

Algorithm Analysis

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Problem Solving

Problem Solving: Main Steps

- 1 Problem definition (model the problem)
- 2 Algorithm design (find an algorithm that solves the modeled problem)
- 3 Algorithm analysis (fast enough? fits into the memory?)
- 4 Implementation
- 5 Testing
- 6 *Maintenance*

1. Problem Definition

- Try to understand what are the **main elements** of the problem that need to be solved. (Functional requirements)
 - Calculate the mean of "n" numbers.
 - Scan a document in English and translate it to Turkish.
- What are the performance requirements? (Non functional requirements)

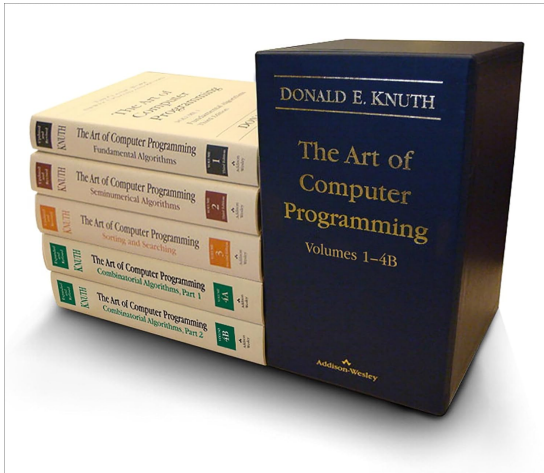
Functional vs Non-Functional Requirements

Functional requirements: "Any Requirement Which Specifies **What** The System Should Do."

Non-Functional requirements: "Any Requirement That Specifies **How** The System Performs A Certain Function"

Non-functional requirements can be considered as quality attributes.





2. Algorithm Design

- **Algorithm:** A clearly specified set of simple instructions to be followed to solve a problem
- An algorithm can be described in natural language, pseudo-code, diagrams etc.
- Knuth's characterization (five properties as requirements for an algorithm):
 - **Input:** Zero or more quantities (externally produced)
 - **Output:** One or more quantities
 - **Definiteness:** Clarity, precision of each instruction
 - **Finiteness:** The algorithm has to stop after a finite (may be very large) number of steps
 - **Effectiveness:** Each instruction has to be basic enough and feasible

3. Algorithm Analysis

- Given an algorithm, will it satisfy the requirements?
- Given a number of algorithms to perform the same computation, which one is "best"?
- The analysis required to estimate the "resource use" of an algorithm
 - Space complexity
 - How much space is required ?
 - Time complexity
 - How much time does it take to run the algorithm ?
- Often, we have to deal with estimates!

4,5,6: Implementation, Testing, Maintenance

- Implementation
 - Decide on the programming language
 - Write clean, well documented code
- Test (How long?)
- Maintenance
 - Bug fixing, version management, new features etc.

Problem Solving: Life-cycle

- 1 Problem definition
- 2 Algorithm design
- 3 Algorithm analysis
- 4 Implementation
- 5 Testing
- 6 *Maintenance*

-> Why do we need Algorithm Analysis in our profession?

-> What should be Analysed?

3. Algorithm Analysis

- Space complexity
 - How much space is required ?
- Time complexity
 - How much time does it take to run the algorithm ?

- Space complexity = The amount of memory required by an algorithm to run to completion
- Some algorithms may be more efficient if data completely loaded into memory
 - Need to look also at system limitations e.g. Classify 20GB of text in various categories – Can I afford to load the entire collection?

Space Complexity (cont'd)

- ❶ **Fixed part:** The size required to store certain data/variables, that is **independent** of the size of the problem:
 - e.g. name of the data collection
 - Same size for classifying 2GB or 1MB of texts
- ❷ **Variable part:** Space needed by variables, whose size is **dependent** on the size of the problem:
 - e.g. actual text
 - Load 2GB of text vs. load 1MB of text

The space requirement $S(P)$ of any program P may therefore be written as $S(P) = c + S_p$ where c is a constant and S_p is the instance characteristics which depends on a particular instance of a problem.

Space Complexity - Example

```
int sum = 0;
int n;
int* numbers;
// Read "n" from user
numbers = new int[n];
// Read "n" integers from user
// Calculate the sum
```

```
int sum = 0;
int n;
// Read "n" from user
int current_number;
// Read "n" many times current_number from user
// Calculate the sum
```

Time Complexity

The analysis required to estimate the resource use of an algorithm is generally a theoretical issue, and therefore a formal framework is required. Some definitions;

$T(N)$

Represents the running time -in terms of the number of basic operations- of an algorithm for input size N .

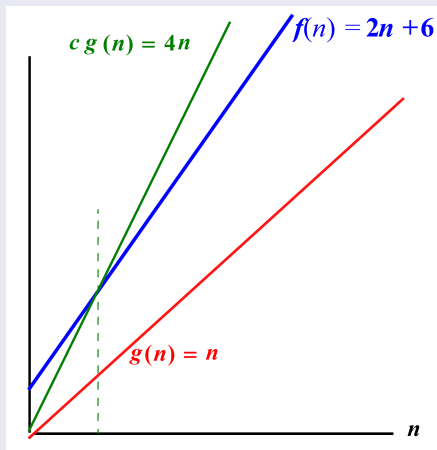
- $T(N) = O(f(N))$ if there are positive constants c and n_0 such that $T(N) \leq cf(N)$ when $N \geq n_0$.
- $T(N) = \Omega(g(N))$ if there are positive constants c and n_0 such that $T(N) \geq cg(N)$ when $N \geq n_0$.
- $T(N) = \Theta(h(N))$ if and only if $T(N) = O(h(N))$ and $T(N) = \Omega(h(N))$
- $T(N) = o(p(N))$ if, for all positive constants c , there exists n_0 such that $T(N) < cp(N)$

Big-Oh Notation

- Why do we need these definitions?
 - We try to establish a relative order among functions.
 - We want to compare their **relative rate of growth**
- $1000N$ vs N^2
- We can say $1000N = O(N^2)$, which is known as Big-Oh notation. Instead of saying "order ..." we say "Big-Oh"

Graphic Illustration

- $f(n) = 2n + 6$
- We need to find a function $g(n)$ and a constant c and n_0 such as $f(n) < cg(n)$ when $n > n_0$
- $g(n) = n$ and $c = 4$ and $n_0 = 3 \rightarrow f(n)$ is $O(n)$
- The order of $f(n)$ is n



Big Omega, Big Theta

- $O(f(n))$: Big-Oh – $f(N)$ is an upper bound on $T(N)$
- $\Omega(f(n))$: Big Omega – $f(N)$ is a lower bound on $T(N)$
- $\Theta(f(n))$: Big Theta – $f(N)$ is a tight bound on $T(N)$
- Consider the difference:
 - $3n + 3$ is $O(n)$ and is $\Theta(n)$
 - $3n + 3$ is $O(n^2)$ but is **not** $\Theta(n^2)$ (Why? -Technical Answer)

- $o(f(n))$: Little-oh – $f(n)$ is $o(g(n))$ if $f(n)$ is $O(g(n))$ and $f(n)$ is not $\Theta(g(n))$
 - $2n + 3$ - Is it $o(n^2)$? (Why? -Technical Answer)
 - $2n + 3$ - Is it $o(n)$? (Why? -Technical Answer)

In other words...

- " $f(n)$ is $O(g(n))$ " \rightarrow growth rate of $f(n) \leq$ growth rate of $g(n)$
- " $f(n)$ is $\Omega(g(n))$ " \rightarrow growth rate of $f(n) \geq$ growth rate of $g(n)$
- " $f(n)$ is $\Theta(g(n))$ " \rightarrow growth rate of $f(n) =$ growth rate of $g(n)$
- " $f(n)$ is $o(g(n))$ " \rightarrow growth rate of $f(n) <$ growth rate of $g(n)$

Examples

- N^3 grows faster than N^2 , we can say $N^2 = O(N^3)$ or $N^3 = \Omega(N^2)$.
- $f(N) = N^2$ and $g(N) = 2N^2$ grows at same rate, we can say $f(N) = O(g(N))$ and $f(N) = \Omega(g(N))$, hence we can say $f(N) = \Theta(g(N))$
- What about $f(n) = 4n^2$? Is it $O(n)$?
 - Find a c and n_0 such that $4n^2 < cn$ for any $n > n_0$

- If $f_1(n)$ is $O(g_1(n))$ and $f_2(n)$ is $O(g_2(n))$
 - $f_1(n) + f_2(n)$ is $O(g_1(n) + g_2(n)) = O(\max(g_1(n), g_2(n)))$
 - $f_1(n) \times f_2(n)$ is $O(g_1(n) \times g_2(n))$
- If $f(N)$ is a polynomial of degree k , then $f(N) = \Theta(N^k)$.
- $\log^k N$ is $O(N)$ for any constant k
- The relative growth rate of two functions can always be determined by computing their limit (But using this method is almost always an overkill)

$$\lim_{n \rightarrow \infty} f_1(n)/f_2(n)$$

Big-Oh and Growth Rate

- We can use the big-Oh notation to rank functions according to their growth rate

	$f(n)$ is $O(g(n))$	$g(n)$ is $O(f(n))$
$g(n)$ grows faster	Yes	No
$f(n)$ grows faster	No	Yes
Same growth	Yes	Yes

Typical Grow Rates

Function	Name
c	Constant
$\log N$	Logarithmic
$\log^2 N$	Log-squared
N	Linear
$N \log N$	
N^2	Quadratic
N^3	Cubic
2^N	Exponential

Some Numbers

$\log n$	n	$n \log n$	n^2	n^3	2^n
0	1	0	1	1	2
1	2	2	4	8	4
2	4	8	16	64	16
3	8	24	64	512	256
4	16	64	256	4096	65536
5	32	160	1024	32768	4294967296

Big-Oh Rules

- If $f(n)$ is a polynomial of degree d , then $f(n)$ is $O(n^d)$, i.e.,
 - ① Drop lower-order terms
 - ② Drop constant factors
- Use the smallest possible class of functions!
 - Say “ $2n$ is $O(n)$ ” instead of “ $2n$ is $O(n^2)$ (which is also true)”
- Use the simplest expression of the class
 - Say “ $3n + 5$ is $O(n)$ ” instead of “ $3n + 5$ is $O(3n)$ ”

More examples

- $50n^3 + 20n + 4$ is $O(n^3)$
 - Would be correct to say $f(n)$ is $O(n^3 + n)$?
 - Not useful, as n^3 exceeds by far n , for large values
 - Would be correct to say $f(n)$ is $O(n^5)$?
 - OK, but $g(n)$ should be as close as possible to $f(n)$
- $3\log(n) + n(\log(n)) = O(?)$

Simple Rule: Drop lower order terms and constant factors

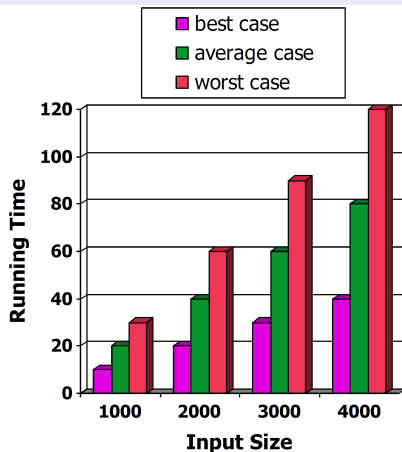
Inappropriate Expressions

~~$f(n) O(g(n))$~~

~~$f(n) O(g(n))$~~

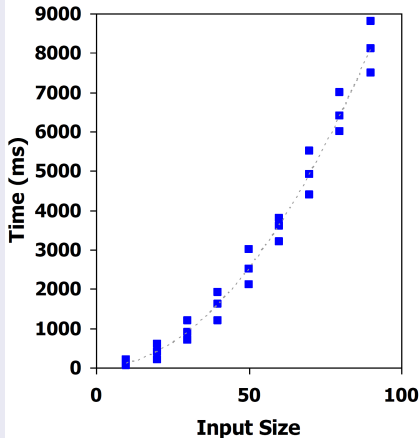
Analyzing Running Time

- The running time of an algorithm varies with the inputs, and typically grows with the **size of the inputs**.
- To evaluate an algorithm or to compare two algorithms, we focus on their relative rates of growth wrt the increase of the input size.
- Generally the **average** running time is **difficult** to determine **theoretically**, hence we focus on the worst case running time. Which one to focus depends on the particular problem.



Experimental Approach

- Write a program to implement the algorithm.
- Run this program with inputs of varying size and composition.
- Get an accurate measure of the actual running time (e.g. system call date).
- Plot the results.
- Problems?



Maximum Subsequence Sum Problem

Given a set of integers A_1, A_2, \dots, A_N , find the maximum value of

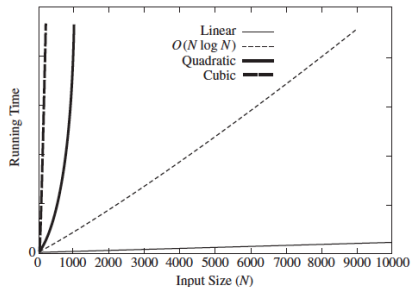
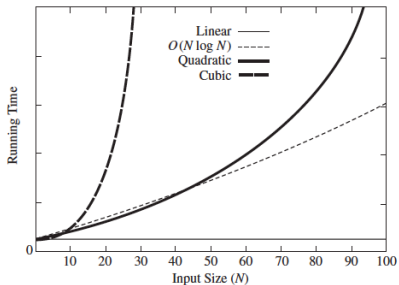
$$\sum_{k=i}^j A_k$$

For convenience, the maximum subsequence sum is zero if all the integers are negative.

Running Times in Seconds For Different Algorithms

Input Size	Algorithm Time			
	1	2	3	4
	$O(N^3)$	$O(N^2)$	$O(N \log N)$	$O(N)$
$N = 100$	0.000159	0.000006	0.000005	0.000002
$N = 1,000$	0.095857	0.000371	0.000060	0.000022
$N = 10,000$	86.67	0.033322	0.000619	0.000222
$N = 100,000$	NA	3.33	0.006700	0.002205
$N = 1,000,000$	NA	NA	0.074870	0.022711

Running Times vs N



Limitations of Experimental Studies

- The algorithm has to be implemented, which may take a long time and could be very difficult.
- Results may not be indicative for the running time on other inputs that are not (or could not since they do not finish in reasonable time) included in the experiments.
- In order to compare two algorithms, the same hardware and software must be used.

Use a Theoretical Approach

- Based on the high-level description of the algorithms, rather than language dependent implementations
- An evaluation of the algorithms that is independent of the hardware and software environments is possible
→ **Generality**

- High-level description of an algorithm.
- More structured than plain English.
- Less detailed than a program.
- Preferred notation for describing algorithms.
- Hides program design issues.

Example: find the maximum element of an array

Algorithm 1 arrayMax(A, n)

```
1: Input array  $A$  of  $n$  integers
2: Output maximum element of  $A$ 
3:  $currentMax \leftarrow A[0]$ .
4: for  $i \leftarrow 1$  to  $n - 1$  do
5:   if  $A[i] > currentMax$  then
      $currentMax \leftarrow A[i]$ 
   return  $currentMax$ 
```

- Control flow
 - if ... then ... [else ...]
 - while ... do ...
 - repeat ... until ...
 - for ... do ...
 - Indentation replaces braces
- Method declaration
Algorithm method (arg [, arg...])
Input ...
Output
- Method call
 - var.method (arg [, arg...])
- MethodReturn value
 - return expression
- MethodExpressions
 - \leftarrow Assignment (equivalent to =)
 - = Equality testing (equivalent to ==)
 - n^2 Superscripts and other mathematical formatting allowed

Primitive Operations

- The basic computations performed by an algorithm
- Identifiable in pseudocode
- Largely independent from the programming language
- Exact definition not important
- Use comments
- Instructions have to be basic enough and feasible
- Examples:
 - Evaluating an expression
 - Assigning a value to a variable
 - Calling a method
 - Returning from a method

Low Level Algorithm Analysis

- Based on primitive operations (low-level computations independent from the programming language)
- For example:
 - Make an addition = 1 operation
 - Calling a method or returning from a method = 1 operation
 - Index in an array = 1 operation
 - Comparison = 1 operation, etc.
- **Method:** Inspect the pseudo-code and count the number of primitive operations executed by the algorithm

Counting Primitive Operations

- By inspecting the code, we can determine the number of primitive operations executed by an algorithm, as a function of the input size.

Algorithm 2 arrayMax(A, n)

```
1: currentMax  $\leftarrow$  A[0].  
2: for  $i \leftarrow 1$  to  $n - 1$  do  
3:   if A[i] > currentMax then  
     currentMax  $\leftarrow$  A[i]  
4: {increment of counter  $i$  }  
   return currentMax
```

#operations
2
2+n (init & loopEnd)
2(n-1)
2(n-1)
2(n-1) (inc & loopStart)
1
Total 7n-1

Estimating Running Time

- Algorithm *arrayMax* executes $7n - 1$ primitive operations.
- Let's define
 - $a :=$ Time taken by the fastest primitive operation
 - $b :=$ Time taken by the slowest primitive operation
- Let $T(n)$ be the actual running time of *arrayMax*. We have

$$a(7n - 1) \leq T(n) \leq b(7n - 1)$$

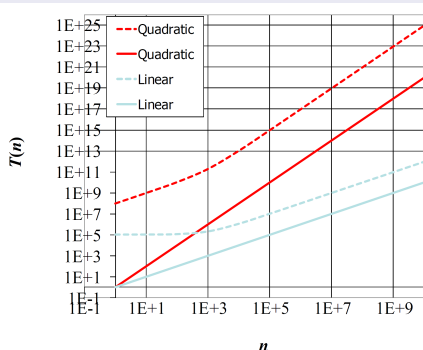
- Therefore, the running time $T(n)$ is bounded by two linear functions

Growth Rate of Running Time

- Changing computer hardware / software
 - Affects $T(n)$ by a constant factor
 - Does not alter the growth rate of $T(n)$
- The linear growth rate of the running time $T(n)$ is an intrinsic property of algorithm *arrayMax*

Constant Factors

- The growth rate is not affected by
 - Constant factors or
 - Lower-order terms
- Examples
 - $10^2n + 10^5$ is a linear function
 - $10^5n^2 + 10^8n$ is a quadratic function



- Growth rates of functions:
 - Linear $\approx n$
 - Quadratic $\approx n^2$
 - Cubic $\approx n^3$
- In a log-log chart, the slope of the line corresponds to the growth rate of the function

- We know:
 - Experimental approach – problems
 - Low level analysis – counting operations is not feasible
- Abstract even further
- Characterize an algorithm as a function of the "problem size"
- e.g.
 - Input data = array \rightarrow problem size is N (length of array)
 - Input data = matrix \rightarrow problem size is $N \times M$

Asymptotic Notation

- We can utilize Big-Oh, Big Omega, Big Theta and Little-Oh notations to analyze running time of algorithms.
- These notations invented by Paul Bachmann, Edmund Landau, and others, collectively are called **Bachmann-Landau notation** or **asymptotic notation**.

Running Time Calculations - General Rules

- FOR loop
 - The number of iterations times the running time of the statements inside the loop.
- Nested loops
 - The product of the sizes of all the loops times the running time of the statement inside the loop.
 - Analyze inside out.
- Consecutive Statements
 - The sum of running time of each segment.
- If/Else
 - The testing time plus the larger of the running time of the cases.

Some Examples

```
for (i=0; i<n; i++)  
    for (j=0; j<n; j++)  
        k++;
```

$O(n^2)$

```
for (i=0; i<n; i++)  
    k++;  
for (i=0; i<n; i++)  
    for (j=0; j<n; j++)  
        k++;
```

$O(n^2)$

Some Examples

```
if (x > 0)
    for (i=0; i<n; i++)
        for (j=0; j<n; j++)
            k++;
else
    for (i=0; i<n; i++)
        k++;
```

$O(n^2)$

Maximum Subsequence Sum Problem

Given a set of integers A_1, A_2, \dots, A_N , find the maximum value of

$$\sum_{k=i}^j A_k$$

For convenience, the maximum subsequence sum is zero if all the integers are negative.

The First Algorithm

```
int MaxSubSum1(vector<int> a) {  
    int maxSum = 0;  
  
    for (int i = 0; i < a.size(); i++)  
        for (int j = i; j < a.size(); j++) {  
            int thisSum = 0;  
  
            for (int k = i; k <= j; k++)  
                thisSum += a[k];  
  
            if (thisSum > maxSum)  
                maxSum = thisSum;  
        }  
    return maxSum;  
}
```

$O(n^3)$

The Second Algorithm

```
int MaxSubSum2(vector<int> a) {  
    int maxSum = 0;  
  
    for (int i = 0; i < a.size(); i++) {  
        thisSum = 0;  
        for (int j = i; j < a.size(); j++) {  
            thisSum += a[j];  
  
            if (thisSum > maxSum)  
                maxSum = thisSum;  
        }  
    }  
    return maxSum;  
}
```

$O(n^2)$

The Third Algorithm

```
// Recursive maximum contiguous sum algorithm
```

```
int maxSubSum3(vector<int> a) {  
    return maxSumRec(a, 0, a.size() - 1);  
}
```

```
// Used by driver function above, this one is called  
recursively
```

```
int maxSumRec(const vector<int>& a, int left, int right) {  
    if (left == right) // base case  
        if (a[left] > 0)  
            return a[left];  
        else  
            return 0;
```

$O(n)$

```
    int center = (left + right) / 2;  
    int maxLeftSum = maxSumRec(a, left, center); //  
recursive call  
    int maxRightSum = maxSumRec(a, center + 1, right); //  
recursive call
```

$T(n') = T(n/2)$

```
    int maxLeftBorderSum = 0, leftBorderSum = 0;
```

The Third Algorithm (Cont.)

```
for (int i = center; i >= left; --i) {
    leftBorderSum += a[i];
    if (leftBorderSum > maxLeftBorderSum)
        maxLeftBorderSum = leftBorderSum;
}

int maxRightBorderSum = 0, rightBorderSum = 0;
for (int j = center+1; j <= right; ++j) {
    rightBorderSum += a[j];
    if (rightBorderSum > maxRightBorderSum)
        maxRightBorderSum = rightBorderSum;
}

return max3(maxLeftSum, maxRightSum,
            maxLeftBorderSum + maxRightBorderSum);
}

int max3(int x, int y, int z) {
    int max = x;
    if (y > max)
        max = y;
    if (z > max)
        max = z;
    return max;
}
```

Recurrence Relation

- $T(1) = 1$
- $T(n) = 2T(n/2) + O(n)$
 - $T(2) = ?$
 - $T(4) = ?$
 - $T(8) = ?$
 - ...
- If $n = 2^k$, $T(n) = n \times (k + 1)$
 - $k = \log n$
 - $T(n) = n(\log n + 1)$

Solving recursive equations by repeated substitution

$$\begin{aligned}T(n) &= T(n/2) + c \text{ substitute for } T(n/2) \\&= T(n/4) + c + c \text{ substitute for } T(n/4) \\&= T(n/8) + c + c + c \\&= T(n/2^3) + 3c \text{ in more compact form} \\&= \dots \\&= T(n/2^k) + kc \text{ "inductive leap"} \\T(n) &= T(n/2^{\log n}) + c \log n \text{ "choose } k = \log n" \\&= T(n/n) + c \log n \\&= T(1) + c \log n = b + c \log n = \Theta(\log n)\end{aligned}$$

Solving recursive equations by telescoping

$$T(n) = T(n/2) + c \text{ initial equation}$$

$$T(n/2) = T(n/4) + c \text{ so this holds}$$

$$T(n/4) = T(n/8) + c \text{ and this ...}$$

$$T(n/8) = T(n/16) + c \text{ and this ...}$$

...

$$T(4) = T(2) + c \text{ eventually ...}$$

$$T(2) = T(1) + c \text{ and this ...}$$

$$T(n) = T(1) + c \log n \text{ sum equations, canceling the terms appearing on both sides}$$

$$T(n) = \Theta(\log n)$$

Logarithms in the Running Time

- An algorithm is $O(\log N)$ if it takes constant time to cut the problem size by a fraction (usually $\frac{1}{2}$).
- On the other hand, if constant time is required to merely reduce the problem by a constant amount (such as to make the problem smaller by 1), then the algorithm is $O(N)$
- Examples of the $O(\log N)$
 - Binary Search
 - Euclid's algorithm for computing the greatest common divisor

The Fourth Algorithm

```
int MaxSubSum4(vector<int> a) {  
    int maxSum=0, thisSum=0;  
  
    for (int j=0; j<a.size(); j++) {  
        thisSum+=a[j];  
  
        if (thisSum>maxSum)  
            maxSum=thisSum;  
        else if (thisSum<0)  
            thisSum=0;  
    }  
    return maxSum;  
}
```

$O(n)$