

MATH241

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# Chapter 1

## Calc I Review

- derivative  $\rightarrow$  rate of change
- $\int_b^a g(x)dx = \text{area under } g(x) \text{ from } a \text{ to } b$
- **FUNDAMENTAL THEOREM OF CALCULUS**

$$\int_b^a f'(x)dx = f(b) - f(a)$$

# Chapter 2

## 3D Coordinates

- x, y, AND z  
crazy, I know

## 12.2 Vectors

A vector is a quantity that has magnitude and direction.

A scalar is a quantity that has only magnitude.

## Chapter 3

### Reviewing all of Calc 3

# Chapter 4

## 11 Basic Vectors

3D coordinates are goofy but I know just about everything for em

### 4.0.1 cross and dot product

goofy properties

$$u \cdot (v \times w) = (u \times w) \cdot v$$

$$u \times u = 0$$

$$u \times v = -(v \times u)$$

$u \times v$  is orthogonal to both  $u$  and  $v$

$u \times v = 0$  if  $u$  and  $v$  are scalar multiples

$u \cdot v = ||u|| ||v|| \cos(\theta) = 0$  if  $u$  and  $v$  are orthogonal

$$\text{proj}_v u = \frac{|v \cdot u|}{||v||}$$



## 4.1 11.5 planes

Given 3 points  $A, B, C$ ,  $AB \times BC$  = normal vector for the plane

given normal vector  $n = \langle a, b, c \rangle$  and points  $P(x_1, y_1, z_1)$

$$x = x_1 + at, y = y_1 + bt, z = z_1 + ct$$

$$a(x - x_1) + b(y - y_1) + c(z - z_1) = 0 \text{ or}$$

$$ax + by + cz + d = 0$$

Distance Formula

Let  $Q$  be a point and  $P$  any point on a plane and  $n$  the normal vector of said plane.

$$d = \frac{|\vec{PQ} \cdot \vec{n}|}{\|\vec{n}\|} = \text{proj}_n PQ$$

Angle between two planes given their normal vectors  $n_1$  and  $n_2$

$$\cos(\theta) = \frac{n_1 \cdot n_2}{\|n_1\| \|n_2\|}$$

**other distance shit that I need to probably look at later**

plane and point, plane and plane, line and point

# Chapter 5

## 12 3D Shenanigans

### 5.1 12.1

I remember how to graph shit in 3D

Practice Question:

$$x^2 + z^2 = 9$$

It is a cylinder of radius 3 parallel to the y-axis

Surfaces in space eh you understand

### 5.2 More Surfaces

Look at revolutions?

### 5.3 12.2 Vectors

Goofy parallelogram addition

vectors are built of components

$$\vec{v} = \langle x, y, z \rangle$$

$$\text{Proj}_v u = \left( \frac{\vec{u} \cdot \vec{v}}{||v||^2} \right) \vec{v} = \text{projection of } v \text{ onto } u = \vec{v} \cos(\theta)$$

$$\cos(\theta) = \left\| \frac{\text{proj}_v u}{||u||} \right\| = \frac{\vec{u} \cdot \vec{v}}{||u|| ||v||}$$

# Chapter 6

## 13 Vector Functions

### 6.1 Unit Tangent Vector

13.2

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|} \text{ where } \mathbf{r} \text{ is a vector function}$$

$$\mathbf{N}(t) = \frac{\mathbf{T}'(t)}{|\mathbf{T}'(t)|} \text{ Normal unit vector}$$

### 6.2 Arc Length and Curvature

13.3

$$L = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt = \text{arclength from } a \text{ to } b$$

$$L(t) = \int_a^t \sqrt{\left(\frac{dx}{du}\right)^2 + \left(\frac{dy}{du}\right)^2 + \left(\frac{dz}{du}\right)^2} du = \text{arc length parameter}$$

$$\frac{ds}{dt} = |r'(t)|$$

if  $\|r'(t)\| = 1$ , then  $t$  is the arc length parameter. That is,  $t = s(t)$ .

### 6.2.1 Curvature

$$K = \frac{|y|}{(1 + (y')^2)^{3/2}} = \left| \frac{d\mathbf{T}}{ds} \right| = \frac{d\mathbf{T}/ds}{ds/dt} = \frac{|\mathbf{T}'(t)|}{|r'(t)|} = \frac{|r' \times r''|}{|r'|^3}$$

$$a(t) = \frac{d^2(x)}{dt^2}T + K \left( \frac{ds}{dt} \right)^2 N \text{ where } \frac{ds}{dt} = \text{speed}$$

### 6.2.2 Binormal Vector

perpendicular to both T and N

$$\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$$

### 6.2.3 Torsion

$$\tau(t) = -\frac{d\mathbf{B}}{ds} \cdot \mathbf{N} = -\frac{\mathbf{B}'(t) \cdot \mathbf{N}(t)}{|r'(t)|} = \frac{[r'(t) \times r''(t)] \cdot r'''(t)}{|r'(t) \times r''(t)|^2}$$

# Chapter 7

## 14 Partial Derivatives

Literally just think of the numbers you're not deriving as a constant Let  $f(x, y) = 3x - x^2y^2 + 2x^3y$

$$f_x(x, y) = z_x = \frac{\partial z}{\partial x} = \frac{\partial}{\partial x} f(x, y) = 3 - 2xy^2 + 6x^2y$$

$$f_y(x, y) = z_y = \frac{\partial z}{\partial y} = \frac{\partial}{\partial y} f(x, y) = 2x^2y + 2x^3$$

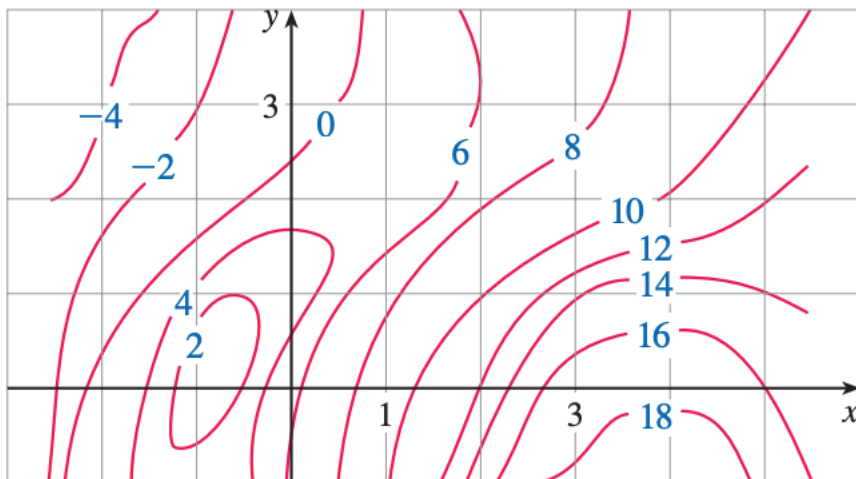
### 7.0.1 higher order notation

$$\frac{\partial}{\partial x} \left( \frac{\partial z}{\partial y} \right) = \frac{\partial^2 z}{\partial x \partial y} = f_{yx}(x, y) \text{ notice the subscript order}$$

## 7.0.2 Partial Derivative Problem

14.3 #6

Estimate  $f_x(2, 1)$  and  $f_y(2, 1)$  in the following contour map.



$(2, 1)$  is on the contour line  $z = 10$ . Because the 12 contour line is as about  $(2.66, 1)$ ,  $f_x(2, 1)$  will probably have a value of about 3.  $f_y(2, 1)$  will be about -2 because of where the 8 contour line is located.

$$f_x(2, 1) \approx 3 \quad f_y(2, 1) \approx -2$$

Quizlet+ give or take agrees phew

## 7.1 Limits

Basically set one of the numbers to a constant or the other variable and see what happens.

Try  $y=0$ ,  $x=0$ ,  $y=x$ ,  $x=y$ ,  $y=mx$ ,  $x=my$ , idfk

### 7.1.1 Limit Practice Problem

2012 practice midterm 1 problem

Exactly one of the two limits exists, show which and why.

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 - y^2}{\sqrt{x^2 + y^2}} \qquad \lim_{(x,y) \rightarrow (0,0)} \frac{xy}{(x^2 + y^2)^2}$$

I can factor the first one

$$\frac{\sqrt{x^2 + y^2} \sqrt{x^2 - y^2}}{\sqrt{x^2 + y^2}} = \sqrt{x^2 - y^2} = 0 \text{ definitely exists}$$

Now I'll prove the other one doesn't exist just for funsies.

line  $y = 0$ ,  $\lim = 0$

line  $y = x$ ,  $\lim$  DNE

## 7.2 Tangent Planes and Linear Approximations

$$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

Calculate the differential and then replace  $dx$  and  $dy$  with  $\Delta x$  and  $\Delta y$

Yea I was basically right. Use the tangent plane as an approximation

$$f(x_0, y_0) \approx f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$



## 7.3 Differentials

$$dz = \frac{\partial z}{\partial x}dx + \frac{\partial z}{\partial y}dy = f_x(x, y)dx + f_y(x, y)dy$$

### Theorem

If  $f_x$  and  $f_y$  are continuous, then  $f$  is differentiable.

### 7.3.1 Clairaut's Theorem

Suppose  $f$  is defined on a disk  $D$  that contains the point  $(a, b)$ . If  $f_{xy}$  and  $f_{yx}$  are both continuous on  $D$ , then

$$f_{xy}(a, b) = f_{yx}(a, b)$$

## 7.4 Chain Rule for Partial Derivatives

14.5

page 1020

Let  $w = f(x, y)$  where  $x = g(t)$  and  $y = h(t)$ . Then

$$\frac{dw}{dt} = \frac{\partial w}{\partial x} \frac{dx}{dt} + \frac{\partial w}{\partial y} \frac{dy}{dt}$$

### 7.4.1 Chain Rule Problem

2012 Practice Midterm 1 #11

An exceptionally tiny spaceship positioned as shown is travelling so that its x-coordinate increases at a rate of  $1/2$  m/s and y-coordinate increases at a rate of  $1/3$  m/s. Use the Chain Rule to calculate the rate at which the distance between the spaceship and the point  $(0, 0)$  is increasing.

$$\frac{\partial x}{\partial t} = \frac{1}{2}t, \frac{\partial y}{\partial t} = \frac{1}{3}t, w = \sqrt{x^2 + y^2}$$

$$\frac{\partial w}{\partial t} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial t}$$

$$\frac{\partial w}{\partial x} = \frac{1}{2}(x^2 + y^2)^{-1/2}2x \quad \frac{\partial w}{\partial y} = \frac{1}{2}(x^2 + y^2)^{-1/2}2y$$

Just plug the numbers in, I don't have the actual answer for this one but this looks correct.

### 7.4.2 Implicit Differentiation

Let  $F(x, y) = 0$  and let  $y = f(x)$

$$\frac{dy}{dx} = -\frac{F_x(x, y)}{F_y(x, y)}$$

## 7.5 Directional Derivatives and Gradients

If  $f$  is a differentiable function of  $x$  and  $y$ , and  $f$  has a directional derivative in the direction of any unit vector  $\vec{u} = \langle a, b \rangle$ , then

$$D_u f(x, y) = f_x(x, y)a + f_y(x, y)b$$

Gives the slope of the function in the direction of  $\vec{u}$

$$\nabla f(x, y) = f_x(x, y)\mathbf{i} + f_y(x, y)\mathbf{j} = \frac{\partial f}{\partial x}\mathbf{i} + \frac{\partial f}{\partial y}\mathbf{j}$$

The gradient exists such that  $\nabla f(x, y) \cdot \mathbf{u} = D_u f(x, y)$

## 7.6 Extrema

The maximum possible directional derivative is  $\|\nabla f(\vec{x})\|$ , and it occurs when  $\vec{u}$  is in the direction of  $\nabla f(\vec{x})$

$$D_u f = \nabla f \cos(\theta)$$

## 7.7 Tangent Planes to Level Surfaces

Let  $S$  be a surface with the equation  $F(x, y, z) = k$ . Let  $P = (x_0, y_0, z_0)$  be a point on  $S$ . Let  $C$  be a curve on  $S$  that

passes through  $P$ .  $C$  has the equation  $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$ . Let  $t_0$  correspond to  $P$ , meaning  $\mathbf{r}(t_0) = P$ .

We can derive  $F$  to get

$$\frac{\partial F}{\partial x} \frac{dx}{dt} + \frac{\partial F}{\partial y} \frac{dy}{dt} + \frac{\partial F}{\partial z} \frac{dz}{dt} = 0 = \nabla F \cdot \mathbf{r}'(t)$$

We can use this and dot product properties to show that the gradient of  $F$  is orthogonal to the tangent vector of  $C$ .

Therefore, the gradient can be the normal vector for a plane tangent to  $S$ . So our tangent plane equation will be

$$F_x(x_0, y_0, z_0)(x - x_0) + F_y(x_0, y_0, z_0)(y - y_0) + F_z(x_0, y_0, z_0)(z - z_0) = 0$$

## 7.8 Extrema

14.7

If  $f(a, b)$  has a local extrema at  $(a, b)$  and the first order partial derivatives of  $f(a, b)$  exist, then  $f_x(a, b) = 0$  and  $f_y(a, b) = 0$

### 7.8.1 Second Derivatives Test

Suppose the second partial derivatives of  $f$  are continuous on a disk with center  $(a, b)$ , and suppose that  $(a, b)$  is a critical point of  $f$ . Let

$$D = D(a, b) = f_{xx}(a, b)f_{yy}(a, b) - [f_{xy}(a, b)]^2$$

1. If  $D > 0$  and  $f_{xx}(a, b) > 0$  then  $f(a, b)$  is a local minimum

2. If  $D > 0$  and  $f_{xx}(a, b) < 0$  then  $f(a, b)$  is a local maximum
3. If  $D < 0$ , then  $f(a, b)$  is a saddle point

## 7.8.2 Extrema Problem

14.7 #5

Find the extrema of  $f(x, y) = x^2 + xy + y^2 + y$

$$f_x = 2x + y \quad f_y = 2y + x + 1 \quad f_{xx} = 2 \quad f_{yy} = 2 \quad f_{xy} = 1$$

Critical points uhh somewhere

$$2x = -y$$

$$-4x + x + 1 = 0 \rightarrow x = 1/3, y = -2/3$$

$$D = f_{xx}f_{yy} - (f_{xy})^2 = 2 * 2 - 1 = 3$$

$D < 0$  = saddle point else

$f_{xx} > 0$  = minimum

$f_{xx} < 0$  = maximum

Minimum at  $(1/3, -2/3)$

## 7.9 Lagrange Multipliers

How to find all the maximum and minimum values of  $f(x, y, z)$  under the constraints that  $g(x, y, z) = k$  for some equation  $g$ .

Step 1: Find all values such that

$$\nabla f(x, y, z) = \lambda \nabla g(x, y, z) \text{ and } g(x, y, z) = k \text{ for some scalar } \lambda$$

Step 2: Evaluate at all points, the biggest is a maximum, the smallest is a minimum.

### 7.9.1 Two constraints

Let  $g(x, y, z) = k$  and  $h(x, y, z) = c$

$$\nabla f(x, y, z) = \lambda \nabla g(x, y, z) + \mu \nabla h(x, y, z)$$

Find the components to get enough equations to solve for the 7 billion variables.

## 7.10 Lagrange Multipliers Example Problems

pg 1061 #6

$$f(x, y) = xe^y \quad g(x, y) = x^2 + y^2 = 2$$

$$\nabla g(x, y) = (2x)\vec{i} + (2y)\vec{j} \quad \nabla f(x, y) = (e^y)\vec{i} + (xe^y)\vec{j}$$

$$2x = \lambda e^y$$

$$2y = \lambda x e^y$$

$$x^2 + y^2 = 2$$

$$2x = \lambda e^y$$

$$y = x^2$$

$$x^4 + x^2 - 2 = 0 \rightarrow x = \frac{-1 \pm 3}{2} \rightarrow x^2 = -2, 1, x = \pm 1$$

$x = -2, y = 4$  not actually allowed  
 $-4 = \lambda e^4 \rightarrow \lambda = -4/e^4$  I don't think this is necessary  
 $(1, 1)$  is a maximum this was a waste of my time  $(-1, 1)$  is a minimum let's fucking go I actually did it right omg

**7.10.1 pg 1061 # 7**

$$f(x, y) = 2x^2 + 6y^2, \quad g(x, y) = x^4 + 3y^4 = 1$$

$$\nabla f(x, y) = 4x\mathbf{i} + 12y\mathbf{j}, \quad \nabla g(x, y) = 4x^3\mathbf{i} + 12y^3\mathbf{j}$$

$$4x = \lambda 4x^3$$

$$12y = \lambda 12y^3$$

$$x^4 + 3y^4 = 1$$

$$\lambda = 1/x^2$$

$$1 = y^2/x^2 \rightarrow \pm x = \pm y$$

$$4x^4 = 1 \rightarrow x = \pm 1/\sqrt{2}, y = \pm 1/\sqrt{2}$$

time to figure out all the sets of points that work

$$(1/\sqrt{2}, 1/\sqrt{2})$$

$$(-1/\sqrt{2}, 1/\sqrt{2})$$

$$(1/\sqrt{2}, -1/\sqrt{2})$$

$$(-1/\sqrt{2}, -1/\sqrt{2})$$

All these points have the exact same  $f(x, y)$  values so they're all maximums?

Ah damn I missed one. the minimums are  $(\pm 1, 0)$  but I give or take understand



pg 1062 # 33

$$f(x, y, z) = yz + xy \quad xy = 1 \quad y^2 + z^2 = 1$$

$$f_x = y = \lambda y$$

$$f_y = z + x = \lambda x + \mu 2y$$

$$f_z = y = \mu 2z$$

$$xy = \lambda$$

$$y^2 + z^2 = 1$$

$$\lambda = 1$$

$$z = \mu 2y$$

$$y = \mu 2z$$

$$z = y/(2\mu)$$

$$4\mu^2 = 1 \rightarrow \mu = \pm 1/2 \text{ IMPORTANT}$$

$$y^2 = z^2 = \pm 1/\sqrt{2}$$

$$x = \pm\sqrt{2}$$

$$(\sqrt{2}, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$$

$$(-\sqrt{2}, -\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}})$$

$$(-\sqrt{2}, -\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$$

$$(\sqrt{2}, \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}})$$

$$f(x, y, z) = 3/2 = \text{maximum}$$

$$f(x, y, z) = 1/2 = \text{minimum}$$

Okay I think I understand this shit assuming I'm given a  
g(x, y, z)

# Chapter 8

## 15 Multiple Integrals

$$\iint_R f(x, y) dA = V$$

### 8.1 Iterated Integrals

Just consider whatever you aren't integrating as constant

$$\int_{x_0}^{x_1} \int_{y_0}^{y_1} f(x, y) dy dx$$

Example

$$\int_1^2 \int_0^3 x^2 y dx dy \rightarrow \int_1^2 \left. \frac{x^3 y}{3} \right|_0^3 dy \rightarrow \int_1^2 9y dy$$

$$\left. 4.5y^2 \right|_1^2 \rightarrow 18 - 4.5 = 13.5$$

## Fubini's Theorem

If  $f(x, y)$  is continuous on a rectangle  $R$ , then

$$\iint_R f(x, y) dA = \int_{y_0}^{y_1} \int_{x_0}^{x_1} f(x, y) dx dy = \int_{x_0}^{x_1} \int_{y_0}^{y_1} f(x, y) dy dx$$

If  $f(x, y)$  can be factored into 2 functions multiplying each other, meaning  $f(x, y) = g(x)h(y)$ , then

$$\iint_R f(x, y) dA = \int_{y_0}^{y_1} \int_{x_0}^{x_1} g(x)h(y) dx dy = \int_{x_0}^{x_1} g(x) dx \int_{y_0}^{y_1} h(y) dy$$

## 8.2 Average Value

$$f_{avg} = \frac{1}{A(R)} \iint_R f(x, y) dA$$

## 8.3 Integrating Over General Regions

$$\iint_D f(x, y) = \int_{x_0}^{x_1} \int_{g(x)_0}^{g(x)_1} f(x, y) dy dx$$

### 8.3.1 Changing Order of Integration

Just fucking floop the shit

$$\int_0^1 \int_x^1 f(x, y) dy dx \longrightarrow \int_0^1 \int_0^y f(x, y) dx dy$$

$y = x$  so  $x = y$  and  $y = 1$  where  $x = 0$

Think of it in picture, thats like literally the only way to do it

## 8.4 15.5 Surface Area

$$A(S) = \iint_D \sqrt{[f_x(x, y)]^2 + [f_y(x, y)]^2 + 1} dA$$

## 8.5 15.6 Triple Integrals

It's like a double integral but another one.

I skipped a bunch of shit but I also dont give a shit I can figure it out fuck you

# Chapter 9

## 16 Vector Calculus

Vector Fields

$$\mathbf{F}(a, b) = P(a, b)\mathbf{i} + Q(a, b)\mathbf{j} = \langle P(a, b), Q(a, b) \rangle$$

Gradient is a vector field

### 9.0.1 Dfn: Conservative

A vector field  $\mathbf{F}$  is conservative if it acts as the gradient for some scalar function. That is, there exists a function  $f(x, y)$  such that

$$\mathbf{F} = \nabla f(x, y)$$

## 9.1 16.2 Line Integrals

Integrate over a line instead of a regular region

$$\text{arclength } L = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

$$\int_C f(x, y) ds = \int_a^b f(x(t), y(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

**Integrating over x and y**

$$\int_C f(x, y) dx = \int_a^b f(x(t), y(t)) x'(t) dt$$

$$\int_C f(x, y) dy = \int_a^b f(x(t), y(t)) y'(t) dt$$

### 9.1.1 Line Integral Problem

$$16.2 \# 9 \int_C x^2 y ds \quad C = \langle \cos(t), \sin(t), t \rangle (0 < t < \pi/2)$$

$$\int_0^{\pi/2} \cos^2(t) \sin(t) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

$$\int_0^{\pi/2} \cos^2(t) \sin(t) \sqrt{(-\sin(t))^2 + (\cos(t))^2 + 1} dt \rightarrow$$

$$\sqrt{2} \int_0^{\pi/2} \cos^2(t) \sin(t) dt \quad u = \cos(t), -du = \sin(t) dt$$

$$-\sqrt{2} \int_1^0 u^2 du = -\sqrt{2}u^3/3 \Big|_1^0 = \sqrt{2}/3$$

### 9.1.2 Integrating Over a Vector Field

Let  $\mathbf{F}$  be integrated over a smooth curve  $C$ .

Let  $F = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(r(t)) \cdot r'(t) dt = \int_C \mathbf{F} \cdot \mathbf{T} ds = \int_C Pdx + Qdy + Rdz$$

## 9.2 The Fundamental Theorem For Line Integrals

$$\int_C \nabla f(x, y) \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$$

also shows how conservative fields get the same shenanigans independent of path

### 9.2.1 Independence of Path Theorem

$\int_C \mathbf{F} \cdot d\mathbf{r}$  is independent of the path taken iff  $\int_C \mathbf{F} \cdot d\mathbf{r} = 0$  for every closed path  $C$  (every loop)

## 9.3 16.4 Green's Theorem

relationship between a double integral of a region and a line integral over the border of that region.

Let  $C$  be a positively oriented (*meaning counterclockwise*), piecewise-smooth, simple closed curve in the plane and let  $D$  be the region bounded by  $C$ . If  $P$  and  $Q$  have continuous partial derivatives on an open region that contains  $D$ , then

$$\int_C P dx + Q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$



## 9.4 Curl

Curl is associated with rotation around a point. The magnitude of curl is the speed of rotation, and the direction of curl is the axis of rotation.

$$\text{curl } \mathbf{F} = \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}$$

Imagine it as a cross product

$$\nabla \times \mathbf{F} = \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

$$\text{curl}(\nabla f) = 0$$

### Theorem

If  $\mathbf{F}$  is function whose components have continuous partial derivatives and  $\text{curl}(\mathbf{F}) = 0$ , then  $\mathbf{F}$  is a conservative vector field.

## 9.5 Divergence

$$\text{div } \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = \nabla \cdot \mathbf{F}$$

$$\text{div curl } \mathbf{F} = 0$$

## 9.6 Vector Forms of Green's Theorem

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \oint_C \mathbf{F} \cdot \mathbf{T} ds = \iint_D (\nabla \times \mathbf{F}) \cdot \mathbf{k} dA$$

also

$$\oint_C \mathbf{F} \cdot \mathbf{n} ds = \iint_D (\nabla \cdot \mathbf{F}(x, y)) dA$$

## 9.7 Parametric Surfaces

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

### 9.7.1 Tangent Planes

$$\mathbf{r}_u \times \mathbf{r}_v = \mathbf{n}$$

### 9.7.2 Surface Area

$$A(S) = \iint_D |\mathbf{r}_u \times \mathbf{r}_v| dA$$

## Surface Area of Graphs of Functions

$$x=x, y=y, z = f(x, y)$$

$$A(S) = \iint_D \sqrt{[f_x(x, y)]^2 + [f_y(x, y)]^2 + 1} dA$$

## 9.8 Surface Integrals

$$\iint_S f(x, y, z) d\mathbf{S} = \iint_D f(r(u, v)) |r_u \times r_v| dA$$

### 9.8.1 Graphs of Functions

$x=x, y=y, z=f(x, y)$

$$\iint_S f(x, y, z) d\mathbf{S} = \iint_D f(x, y, f(x, y)) \sqrt{[f_x(x, y)]^2 + [f_y(x, y)]^2 + 1} dA$$

Similar vibes as line integrals using arclength

## 9.9 Oriented Surfaces

the unit vector for certain surfaces can be either  $\mathbf{n}$  or  $-\mathbf{n}$ . Let  $S$  be a surface given by the vector function  $r(u, v)$

$$\mathbf{n} = \frac{r_u \times r_v}{|r_u \times r_v|}$$

Yea I don't actually entirely know how the orientation changes things I'll be honest

## 9.10 Flux

if  $\mathbf{F}$  is a continuous vector field over a surface  $S$  with a normal vector  $\mathbf{n}$ , then the Surface Integral of  $\mathbf{F}$  over  $S$ , or the Flux of

$\mathbf{F}$  over  $S$ , is:

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_S \mathbf{F} \cdot \mathbf{n} d\mathbf{S} = \iint_D \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA$$

Where  $D$  is the parameter domain.

if  $S$  is given by  $g(x, y) = z$

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \langle P, Q, R \rangle \cdot \left\langle -\frac{\partial g}{\partial x}, -\frac{\partial g}{\partial y}, 1 \right\rangle dA$$

## 9.11 Stoke's Theorem

let  $\mathbf{F}$  be a piecewise smooth surface bounded by  $S$ , a region with a boundary  $C$  with positive (counterclockwise) orientation

$$\int_C \mathbf{F} d\mathbf{r} = \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}$$

Literally just generalized Green's Theorem for higher dimensions.

## 9.12 Divergence Theorem

Green's Theorem Extended to Vector Fields

Let  $E$  be a simple solid region and let  $S$  be the boundary surface of  $E$ , given with positive (outward) orientation. Let  $\mathbf{F}$  be a vector field whose component functions have continuous partial derivatives on an open region that contains  $E$ . Then

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iiint_E \nabla \cdot \mathbf{F} \, dV$$

## Chapter 10

### Extras: Cylindrical and Spherical Coordinates

#### 10.1 Polar Coordinates

$$\iint_S f(x, y) dA = \iint_D f(r \cos(\theta), r \sin(\theta)) r dr d\theta$$

#### 10.2 Cylindrical Coordinates

instead of  $(x, y, z)$ , you got  $(r, \theta, z)$ , where  $\theta$  is counter-clockwise relative to the  $+x$  line

$$\iiint_A f(x, y, z) dA = \iiint_A f(r \cos(\theta), r \sin(\theta), z) r dz dr d\theta$$

## 10.3 Spherical Coordinates

instead of  $(x, y, z)$ , you got  $(r, \theta, \phi)$ , where  $\phi$  goes down from the  $+z$  line

$$\iiint_A f(x, y, z) dV = \iiint_A f(\rho \sin(\phi) \cos(\theta), \rho \sin(\phi) \sin(\theta), \rho \cos(\phi)) \rho^2 \sin(\phi) d\rho d\theta d\phi$$

## 10.4 Jacobians

A 1D Jacobian is just a u-sub.

Let  $x = g(u, v)$  and  $y = h(u, v)$ . The Jacobian is

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

Change of Variables

$$\iint_R f(x, y) dA = \iint_S f(g(u, v), h(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

3 variables

$$\iiint_R f(x, y, z) dV = \iiint_S f(x(), y(), z()) \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| du dv dw$$

(3d determinant)

$$a \begin{bmatrix} e & f \\ h & i \end{bmatrix} - b \begin{bmatrix} d & f \\ g & i \end{bmatrix} + c \begin{bmatrix} d & e \\ g & h \end{bmatrix}$$

# Chapter 11

## Test Problems

### 11.1 Midterm 2 2012 #4

Let  $C$  be the curve in  $\mathbb{R}^3$  parameterized by  $r(t) = \langle \sin(t), 2t, \cos(t) \rangle$   
Compute the length of  $C$  over  $0 < t < \pi/2$ .

$$\text{arclength}(C) = \int_0^{\pi/2} \sqrt{\frac{dx}{dt} + \frac{dy}{dt} + \frac{dz}{dt}} dt$$