

## COS30018 Assignment B – Task 4

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This week I created a function which takes in the desired type of deep learning network (LSTM, GRU, RNN), amount of layers, layer size and dropout amount. It will create a new keras sequential model of n layers and compile it to use for training.

The type of DL network is parsed into the function as a string, so the first thing that the function contains is a dictionary to map a string into the correct keras layer class. If the 'model\_type' parsed to the func is not recognised, then the default of LSTM will be used. Then a new sequential model will be created. From there, the function will iterate through a loop 'n\_layers' – 1 times, adding a new layer to the model on each iteration. Note that on the first iteration, the layer added includes the input data as 'input\_shape'. The subsequent layers do not need this as they receive the data from the previous layers. Once that is done, the final layer is added which has 'return\_sequences' set to false as there are no more layers for it to return the data to. Lastly, the function defines loss and optimizer values, the output layer with a single neuron and compiles the model to return to the main program.

See screenshot of code for specifics on the implementation with line by line commenting. Output results for a variety of settings have also been included. LSTM seemed to be the most effective network, but it was sensitive to overtraining and performed worse with an excessive amount of layers.

```

CreateCustomModel.py 2, U
CreateCustomModel.py > ...
1  from tensorflow.keras.models import Sequential
2  from tensorflow.keras.layers import Dense, Dropout, LSTM, SimpleRNN, GRU
3
4  def MakeCustomModel(model_type, input_data, n_layers, units, dropout):
5
6      #dictionary to map model_type to the appropriate Keras class
7      model_layer_dict = {
8          'LSTM': LSTM,
9          'RNN': SimpleRNN,
10         'GRU': GRU
11     }
12
13     #if not valid model type is parsed, select LSTM as default
14     if (model_type not in model_layer_dict):
15         model_type = LSTM
16
17
18     #create a blank sequential model that we will add layers to
19     model = Sequential()
20
21     for i in range(n_layers - 1):
22         if (i == 0):
23             #Add first layer, specify input shape which is not needed in future layers
24             model.add(model_layer_dict[model_type](units, return_sequences=True, input_shape = input_data))
25         else:
26             #add the rest of the layers
27             model.add(model_layer_dict[model_type](units, return_sequences=True))
28
29         # add dropout on each layer, prevents overfitting by randomly dropping some neurons
30         model.add(Dropout(dropout))
31
32
33     # add final layer, dont need to return sequences as this is the output layer
34     model.add(model_layer_dict[model_type](units, return_sequences=False))
35
36     #specify loss function, mean absolute error punishes severe miscalculations
37     loss = "mean_absolute_error"
38     #optimizer minimizes the loss and updates the weights
39     optimizer="rmsprop"
40     # add output layer
41     model.add(Dense(1, activation="linear"))
42     #compile the model and specify the loss, optimizer and metrics to track
43     model.compile(loss=loss, metrics = [loss], optimizer = optimizer)
44     return model #return complete model

```

```

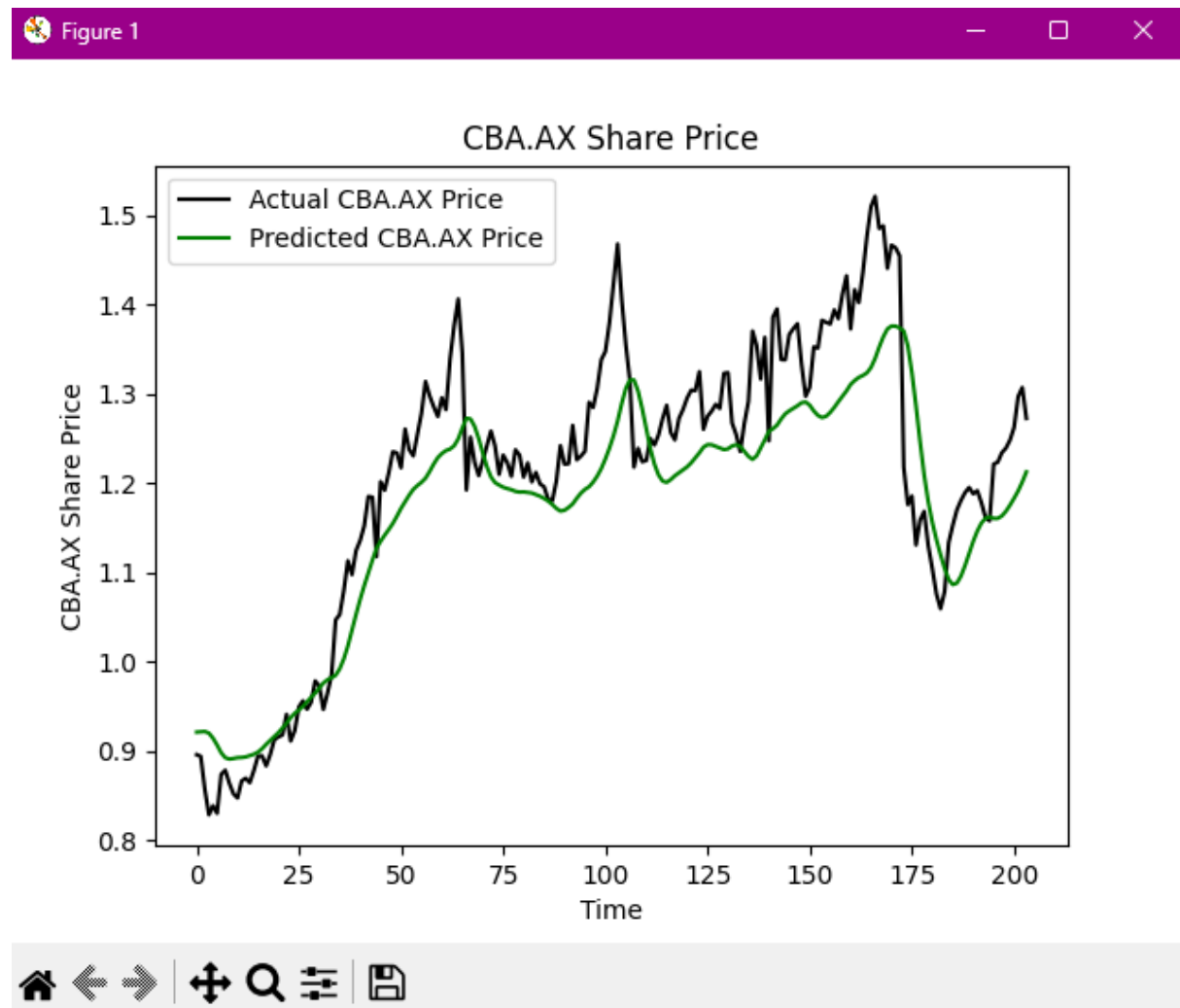
x_train = np.reshape(x_train, (x_train.shape[0], x_train.shape[1], 1))
# We now reshape x_train into a 3D array(p, q, 1); Note that x_train
# is an array of p inputs with each input being a 2D array

input_shape=(x_train.shape[1], 1)

model = MakeCustomModel('LSTM', input_shape, 2, 256, 0.3)

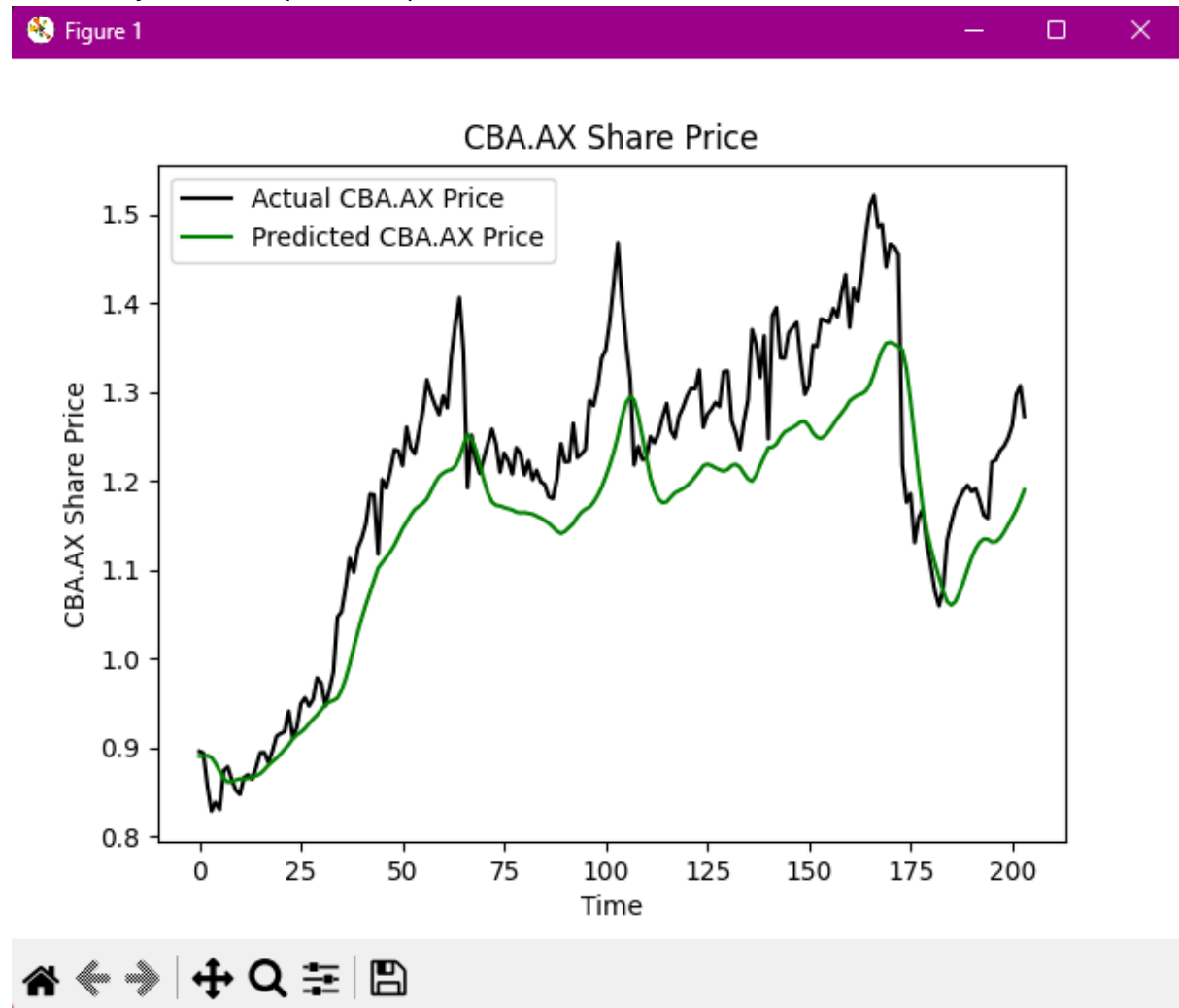
```

LSTM, 3 layers, 256 units, 0.3 dropout, 25 epochs



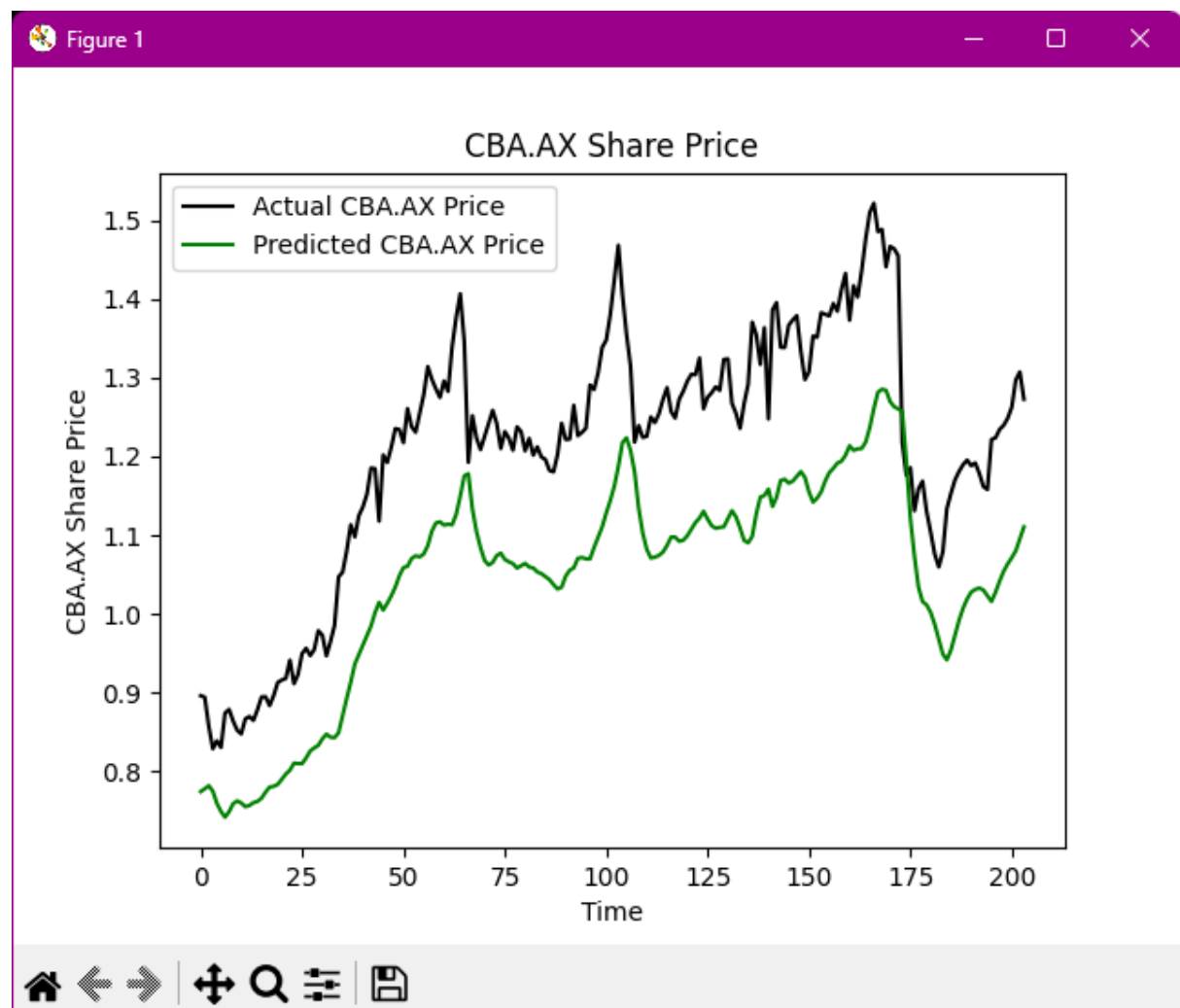
These settings were relatively accurate, but undershooting most of the time.

LSTM, 3 layers, 0.3 dropout, 30 epochs:



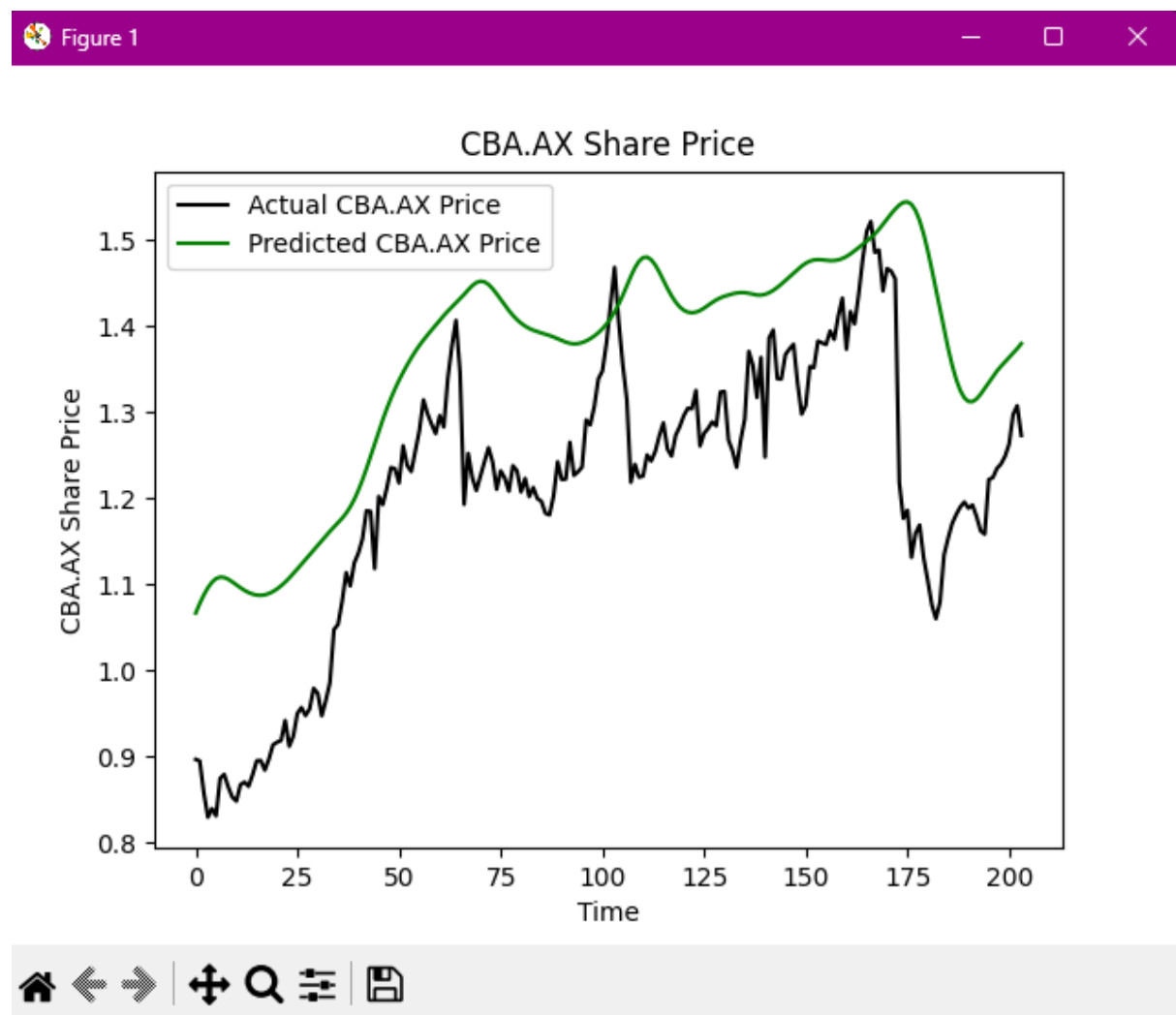
Adding 5 epochs did not have a positive effect.

GRU, 3 layers, 256 units, 0.3 dropout, 25 epochs



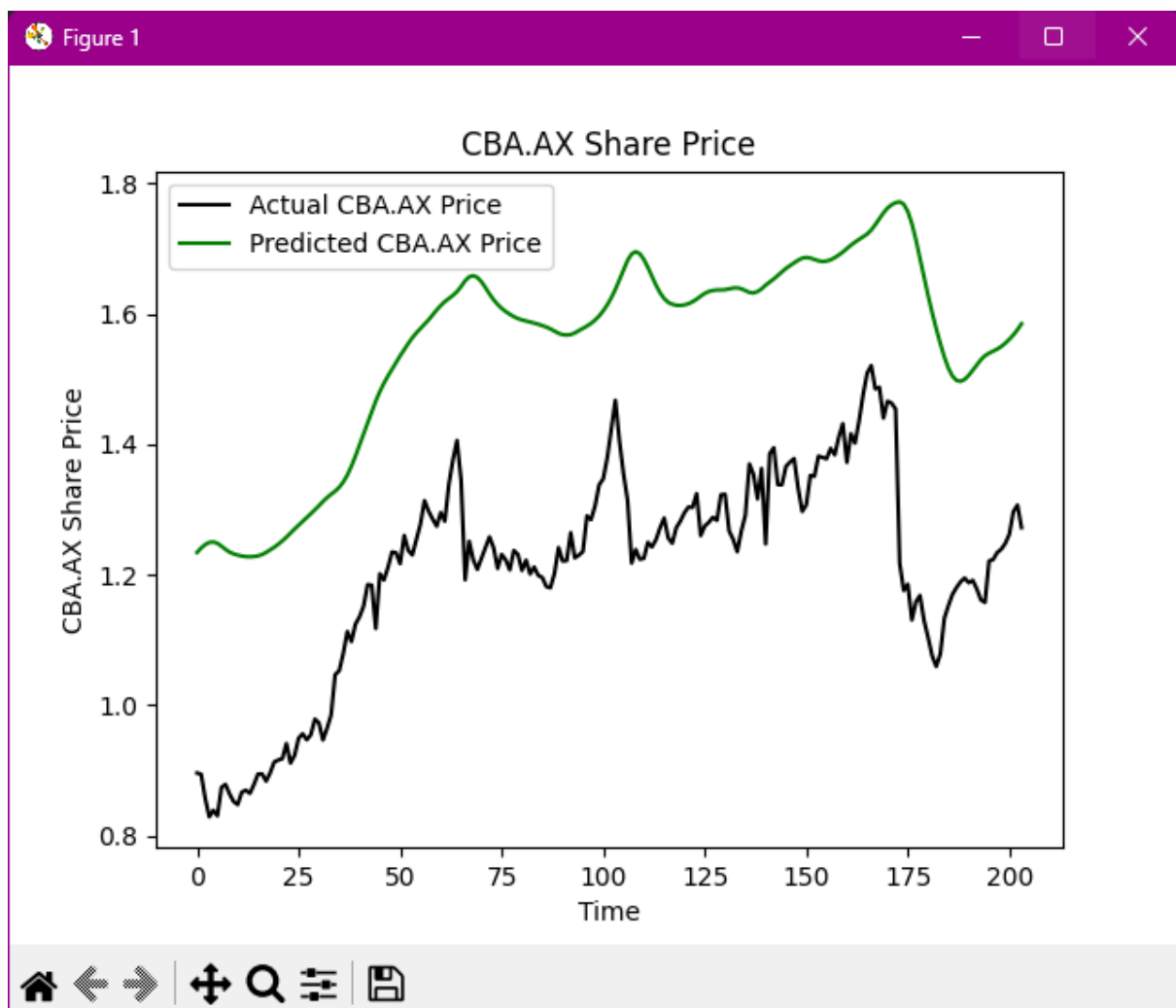
GRU seemed to be less accurate than LSTM.

LSTM, 6 layers, 256 units, 0.3 dropout, 25 epochs



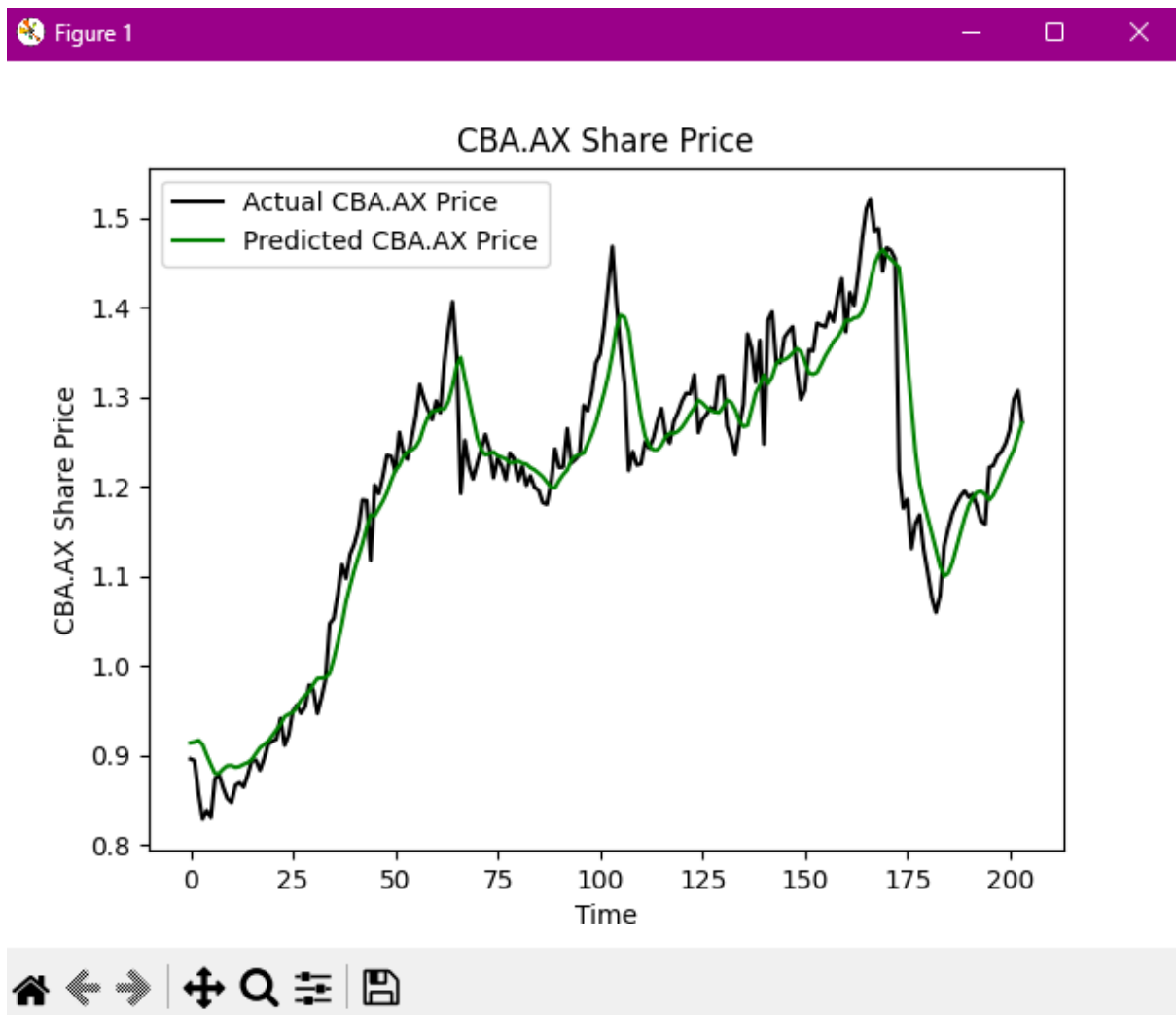
LSTM 6 layers seemed much less accurate than 3 before.

LSTM, 4 layers, 256 units, 0.3 dropout, 25 epochs



LSTM 4 layers seemed even worse than 6 which is interesting. Not sure why it would get worse after 3 and better at 6.

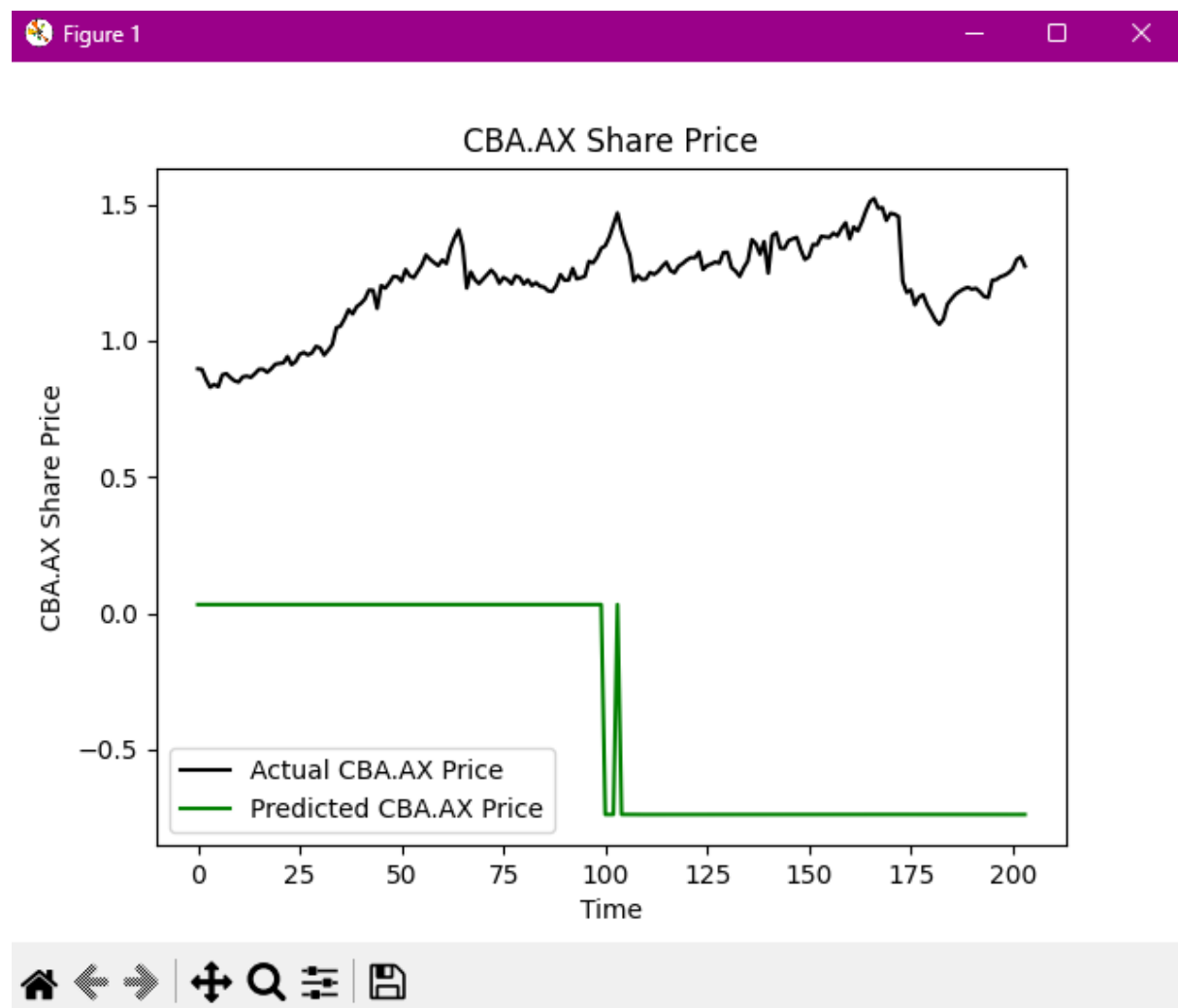
LSTM, 2 layers, 256 units, 0.3 dropout, 25 epochs



This was by far the best result, with 2 layers and 25 epochs.

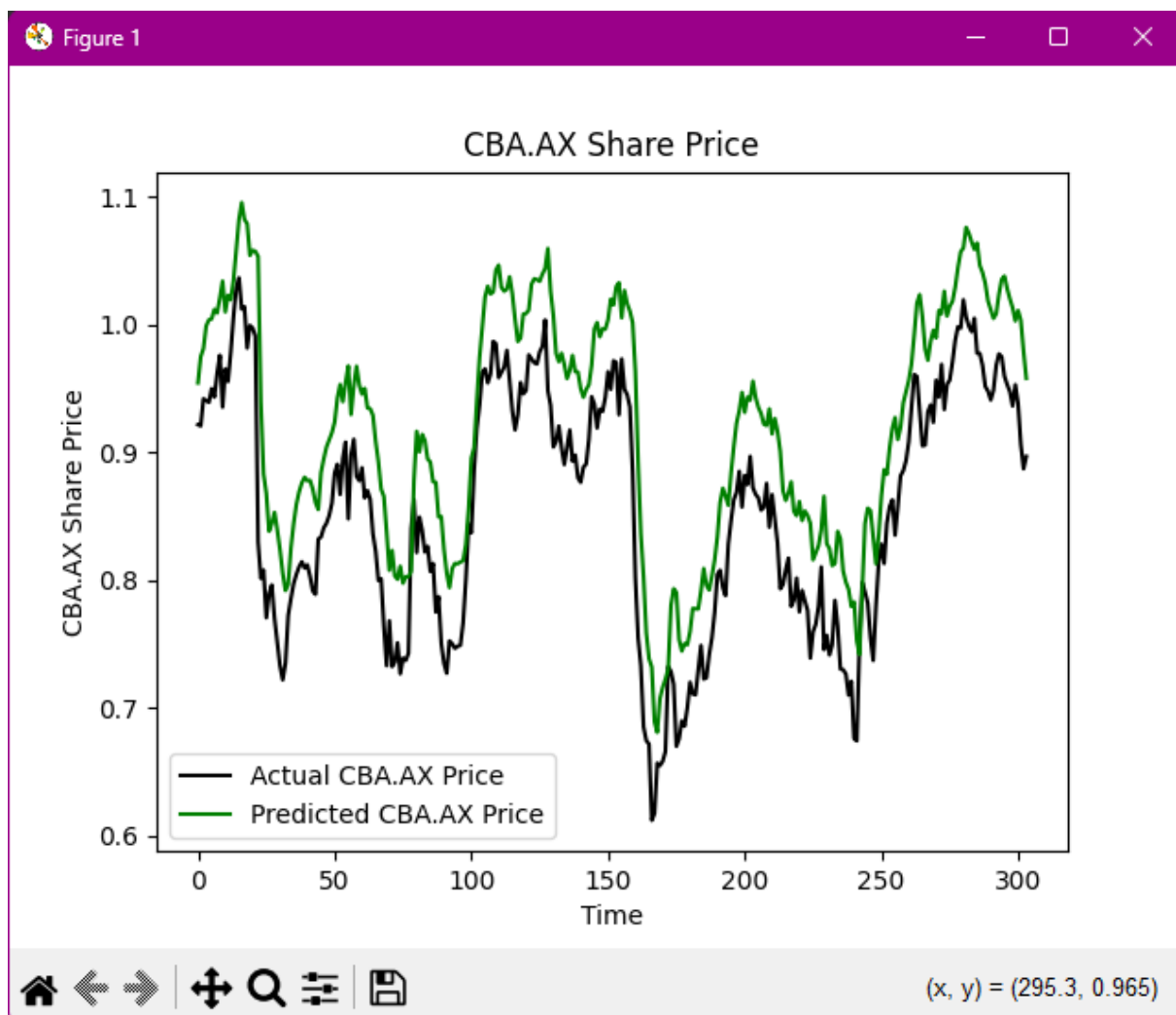


RNN, 2 layers, 1024 units, 0.3 dropout, 50 epochs



RNN networks did not seem to be very effective, even with a large layer size and amount of epochs.

LSTM, 2 layers, 1024 units, 0.3 dropout and 50 epochs



LSTM with 2 large layers and 50 epochs was good but not as good as the 2 layer LSTM from before.