

PHYS 325

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Fall 2024

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# Chapter 1

## PHYS325

I missed everything from the first 2 weeks because my laptop exploded whoopsies

# Chapter 2

## Equations of motion

derive the equations of motion to solve for a trajectory  $\vec{r}(t)$  which is a position vector with respect to time

### 2.1 Newton's Second Law

$$\vec{F} = m\vec{a} = m\frac{d^2\vec{r}(t)}{dt^2} \quad \vec{F} = \frac{d\vec{p}(t)}{dt}$$

### 2.2 Strategy

1. choose a reference frame and coordinates
2. identify all the relevant forces (external forces)  
make a force diagram lol
3. integrate N2 for a given force  $\vec{F}(\vec{r}, \dot{\vec{r}}, t)$  to find  $\vec{r}(t)$

4. fix integration constants from initial or boundary conditions.  
(e.g.  $\vec{v}_0 = \vec{v}(t=0) = 0$ )

5.

$$\vec{F} = 0$$

$$\text{from } N2L0 = \vec{F} = m\vec{a} = m\frac{d\vec{v}}{dt}$$

$$\rightarrow \vec{v} = \text{const} = \vec{v}_0$$

$$\vec{r}(t) = \int v_0 dt = v_0 t + r_0$$

6. if  $F$  is constant

$$\dot{\vec{v}} = \ddot{\vec{r}} = \vec{a} = \frac{\vec{F}_0}{m}$$

$$\int dv = \int \frac{F_0}{m} dt \rightarrow \vec{v}(t) = \frac{F_0}{m} t + \vec{v}_0$$

$$\vec{r}(t) = \int dr = \int \vec{v} dt =$$

$$\frac{1}{2} \frac{\vec{F}_0}{m} t^2 + \vec{v}_0 t + \vec{r}_0$$

only valid for constant force

### 2.2.1 Time Dependent Force

$$\frac{d\vec{v}}{dt} = \vec{a} = \frac{\vec{F}}{m}$$

separation of variables

$$d\vec{v} = \frac{\vec{F}(t)}{m} dt$$

$$\int d\vec{v} = \int \frac{\vec{F}(t)}{m} dt$$

$$\vec{v}(t) = \frac{\vec{F}}{m} + \vec{C} \quad \vec{F} = \int F(t) dt$$

C is the integration constant

$$\vec{v} = \frac{d\vec{r}}{dt}$$

$$\vec{r} = \int \vec{v} dt$$

### 2.2.2 Example: Forced Harmonic Oscillator

A particle  $m$  moves along  $-\infty < x < \infty$ . It is subjected to a force  $F = F_0 \cos(\alpha t)$ . It starts at time  $t = 0, x_0 = x(t = 0) = 0, v_0 = v(t = 0) = 0$

1. coordinate system is just 1D
2. force is  $F = F_0 \cos(\alpha t)$

3. equation of motion from N2L is  $\frac{dv}{dt} = a = \frac{F}{m}$

4. separation of variables

$$\begin{aligned} dv &= \frac{F}{m} dt = \frac{F_0}{m} dt = \frac{F_0}{m} \cos \alpha t dt \\ v(t) &= \int dv = \frac{F_0}{m} \int \cos(\alpha t) dt = \frac{F_0}{m} \frac{1}{\alpha} \sin \alpha t + C_1 \\ x(t) &= \int v dt = \int \left( \frac{F_0}{\alpha m} \sin(\alpha t) + C_1 \right) dt = \\ &= -\frac{F_0}{\alpha^2 m} \cos(\alpha t) + C_1(t) + C_2 \end{aligned}$$

5. find initial conditions

$$\begin{aligned} 0 &= v_0 = \frac{F_0}{\alpha m} \sin \alpha 0 + C_1 \rightarrow C_1 = 0 \\ 0 &= x_0 = -\frac{F_0}{\alpha^2 m} \cos(\alpha 0) + 0 + C_2 \rightarrow \\ C_2 &= \frac{F_0}{\alpha^2 m} \\ x(t) &= \frac{F_0}{\alpha^2 m} (1 - \cos(\alpha t)) \\ v(t) &= \frac{F_0}{\alpha m} \sin(\alpha t) \end{aligned}$$

## 2.3 Position Dependent Force

focusing on 1 dimension for simplicity

get the equation of motion from Newton's 2nd Law



$$F(x) = ma = m \frac{dv}{dt}$$

chain rule

$$\frac{dv}{dt} = \frac{dv}{dx} \frac{dx}{dt} = v \frac{dv}{dx}$$

$$mv \frac{dv}{dx} = F(x)$$

separation of variables

$$mv dv = F(x) dx$$

Use definite integrals. relabel  $v = v'$  and  $x = x'$  (not derivatives)

$$m \int_{v_0}^v v' dv' = \int_{x_0}^x F(x') dx'$$

$$\frac{1}{2}m(v^2 - v_0^2) = \int_{x_0}^x F(x') dx'$$

solve for  $v$

It looks like change in kinetic energy and work

$$\Delta T = \frac{1}{2}m(v^2 - v_0^2) \quad W = \int F(x) dx$$

if force is conservative, it is path independent,

and it can be written as a gradient of a potential  $\vec{F} = -\nabla U$

$$F = -\frac{dU}{dx}$$

$$T - T_0 = \int_{x_0}^x -\frac{dU}{dx} dx' = -(U(x) - U(x_0))$$

$$E = T + U(x) = T_0 + U(x_0)$$

Conservation of Mechanical Energy

$$E = T + U(x) = \frac{1}{2}mv^2 + U(x)$$

$$v = \pm \sqrt{\frac{2}{m}(E - U(x))}$$

use  $v = \frac{dx}{dt}$  to find  $x(t)$

## 2.4 Analyzing the Potential

infer velocity and position

given energy, what is motion

$$E = E_0 = E(x_0) = T(x_0) + U(x_0)$$

$$U(x_0) = E_0 = \text{const} \rightarrow T(x_0) = 0 \rightarrow v(x_0) = C$$

### 2.4.1 case 2: energy of particle is \_

$$E = E_1 = T(x) + U(x)$$

particle can move between  $x_{1a}$  and  $x_{1b}$

$$x_0 : E_1 = E = T + U(x_0)$$

potential energy is at minimum, kinetic at max

$v(x_0)$  is maximal

**2.4.2 Case 3:**  $E = E_2 = U(x_2)$ 

$$T(x_2) = 0 \text{ so } v = 0$$