AirMapSDK-Embedded

version 1.0A

AirMap

September 29, 2016

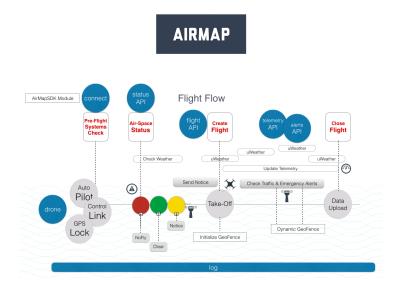
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Welcome to AirMap's documentation!

Airmap -- Airspace Management For Drones.

AirMapSDK is a Python library for interfacing with the Airmap API.



Pre-Requistes:

Airmap developer account
X-API-Key from your account
GPS data (fake gps included)
OAuth token
pip
getAirmap.py (copy to /home/root/installs directory or similar)
AirMapSDK-Embedded is pre-installed

Wi-Fi Connectivity

ifconfig (check for wlan0 or LTE ethX)
cd /etc
sudo wpa_passphrase yourSSID yourPassphrase > wpa-Aero.conf
sudo wpa_supplicant -i wlan0 -c /etc/wpa-Aero.conf &
sudo dhclient wlan0

Update AirMapSDK-Embedded

cd /etc/airmap python getAirmap.py airmap AirMapSDK-Embedded unzip AirMapSDK-Embedded-master.zip cd AirMapSDK-Embedded-master

User Example

cd /etc/airmap/AirMapSDK-Embedded python userapp.py

API Example

(connect) airmap.connect.set_XAPIKey(xapikey) - Set your X-API-Key from your Airmap account (connect) airmap.connect.get_boardID() - Retrieve CID information (connect) airmap.connect.connect() - Check internet connection and endpoint status Returns: True if ready (statusAPI) airmap.statusAPI.get_status(lat,lon,Weather.on) - Given position retreive airspace data (statusAPI) Parse status information including weather, advisories, and maximum flight bounds (see statusAPI documentation) (user) Process required notifications if needed (connect) airmap.connect.get_SecureToken() - get security token

(flightAPI) airmap.flightAPI.create_FlightPoint (flight time,lat,lon,publicflight?,sendnotifications?) - Setup the flight and flight time Returns flightID

(flightAPI) airmap.flightAPI.get_PilotID() - Returns pilotID for this account

(flightAPI) airmap.flightAPI.end_Flight(flightID) - End the flight specified by flight ID

(flightAPI) airmap.flightAPI.delete_Flight(flightID) - Delete flight described by flightID

(flightAPI) airmap.flightAPI.get_FlightList(pilotID) - Get all flights for pilotID

(flightAPI) airmap.flightAPI.cmd_KillFlights(pilotID) - Delete all flights under specified pilotID

Documentation can be found at https://developer.airmap.io

Source code can be found at https://github.com/...

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Contents:

airmap Package

airdefs Module

airdefs AirMapSDK

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class airmap.airdefs.Advisories (distance, last_updated, name, city, color, country, longitude,
properties, state, latitude, type, id)

Adivosry group list

Notes: Distance, date of last update, name, city, color(status), country, longitude, properties, state,

latitude, type, id

class airmap.airdefs.Advisory

Advisoy information (Pre-Flight, In-Flight)

Notes: Advisory status color list

class Color

Flight status color code

Colors

Color code

Parameters:

• gray -- Disbabled

• green -- Go

• yellow -- Advise

• red -- NoFly

alias of Enum

enum (*sequential, **named)

class airmap.airdefs.Globals

Global settings

Notes: Session parametes address, port, timeot, api key, token, pilot id, flight id

AirConnected = False

dbgPrint (data)

Debug send to console

Parameters: data -- Debug or information to send to console

```
Returns: None
 httpPort = 80
 httpsAddr = 'api.airmap.io'
 httpsPort = 443
 keyAddr = 'sso.airmap.io'
 myFlightID = None
 myToken = None
 pilotIDValid = False
 pilot_id = None
 strPrint (data)
   Information send to console
        Parameters:
                     data -- information to send to console
           Returns:
                      None
 telemetryAddr = 'api-aero-telemetry.airmap.com'
 thisBID = None
 timeOut = 18
 xapikey = None
class airmap.airdefs.Notify
 Enable notifications
      Parameters:
                       • on -- Enable notifications
                       • off -- Disable notifications
 off = False
 on = True
class airmap.airdefs.Properties (prop_name, prop_value)
 Name to Value Keypairs
class airmap.airdefs.Public
 Make flight public
      Parameters:
                       • on -- Public flight
                       • off -- Private flight
 off = False
 on = True
class airmap.airdefs.Requirement
 Notification requirments contact key pair list
 State
```

```
alias of Enum
  enum (*sequential, **named)
class airmap.airdefs.Startup
  Startup configuration
            Notes:
  class Drone
    Drone information (ID, Location, Status)
    State
      alias of Enum
    enum (*sequential, **named)
class airmap.airdefs.Weather
  Weather control parameters
      Parameters:
                        • on -- Enable weather data
                        • off -- Disable weather data
  off = 'false'
```

connect Module

connect AirMapSDK

on ='true'

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class airmap.connect.Connect

connect ()

Connect to service

Param: None

Returns: True - if connected otherwise False

connection = None Connection instance

Notes: HTTPS access variable

get_SecureToken ()

Retrieve security token and refresh

Param: None

Returns: Token if successful otherwise False

Todo: Remove hardcoded token and add token from https endpoint based on CID

get_boardID ()

Retrieve CID from mmcblk0

Param: None

Returns: CID otherwise False

headers = None

Connection headerssecurity and format

Notes: Security and format headers

os = <module 'os' from '/usr/lib/python2.7/os.pyc'>
 OS access

Notes: Run sys commands

set_Timeout (time_out)

Set https request timeout time

Parameters: time_out -- Timeout time in seconds

Returns: True - Success, False - Fail

set_XAPIKey (xapikey)

Set https request timeout time

Parameters: xapikey -- X-API-Key from developers account

Returns: True - Success, False - Fail

thisGlobals = <airmap.airdefs.Globals instance at 0x2ab568519c20> Global parameter access

Notes: Endpoint address, ports, token, id(s)

statusAPI Module

statusAPI AirMapSDK

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class airmap.statusAPI.Status

```
cmd_ProcessAdvisories ()
```

connection = None

get_Advisories ()

get_Advisory (id)

get_Condition ()

get_Humidity ()

get_MaxDistance ()

get_Precipitation ()

get_StatusCode ()

get_StatusColor ()

get_Temperature ()

get_Visibility ()

get_WindGusting ()

get_WindHeading ()

```
get_WindSpeed ()
get_status (gps_lat, gps_lon, weather)
headers = None
levelDown (data)
localAdvisories = []
localLevelDown = []
localProperties = []
os = <module 'os' from '/usr/lib/python2.7/os.pyc'>
status_json = None
thisGlobals = <airmap.airdefs.Globals instance at 0x2ab568519d88>
```

flightAPI Module

flightAPI AirMapSDK

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```
class airmap.flightAPI.Flight
  cmd_KillFlights (pilotID)
  connection = None
  create_FlightPoint (time, lat, lon, public, notify)
  delete_Flight (flightID)
  end_Flight (flightID)
  get_FlightList (pilotID)
  get_PilotID ()
  headers = None
  os = <module 'os' from '/usr/lib/python2.7/os.pyc'>
  thisGlobals = <airmap.airdefs.Globals instance at 0x2ab568519ea8>
```

drone Module

drone AirMapSDK

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class airmap.drone.drone

log Module

log AirMapSDK

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class airmap.log.log

telemetryAPI Module

telemetryAPI AirMapSDK

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class airmap.telemetryAPI.Telemetry

connection = None

headers = None

os = <module 'os' from '/usr/lib/python2.7/os.pyc'>

post_Telemetry (flightID, lat, lon, alt, ground_speed, heading, barometer, status, battery,
drone, seq, logused)

put_Telemetry (flightID, lat, lon, alt, ground_speed, heading, barometer, status, battery,
drone, seq, logused)

thisGlobals = <airmap.airdefs.Globals instance at 0x2ab568519f80>

alertsAPI Module

alertsAPI AirMapSDK

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class airmap.alertsAPI.alertsAPI

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