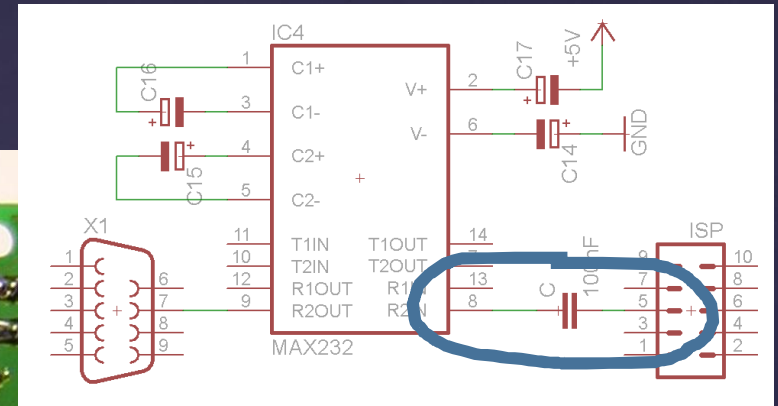
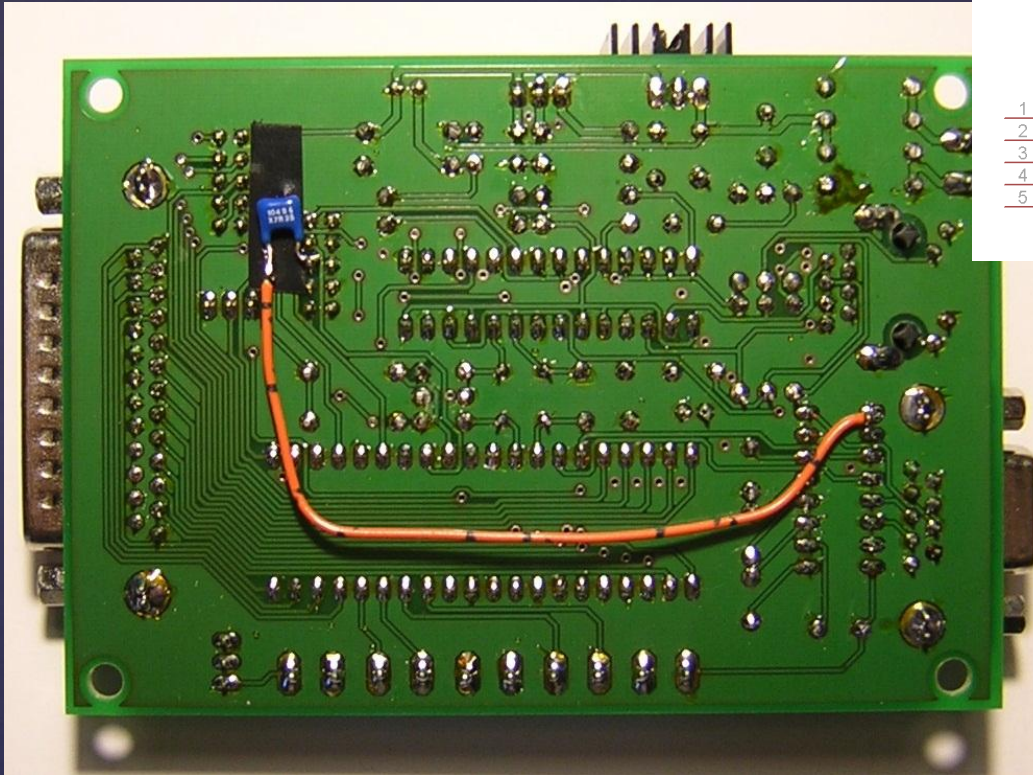


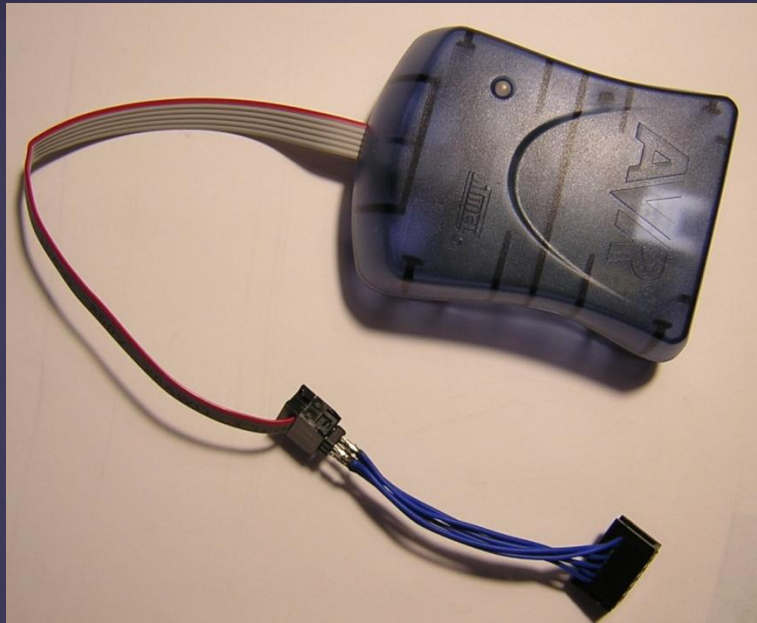
# CheapNetDuinoHack

{ Using a Pollin AVR NetIO as Arduino w/ Ethernet  
Markus Gebhard, Karlsruhe @ elektro:camp 2013:04



Add a RESET line for  
the Arduino IDE

# Pollin AVR NetIO arduinofied



```

11  /* onboard LED is used to indicate, that the bootloader
12  /* if monitor functions are included, LED goes on after
13  #if defined __AVR_ATmega128__ || defined __AVR_ATmega162__
14  /* Onboard LED is connected to pin PB7 (e.g. Crumb128,
15  #define LED_DDR DDRB
16  #define LED_PORT PORTB
17  #define LED_PIN PINB
18  #define LED PINB7

```

or the MEGA and enter bo

UART, so only one pin is

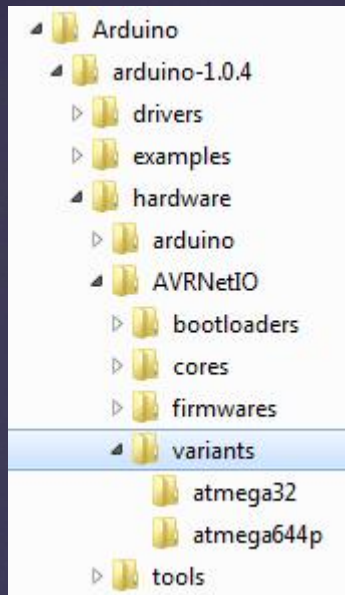
```

115 #define BL_PORT PORTF
116 #define BL_PIN PINF
117 #define BL0 PINF7
118 #define BL1 PINF6
119 #elif defined __AVR_ATmega1280__
120 /* we just don't do anything for the MEGA and enter bo
121 #elif defined __AVR_ATmega644P__ // the ATmega644P ha
122 #define BL_DDR DDRD
123 #define BL_PORT PORTD
124 #define BL_PIN PIND
125 #define BL0 PIND0
126 #define BL1 PIND2
127 #elif defined __AVR_ATmega32__
128 #define BL_DDR DDRD
129 #define BL_PORT PORTD
130 #define BL_PIN PIND
131 #define BL PIND0
132 #else
133 /* other ATmegs have only one UART, so only one pin is
134 #define BL_DDR DDRD
135 #define BL_PORT PORTD
136 #define BL_PIN PIND
137 #define BL PIND6
138 #endif
139
140
141 /* onboard LED is used to indicate, that the bootloader
142 /* if monitor functions are included, LED goes on after
143 #if defined __AVR_ATmega128__ || defined __AVR_ATmega162__
144 /* Onboard LED is connected to pin PB7 (e.g. Crumb128,
145 #define LED_DDR DDRB
146 #define LED_PORT PORTB
147 #define LED_PIN PINB
148 #define LED PINB7
149 #elif defined __AVR_ATmega644P__ || defined __AVR_ATmega1280__
150 /* use an LED on pin B1 (AVRNetIO jumper to select pr
151 #define LED_DDR DDRB
152 #define LED_PORT PORTB
153 #define LED_PIN PINB

```

# Flash Arduino Bootloader

Adapt standard ATmegaBOOT\_168.c for ATmega32/644 – basically  
 PINs, chip IDs and #defines – no serious changes required...

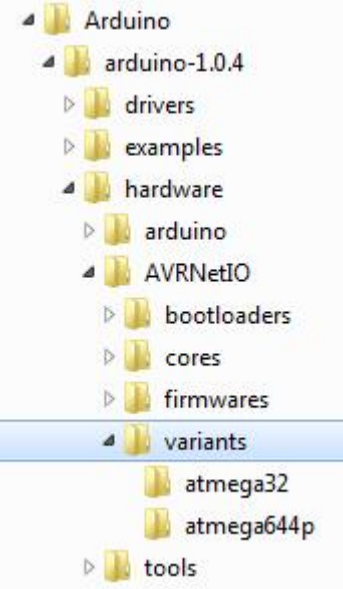


```
boards.txt
1 #####
2 AVRNetIO_32.name=AVRNetIO w/ ATmega32
3
4 AVRNetIO_32.upload.protocol=stk500
5 AVRNetIO_32.upload.maximum_size=30720
6 AVRNetIO_32.upload.speed=19200
7
8 AVRNetIO_32.bootloader.low_fuses=0xBF
9 AVRNetIO_32.bootloader.high_fuses=0xC8
10 AVRNetIO_32.bootloader.path=atmega
11 AVRNetIO_32.bootloader.file=ATmegaBOOT_32.hex
12 AVRNetIO_32.bootloader.lock_bits=0xFF
13
14 AVRNetIO_32.build.mcu=atmega32
15 AVRNetIO_32.build.f_cpu=16000000L
16 AVRNetIO_32.build.core=arduino
17 AVRNetIO_32.build.variant=atmega32
18
19 #####
20 AVRNetIO_644p.name=AVRNetIO w/ ATmega644P
21
22 AVRNetIO_644p.upload.protocol=stk500
23 AVRNetIO_644p.upload.maximum_size=63488
24 AVRNetIO_644p.upload.speed=19200
25
```

# Hardware for Arduino IDE

→ boards.txt





```
// ATME6L ATMEGA32
//
//
//                                     +---\ /---+
// Ext7          T0          D0   PB0  1 |           |40   PA0  AI0/D24 Eingang1/SubD10
// J11           T1          D1   PB1  2 |           |39   PA1  AI1/D25 Eingang2/SubD11
// ENC-INT       INT2        D2   PB2  3 |           |38   PA2  AI2/D26 Eingang3/SubD12
// Ext8          PWM         D3   PB3  4 |           |37   PA3  AI3/D27 Eingang4/SubD13
// ENC-SPI/ISP   SS          D4   PB4  5 |           |36   PA4  AI4/D28 ADC1
// ENC-SPI/ISP   MOSI        D5   PB5  6 |           |35   PA5  AI5/D29 ADC2
// ENC-SPI/ISP   MISO        D6   PB6  7 |           |34   PA6  AI6/D30 ADC3
// ENC-SPI/ISP   SCK         D7   PB7  8 |           |33   PA7  AI7/D31 ADC4
//
//                               RST  9 |           |32   AREF
//                               VCC 10|           |31   GND
//                               GND 11|           |30   AVCC
//
//                   XTAL2 12|           |29   PC7  D23      Ausgang8/SubD9
//                   XTAL1 13|           |28   PC6  D22      Ausgang7/SubD8
// MAX232-RX     RX0        D8   PD0 14|           |27   PC5  D21  TDI Ausgang6/SubD7
// MAX232-TX     TX0        D9   PD1 15|           |26   PC4  D20  TDO Ausgang5/SubD6
// Ext1          INT0       D10  PD2 16|           |25   PC3  D19  TMS Ausgang4/SubD5
// Ext2          INT1       D11  PD3 17|           |24   PC2  D18  TCK Ausgang3/SubD4
// Ext3          PWM        D12  PD4 18|           |23   PC1  D17  SDA Ausgang2/SubD3
// Ext4          PWM        D13  PD5 19|           |22   PC0  D16  SCL Ausgang1/SubD2
// Ext5          PD6 20|           |21   PD7  D15  PWM Ext6
//
//                                     +-----+
//
#define NOT_A_PIN 0
#define NOT_A_PORT 0

#define NOT_ON_TIMER 0
#define TIMER0 1
#define TIMER1A 2
```

# Hardware for Arduino IDE

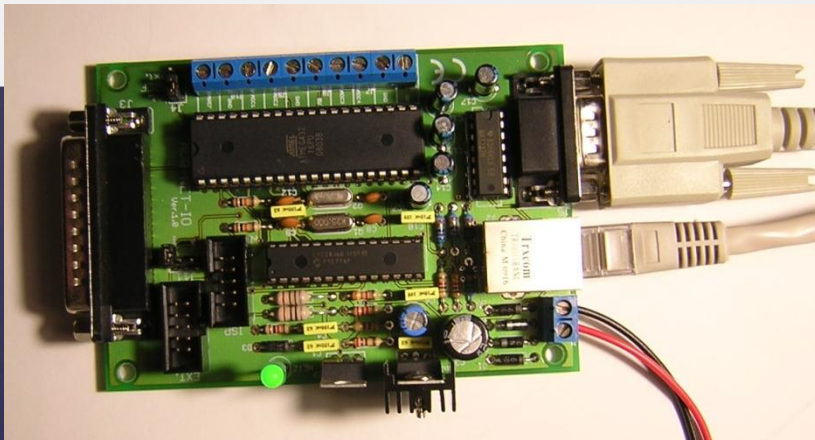
## → pins\_arduino.h variants



Use Jean-Claude's brilliant ethercard driver...

# Enjoy a cheap Arduino w/ ethernet capability

```
Received Data
1 5 10 15 20 25 30 35 40 45 50 55 60 65 70 75 80 85
AVRNetIO Test
Assigned IP address 192.168.0.128
GET /?o1=1&o4=1&o5=1&o8=1 HTTP/1.1
Host: 192.168.0.128
User-Agent: Mozilla/5.0 (Windows NT 6.1; WOW64; rv:20.0) Gecko/20100101 Firefox/20.0
Accept: text/html,application/xhtml+xml,application/xml;q=0.9,*/*;q=0.8
Accept-Language: de-de;q=0.8,en-us;q=0.5,en;q=0.3
Accept-Encoding: gzip, deflate
DNT: 1
Referer: http://192.168.0.128/?o1=1&o4=1&o5=1&o8=1
Connection: keep-alive
```



Simple AVRNetIO webserver

<input checked="" type="checkbox"/> Output 1	<input type="checkbox"/> Output 2
<input type="checkbox"/> Output 3	<input checked="" type="checkbox"/> Output 4
<input checked="" type="checkbox"/> Output 5	<input type="checkbox"/> Output 6
<input type="checkbox"/> Output 7	<input checked="" type="checkbox"/> Output 8
Input 1: 1	Input 2: 1
Input 3: 1	Input 4: 1
ADC1: 824	ADC2: 666
ADC3: 435	ADC4: 331
<input type="button" value="Daten absenden"/>	

# Easy Server

<https://github.com/gebhardm/energyhacks/tree/master/AVRNetIOduino>

With ideas taken from

<http://sanguino.cc/>

<http://son.ffdf-clan.de/?path=start>

# Resources