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Romberg算法:

1. 计算积分区间两端点函数值 $f(a), f(b)$, 计算 T_1 ;
2. 将区间 $[a, b]$ 分半, 计算 $f((a+b)/2)$, T_2, S_1 ;
3. 再将区间分半, 算出 $f(a+(b-a)/2)$ 和 $f(a+3(b-a)/4)$, 由此计算 T_4, S_2, C_1 ;
4. 再将区间分半, 计算 T_8, S_4, C_2 , 进而计算 R_1 ;
5. 再将区间分半, 重复第四步工作, 计算 T_{16}, S_8, C_4, R_2 , 反复进行这一过程, 可以计算 R_1, R_2, R_4, \dots , 直到最终两个 R 之差不超过给定精度即可。

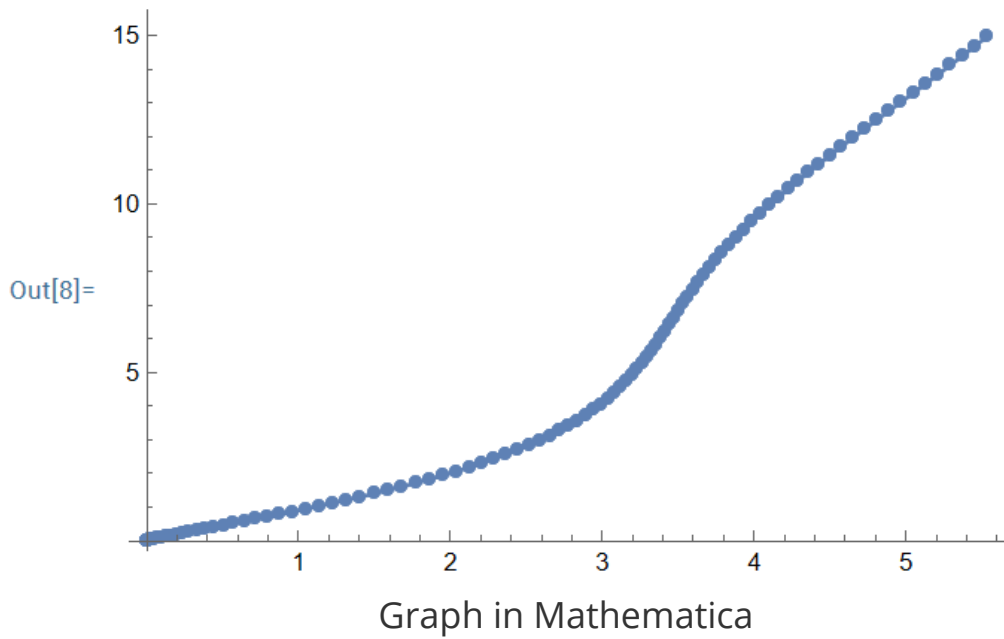
其计算过程是将区间逐次分半，加速得到积分近似值，因此称为**逐次分半加速法**

1. 根据 $a_x(t), a_y(t)$, 使用Romberg算法求得 $v_x(t), v_y(t)$
2. 根据 $v_x(t), v_y(t)$, 使用Romberg算法求得 $x(t), y(t)$

当 $M = 8$ 时, 运行结果如下:

{0,0},{0.000137185,0.000155819},{0.00102216,0.00115882},{0.00327356,0.00366921},{0.00742936,0.00818836},{0.0139661,0.0151038},{0.0233072,0.0247169},{0.0358262,0.0372634},{0.0518488,0.0529278},{0.0716543,0.0718552},{0.0954757,0.0941587},{0.123501,0.119926},{0.155872,0.149225},{0.192687,0.182107},{0.234062,0.21861},{0.279826,0.258759},{0.330131,0.302573},{0.384846,0.350601},{0.443862,0.401228},{0.507034,0.456072},{0.574182,0.514587},{0.645094,0.576763},{0.719528,0.642589},{0.797217,0.71205},{0.877866,0.785128},{0.961164,0.861806},{1.04678,0.942063},{1.13437,1.02588},{1.22357,1.11323},{1.31403,1.20409},{1.40537,1.29845},{1.49723,1.39627},{1.58924,1.49753},{1.68104,1.6022},{1.77228,1.71927},{1.86263,1.82171},{1.95175,1.93649},{2.03995,2.05459},{2.12514,2.17598},{2.20885,2.30064},{2.29026,2.42854},{2.36914,2.55966},{2.44533,2.69397},{2.51865,2.83146},{2.5899,2.97209},{2.65628,3.11584},{2.72043,3.2627},{2.78143,3.41263},{2.83927,3.56561},{2.89399,3.72163},{2.94565,3.88065},{2.99436,4.04266},{3.04022,4.20763},{3.0834,4.37555},{3.12405,4.54639},{3.16239,4.72013},{3.19861,4.89675},{3.23296,5.07622},{3.26569,5.25854},{3.29705,5.44368},{3.32733,5.63161},{3.35679,5.82233},{3.38573,6.0158},{3.41443,6.21202},{3.44318,6.41096},{3.47226,6.61261},{3.50194,6.81694},{3.5325,7.02394},{3.56418,7.23359},{3.59723,7.44587},{3.63188,7.66078},{3.66832,7.87828},{3.70676,8.09836},{3.74734,8.32101},{3.79022,8.54621},{3.83552,8.77394},{3.88332,9.00419},{3.93369,9.23694},{3.98668,9.47218},{4.04231,9.70899},{4.10055,9.95006},{4.16137,10.1927},{4.22471,10.4377},{4.29049,10.6851},{4.35858,10.935},{4.42887,11.1872},{4.5012,11.4418},{4.57539,11.6988},{4.65126,11.9581},{4.7286,12.2197},{4.8072,12.4836},{4.88683,12.7499},{4.96726,13.0184},{5.04823,13.2892},{5.12913,13.5623},{5.21086,13.8376},{5.29202,14.1152},{5.37275,14.395},{5.45283,14.677},{5.53202,14.9612}.

Output in VScode



三、算法比较

M	4	8	12	16	20
达到要求精度的比例	0.0686937	0.648624	1	1	1

当 $M \geq 12$ 后，均达到精度，达到误差要求的次数/调用总次数 = 1

四、结果和分析

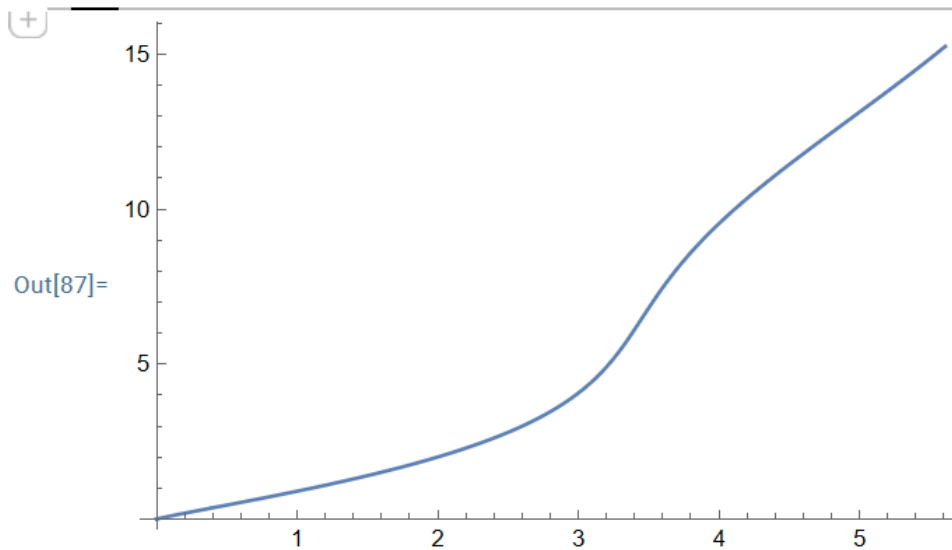
- 结果与MMA模拟结果一致，y方向速度恒增，x方向速度变化趋势类似正弦波的衰弱分布
- M在一定范围内时，越大，精度越高，计算次数越多,此时精度依赖于M和e，当M大于某个临界值后，M变化不影响精度和计算次数，此时精度只依赖于e。

可以将M取值很大，就能保证一定达到设置精度，或取精度次数/总次数>某临界值，减少运算次数，使其大多数达到精度。

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In[82]:= Ax[t_] =  $\frac{\text{Sin}[t]}{\text{Sqrt}[t] + 1}$ ;
          Ay[t_] =  $\frac{\text{Log}[t + 1]}{t + 1}$ ;
          X[t_] = NIntegrate[Ax[r], {s, 0, t}, {r, 0, s}];
          Y[t_] = NIntegrate[Ay[r], {s, 0, t}, {r, 0, s}];
          data = Table[{X[t], Y[t]}, {t, 0.1, 10, 0.1}];
          ListLinePlot[data]

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Simulate in Mathematica