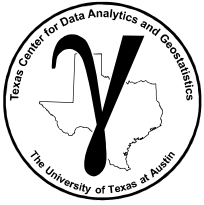


# **PGE 383**

## **Ensemble Tree Methods**

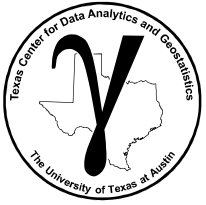
- **Ensemble Methods**
- **Bootstrap**
- **Tree Bagging**
- **Random Forest**
- **Ensemble Tree Methods Hands-on**



# **PGE 383**

## **Ensemble Tree Methods**

- **Ensemble Methods**

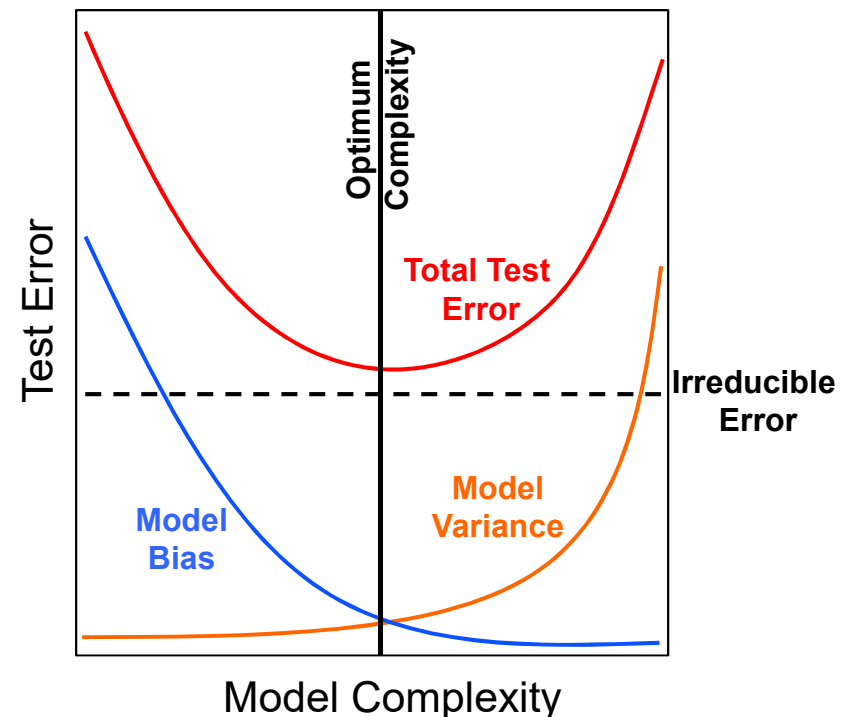


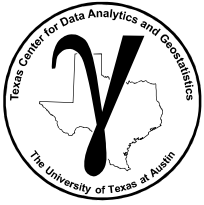
# Model Bias and Variance Trade-off

- The **Expected Test Mean Square Error** may be calculated as:

$$E \left[ (y_0 - \hat{f}(x_1^0, \dots, x_m^0))^2 \right] = \underbrace{\text{Var}(\hat{f}(x_1^0, \dots, x_m^0))}_{\text{Model Variance}} + \underbrace{[\text{Bias}(\hat{f}(x_1^0, \dots, x_m^0))]^2}_{\text{Model Bias}} + \underbrace{\text{Var}(\epsilon)}_{\text{Irreducible}}$$

- Model Variance** is the variance if we had estimated the model with a different training set / sensitivity to data /
- Model Bias** is error due to using an approximate model / model is too simple
- Irreducible error** is due to missing variables and limited samples can't be fixed with modeling / entire feature space is not sampled





# Reducing Model Variance

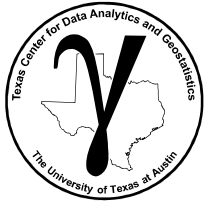
- We can improve the **Expected Test Mean Square Error** by reducing the **model variance**:

$$Var(\hat{f}(x_1^0, \dots, x_m^0))$$

- Averaging is an efficient method to reduce variance:

$$\sigma_{\bar{x}}^2 = \frac{\sigma_s^2}{n}$$

- From standard error we can observe the reduction in variance through averaging.
  - This is maximal when the values averaged are not correlated.



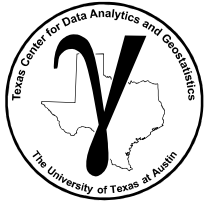
# Ensemble Prediction Method

- Calculate multiple estimates for our prediction problem.
- This requires multiple prediction models.

$$\hat{f}^b(X_1, \dots, X_m)$$

- We can train multiple models on multiple training datasets.
- But we only have access to a single dataset

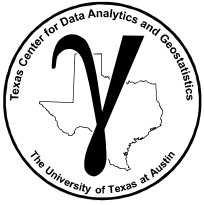
$$Y, X_1, \dots, X_m$$



# **PGE 383**

## **Ensemble Tree Methods**

- **Bootstrap**



# Bootstrap Definition

## Bootstrap

- method to assess the uncertainty in a sample statistic by repeated random sampling with replacement

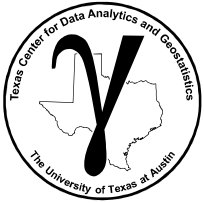
## Assumptions

- sufficient, representative sampling

## Limitations

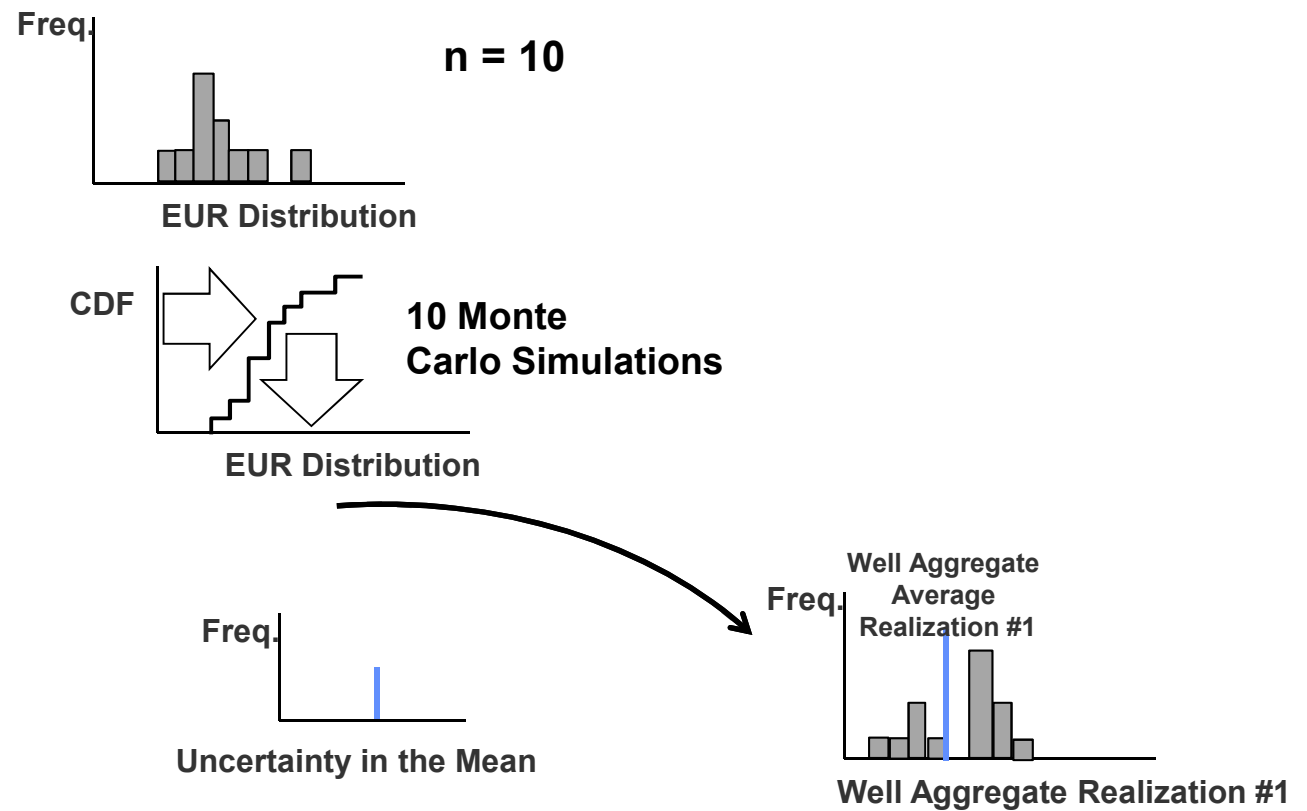
- assumes the samples are representative
- assumes stationarity
- only accounts for uncertainty due to too few samples, e.g. no uncertainty due to changes away from data
- does not account for area of interest
- assumes the samples are independent
- does not account for other local information sources

**No spatial  
Context**

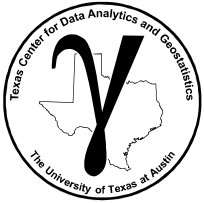


# Bootstrap Method

## Bootstrap for Uncertainty in the Mean

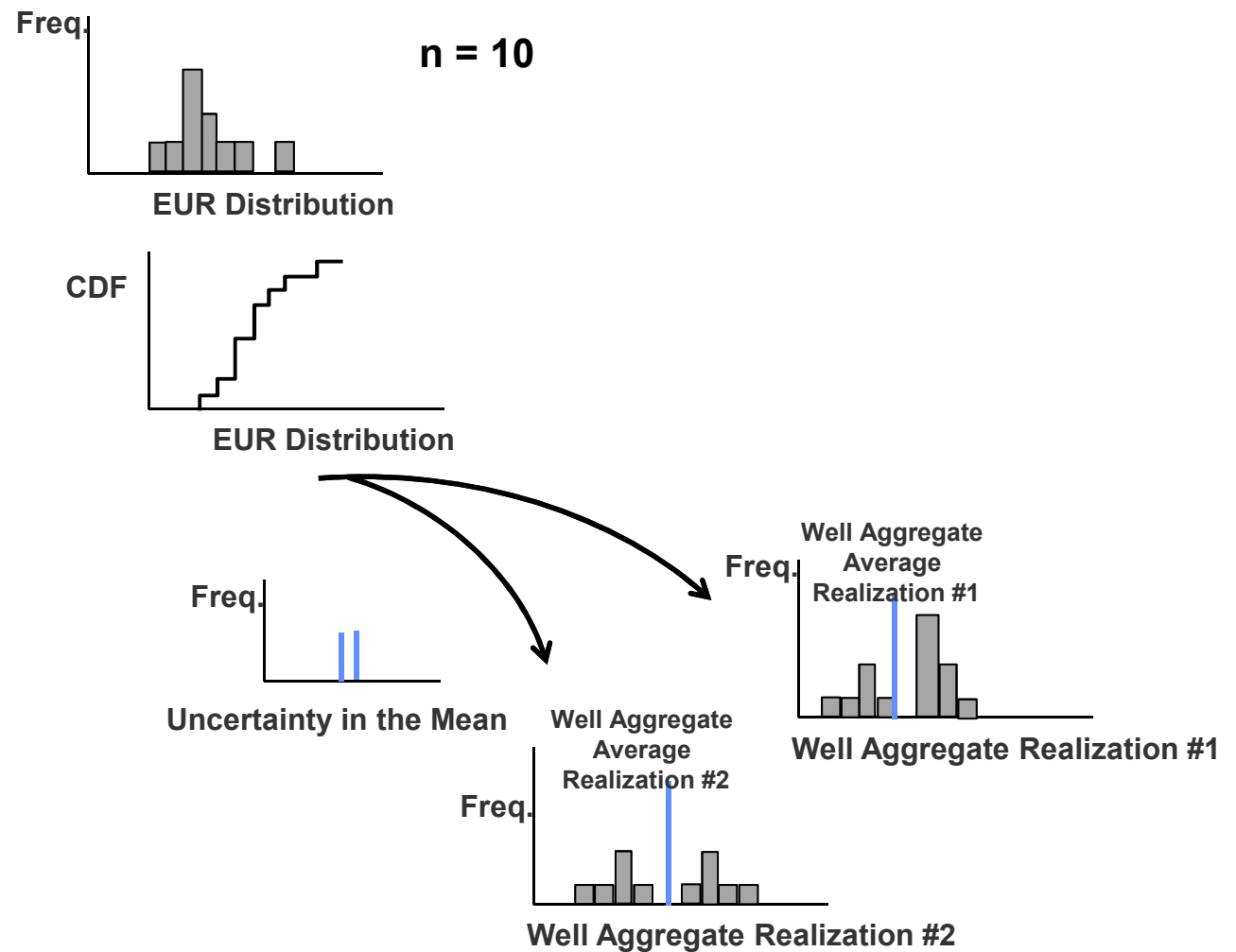


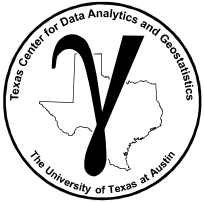




# Bootstrap Method

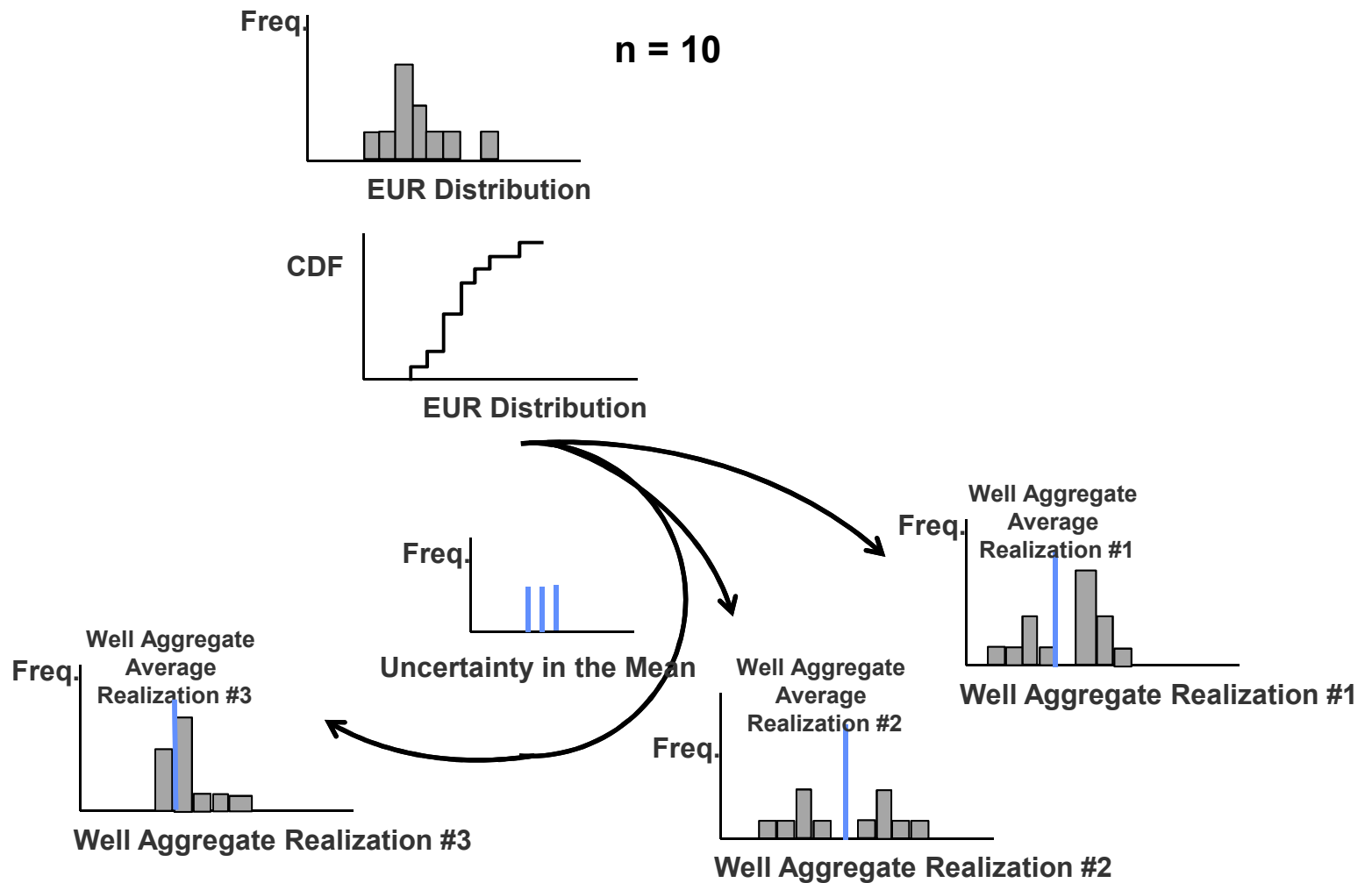
## Bootstrap for Uncertainty in the Mean

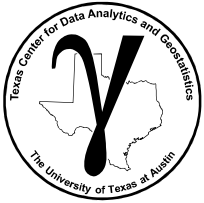




# Bootstrap Method

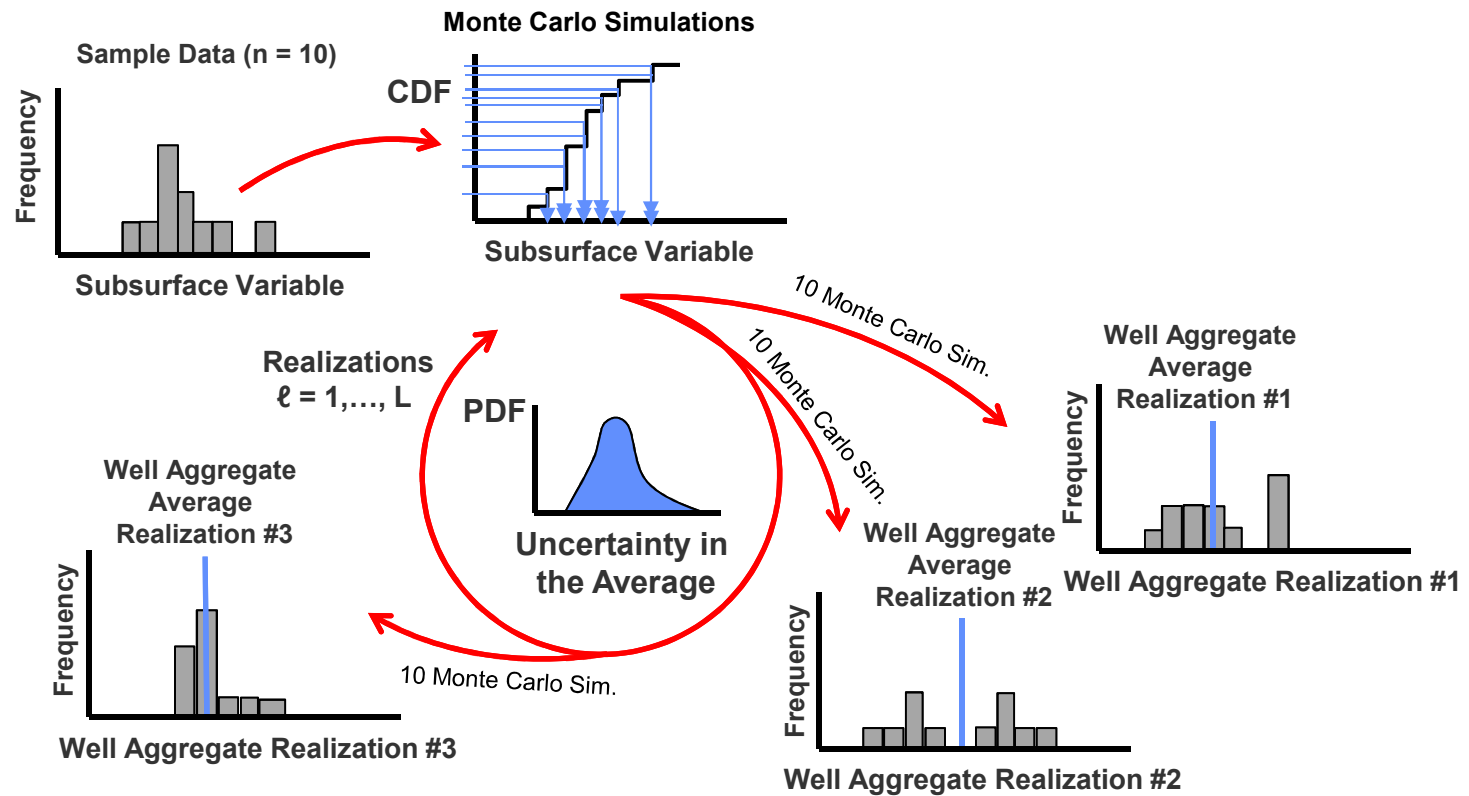
## Bootstrap for Uncertainty in the Mean

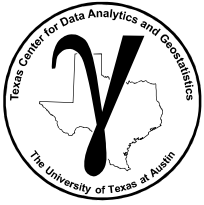




# Bootstrap Method

## Bootstrap for Uncertainty in the Mean



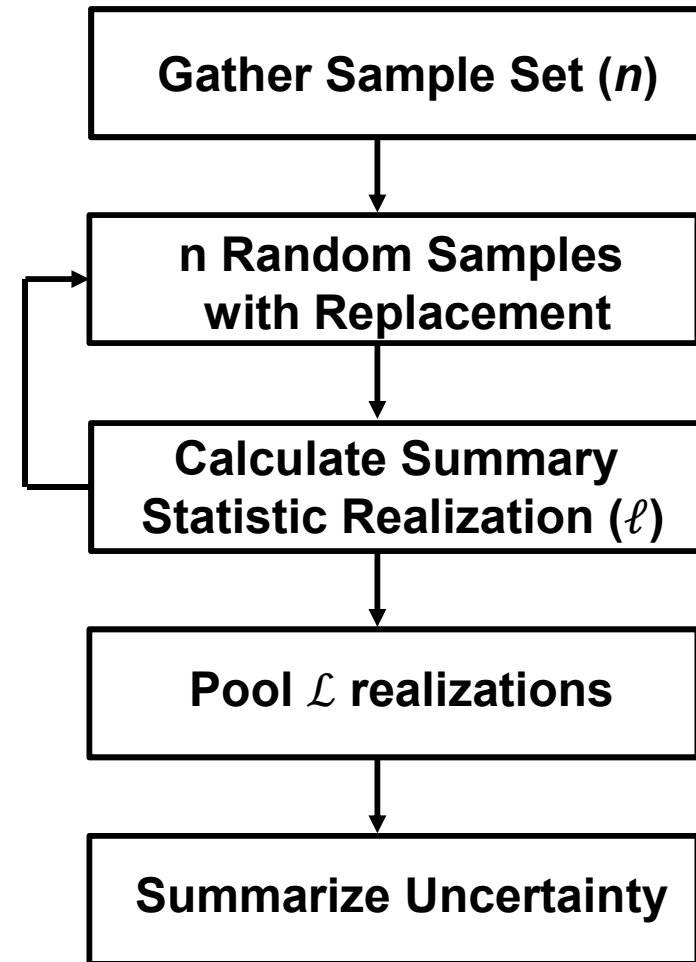


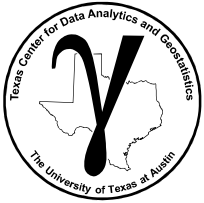
# Bootstrap Method

- Bootstrap Approach (Efron, 1982)
- Statistical resampling procedure to calculate uncertainty in a calculated statistic from the data itself.
- For uncertainty in the mean solution is standard error:

$$\sigma_x^2 = \frac{\sigma_s^2}{n}$$

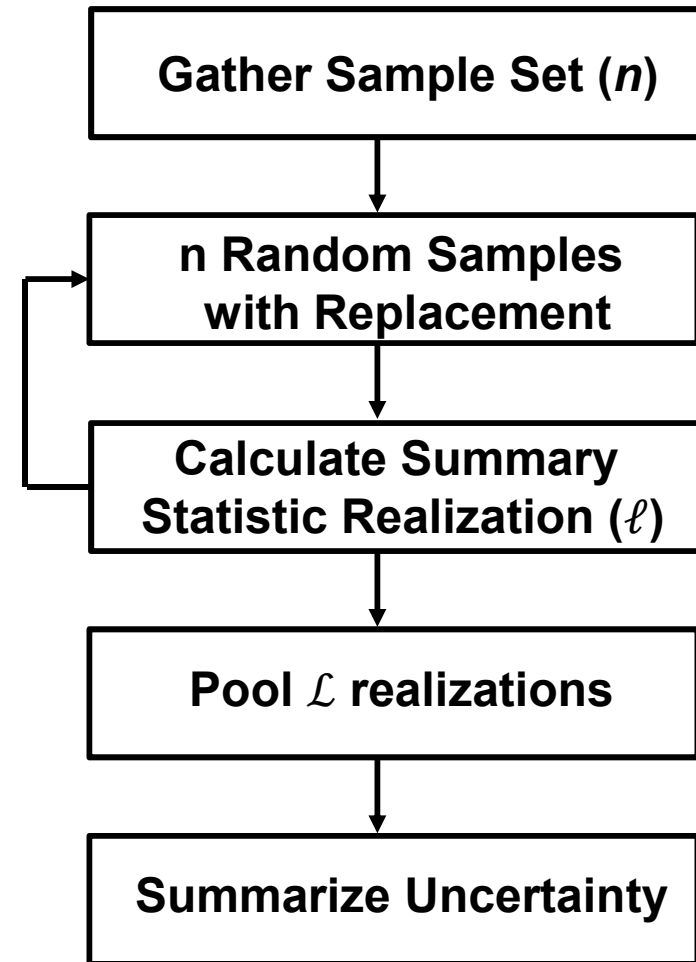
- Extremely powerful. Could get uncertainty in any statistic! e.g. P13, skew etc.
- Would not be possible without bootstrap.
- Advanced forms account for spatial information and strategy (game theory).

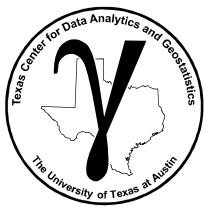




# Bootstrap Method

- You now know about one of the most powerful tools ever!
- Caveats:
  - assumes the sample set is representative
  - unbiased and covers the full range
  - assumes all samples are independent if not consider Journel's spatial bootstrap (1993).
- You can do bootstrap in Excel.





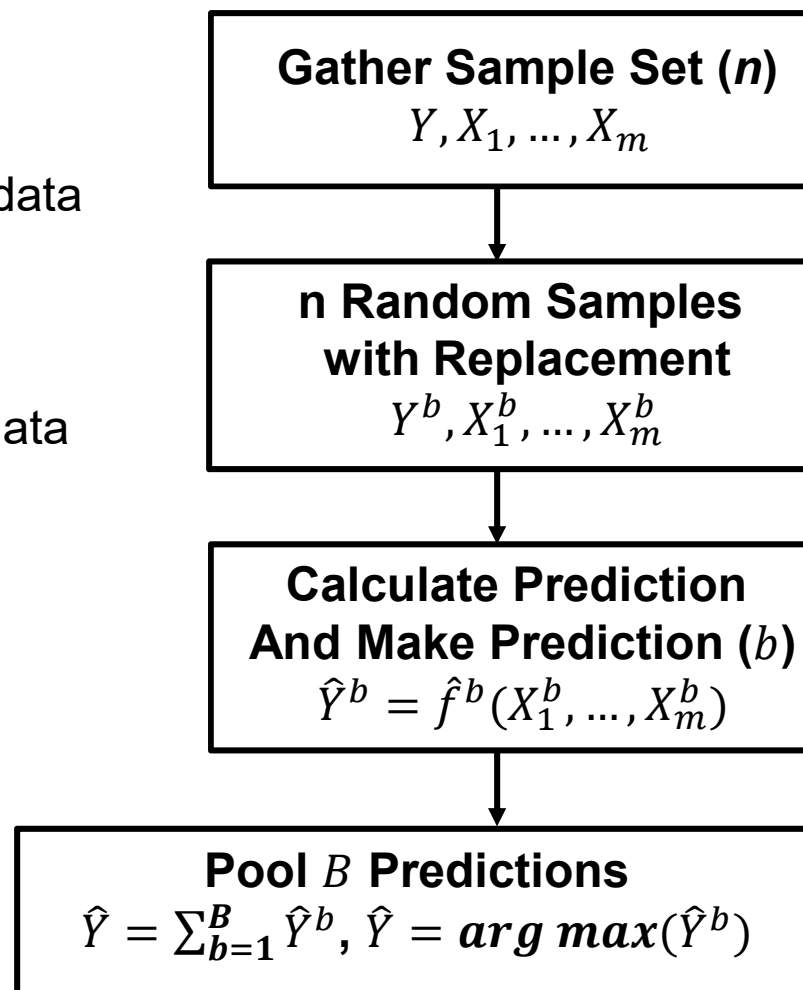
# Bootstrap For Ensemble Methods

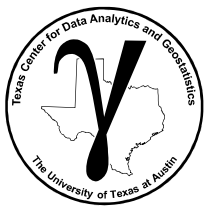
1. Apply statistical bootstrap to obtain multiple realizations of the training data

$$Y^b, X_1^b, \dots, X_m^b, b = 1, \dots, B$$

2. Build a prediction model for each data realization

$$\hat{Y}^b = \hat{f}^b(X_1^b, \dots, X_m^b)$$





# Bootstrap For Ensemble Methods

3. Apply all prediction models for each prediction:

- Regression – aggregate the ensemble predictions with the average

$$\hat{Y} = \sum_{b=1}^B \hat{Y}^b$$

- Classification – aggregate the ensemble predictions with majority-rule

$$\hat{Y} = \arg \max(\hat{Y}^b)$$

**Gather Sample Set ( $n$ )**

$Y, X_1, \dots, X_m$

**$n$  Random Samples  
with Replacement**

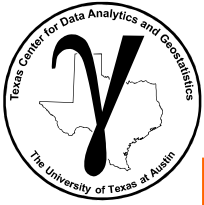
$Y^b, X_1^b, \dots, X_m^b$

**Calculate Prediction  
And Make Prediction ( $b$ )**

$\hat{Y}^b = \hat{f}^b(X_1^b, \dots, X_m^b)$

**Pool  $B$  Predictions**

$\hat{Y} = \sum_{b=1}^B \hat{Y}^b, \hat{Y} = \arg \max(\hat{Y}^b)$

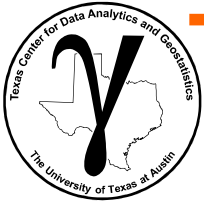


# **PGE 383 Lecture 26**

## **Ensemble Tree Methods**

- **Tree Bagging**



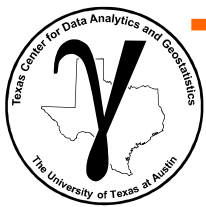


# Tree Bagging

Build an ensemble of decision trees with multiple, bootstrap realizations of the data.

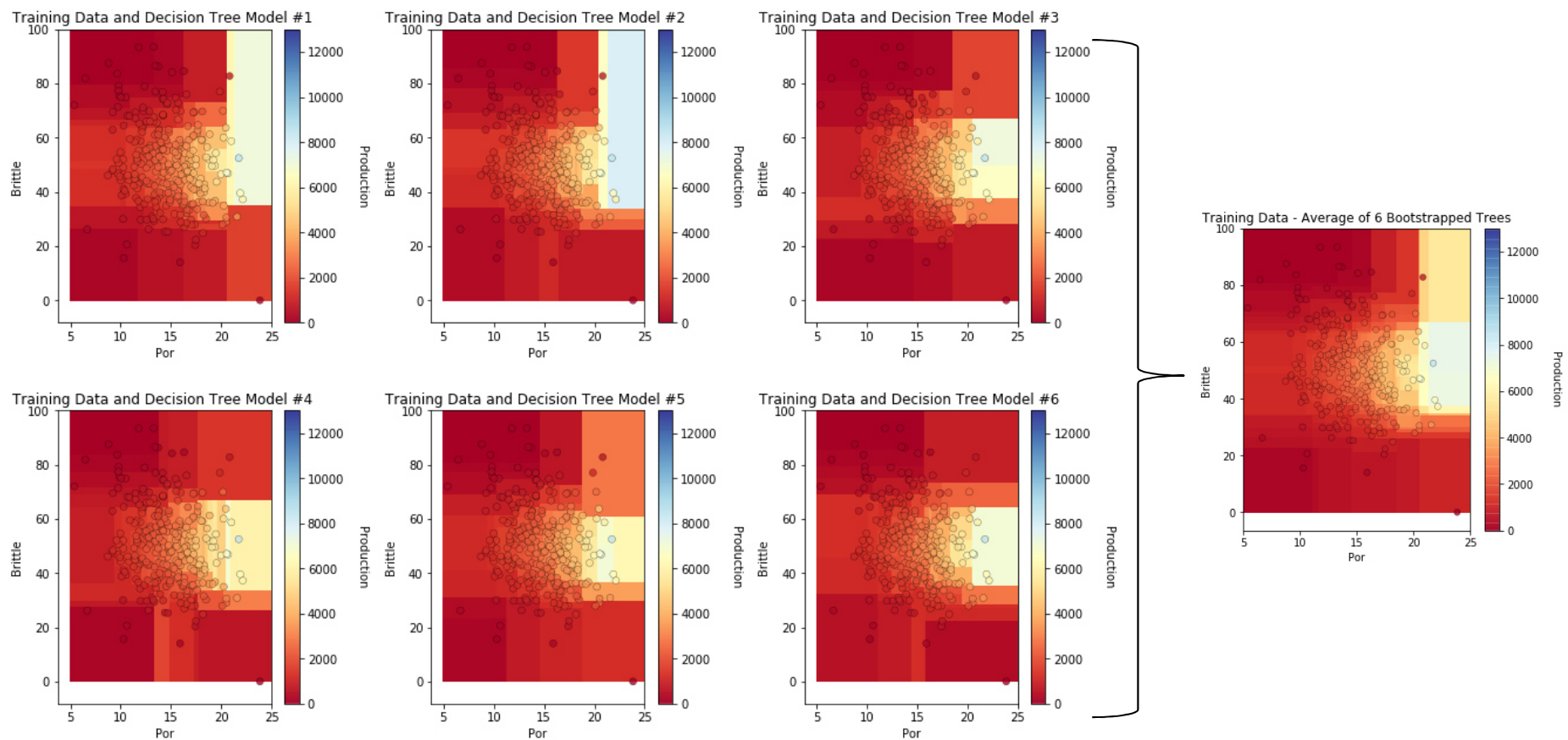
Comments:

- The ensemble approach **reduces model variance as expected**
- **Grow each tree to be complicated.** We can overfit each tree, the ensemble approach reduces the risk of overfit
- In expectation,  $1/3$  of the data is not used for each tree, this provides the opportunity to have access to out-of-bag samples for cross validation, so **we can build our model and cross validate with all the data at once**
- We want the trees to be decorrelated, diverse to maximize the reduction in model variance, **this leads to random forest**

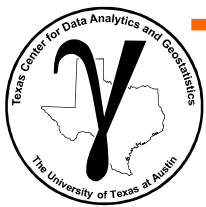


# Tree Bagging Example

Build an ensemble of decision trees with multiple, bootstrap realizations of the data and average the predictions from all models.

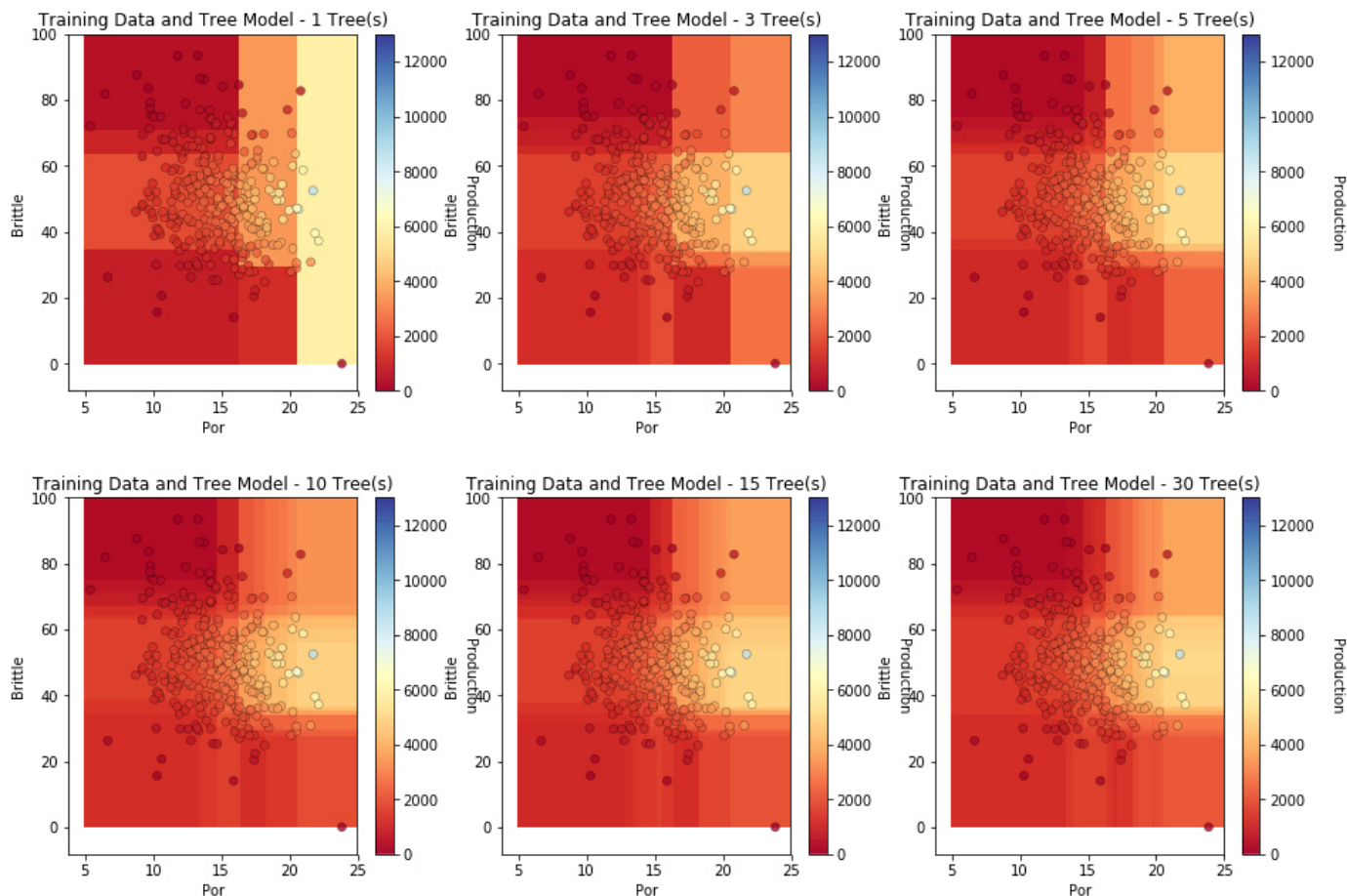


6 bootstrapped, complicated decision trees (left) and the average of all 6 models (right).

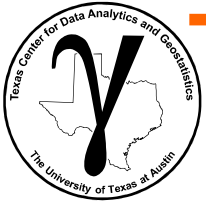


# Tree Bagging Example

Observe the impact on the prediction model with the addition of more trees – transition from a discontinuous to continuous prediction model!

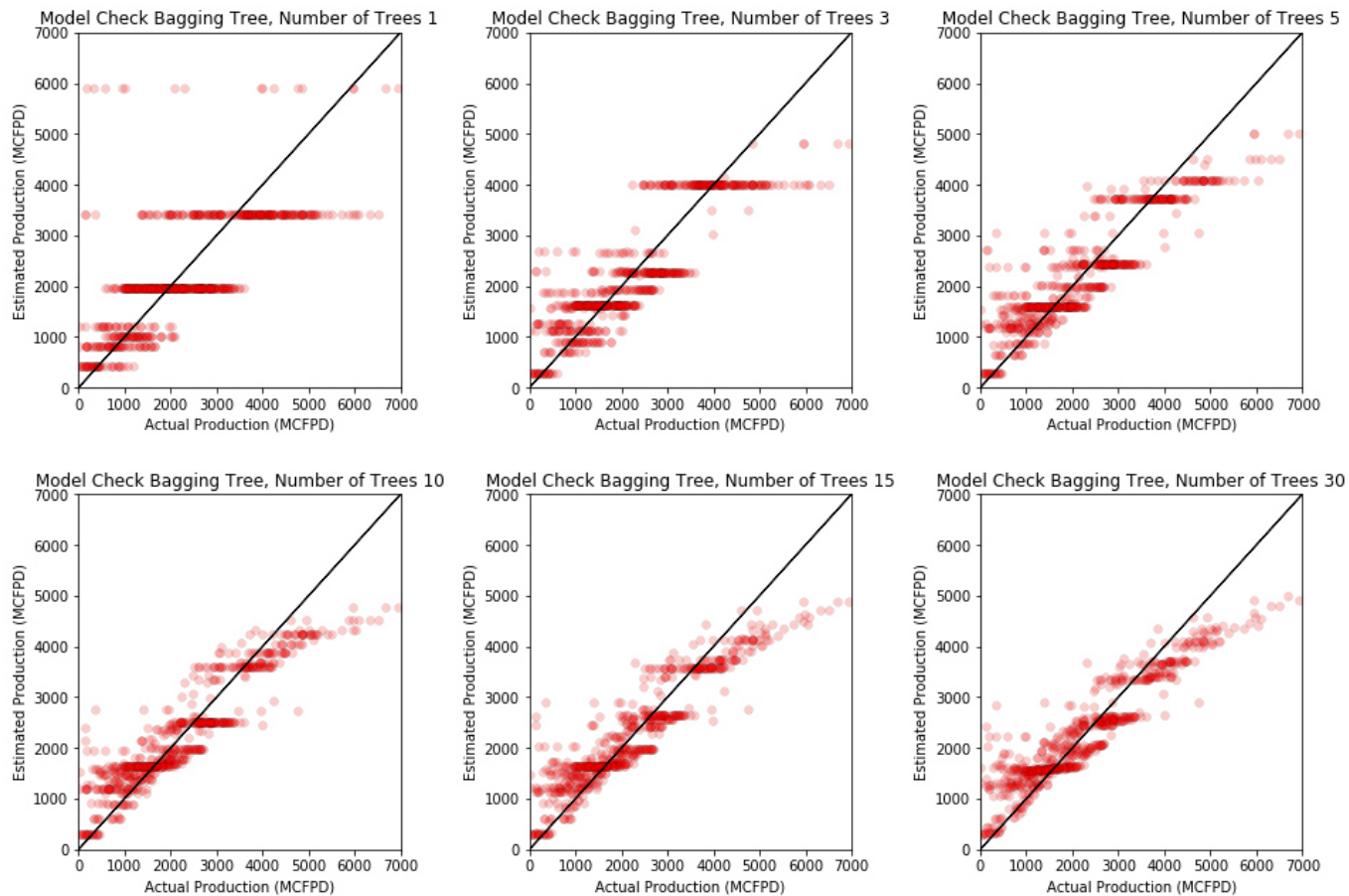


6 tree bagging prediction models and all training data with increasing number of trees.

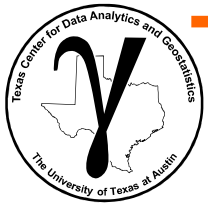


# Tree Bagging Example

Observe the improved testing accuracy in cross validation with increasing number of trees.

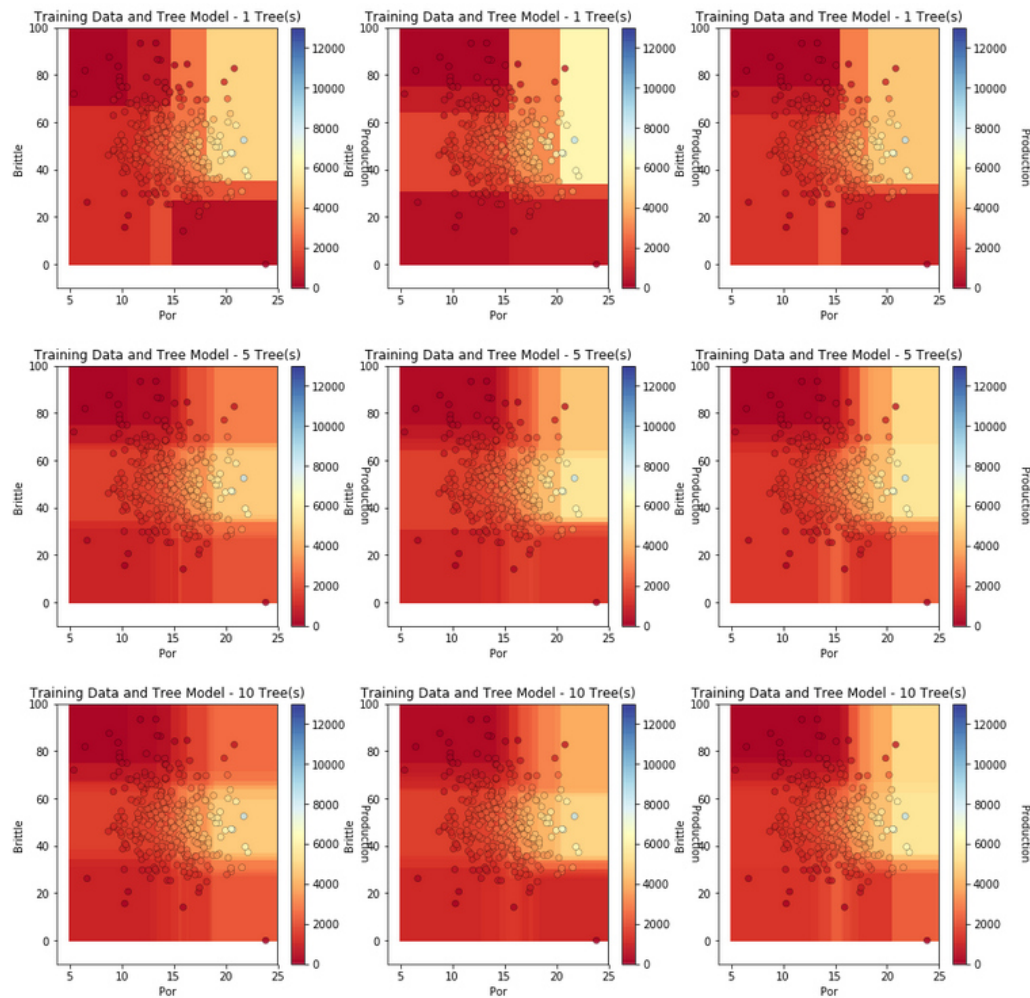


Cross validation with 6 tree bagging prediction models with increasing number of trees.

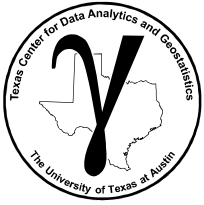


# Tree Bagging Example

Observe the reduction in model variance with increasing number of trees.



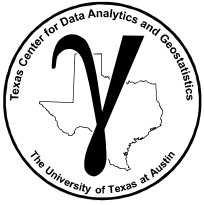
3 models with 1, 5 and 10 trees to demonstrate the reduction in model variance with increased ensemble aggregation.



# **PGE 383**

## **Ensemble Tree Methods**

- **Random Forest**



# Random Forest

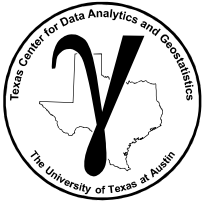
A limitation with tree bagging is that the individual trees may be highly correlated

- This occurs when there is a dominant predictor feature as it will always be applied to the top split(s)
  - the result is all the trees in the ensemble are very similar (i.e. correlated)
- With highly correlated trees, there is significantly less reduction in model variance with the ensemble
- Random forest is tree bagging and for each split only a subset of the  $m$  available predictors are candidates for splits (selected at random)

$$p = \sqrt{m}$$

- This forces each tree in the ensemble to evolve in dissimilar manner

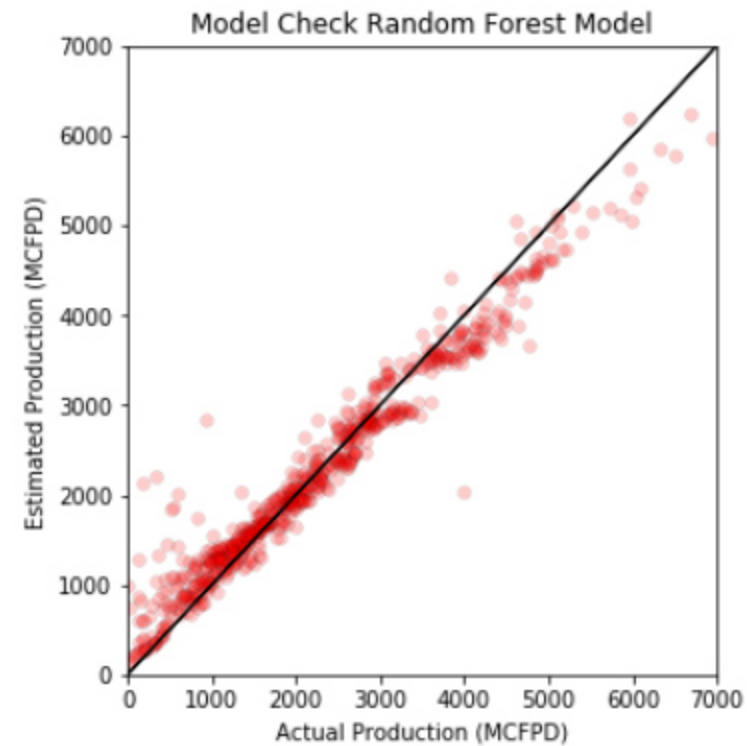
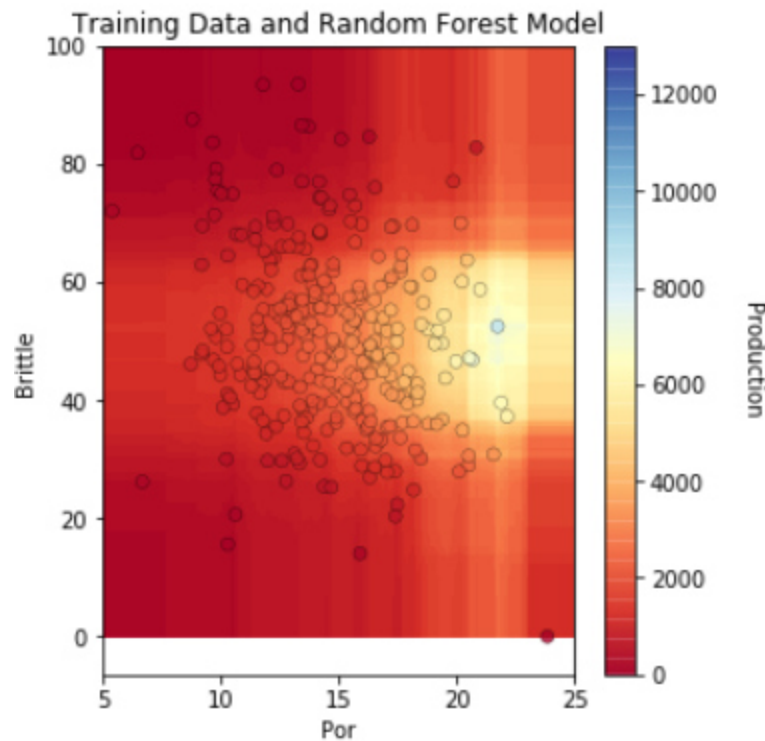




# Random Forest Example

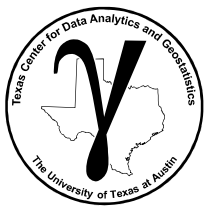
Example random forest model for the previous prediction problem

- 300 trees, trained to a maximum depth of 3, 1 predictor selected for each split



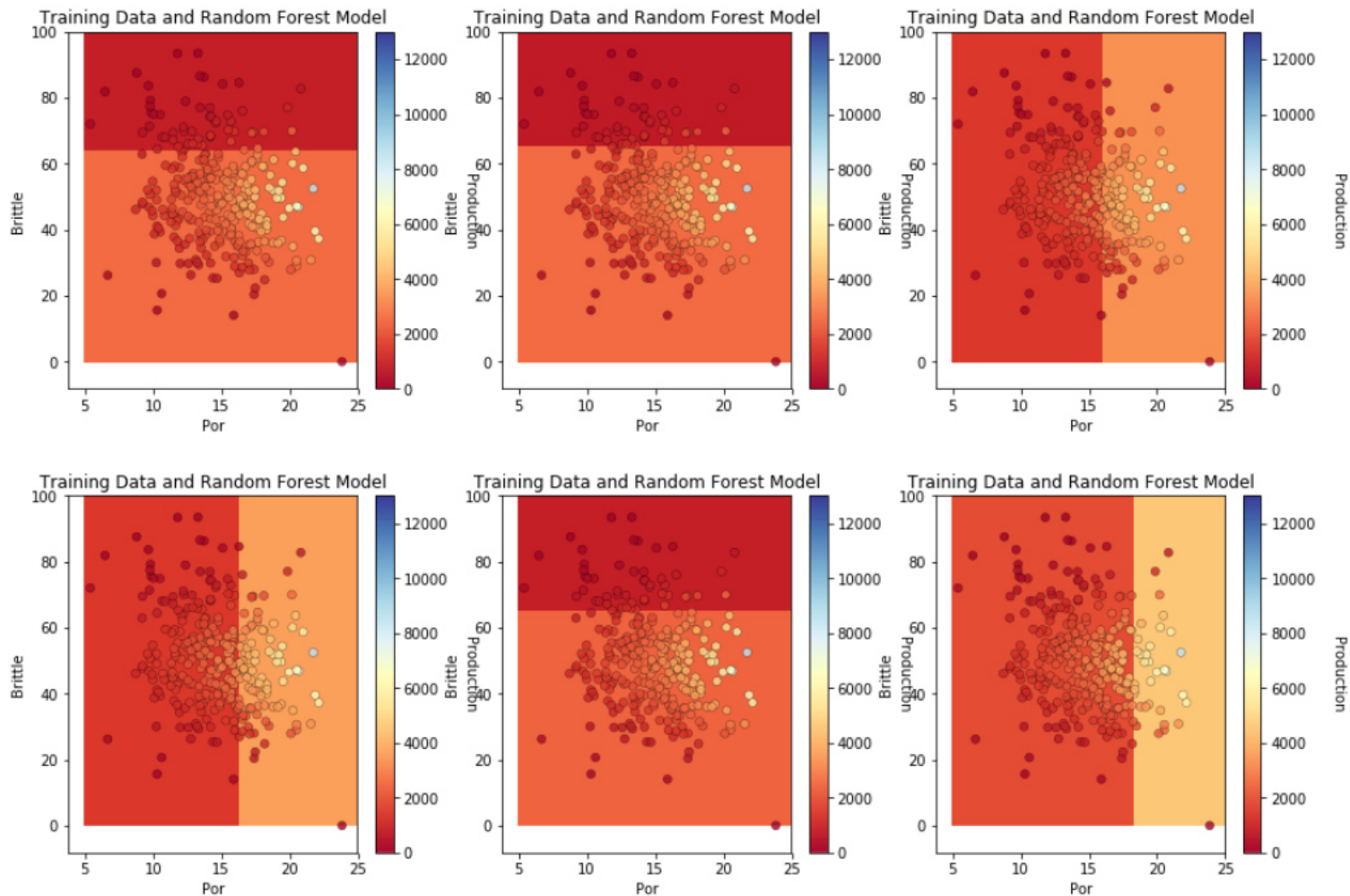
Random forest prediction model and model cross validation.



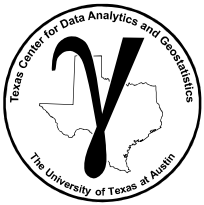


# Random Forest Example

Are the trees diverse? Let's freeze 6 trees at the first split.

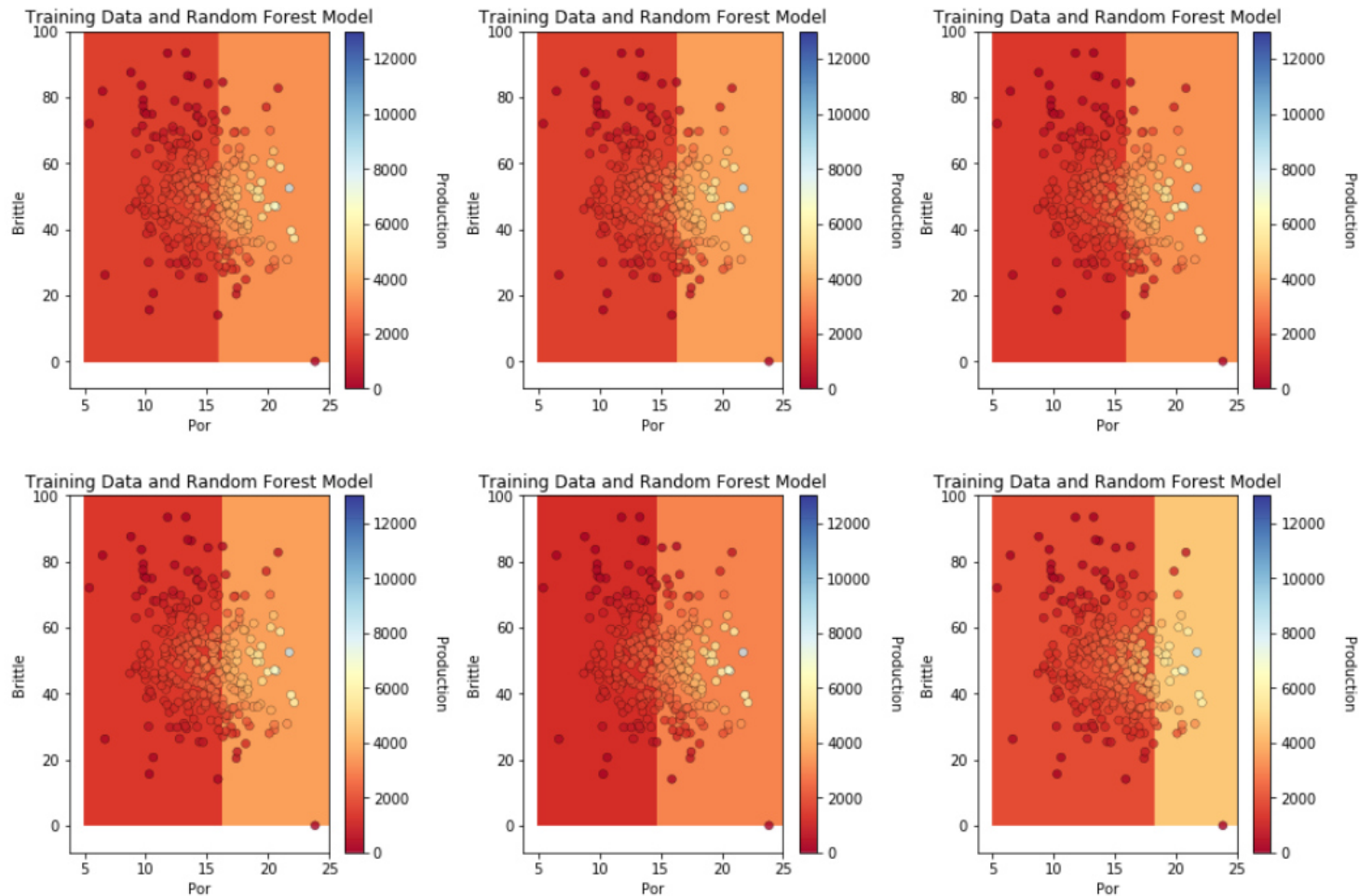


6 tree from a random forest frozen at the first split ( $p = 1$ )

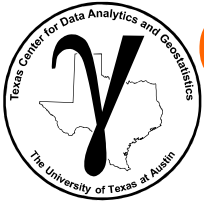


# Random Forest Example

Now compare to tree bagging, just set  $p = m$  to get tree bagging from random forest! There is very little tree diversity on the first split!



6 tree from tree bagging frozen at the first split ( $p = 1$ )



# Out-of-Bag Cross Validation Hyperparameter Tuning

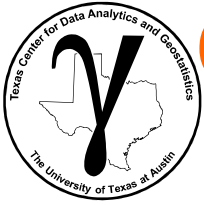
During the construction of  $B$  decision trees (tree bagging and random forest)

- Build a decision tree with the 2/3 of data (in expectation) sampled with bootstrap
  - The data not used in the current model training are known as out-of-bag samples
  - Predict at the out-of-bag samples
- Pool the B/3 predictions for each sample data from all the B models and make an out-of-bag prediction

$$\hat{y}_\alpha^* = \sum_{b=1}^{\frac{B}{3}} \hat{y}_\alpha^{*,b}$$

- Calculate the out-of-bag mean square error to assess model performance.

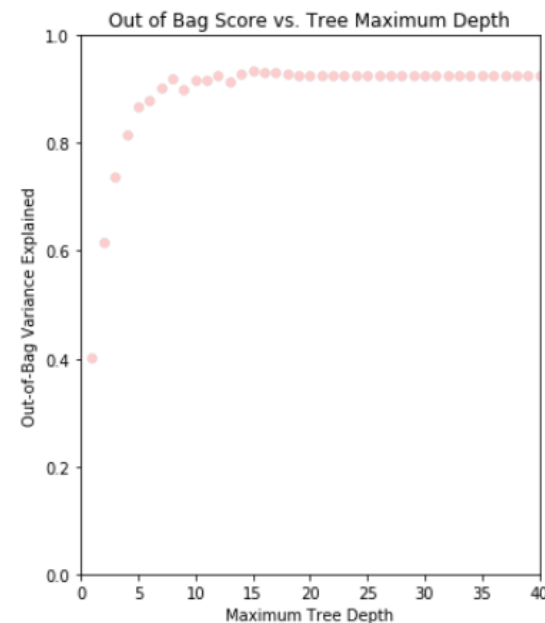
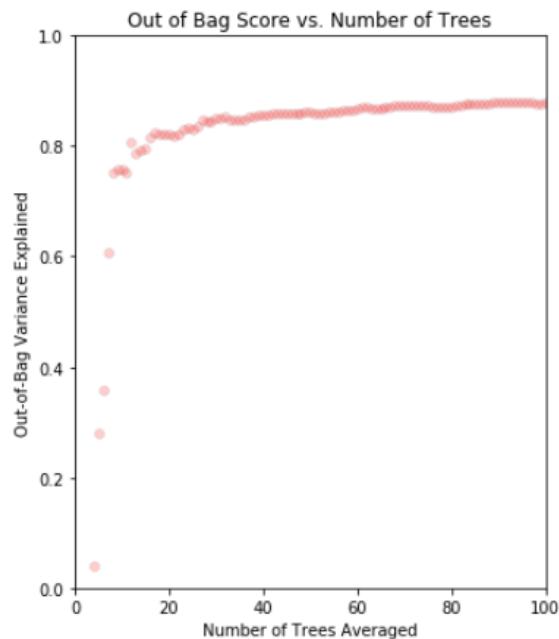
$$MSE_{OOB} = \sum_{b=1}^{\frac{B}{3}} [\hat{y}_\alpha^* - y_\alpha]^2$$



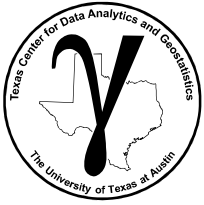
# Out-of-Bag Cross Validation Hyperparameter Tuning

For previous random forest

- Loop over multiple hyperparameters and calculate the out-of-bag prediction performance



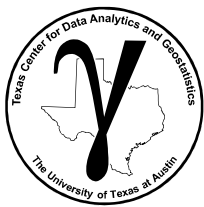
- note that our random forest model is robust and resistant to overfit, the out-of-bag performance evaluation is approximately monotonically increasing



# **PGE 383**

## **Ensemble Tree Methods**

- **Ensemble Tree Methods Hands-on**



# Ensemble Tree Demonstration

Demonstration workflow with ensemble tree regression.



## Subsurface Machine Learning with Ensemble Tree Regressor Methods

### Tree Bagging and Random Forest for Subsurface Modeling in Python

Michael Pyrcz, Associate Professor, University of Texas at Austin

[Twitter](#) | [GitHub](#) | [Website](#) | [Google Scholar](#) | [Book](#) | [YouTube](#) | [LinkedIn](#) | [GeostatsPy](#)

### PGE 383 Exercise: Ensemble Tree Regressors for Subsurface Modeling in Python

Here's a simple workflow, demonstration of tree bagging and random forest for subsurface modeling workflows. This should help you get started with building subsurface models that data analytics and machine learning. Here's some basic details about ensemble tree methods.

#### Ensemble Tree Methods

Machine learning method for supervised learning for classification and regression analysis. Here are some key aspects of random forest.

#### Prediction

- estimate a function  $\hat{f}$  such that we predict a response feature  $Y$  from a set of predictor features  $X_1, \dots, X_m$ .
- the prediction is of the form  $\hat{Y} = \hat{f}(X_1, \dots, X_m)$

#### Supervised Learning

- the response feature label,  $Y$ , is available over the training and testing data

#### Based on an Ensemble of Decision Trees

These are the concepts related to decision tree.

#### Hierarchical, Binary Segmentation of the Feature Space

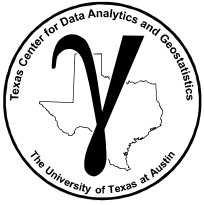
The fundamental idea is to divide the predictor space,  $X_1, \dots, X_m$ , into  $J$  mutually exclusive, exhaustive regions

- **mutually exclusive** – any combination of predictors only belongs to a single region,  $R_j$
- **exhaustive** – all combinations of predictors belong a region,  $R_j$ , regions cover entire feature space (range of the variables being considered)

For every observation in a region,  $R_j$ , we use the same prediction,  $\hat{Y}(R_j)$

For example predict production,  $\hat{Y}$ , from porosity,  $X_1$

File SubsurfaceDataAnalytics\_EnsembleTree.ipynb at <https://git.io/fjX23>.



# **PGE 383**

## **Ensemble Tree Methods**

- **Ensemble Methods**
- **Bootstrap**
- **Tree Bagging**
- **Random Forest**
- **Ensemble Tree Methods Hands-on**