



# COMP90049 Knowledge Technologies

Clustering  
(Lecture Set 9) 2013

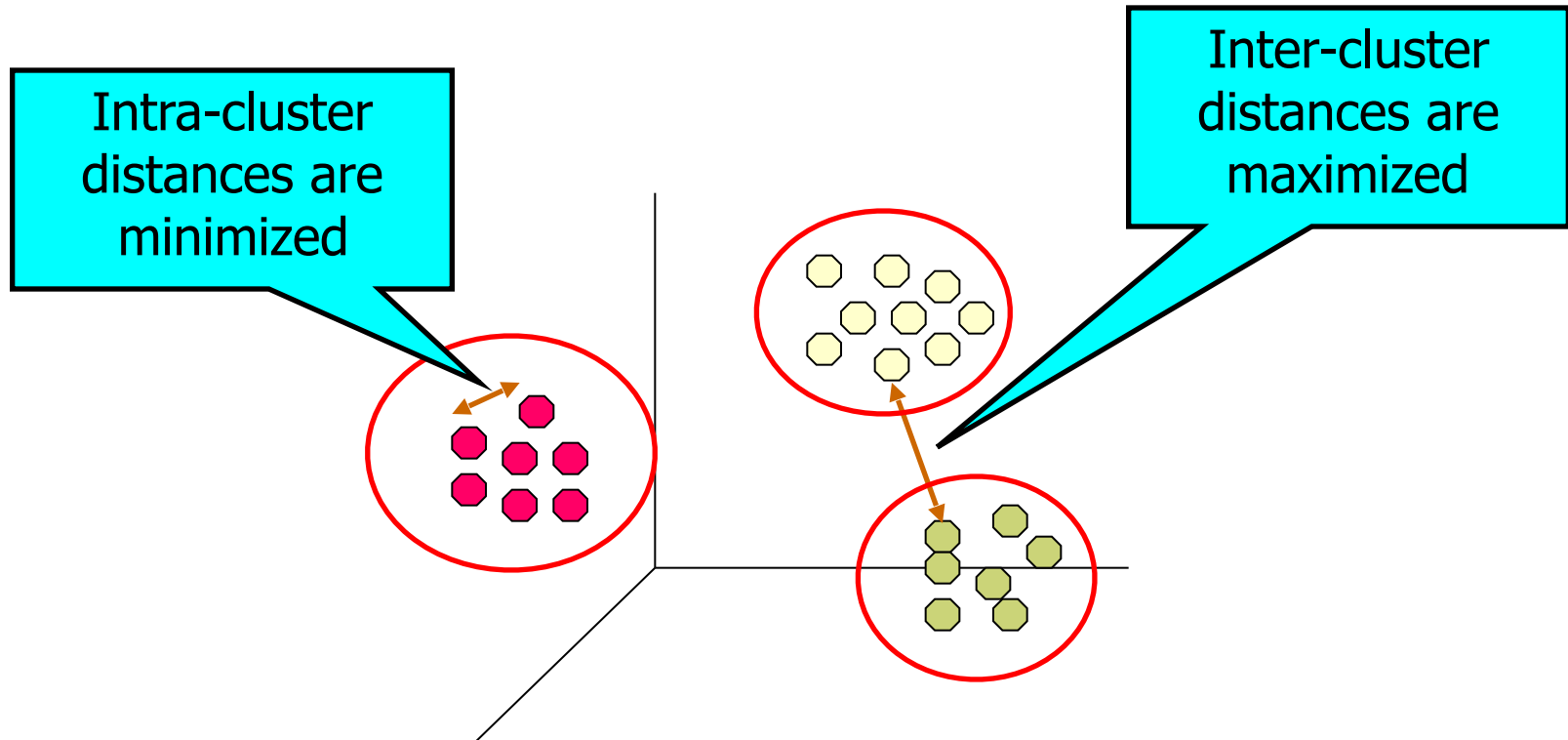
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Engineering  
The Melbourne School of Engineering

Some of slides are derived from Prof Vipin Kumar and modified, <http://www-users.cs.umn.edu/~kumar/>

# What is Cluster Analysis?

Finding groups of objects such that the objects in a group will be similar (or related) to one another and different from (or unrelated to) the objects in other groups. Of course we need define what we mean by “similar”!



# Applications of Cluster Analysis

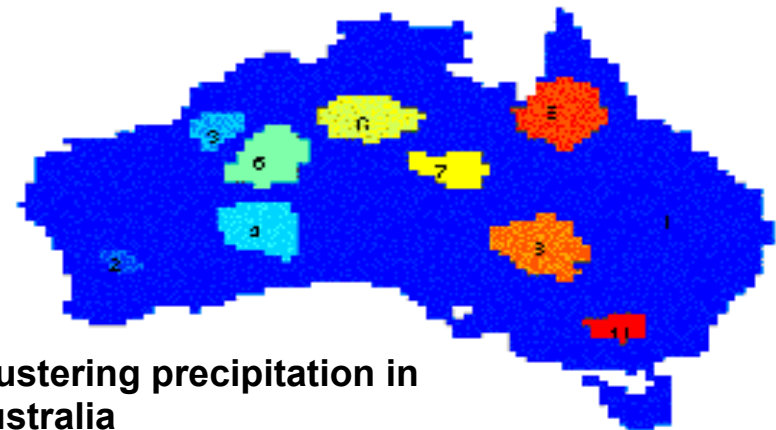
## Understanding

- Group related documents for browsing, group genes and proteins that have similar functionality, or group stocks with similar price fluctuations

## Summarization

- Reduce the size of large data sets

	<i>Discovered Clusters</i>	<i>Industry Group</i>
<b>1</b>	Applied-Matl-DOWN, Bay-Network-DOWN, 3-COM-DOWN, Cabletron-Sys-DOWN, CISCO-DOWN, HP-DOWN, DSC-Comm-DOWN, INTEL-DOWN, LSI-Logic-DOWN, Micron-Tech-DOWN, Texas-Inst-DOWN, Tellabs-Inc-DOWN, Natl-Semiconduct-DOWN, Oracl-DOWN, SGI-DOWN, Sun-DOWN	Technology1-DOWN
<b>2</b>	Apple-Comp-DOWN, Autodesk-DOWN, DEC-DOWN, ADV-Micro-Device-DOWN, Andrew-Corp-DOWN, Computer-Assoc-DOWN, Circuit-City-DOWN, Compaq-DOWN, EMC-Corp-DOWN, Gen-Inst-DOWN, Motorola-DOWN, Microsoft-DOWN, Scientific-Atl-DOWN	Technology2-DOWN
<b>3</b>	Fannie-Mae-DOWN, Fed-Home-Loan-DOWN, MBNA-Corp-DOWN, Morgan-Stanley-DOWN	Financial-DOWN
<b>4</b>	Baker-Hughes-UP, Dresser-Inds-UP, Halliburton-HLD-UP, Louisiana-Land-UP, Phillips-Petro-UP, Unocal-UP, Schlumberger-UP	Oil-UP



Clustering precipitation in Australia

## What is not Cluster Analysis

### **Supervised classification**

- Have class label information

### **Simple segmentation**

- Dividing students into different registration groups alphabetically, by last name

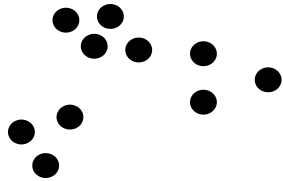
### **Results of a query**

- Groupings are a result of an external specification

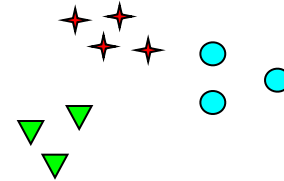
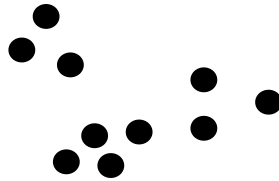
### **Graph partitioning**

- Some mutual relevance and synergy, but areas are not identical

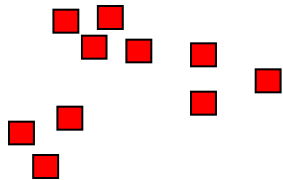
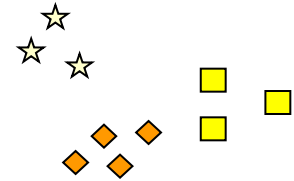
## Notion of a Cluster can be Ambiguous



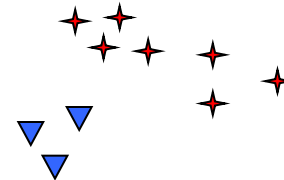
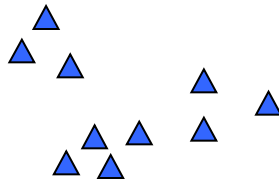
How many clusters?



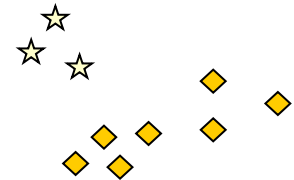
Six Clusters



Two Clusters



Four Clusters



# Types of Clustering

A **clustering** is a set of clusters

Important distinction between **hierarchical** and **partitional** sets of clusters

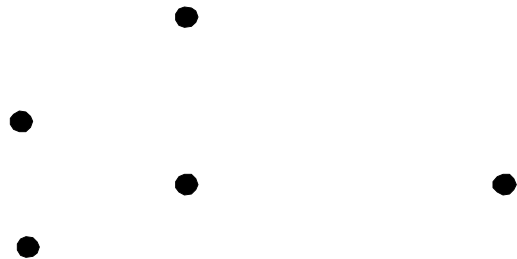
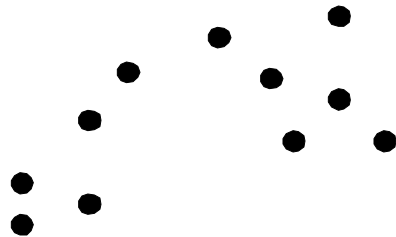
## Partitional Clustering

- A division data objects into non-overlapping subsets (clusters) such that each data object is in exactly one subset

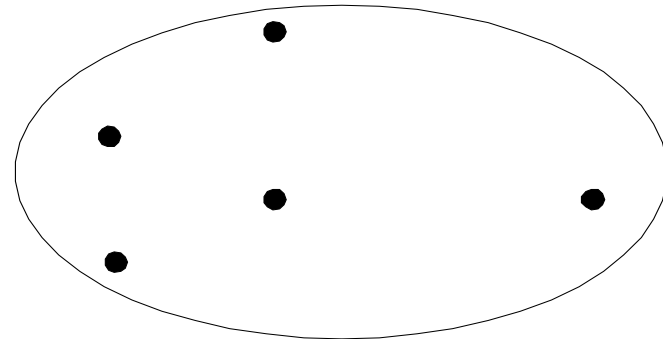
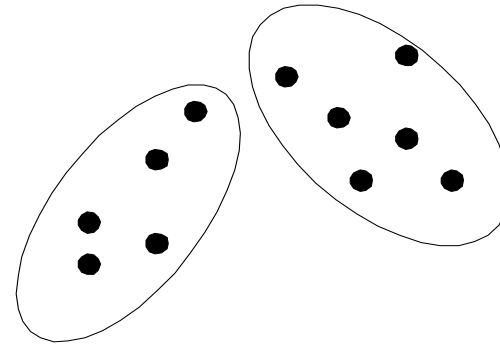
## Hierarchical clustering

- A set of nested clusters organized as a hierarchical tree

## Partitional Clustering

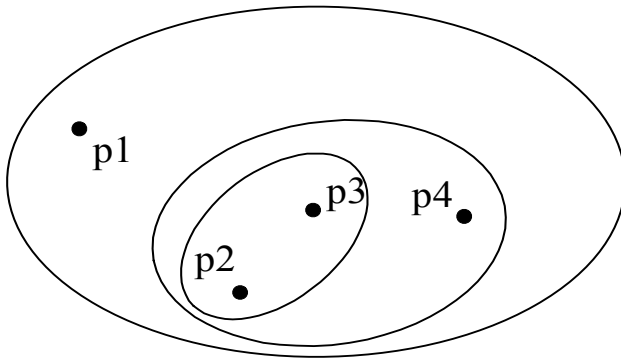


**Original Points**

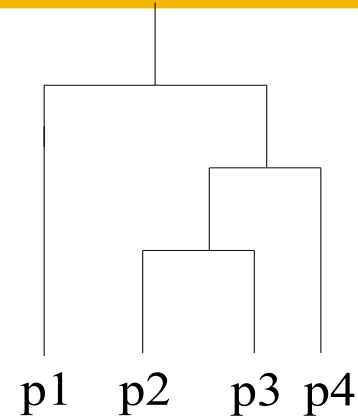


**A Partitional Clustering**

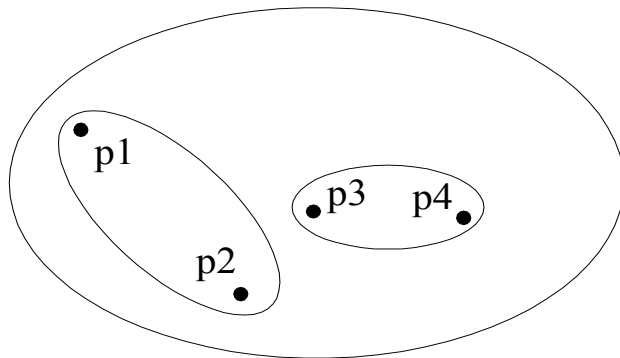
# Hierarchical Clustering



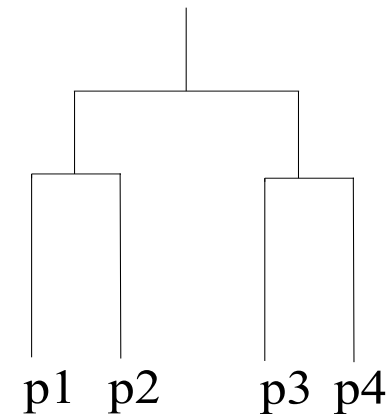
**Traditional Hierarchical Clustering**



**Traditional Dendrogram**



**Non-traditional Hierarchical Clustering**



**Non-traditional Dendrogram**



## Other Distinctions Between Sets of Clusters

### **Exclusive versus non-exclusive**

- In non-exclusive clusterings, points may belong to multiple clusters.
- Can represent multiple classes or 'border' points

### **Fuzzy versus non-fuzzy**

- In fuzzy clustering, a point belongs to every cluster with some weight between 0 and 1
- Weights must sum to 1
- Probabilistic clustering has similar characteristics

### **Partial versus complete**

- In some cases, we only want to cluster some of the data

### **Heterogeneous versus homogeneous**

- Cluster of widely different sizes, shapes, and densities

# Types of Clusters

**Well-separated clusters**

**Center-based clusters**

**Contiguous clusters**

**Density-based clusters**

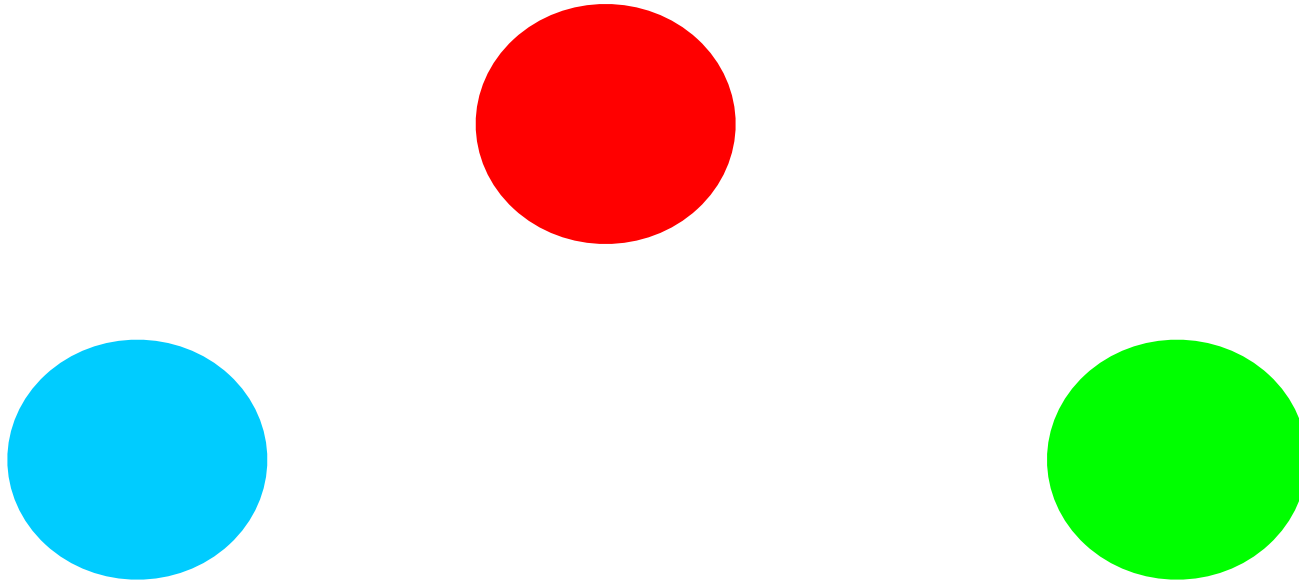
**Property or Conceptual**

**Described by an Objective Function**

## Types of Clusters: Well-Separated (easiest clustering)

### Well-Separated Clusters:

- A cluster is a set of points such that any point in a cluster is closer (or more similar) to every other point in the cluster than to any point not in the cluster.



**3 well-separated clusters**

## Types of Clusters: Center-Based

### Center-based

- A cluster is a set of objects such that an object in a cluster is closer (more similar) to the “center” of a cluster, than to the center of any other cluster
- The center of a cluster is often a **centroid**, the average of all the points in the cluster, or a **medoid**, the most “representative” point of a cluster

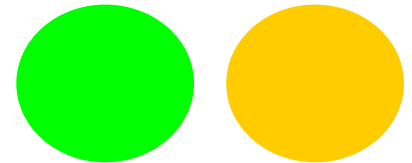
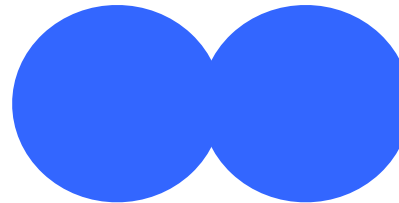
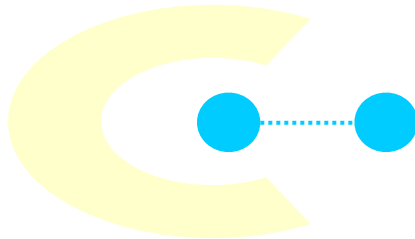
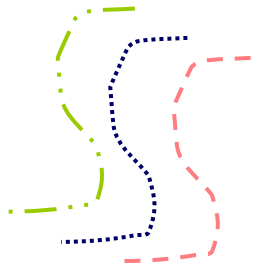


**4 center-based clusters**

## Types of Clusters: Contiguity-Based

### Contiguous Cluster (Nearest neighbor or Transitive)

- A cluster is a set of points such that a point in a cluster is closer (or more similar) to one or more other points in the cluster than to any point not in the cluster.

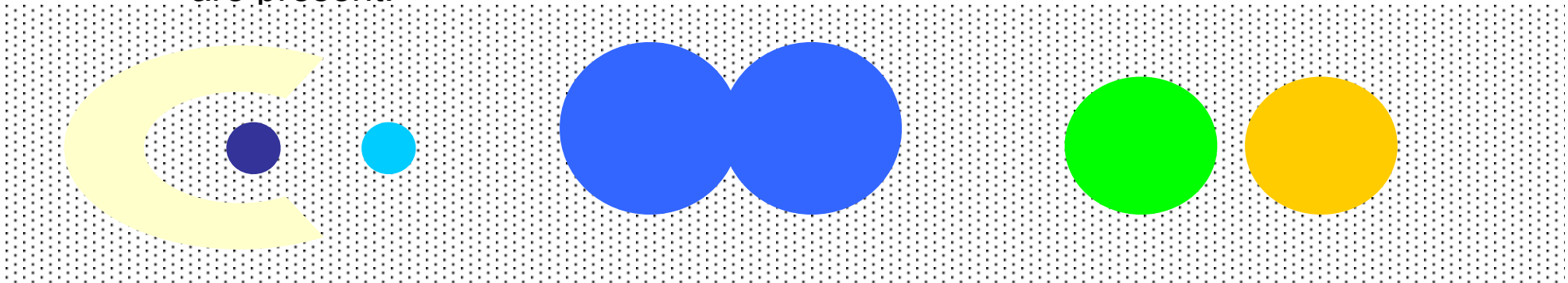


**8 contiguous clusters**

## Types of Clusters: Density-Based

### Density-based

- A cluster is a dense region of points, which is separated by low-density regions, from other regions of high density.
- Used when the clusters are irregular or intertwined, and when noise and outliers are present.

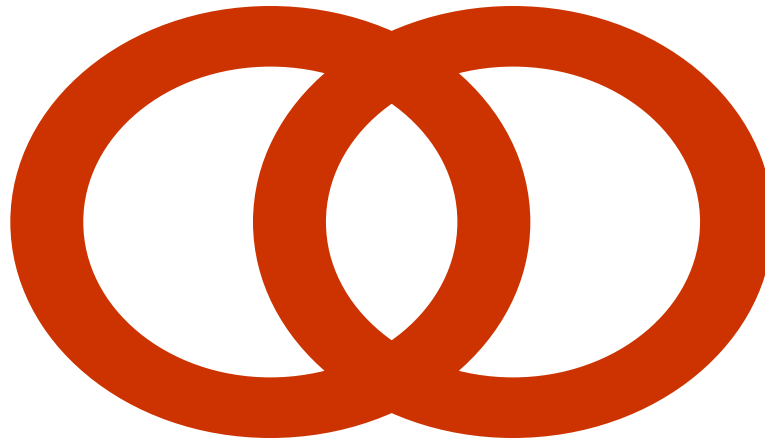


**6 density-based clusters**

## Types of Clusters: Conceptual Clusters

### Shared Property or Conceptual Clusters

- Finds clusters that share some common property or represent a particular concept.



**2 Overlapping Circles**

## Types of Clusters: Objective Function

### Clusters Defined by an Objective Function

- Finds clusters that minimize or maximize an objective function.
- Enumerate all possible ways of dividing the points into clusters and evaluate the 'goodness' of each potential set of clusters by using the given objective function. (NP Hard)
- Can have global or local objectives.
  - Hierarchical clustering algorithms typically have local objectives
  - Partitional algorithms typically have global objectives
- A variation of the global objective function approach is to fit the data to a parameterized model.
  - Parameters for the model are determined from the data.
  - Mixture models assume that the data is a 'mixture' of a number of statistical distributions.



## Types of Clusters: Objective Function ...

### **Map the clustering problem to a different domain and solve a related problem in that domain**

- Proximity matrix defines a weighted graph, where the nodes are the points being clustered, and the weighted edges represent the proximities between points
- Clustering is equivalent to breaking the graph into connected components, one for each cluster.
- Want to minimize the edge weight between clusters and maximize the edge weight within clusters

## Characteristics of the Input Data Are Important

### Type of proximity or density measure

- This is a derived measure, but central to clustering

### Sparseness

- Dictates type of similarity
- Adds to efficiency

### Attribute type

- Dictates type of similarity

### Type of Data

- Dictates type of similarity
- Other characteristics, e.g., autocorrelation

### Dimensionality

### Noise and Outliers

### Type of Distribution

# Clustering Algorithms

**K-means and its variants**

**Hierarchical clustering**

**Density-based clustering**

## K-means Clustering

### Partitional clustering approach

Each cluster is associated with a **centroid** (center point)

Each point is assigned to the cluster with the closest centroid

Number of clusters,  $K$ , must be specified

The basic algorithm is very simple

- 
- 1: Select  $K$  points as the initial centroids.
  - 2: **repeat**
  - 3:     Form  $K$  clusters by assigning all points to the closest centroid.
  - 4:     Recompute the centroid of each cluster.
  - 5: **until** The centroids don't change
-

## K-means Clustering – Details

**Initial centroids are often chosen randomly.**

- Clusters produced vary from one run to another.

**The centroid is (typically) the mean of the points in the cluster.**

**‘Closeness’ is measured by Euclidean distance, cosine similarity, correlation, etc.**

**K-means will converge for common similarity measures mentioned above.**

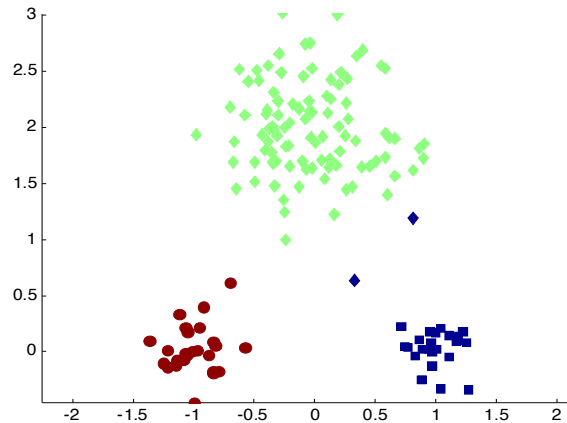
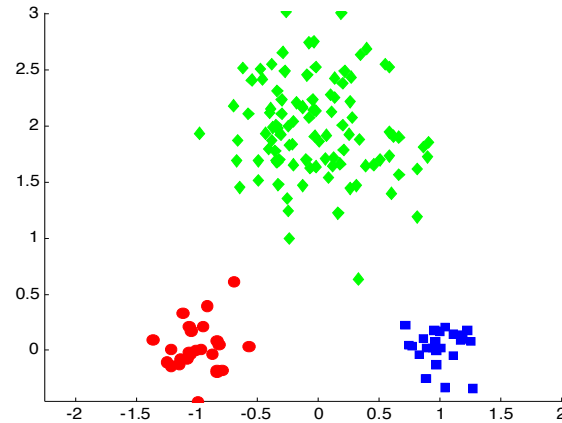
**Most of the convergence happens in the first few iterations.**

- Often the stopping condition is changed to ‘Until relatively few points change clusters’ (this way the stopping criterion will not depend on the type of similarity or dimensionality)

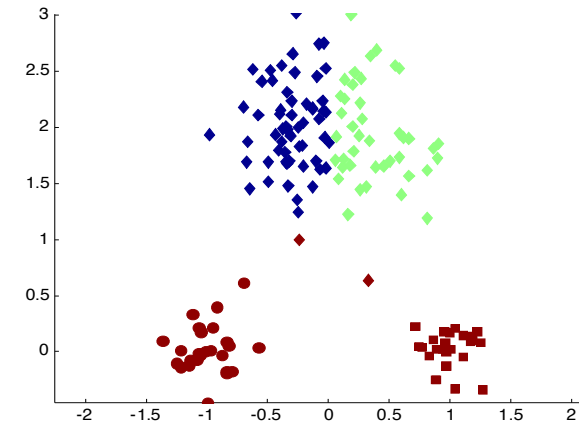
**Complexity is  $O(n * K * I * d)$**

- $n$  = number of points,  $K$  = number of clusters,  
 $I$  = number of iterations,  $d$  = number of attributes
- Unfortunately we cannot a priori know the value of  $I$ !

**Original Points**

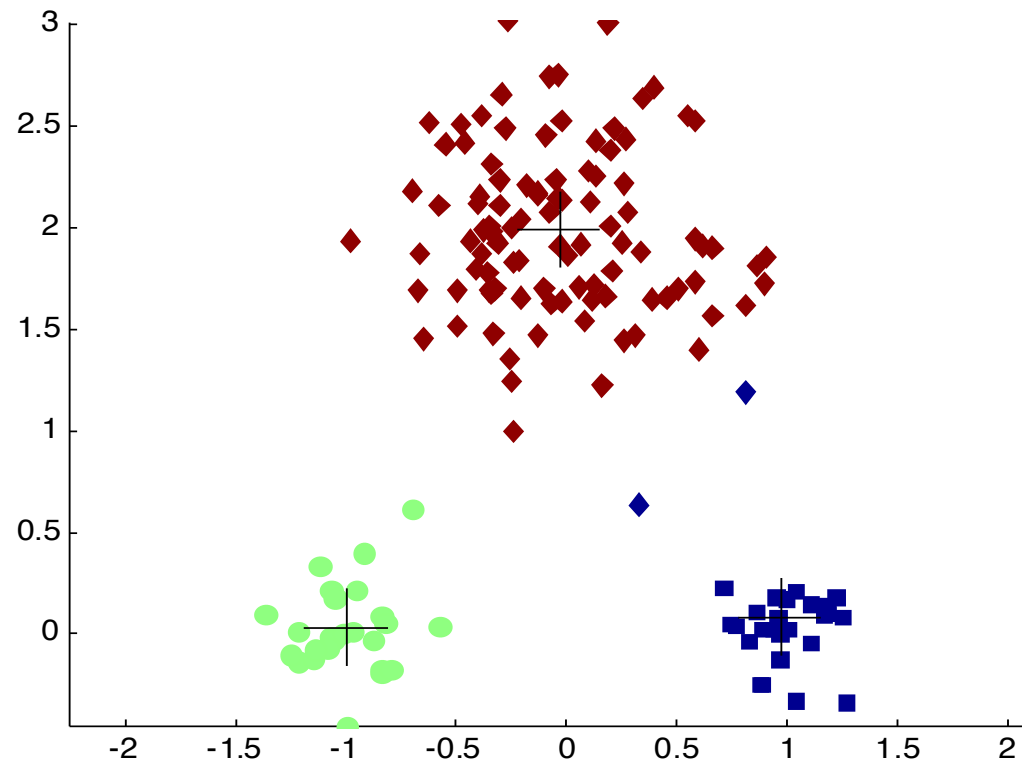


**Optimal Clustering**

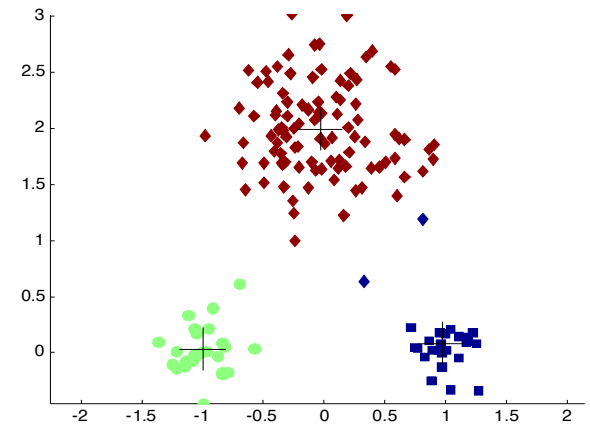
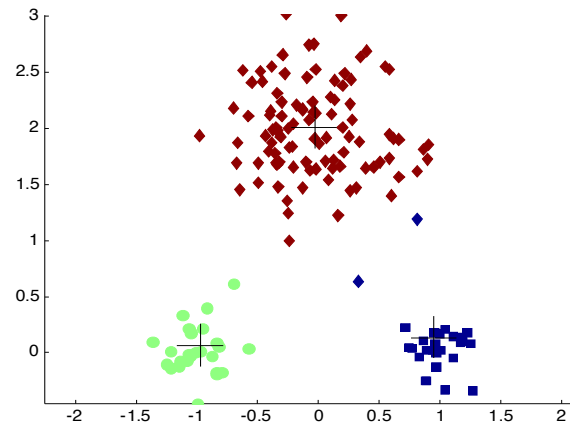
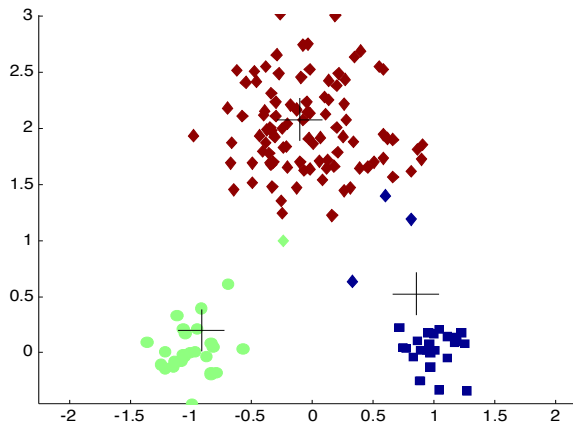
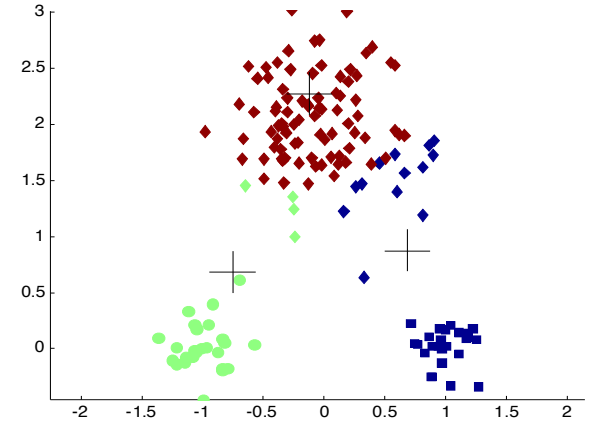
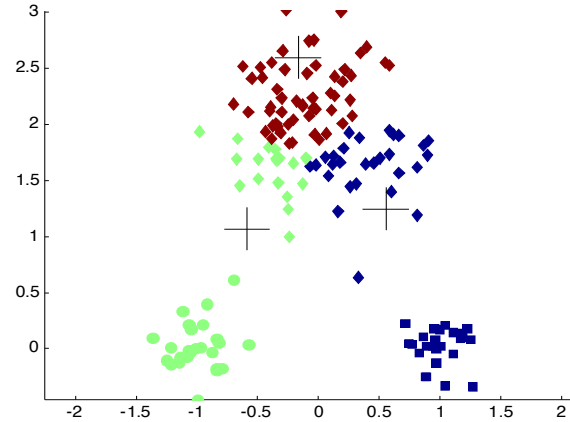
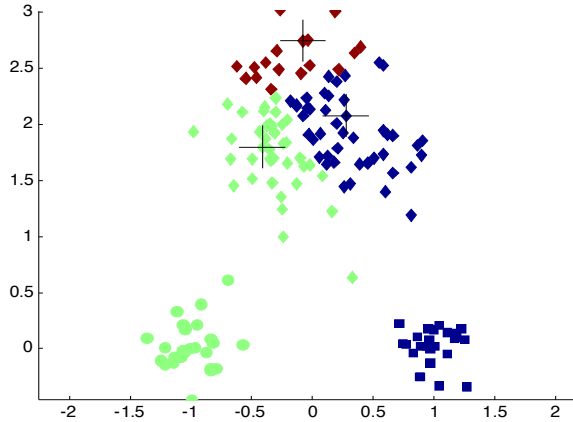


**Sub-optimal Clustering**

# Importance of Choosing Initial Centroids



# Importance of Choosing Initial Centroids





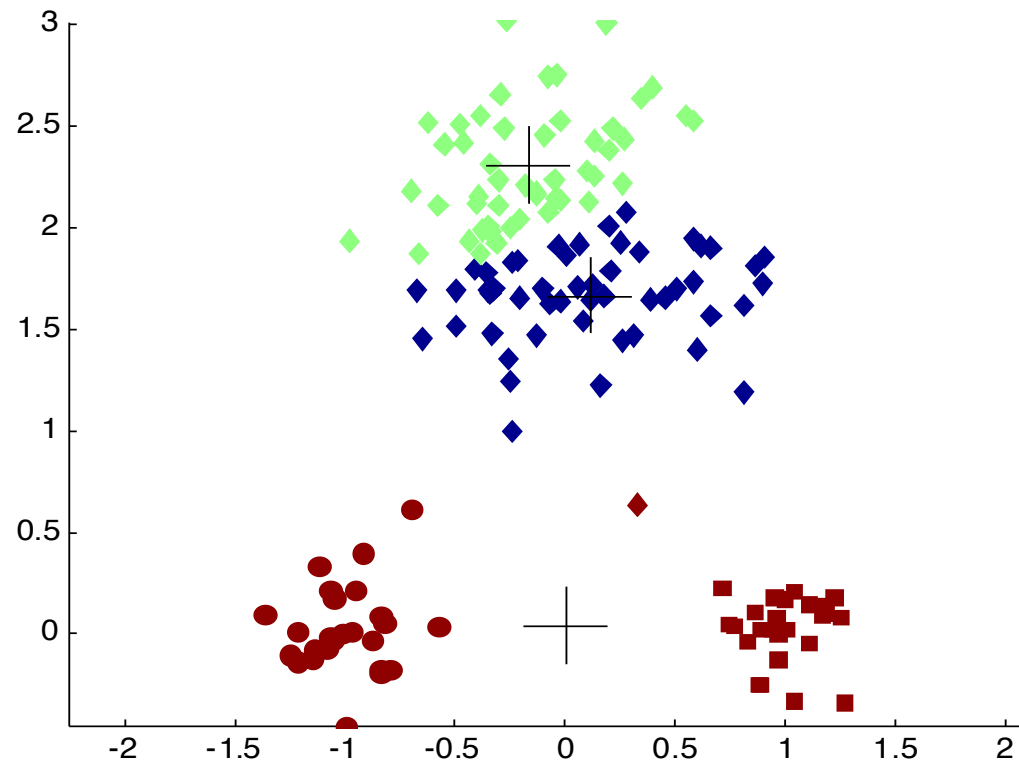
# Evaluating K-means Clusters

## Most common measure is Sum of Squared Error (SSE)

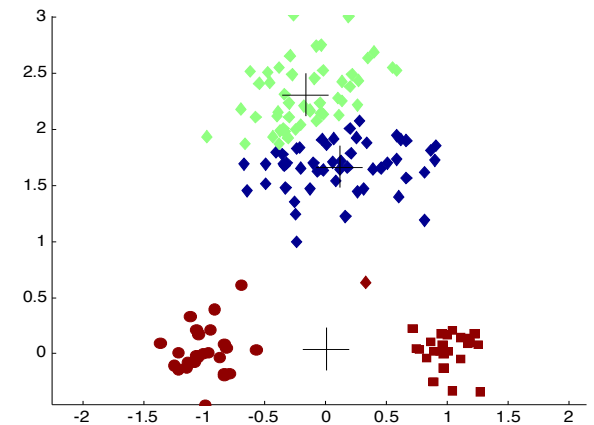
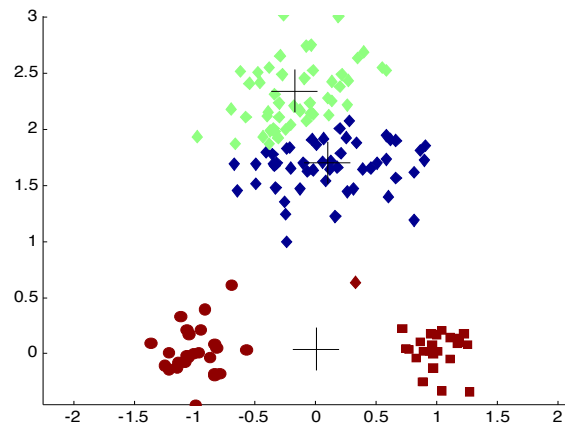
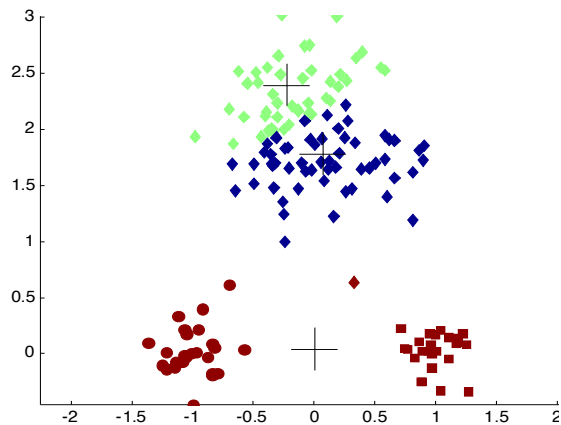
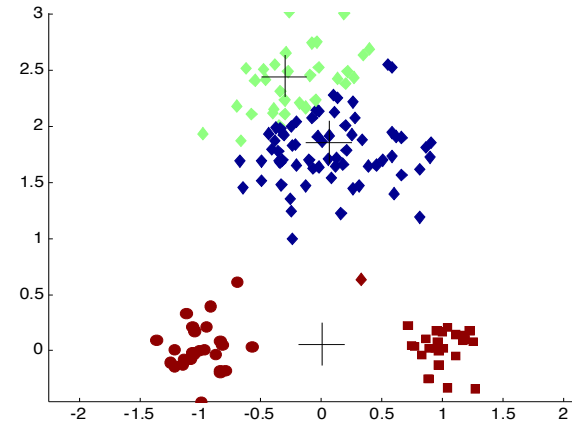
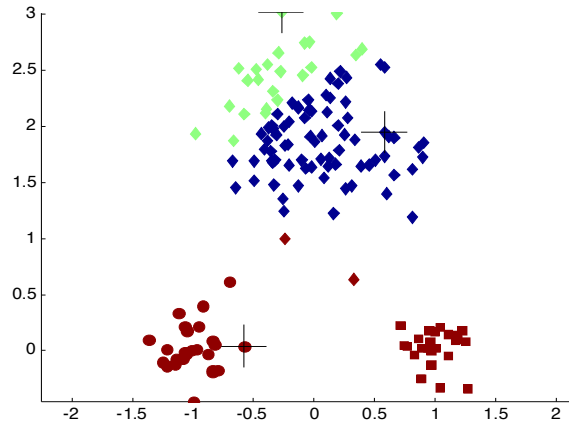
- For each point, the error is the distance to the nearest cluster
- To get SSE, we square these errors and sum them.

$$SSE = \sum_{i=1}^K \sum_{x \in C_i} dist^2(m_i, x)$$

- $x$  is a data point in cluster  $C_i$  and  $m_i$  is the representative point for cluster  $C_i$   
can show that  $m_i$  corresponds to the center (mean) of the cluster
- Given two clusters, we can choose the one with the smallest error
- One easy way to reduce SSE is to increase  $K$ , the number of clusters  
A good clustering with smaller  $K$  can have a lower SSE than a poor clustering with higher  $K$



# Importance of Choosing Initial Centroids ...

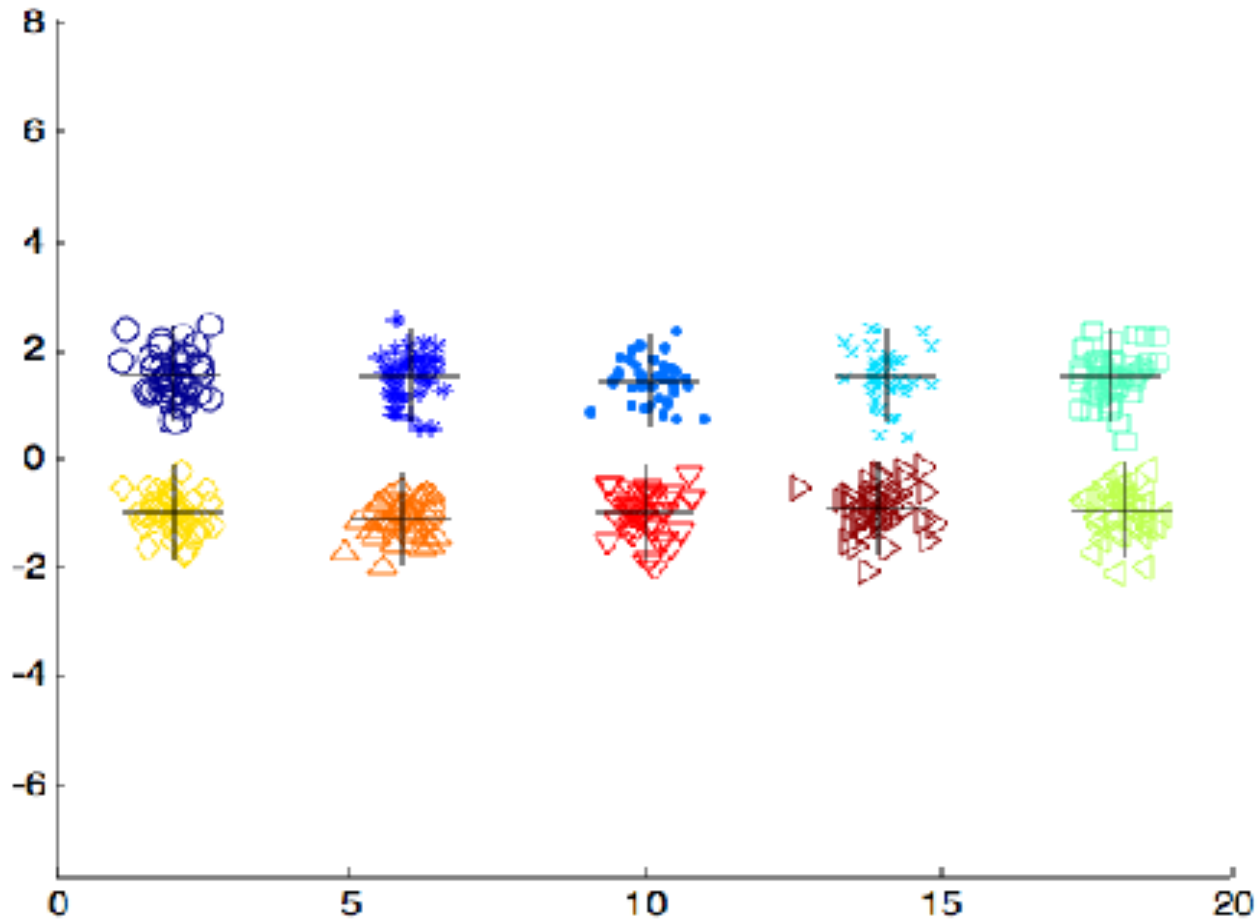


**If there are K 'real' clusters then the chance of selecting one centroid from each cluster is small.**

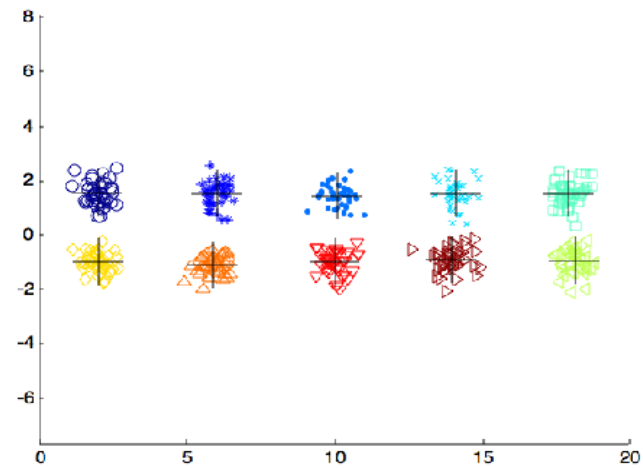
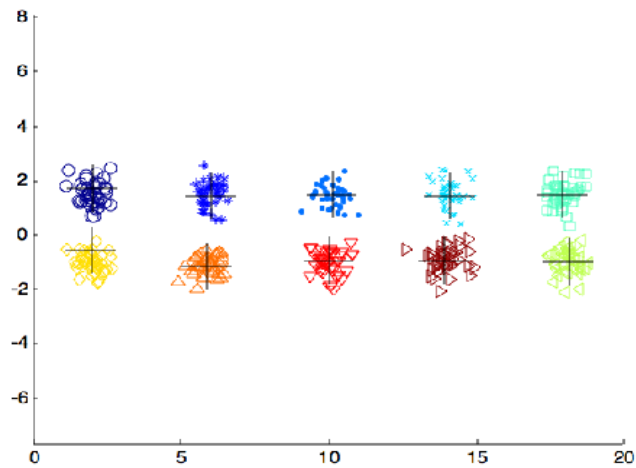
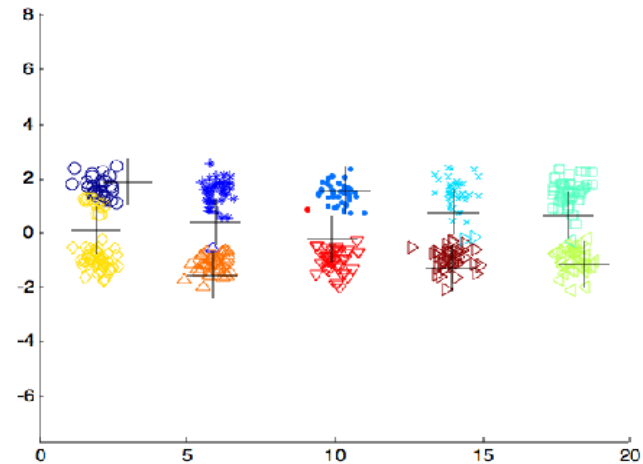
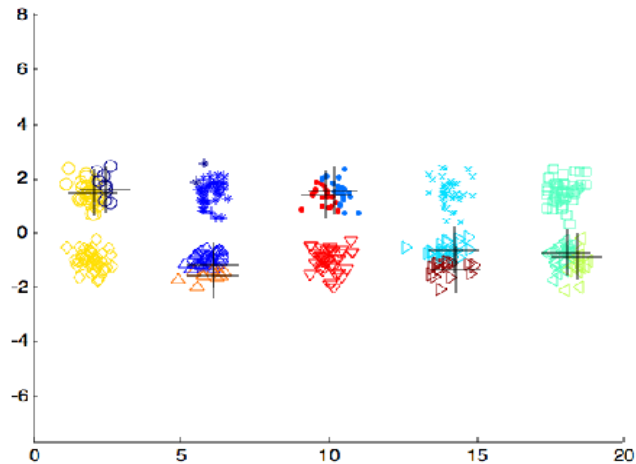
- Chance is relatively small when K is large
- If clusters are the same size, n, then

$$P = \frac{\text{\# of ways to select one centroid from each cluster}}{\text{\# of ways to select K centroids}} = \frac{\binom{n}{1}^K}{\binom{nK}{K}} \cong \frac{n^K}{\frac{(nK)^K}{K!}}$$
$$= \frac{K!}{K^K}$$

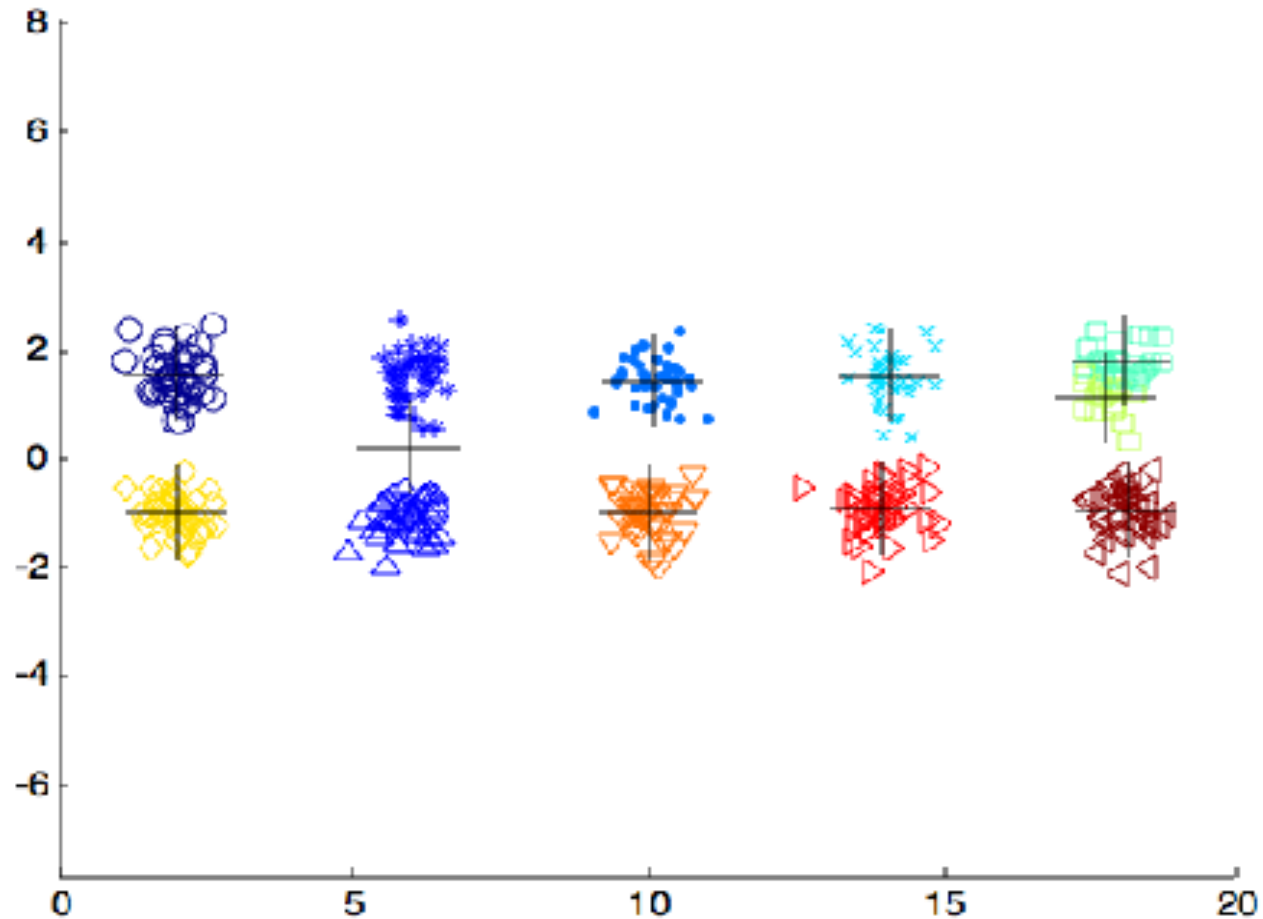
- For example, if K = 10, then probability = 10!/10<sup>10</sup> = 0.00036
- Sometimes the initial centroids will readjust themselves in 'right' way, and sometimes they don't
- Consider an example of five pairs of clusters



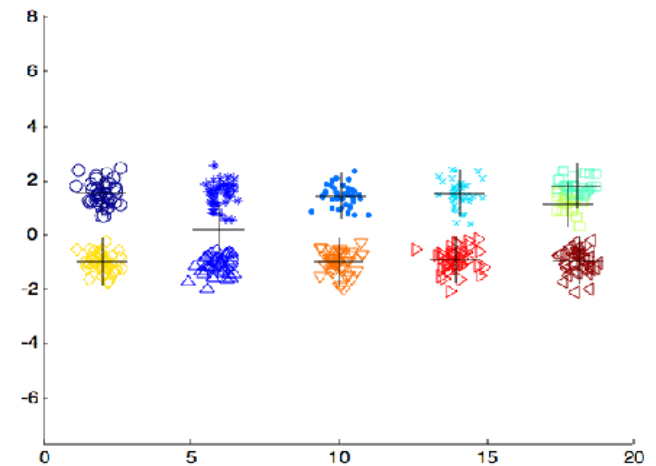
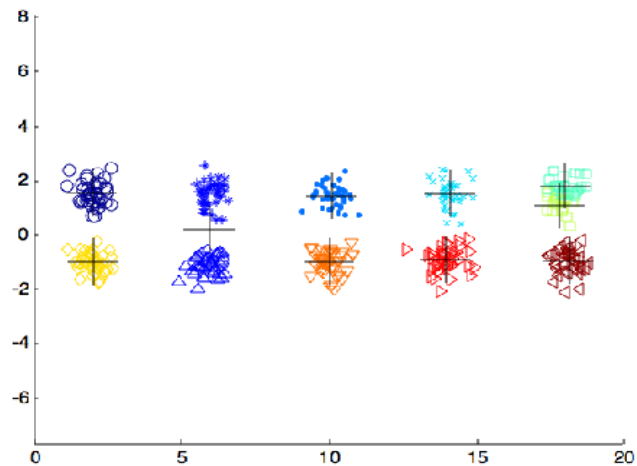
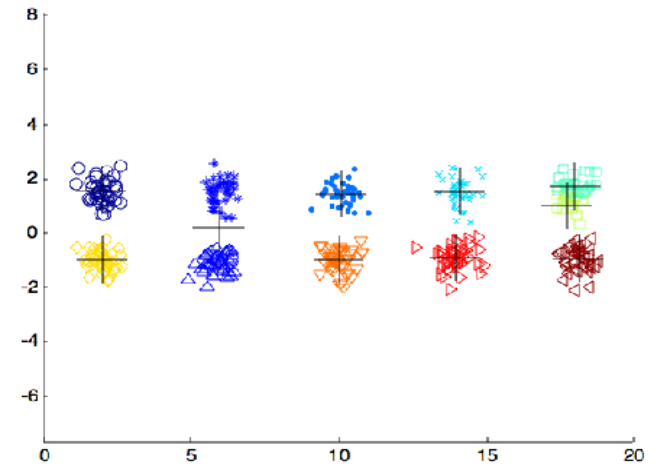
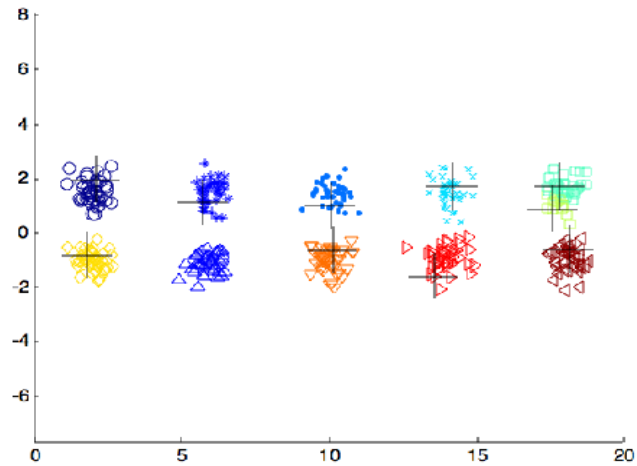
**Starting with two initial centroids in one cluster of each pair of clusters**



**Starting with two initial centroids in one cluster of each pair of clusters**



Starting with some pairs of clusters having three initial centroids, while other have only one.



**Starting with some pairs of clusters having three initial centroids, while other have only one.**



# Solutions to Initial Centroids Problem

## Multiple runs

- Helps, but probability is not on your side

## Sample and use hierarchical clustering to determine initial centroids

## Select more than $k$ initial centroids and then select among these initial centroids

- Select most widely separated

## Postprocessing

## Bisecting K-means

- Not as susceptible to initialization issues

# Handling Empty Clusters

## Basic K-means algorithm can yield empty clusters

### Several strategies

- Choose the point that contributes most to SSE
- Choose a point from the cluster with the highest SSE
- If there are several empty clusters, the above can be repeated several times.

# Updating Centers Incrementally

**In the basic K-means algorithm, centroids are updated after all points are assigned to a centroid**

**An alternative is to update the centroids after each assignment (incremental approach)**

- Each assignment updates zero or two centroids
- More expensive
- Introduces an order dependency
- Never get an empty cluster
- Can use “weights” to change the impact

# Pre-processing and Post-processing

## Pre-processing

- Normalize the data
- Eliminate outliers

## Post-processing

- Eliminate small clusters that may represent outliers
- Split 'loose' clusters, i.e., clusters with relatively high SSE
- Merge clusters that are 'close' and that have relatively low SSE
- Can use these steps during the clustering process

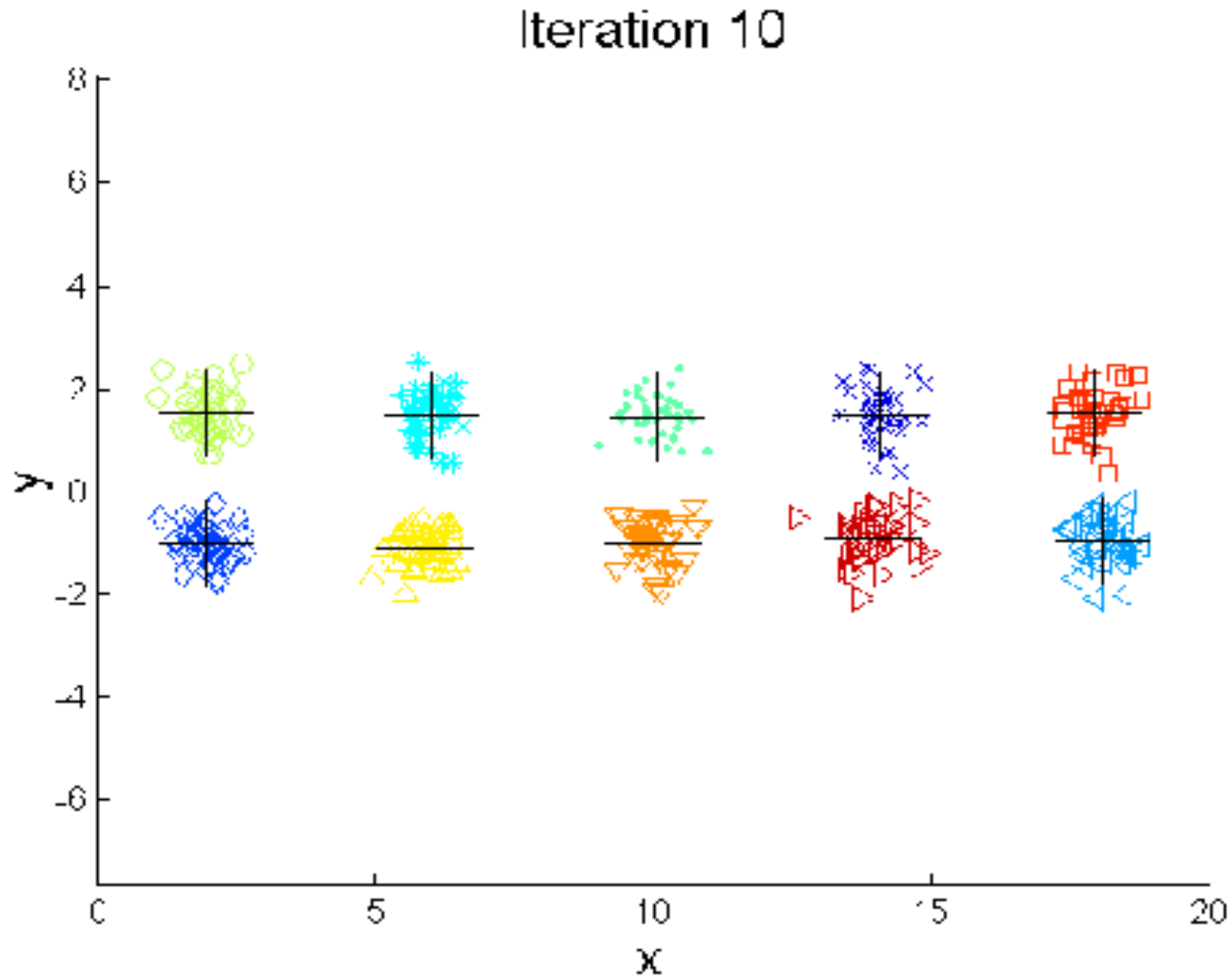
## Bisecting K-means algorithm

- Variant of K-means that can produce a partitional or a hierarchical clustering

---

```
1: Initialize the list of clusters to contain the cluster containing all points.
2: repeat
3:   Select a cluster from the list of clusters
4:   for  $i = 1$  to number_of_iterations do
5:     Bisect the selected cluster using basic K-means
6:   end for
7:   Add the two clusters from the bisection with the lowest SSE to the list of clusters.
8: until Until the list of clusters contains  $K$  clusters
```

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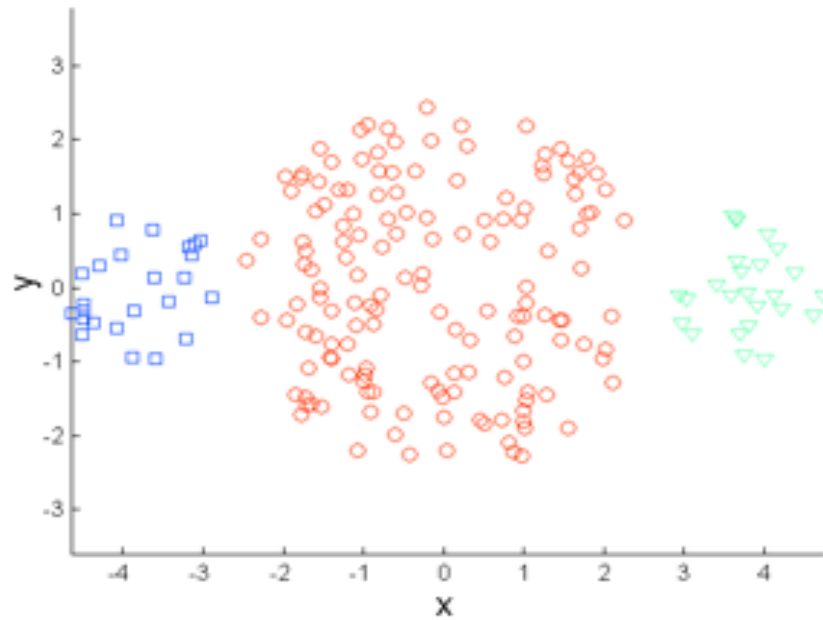


## Limitations of K-means

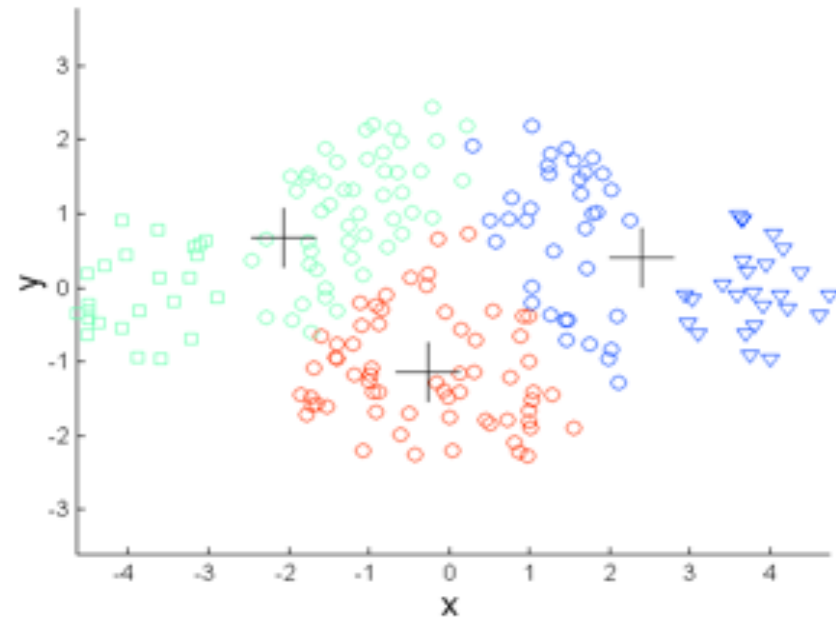
### **K-means has problems when clusters are of differing**

- Sizes
- Densities
- Non-globular shapes

### **K-means has problems when the data contains outliers.**

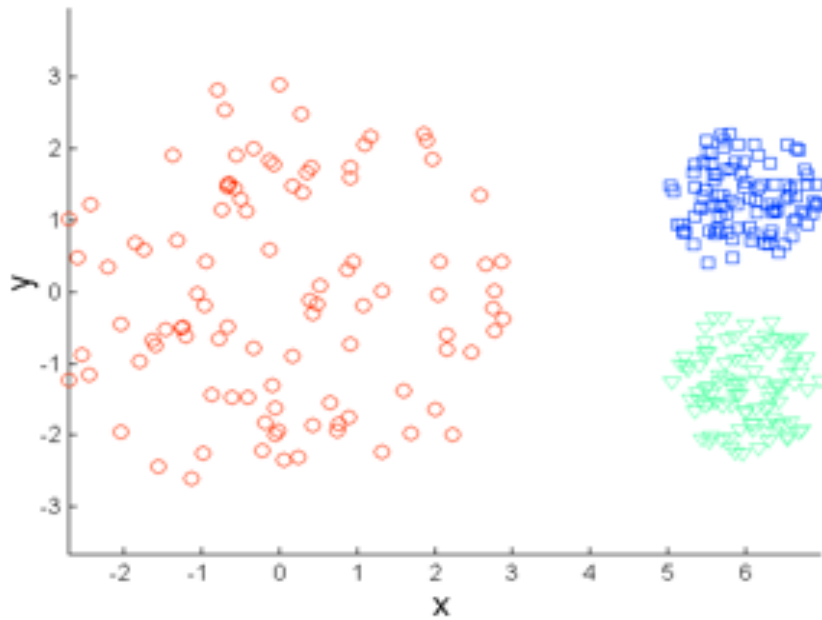


**Original Points**

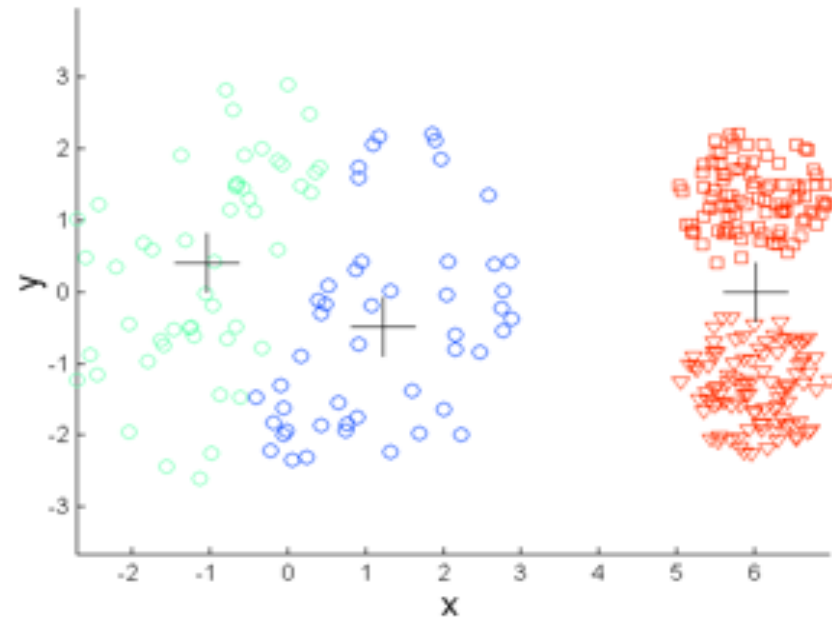


**K-means (3 Clusters)**

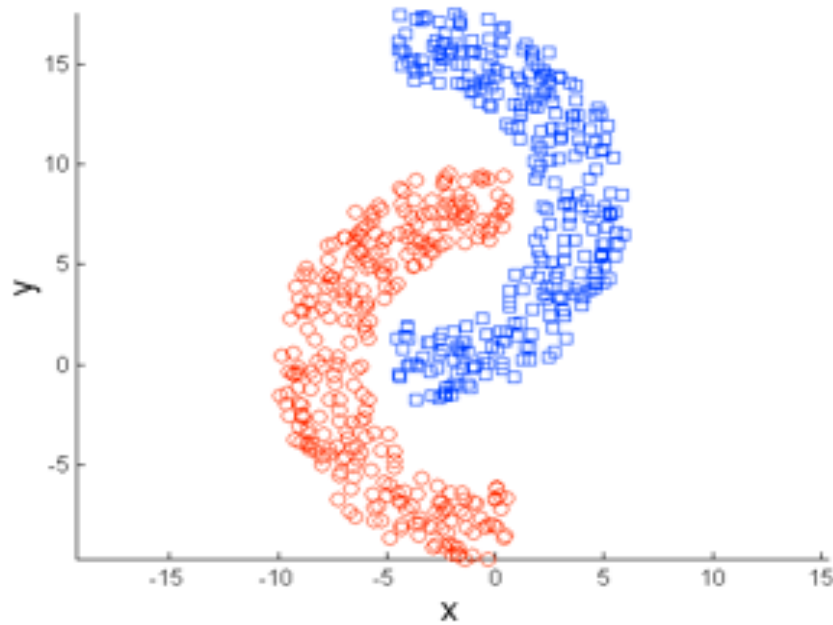




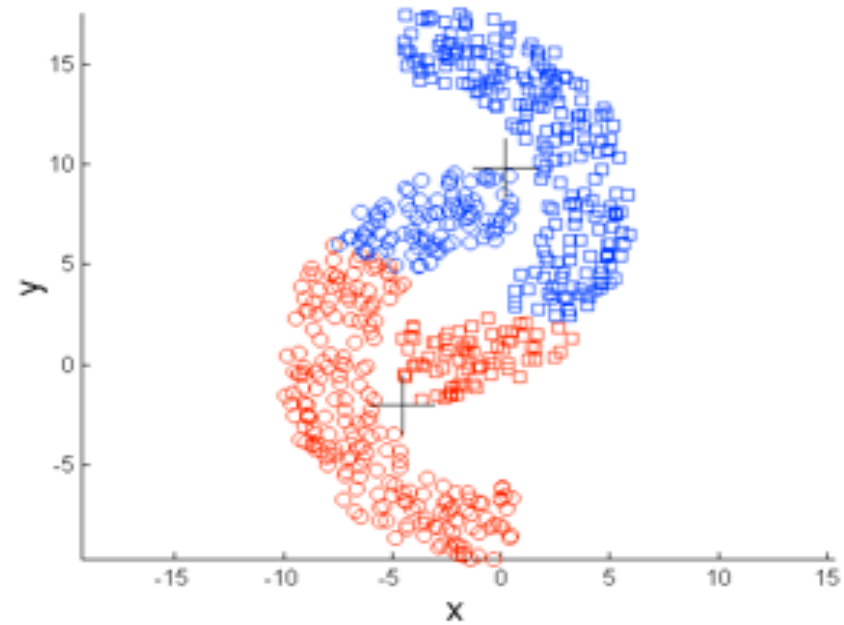
**Original Points**



**K-means (3 Clusters)**



**Original Points**



**K-means (2 Clusters)**

## Final Comment on Clustering

**Clustering is in the eyes of the beholder**

**“The validation of clustering structures is the most difficult and frustrating part of cluster analysis.**

**Without a strong effort in this direction, cluster analysis will remain a black art accessible only to those true believers who have experience and great courage.”**

***Algorithms for Clustering Data, Jain and Dubes***