

oomph::DistributableLinearAlgebraObject

```
graph BT; A[oomph::DistributableLinearAlgebraObject] <-- B[oomph::Preconditioner]; B <-- C[oomph::BlockPreconditioner< CRDoubleMatrix >]; C <-- D[oomph::PseudoElasticPreconditioner];
```

oomph::Preconditioner

oomph::BlockPreconditioner< CRDoubleMatrix >

oomph::PseudoElasticPreconditioner