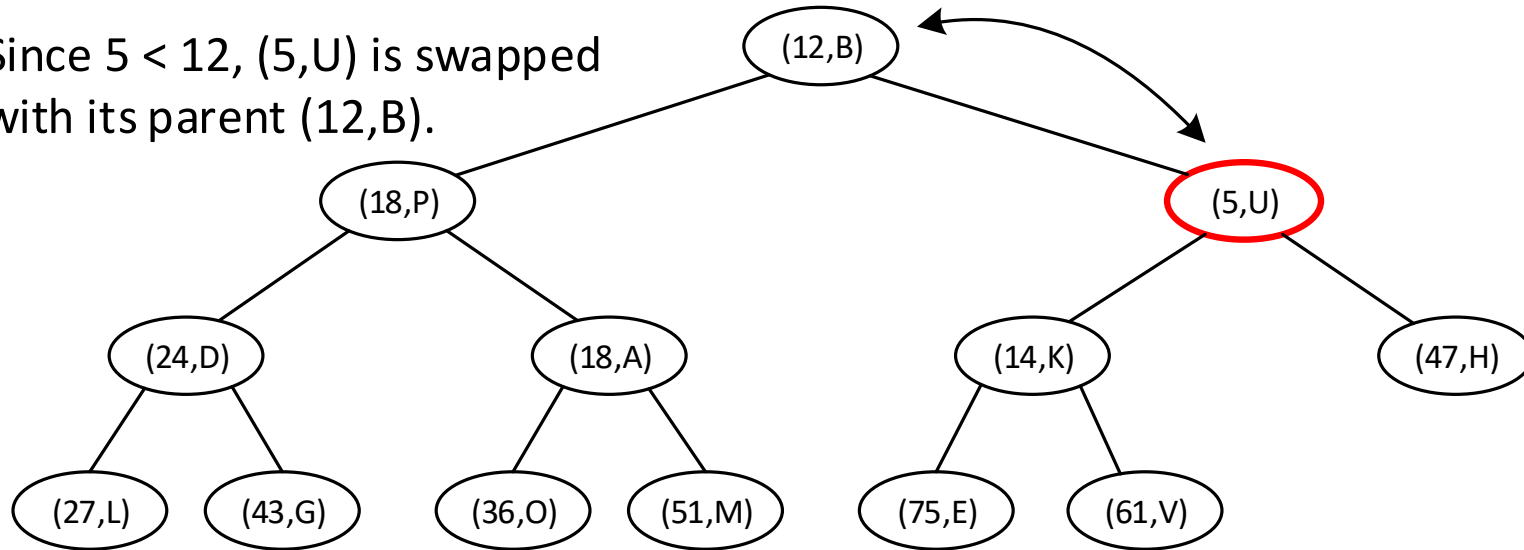


# Priority Queues

## Implementing Using a Heap

- Illustration

Since  $5 < 12$ , (5,U) is swapped with its parent (12,B).

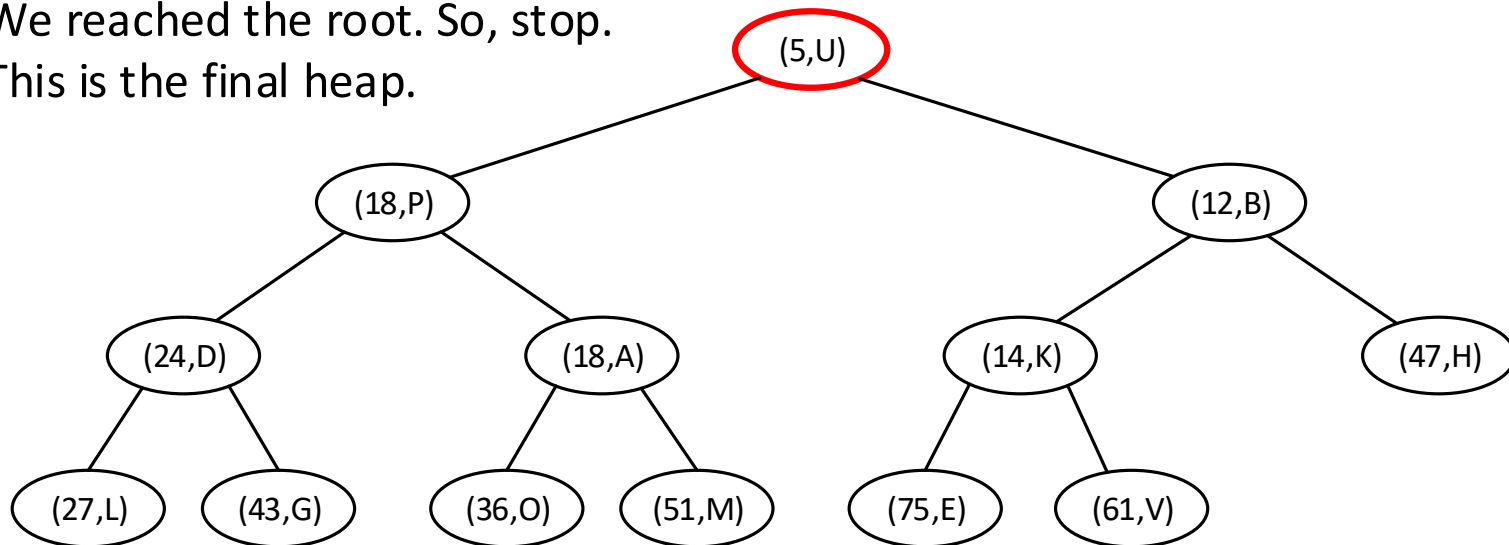


# Priority Queues

## Implementing Using a Heap

- Illustration

We reached the root. So, stop.  
This is the final heap.



# Priority Queues

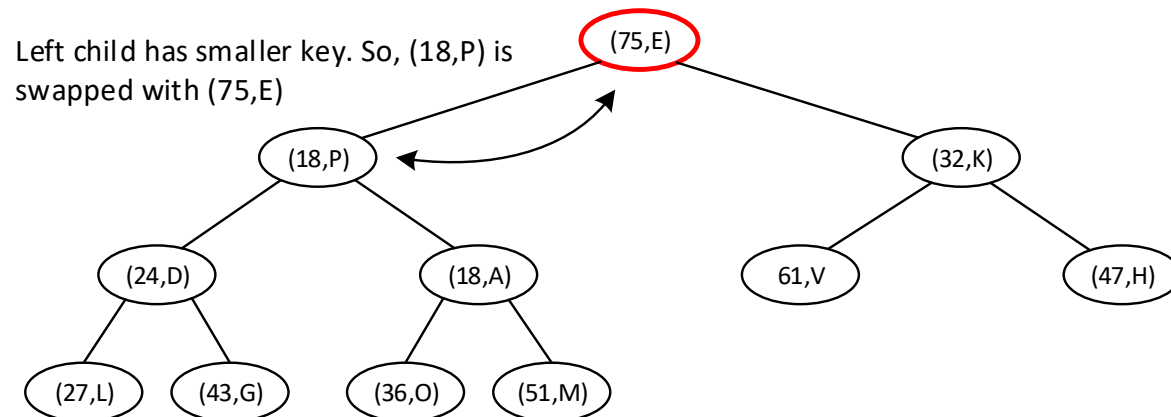
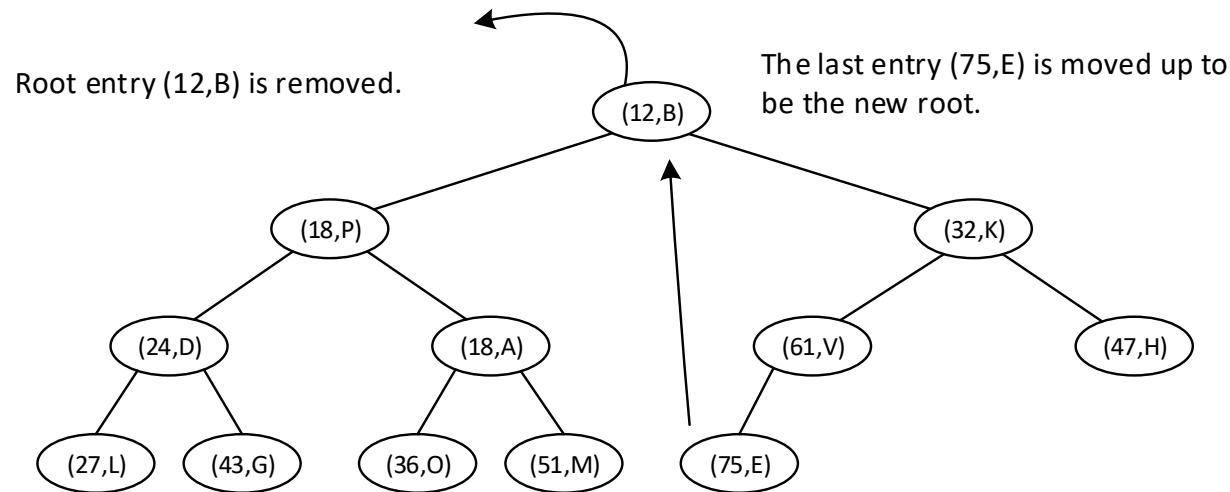
## Implementing Using a Heap

- Removing the entry with minimal key
  - Step1: Remove the root
  - Step 2: Last node is move up to the root and perform *down-heap bubbling*.
- Down-heap bubbling is opposite of up-heap bubbling.

# Priority Queues

## Implementing Using a Heap

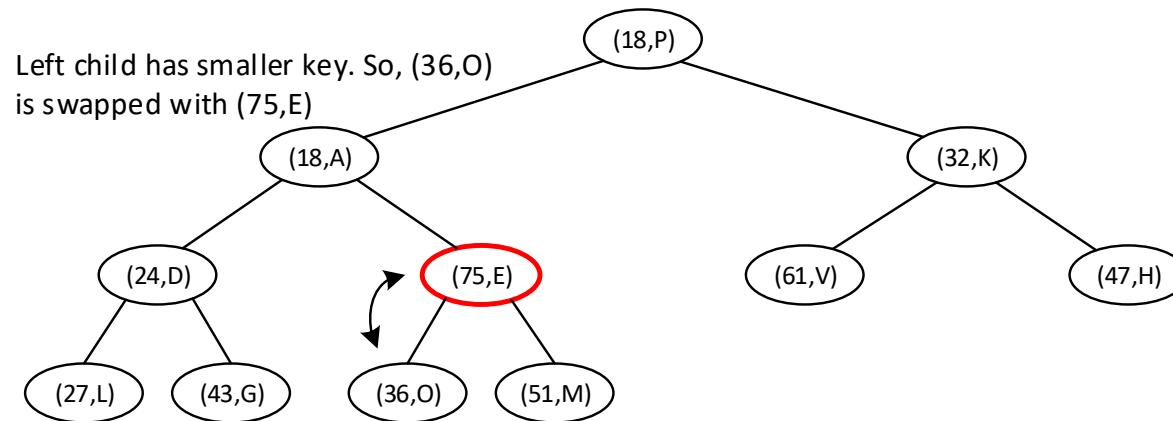
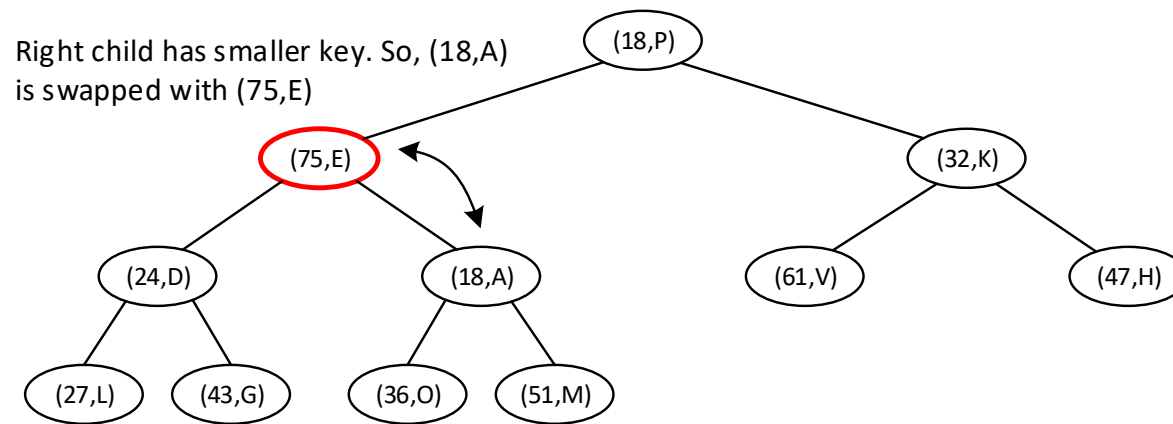
- Illustration



# Priority Queues

## Implementing Using a Heap

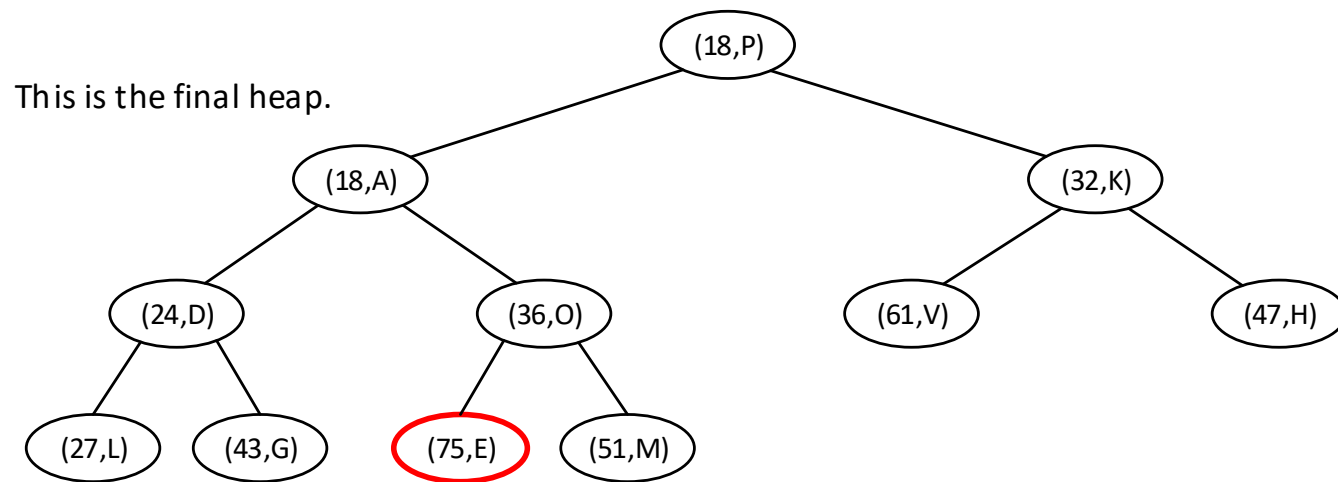
- Illustration



# Priority Queues

## Implementing Using a Heap

- Illustration



# Priority Queues

## Array-Based Heap

- The level number of a position  $p$ ,  $f(p)$ , is defined as follow:
  - If  $p$  is the root,  $f(p) = 0$
  - If  $p$  is the left child of position  $q$ ,  $f(p) = 2 * f(q) + 1$
  - If  $p$  is the right child of position  $q$ ,  $f(p) = 2 * f(q) + 2$
- The level number is used as the index in an array where the entry with position  $p$  is stored.



# Priority Queues

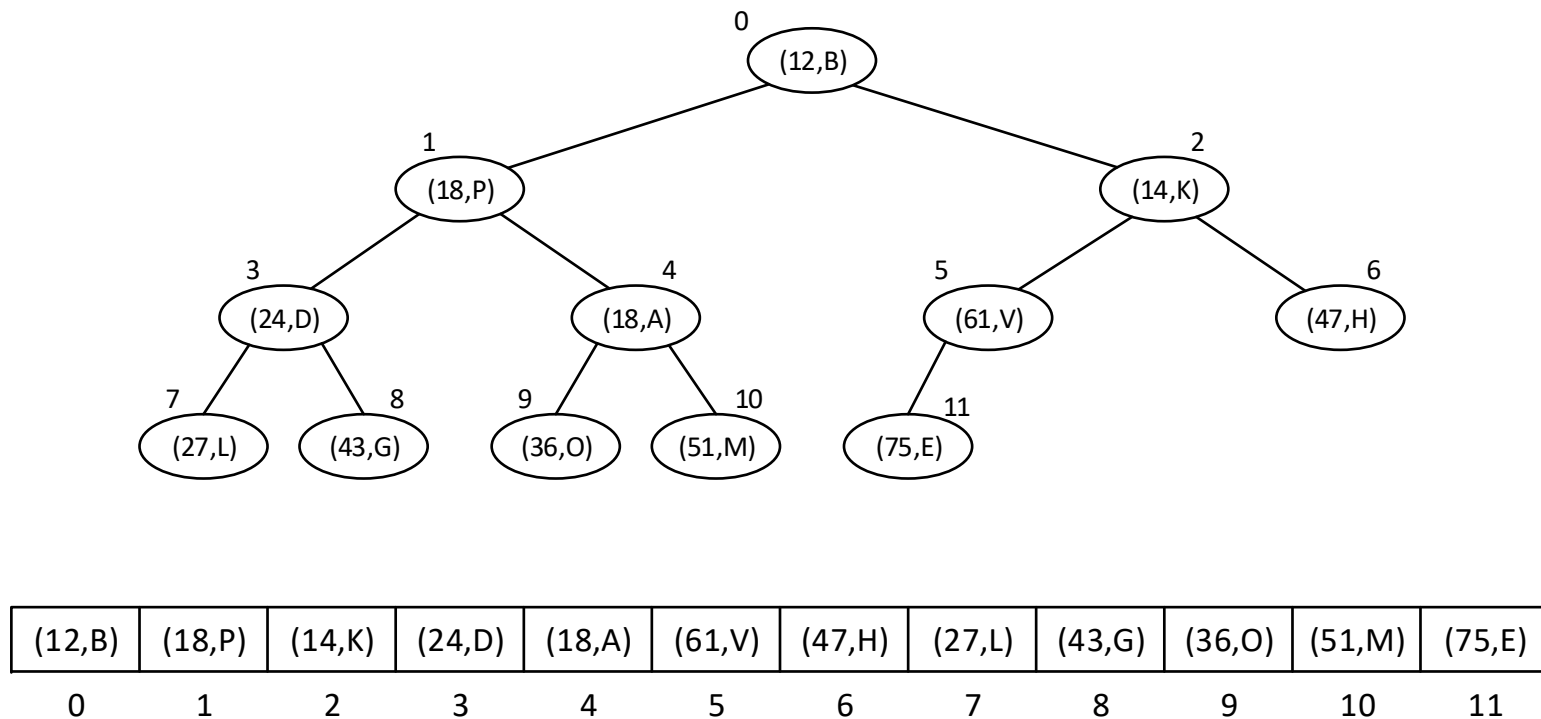
## Array-Based Heap

- Then, the entry at position  $p$  is stored in  $A[f(p)]$ .
- Index of the root node is 0.
- Index of left child of  $p = 2 * f(p) + 1$
- Index of right child of  $p = 2 * f(p) + 2$
- Index of parent of  $p = \lfloor (f(p) - 1) / 2 \rfloor$

# Priority Queues

## Array-Based Heap

- Example



# Priority Queues

## Array-Based Heap

- *HeapPriorityQueue* class implements a priority queue using a heap.
- A heap is implemented using *ArrayList*.
- Will briefly discuss *upheap*, *downheap*, *insert*, and *removeMin* methods.
- *HeapPriorityQueue.java* code

# Priority Queues

## Analysis of Heap-Based Priority Queue

- insertion:
  - *upheap* method takes  $O(\log n)$
  - So, insertion takes  $O(\log n)$
- removeMin:
  - *downheap* method takes  $O(\log n)$
  - So, removeMin takes  $O(\log n)$

Method	Running Time
size, isEmpty	$O(1)$
min	$O(1)$
insert	$O(\log n)$
removeMin	$O(\log n)$

# Priority Queues

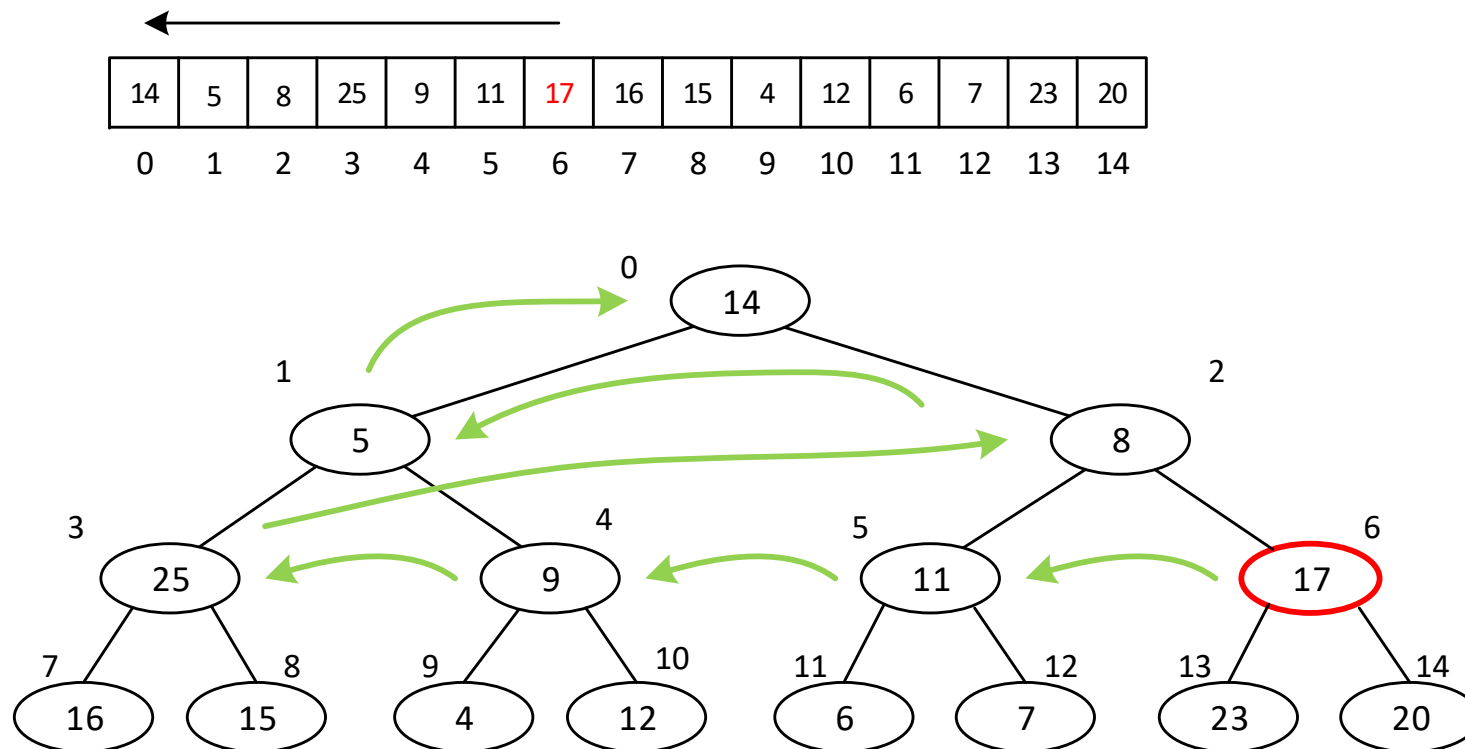
## Bottom-up Heap Construction

- Given  $n$  elements, we can build a heap with  $n$  successive insertions  $\Rightarrow$  takes  $O(n \log n)$  time.
- $O(n)$  time algorithm
  - Begin at the parent of the last node, move backward to the root.
  - At each node, perform down-heap bubbling.

# Priority Queues

## Bottom-up Heap Construction

- Illustration



# Priority Queues

## Bottom-up Heap Construction

- Java implementation

```
1  public HeapPriorityQueue(K[ ] keys, V[ ] values) {  
2      super();  
3      for (int j=0; j < Math.min(keys.length, values.length); j++)  
4          heap.add(new PQEntry<>(keys[j], values[j]));  
5      heapify();  
6  }  
  
7  protected void heapify() {  
8      int startIndex = parent(size()-1); // start at PARENT of last entry  
9      for (int j=startIndex; j >= 0; j--) // loop until processing the root  
10         downheap(j);  
11 }
```

# Priority Queues

## Java's Priority Queue

- *java.util.PriorityQueue*
- An entry is a single element.
- Some operations in Java's *PriorityQueue*
  - `add(E e)`: Inserts the specified element *e* to the priority queue.
  - `isEmpty( )`: Returns true if the priority queue contains no element.
  - `peek( )`: Retrieves, but does not remove, a minimal element from the priority queue.
  - `remove( )`: Removes a minimal element from the priority queue.
  - `size( )`: Returns the number of elements in the priority queue.



# Priority Queues

## Heap-Sort

- Uses array-based heap data structure.
- In-place sorting: no additional storage is used.
- Uses a *maximum-oriented* heap.
- *maximum-oriented* heap: In a heap  $T$ , for every position  $p$ , except the root, the key stored at  $p$  is *smaller* than or equal to the key stored at  $p$ 's parent.
- Sorting steps:
  1. Given  $n$  elements are inserted into a maximum-oriented heap.
  2. Repeat the following until only one node is left in the heap:  
Root is swapped with the last node, heap size is decremented, perform down-heap bubbling.

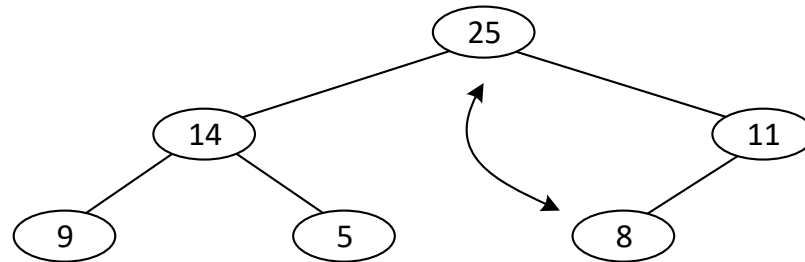
# Priority Queues

## Sorting with Priority Queue

- Illustration

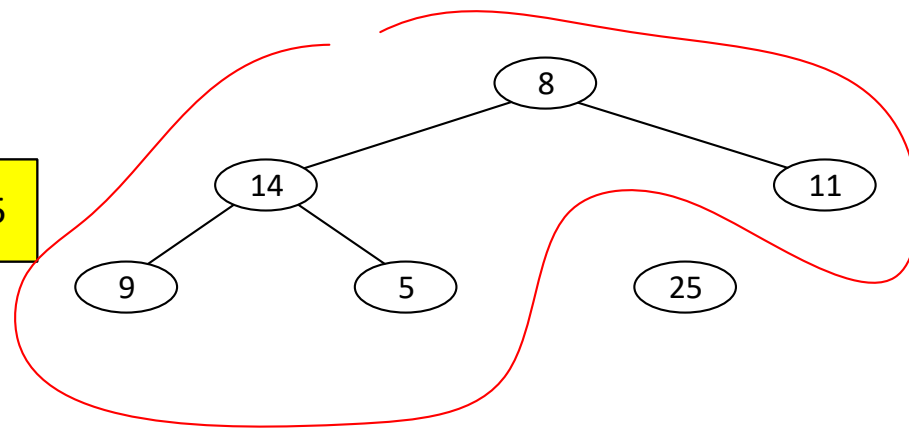
The maximum-oriented heap after the first step.  
The root node and the last node is swapped.  
Heap size is decremented.

25	14	11	9	5	8
----	----	----	---	---	---



Down-heap bubbling is applied on the root.

8	14	11	9	5	25
---	----	----	---	---	----



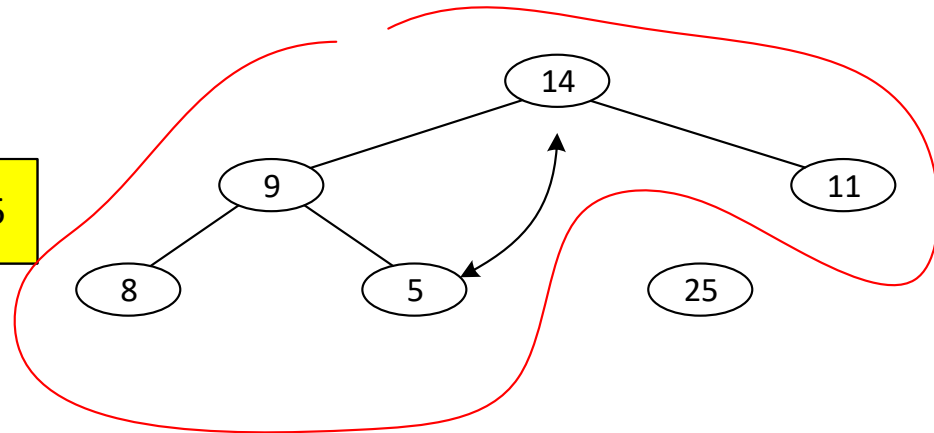
# Priority Queues

## Sorting with Priority Queue

- Illustration

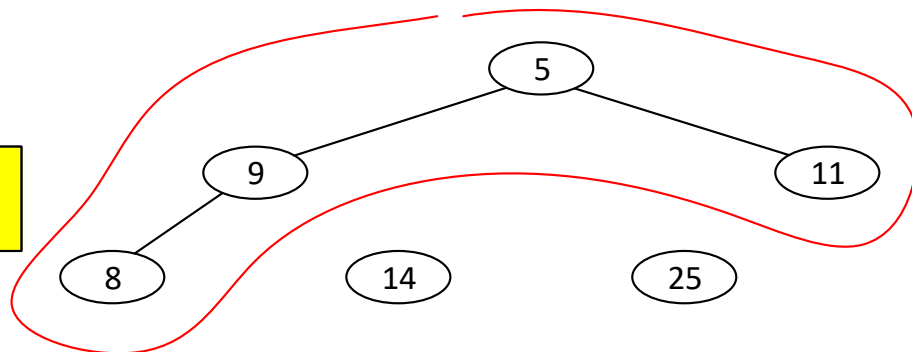
The root node is swapped with the last node. Heap size is decremented.

14	9	11	8	5	25
----	---	----	---	---	----



Down-heap bubbling is applied on the root.

5	9	11	8	14	25
---	---	----	---	----	----



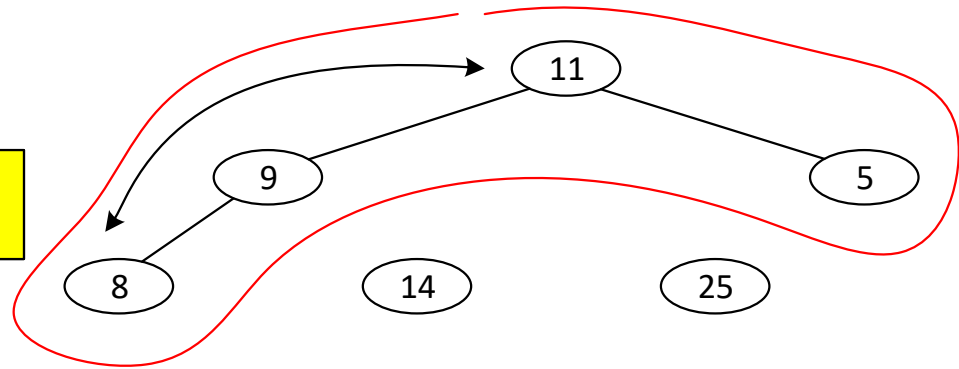
# Priority Queues

## Sorting with Priority Queue

- Illustration

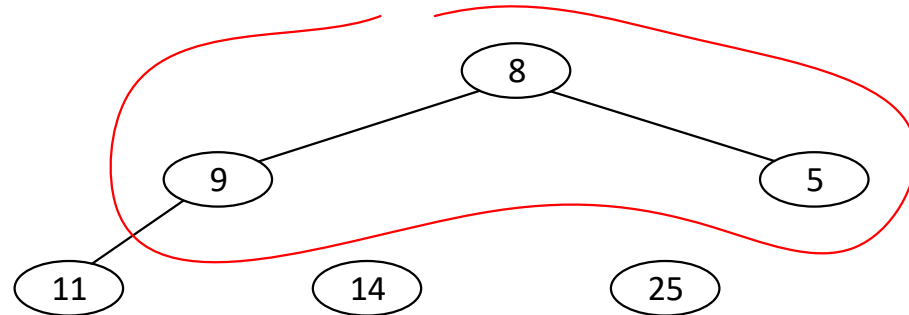
The root node is swapped with the last node. Heap size is decremented.

11	9	5	8	14	25
----	---	---	---	----	----



Down-heap bubbling is applied on the root.

8	9	5	11	14	25
---	---	---	----	----	----



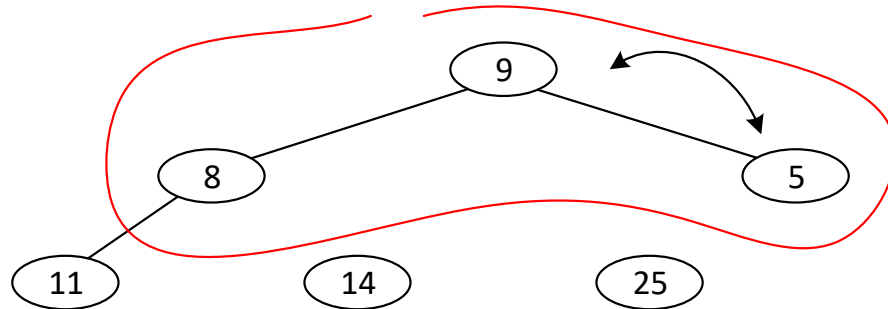
# Priority Queues

## Sorting with Priority Queue

- Illustration

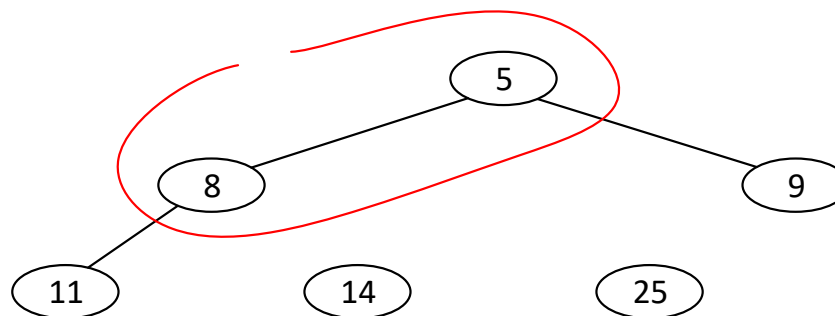
The root node is swapped with the last node. Heap size is decremented.

9	8	5	11	14	25
---	---	---	----	----	----



Down-heap bubbling is applied on the root.

5	8	9	11	14	25
---	---	---	----	----	----



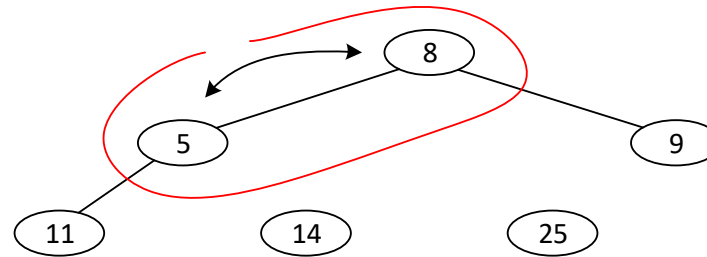
# Priority Queues

## Sorting with Priority Queue

- Illustration

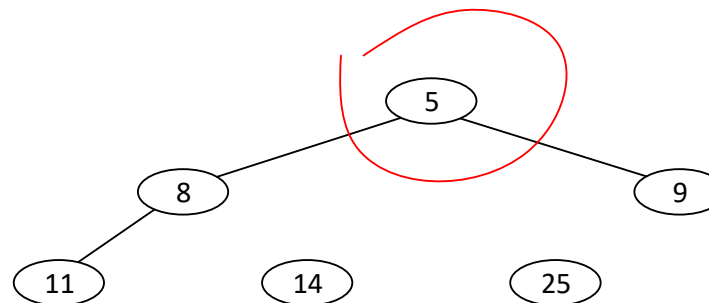
The root node is swapped with the last node. Heap size is decremented.

8	5	9	11	14	25
---	---	---	----	----	----



At this time the array is sorted.

5	8	9	11	14	25
---	---	---	----	----	----



# Priority Queues

## Adaptable Priority Queue

- Can remove arbitrary entry (not just the root).
- Can replace the key of an entry.
- Can replace the value of an entry.

# References

- M.T. Goodrich, R. Tamassia, and M.H. Goldwasser, “Data Structures and Algorithms in Java,” Sixth Edition, Wiley, 2014.