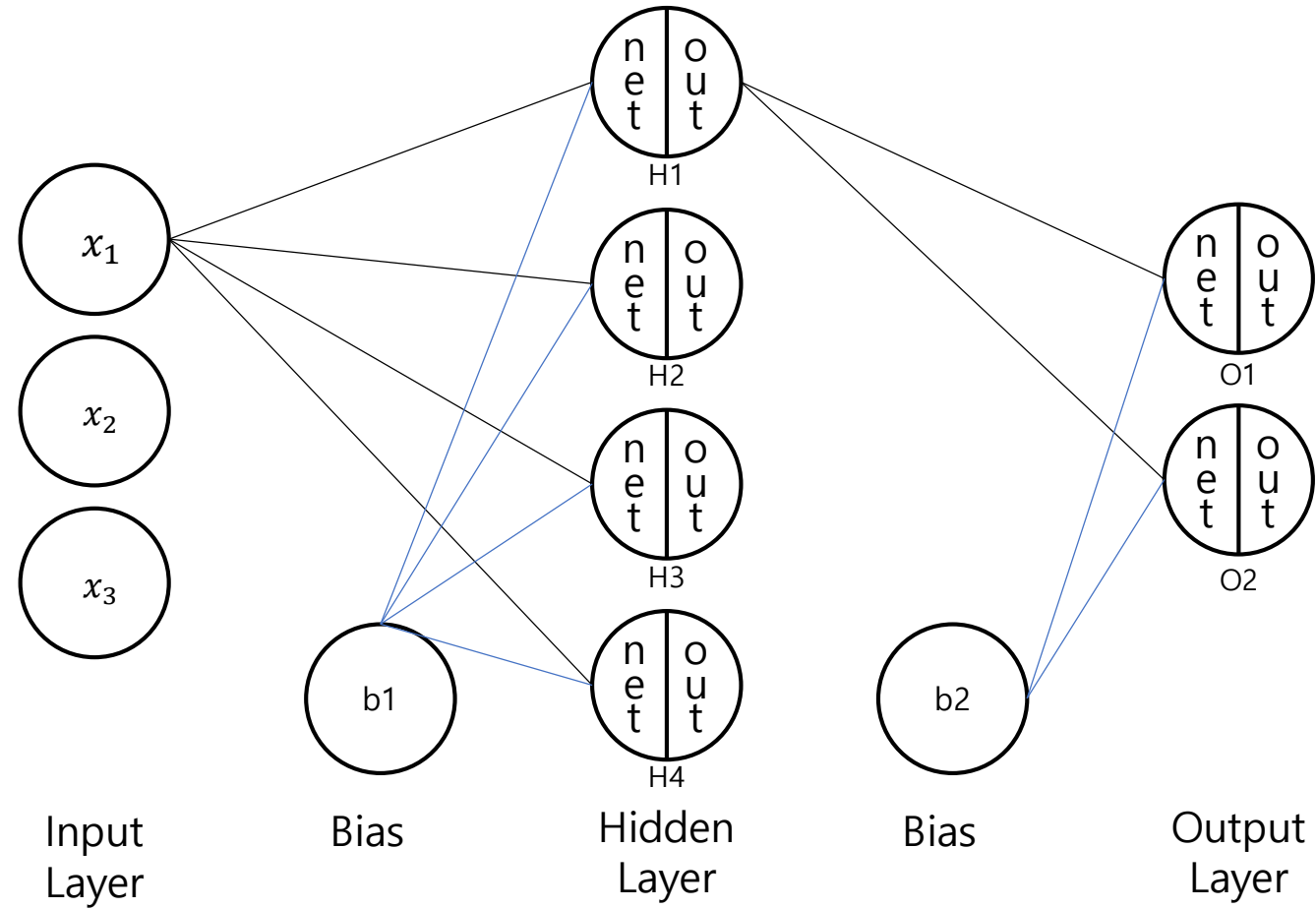


# 오차역전파 계산하기

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## 0. 모델 모형



설명을 위해 3개의 인풋과 4개의 히든 레이어, 2개의 아웃풋으로 구성된 신경망입니다.

## 1. 변수 설명

$$W_{IH} = \begin{pmatrix} w_{11} & w_{12} & w_{13} & w_{14} \\ w_{21} & w_{22} & w_{23} & w_{24} \\ w_{31} & w_{32} & w_{33} & w_{34} \end{pmatrix}, w_{ij} = x_i \text{ to } net_{Hj}$$

$W_{IH}$ : 인풋 레이어에서 히든 레이어로의 가중치

$w_{ij}$ :  $i$ 번째 인풋에서  $j$ 번째 히든 레이어로의 가중치

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$$net_{H1} = b1 + x_1w_{11} + x_2w_{21} + x_3w_{31}$$

$$net_{H2} = b1 + x_1w_{12} + x_2w_{22} + x_3w_{32}$$

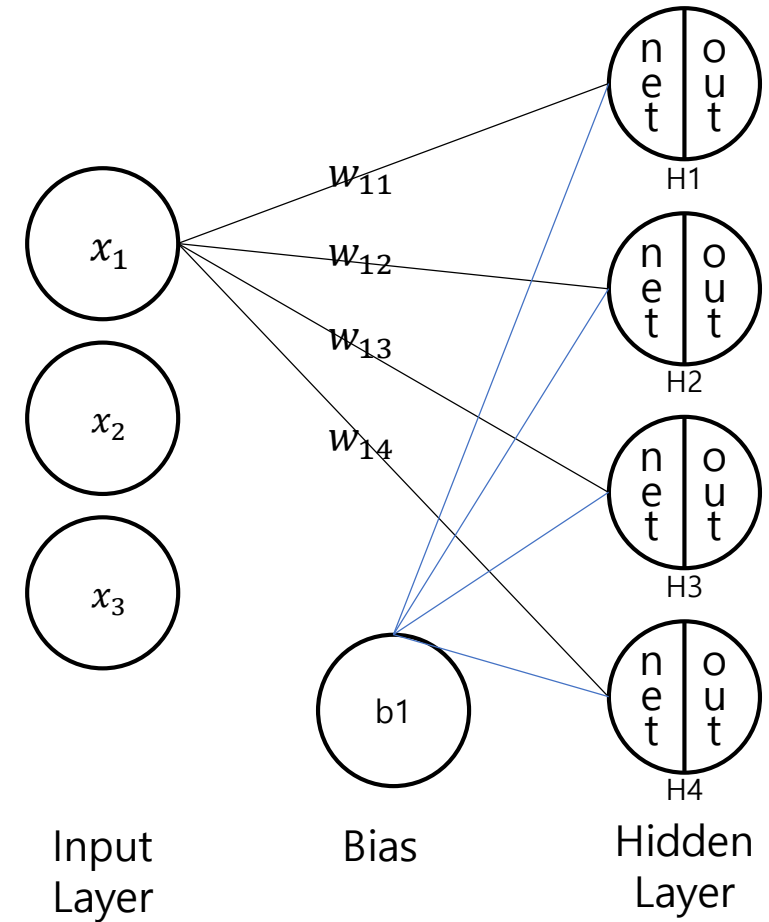
$$net_{H3} = b1 + x_1w_{13} + x_2w_{23} + x_3w_{33}$$

$$net_{H4} = b1 + x_1w_{14} + x_2w_{24} + x_3w_{34}$$

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$$out_{Hi} = \frac{1}{1 + e^{-net_{Hi}}}$$

이 예에서 활성화 함수는 시그모이드 함수를 사용



## 1. 변수 설명

$$W_{HO} = \begin{pmatrix} w'_{11} & w'_{12} \\ w'_{21} & w'_{22} \\ w'_{31} & w'_{32} \\ w'_{41} & w'_{42} \end{pmatrix}, w'_{ij} = \text{out}_{Hi} \text{ to } \text{net}_{Oj}$$

$W_{HO}$ : 히든 레이어에서 아웃풋 레이어로의 가중치

$w'_{ij}$ :  $i$ 번째 히든레이어에서  $j$ 번째 아웃풋 레이어로의 가중치

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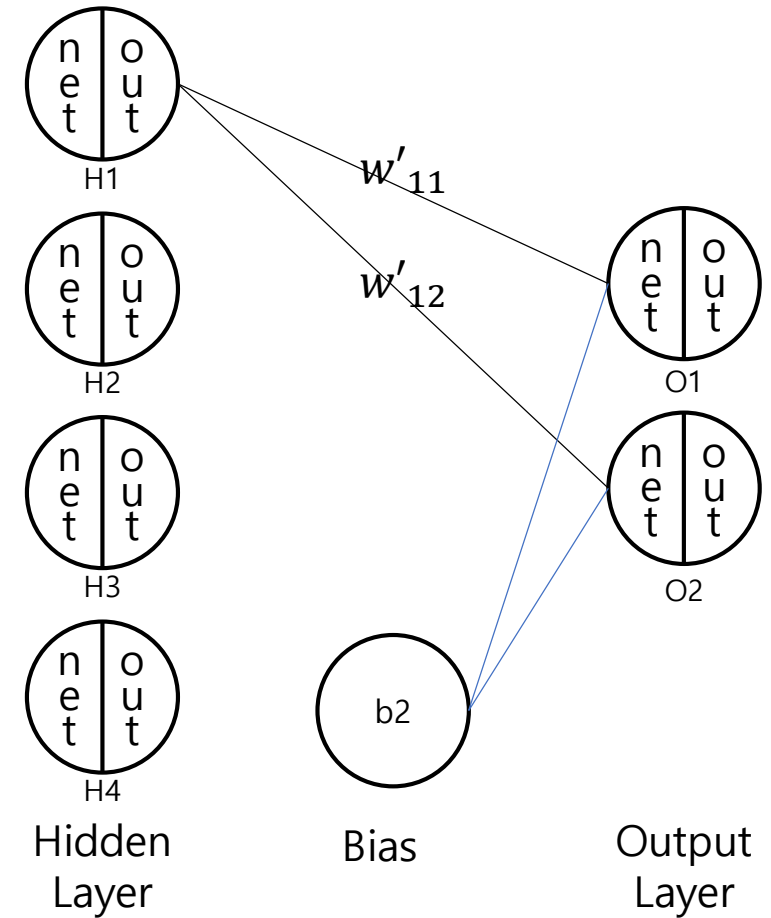
$$\text{net}_{O1} = b2 + \text{out}_{H1}w'_{11} + \text{out}_{H2}w'_{21} + \text{out}_{H3}w'_{31} + \text{out}_{H4}w'_{41}$$

$$\text{net}_{O2} = b2 + \text{out}_{H1}w'_{12} + \text{out}_{H2}w'_{22} + \text{out}_{H3}w'_{32} + \text{out}_{H4}w'_{42}$$

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$$\text{out}_{oi} = \frac{1}{1 + e^{-\text{net}_{oi}}}$$

이 예에서 활성화 함수는 시그모이드 함수를 사용



## 1. 변수 설명

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에러함수

$$\begin{aligned} E_{Total} &= \frac{1}{2} \sum (target - out)^2 \\ &= \frac{1}{2} \{(target_1 - out_{o1})^2 + (target_2 - out_{o2})^2\} \end{aligned}$$

## 2. $W_{HO}$

우선  $W_{HO}$ 에 대해 계산하겠습니다.

1번째 히든레이어에서 1번째 아웃풋으로의 가중치를

체인룰을 이용하면 다음과 같이 계산할 수 있습니다

$$\frac{\partial E_{Total}}{\partial w'_{11}} = \frac{\partial E_{Total}}{\partial out_{01}} \times \frac{\partial out_{01}}{\partial net_{01}} \times \frac{\partial net_{01}}{\partial w'_{11}}$$

$$\frac{\partial E_{Total}}{\partial out_{01}} = (out_{01} - y_1) \dots \dots \dots (1)$$

$$\frac{\partial out_{01}}{\partial net_{01}} = out_{01}(1 - out_{01}) \dots (2)$$

$$\frac{\partial net_{01}}{\partial w'_{11}} = out_{H1} \dots \dots \dots (3)$$

(1),(2),(3)을 곱하면

$$= (out_{01} - y_1)out_{01}(1 - out_{01})out_{H1}$$

$$\delta_{01} = (out_{01} - y_1)out_{01}(1 - out_{01})$$

$$\frac{\partial E_{Total}}{\partial w'_{11}} = \delta_{01}out_{H1}$$

계속해서 첫번째 아웃풋으로의 값들을 계산하면

$$\begin{aligned} \frac{\partial E_{Total}}{\partial w'_{21}} &= (out_{01} - y_1)out_{01}(1 - out_{01})out_{H2} \\ &= \delta_{01}out_{H2} \end{aligned} \quad , \quad \frac{\partial E_{Total}}{\partial w'_{31}} = \delta_{01}out_{H3} \quad , \quad \frac{\partial E_{Total}}{\partial w'_{41}} = \delta_{01}out_{H4}$$

## 2. $W_{HO}$

2번 아웃풋으로의 가중치들에 대해서 계산 과정입니다.

$$\frac{\partial E_{Total}}{\partial w'_{12}} = \frac{\partial E_{Total}}{\partial out_{O2}} \times \frac{\partial out_{O2}}{\partial net_{O2}} \times \frac{\partial net_{O2}}{\partial w'_{21}}$$

$$\frac{\partial E_{Total}}{\partial out_{O2}} = (out_{O2} - y_2) \dots\dots\dots (1)$$

$$\frac{\partial out_{O2}}{\partial net_{O2}} = out_{O2}(1 - out_{O2}) \dots (2)$$

$$\frac{\partial net_{O2}}{\partial w'_{21}} = out_{H1} \dots\dots\dots (3)$$

(1),(2),(3)을 곱하면

$$= (out_{O2} - y_2)out_{O2}(1 - out_{O2})out_{H1}$$



$$\delta_{O2} = (out_{O2} - y_2)out_{O2}(1 - out_{O2})$$



$$\frac{\partial E_{Total}}{\partial w'_{21}} = \delta_{O2}out_{H1}$$

위 과정을 계속 하면  $W_{HO}$ 를 갱신하기 위한 행렬은 다음과 같습니다.

$$\begin{pmatrix} \delta_{O1}out_{H1} & \delta_{O2}out_{H1} \\ \delta_{O1}out_{H2} & \delta_{O2}out_{H2} \\ \delta_{O1}out_{H3} & \delta_{O2}out_{H3} \\ \delta_{O1}out_{H4} & \delta_{O2}out_{H4} \end{pmatrix}$$

## 2. $W_{HO}$

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$W_{HO}$ 를 갱신하기 위해서 위 값에 *learning rate*를 곱한 후 빼면

$$W_{HO}^{(new)} = \begin{pmatrix} w'_{11} & w'_{12} \\ w'_{21} & w'_{22} \\ w'_{31} & w'_{32} \\ w'_{41} & w'_{42} \end{pmatrix} - lr * \begin{pmatrix} \delta_{O1}out_{H1} & \delta_{O2}out_{H1} \\ \delta_{O1}out_{H2} & \delta_{O2}out_{H2} \\ \delta_{O1}out_{H3} & \delta_{O2}out_{H3} \\ \delta_{O1}out_{H4} & \delta_{O2}out_{H4} \end{pmatrix}$$

그리고  $b2$ 는 다음과 같습니다.

$$\frac{\partial E_{Total}}{\partial b_2} = \frac{\partial E_1}{\partial b_2} + \frac{\partial E_2}{\partial b_2} = \delta_{O1} + \delta_{O2}$$

$$b2^{(new)} = b2 - lr * (\delta_{O1} + \delta_{O2})$$



### 3. $W_{IH}$

이번에는  $W_{IH}$ 에 대해 계산해보겠습니다.

1번째 인풋에서 1번째 히든레이어로의 가중치를 계산해보겠습니다.

$$\frac{\partial E_{Total}}{\partial w_{11}} = \frac{\partial E_{Total}}{\partial out_{H1}} \times \frac{\partial out_{H1}}{\partial net_{H1}} \times \frac{\partial net_{H1}}{\partial w_{11}}$$

여기서 1번째 히든레이어는 1번째 아웃풋과 2번째 아웃풋 둘 다에게 영향을 미침으로

$$\frac{\partial E_{Total}}{\partial out_{H1}} = \frac{\partial E_1}{\partial out_{H1}} + \frac{\partial E_2}{\partial out_{H1}}$$

$$= \frac{\partial E_1}{\partial net_{O1}} \times \frac{\partial E_{Total}}{\partial out_{H1}} + \frac{\partial E_{Total}}{\partial out_{H1}} \times \frac{\partial E_{Total}}{\partial out_{H1}}$$

$$= \delta_{O1}w'_{11} + \delta_{O2}w'_{12} \dots\dots\dots (1)$$

$$\frac{\partial out_{H1}}{\partial net_{H1}} = out_{H1}(1 - out_{H1}) \dots\dots\dots (2)$$

$$\frac{\partial net_{H1}}{\partial w_{11}} = x_1 \dots\dots\dots (3)$$

(1),(2),(3)을 곱하면

$$= (\delta_{O1}w'_{11} + \delta_{O2}w'_{12})out_{H1}(1 - out_{H1})x_1$$

$$\delta_{H1} = (\delta_{O1}w'_{11} + \delta_{O2}w'_{12})out_{H1}(1 - out_{H1})$$



$$\frac{\partial E_{Total}}{\partial w_{11}} = \delta_{H1}x_1$$

### 3. $W_{IH}$

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계속해서 다른 값들에 대해 계산하면

$$\frac{\partial E_{Total}}{\partial w_{12}} = \underbrace{(\delta_{O1}w'_{21} + \delta_{O2}w'_{22})}_{\delta_{H2}} out_{H2}(1 - out_{H2}) x_1$$
$$\delta_{H2} = (\delta_{O1}w'_{21} + \delta_{O2}w'_{22})out_{H2}(1 - out_{H2}) \quad \Rightarrow \quad \frac{\partial E_{Total}}{\partial w_{12}} = \delta_{H2}x_1$$

위 과정을 다른 가중치들에 대해서 계산을 하면  $W_{IH}$ 을 갱신하기 위한 행렬은 다음과 같습니다.

$$\begin{pmatrix} \delta_{H1}x_1 & \delta_{H2}x_1 & \delta_{H3}x_1 & \delta_{H4}x_1 \\ \delta_{H1}x_2 & \delta_{H2}x_2 & \delta_{H3}x_2 & \delta_{H4}x_2 \\ \delta_{H1}x_3 & \delta_{H2}x_3 & \delta_{H3}x_3 & \delta_{H4}x_3 \end{pmatrix}$$

### 3. $W_{IH}$

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$W_{IH}$ 를 갱신하기 위해서 위 값에 *learning rate*를 곱한 후 빼면

$$W_{IH}^{(new)} = \begin{pmatrix} w_{11} & w_{12} & w_{13} & w_{14} \\ w_{21} & w_{22} & w_{23} & w_{24} \\ w_{31} & w_{32} & w_{33} & w_{34} \end{pmatrix} - lr * \begin{pmatrix} \delta_{H1}x_1 & \delta_{H2}x_1 & \delta_{H3}x_1 & \delta_{H4}x_1 \\ \delta_{H1}x_2 & \delta_{H2}x_2 & \delta_{H3}x_2 & \delta_{H4}x_2 \\ \delta_{H1}x_3 & \delta_{H2}x_3 & \delta_{H3}x_3 & \delta_{H4}x_3 \end{pmatrix}$$

그리고  $b1$ 는 다음과 같습니다.

$$\begin{aligned} \frac{\partial E_{Total}}{\partial b_1} &= \frac{\partial E_1}{\partial out_{H1}} * \frac{\partial out_{H1}}{\partial net_{H1}} * \frac{\partial net_{H1}}{\partial b_1} + \dots + \frac{\partial E_2}{\partial out_{H4}} * \frac{\partial out_{H4}}{\partial net_{H4}} * \frac{\partial net_{H4}}{\partial b_1} \\ &= \delta_{H1} + \delta_{H2} + \delta_{H3} + \delta_{H4} \end{aligned}$$

$$b1^{(new)} = b1 - lr * (\delta_{H1} + \delta_{H2} + \delta_{H3} + \delta_{H4})$$

## 4. 구현

$$W_{HO}^{(new)} = \begin{pmatrix} w'_{11} & w'_{12} \\ w'_{21} & w'_{22} \\ w'_{31} & w'_{32} \\ w'_{41} & w'_{42} \end{pmatrix} - lr * \begin{pmatrix} \delta_{O1}out_{H1} & \delta_{O2}out_{H1} \\ \delta_{O1}out_{H2} & \delta_{O2}out_{H2} \\ \delta_{O1}out_{H3} & \delta_{O2}out_{H3} \\ \delta_{O1}out_{H4} & \delta_{O2}out_{H4} \end{pmatrix}$$

$$\delta_{O1} = (out_{O1} - y_1)out_{O1}(1 - out_{O1})$$

➡  $(out_{O1} \quad out_{O2}) - (y_1 \quad y_2) = (out_{O1} - y_1 \quad out_{O2} - y_2)$

$$(out_{O1} - y_1 \quad out_{O2} - y_2) \odot (out_{O1}(1 - out_{O1}) \quad out_{O2}(1 - out_{O2})) = (\delta_{O1} \quad \delta_{O2})$$

$\odot$ : 행렬의 가로 곱 eg)  $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \odot \begin{pmatrix} 4 & 3 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 \times 4 & 2 \times 3 \\ 3 \times 2 & 4 \times 1 \end{pmatrix}$

➡  $\begin{pmatrix} out_{H1} \\ out_{H2} \\ out_{H3} \\ out_{H4} \end{pmatrix} \circ (\delta_{O1} \quad \delta_{O2}) = \begin{pmatrix} \delta_{O1}out_{H1} & \delta_{O2}out_{H1} \\ \delta_{O1}out_{H2} & \delta_{O2}out_{H2} \\ \delta_{O1}out_{H3} & \delta_{O2}out_{H3} \\ \delta_{O1}out_{H4} & \delta_{O2}out_{H4} \end{pmatrix}$

## 4. 구현

$$W_{IH}^{(new)} = \begin{pmatrix} w_{11} & w_{12} & w_{13} & w_{14} \\ w_{21} & w_{22} & w_{23} & w_{24} \\ w_{31} & w_{32} & w_{33} & w_{34} \end{pmatrix} - lr * \begin{pmatrix} \delta_{H1}x_1 & \delta_{H2}x_1 & \delta_{H3}x_1 & \delta_{H4}x_1 \\ \delta_{H1}x_2 & \delta_{H2}x_2 & \delta_{H3}x_2 & \delta_{H4}x_2 \\ \delta_{H1}x_3 & \delta_{H2}x_3 & \delta_{H3}x_3 & \delta_{H4}x_3 \end{pmatrix}$$

$$\delta_{H1} = (\delta_{O1}w'_{11} + \delta_{O2}w'_{12})out_{H1}(1 - out_{H1})$$

$$\begin{aligned} \Rightarrow (\delta_{O1} \quad \delta_{O2}) \circ \begin{pmatrix} w'_{11} & w'_{12} \\ w'_{21} & w'_{22} \\ w'_{31} & w'_{32} \\ w'_{41} & w'_{42} \end{pmatrix}^T &= (\delta_{O1} \quad \delta_{O2}) \circ \begin{pmatrix} w'_{11} & w'_{21} & w'_{31} & w'_{41} \\ w'_{12} & w'_{22} & w'_{32} & w'_{42} \end{pmatrix} \\ &= (\delta_{O1}w'_{11} + \delta_{O2}w'_{12} \quad \delta_{O1}w'_{21} + \delta_{O2}w'_{22} \quad \delta_{O1}w'_{31} + \delta_{O2}w'_{32} \quad \delta_{O1}w'_{41} + \delta_{O2}w'_{42}) \end{aligned}$$

$$\begin{aligned} & \begin{pmatrix} \delta_{O1}w'_{11} + \delta_{O2}w'_{12} & \delta_{O1}w'_{21} + \delta_{O2}w'_{22} & \delta_{O1}w'_{31} + \delta_{O2}w'_{32} & \delta_{O1}w'_{41} + \delta_{O2}w'_{42} \\ \odot(out_{H1}(1 - out_{H1}) & out_{H2}(1 - out_{H2}) & out_{H3}(1 - out_{H3}) & out_{H4}(1 - out_{H4})) \end{pmatrix} \\ &= (\delta_{H1} \quad \delta_{H2} \quad \delta_{H3} \quad \delta_{H4}) \end{aligned}$$

## 4. 구현

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$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \circ (\delta_{H1} \quad \delta_{H2} \quad \delta_{H3} \quad \delta_{H4}) = \begin{pmatrix} \delta_{H1}x_1 & \delta_{H2}x_1 & \delta_{H3}x_1 & \delta_{H4}x_1 \\ \delta_{H1}x_2 & \delta_{H2}x_2 & \delta_{H3}x_2 & \delta_{H4}x_2 \\ \delta_{H1}x_3 & \delta_{H2}x_3 & \delta_{H3}x_3 & \delta_{H4}x_3 \end{pmatrix}$$