

Bluetooth Module (master/slave)

Index

BLUETOOTH MODULE	
OVERVIEW	
LICENSE	2
SPECIFICATIONS	3
Hardware features	
SOFTWARE FEATURES	3
SOFTWARE INSTRUCTION	
WORKING SKETCH MAP	
FLOWCHART	4
COMMANDS TO CHANGE DEFAULT SETTINGS	5
COMMANDS FOR NORMAL OPERATION:	
PINOUT	8
PIN FUNCTION	g
DEVISION HISTORY	11

Overview



Serial port Bluetooth module is fully qualified Bluetooth V2.0+EDR(Enhanced Data Rate) 3Mbps Modulation with complete 2.4GHz radio transceiver and baseband. It uses CSR Bluecore 04-External single chip Bluetooth system with CMOS technology and with AFH(Adaptive Frequency Hopping Feature). It even has the smallest footprint as small as 12.7mmx27mm. Hope it will simplify your overall design/development cycle.

License



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Specifications

Hardware features

- Typical -80dBm sensitivity
- Up to +4dBm RF transmit power with power level control
- Fully Qualified Bluetooth V2.0+EDR 3Mbps Modulation
- Integrated 15-bit Linear 8KHz Sample Frequency (not in default profile)
- External 8Mbit Flash
- Low Power 1.8V Operation ,1.8 to 3.6V I/O
- PIO control
- UART interface with programmable baud rate
- Integrated PCB antenna
- SMD package
- With PCM Out & PCM in (not in default profile)
- With edge connector

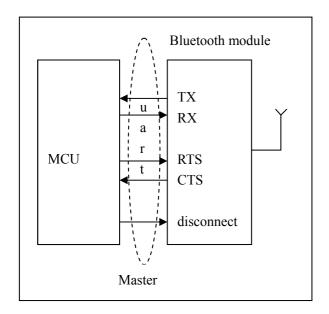
Software features

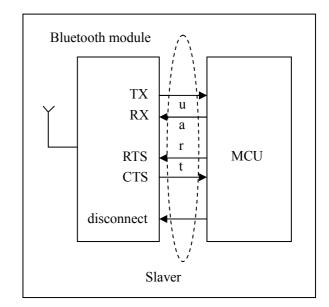
- Default Baud rate: 38400, Data bits:8, Stop bit:1,Parity:No parity, Data control: has. Supported baud rate: 9600,19200,38400,57600,115200,230400,460800.
- Use CTS and RTS to control the data stream, deep sleep and wake up.
- When a rising pulse is detected in PIO0, device will be disconnected.
- Status instruction port PIO1: low-disconnected, high-connected;
- PIO10 connected red led, PIO11 connected blue led. When master and slave are paired, red and blue led blinks 1time/2s in interval, while disconnected only blue led blinks 2times/s.
- Auto-connect the last device on power as default.
- Permit matched device connect by default.
- Default PINCODE:"0000".
- Auto-reconnect in 30 min when disconnected as a result of beyond the range of connection.



Software Instruction

Working Sketch Map

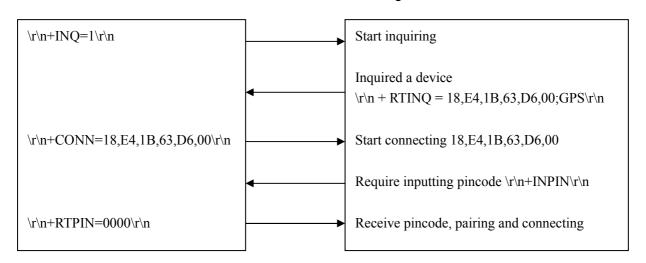




Flowchart

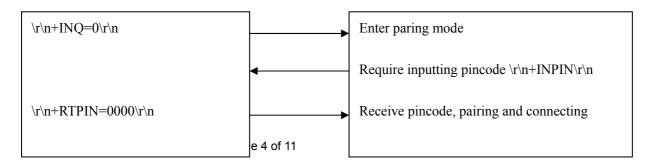
Master MCU Instructions

Message and feedback of Bluetooth Module



Slave MCU Instructions

Message and feedback of Bluetooth Module





Commands to change default settings

1. Set working MODE

\r\n+STWMOD=0\r\n Set device working as client (slave), Save and Rest \r\n+STWMOD=1\r\n Set device working as server (master), Save and Rest

2. Set BAUDRATE

\r\n+STBD=115200\r\n Set baudrate 115200, Save and Rest Supported baudrate: 9600, 19200,38400,57600,115200,230400,460800.

3. Set MASTER NAME

\r\n+STNA=abcdefg Set device name "abcdefg", Save and Rest

4. Auto-connect the last paired device on power

\r\n+STAUTO=0\r\n Forbidden, Save and Rest \r\n+STAUTO=1\r\n Permit, Save and Rest

5. Permit Paired device to connect me

\r\n+STOAUT=0\r\n Forbidden, Save and Rest \r\n+STOAUT=1\r\n Permit, Save and Rest

6. Set PINCODE

\r\n +STPIN=222\r\n Set pincode "2222", Save and Rest

7. Delete PINCODE(input PINCODE by MCU)

\r\n+DLPIN\r\n Delete pincode, Save and Rest



8. Open ECHO

\r\n+STECHO\r\n Open controlling command echo

9. Read local ADDRESS CODE

\r\n+RTADDR\r\n Return address of the device

10. Auto-reconnecting when master device is beyond the valid range (slave device will auto-reconnect in 30 min when it is beyond the valid range)

\r\n+LOSSRECONN=0\r\n Open \r\n+LOSSRECONN=1\r\n Close

Commands for Normal Operation:

1. Inquire SLAVER

a) Master

\r\n+INQ=0\r\n Stop Inquiring

\r\n+INQ=1\r\n Begin/Restart Inquiring

b) Slave

\r\n+INQ=0\r\n Enable been inquired \r\n+INQ=1\r\n Disable been inquired

2. Bluetooth module returns inquiring result

\r\n+RTINQ=aa,bb,cc,dd,ee,ff;name\r\n A serial Bluetooth device with the address "aa,bb,cc,dd,ee,ff" and the name "name" is inquired



3. Connect device

\r\n+CONN=aa,bb,cc,dd,ee,ff\r\n

Connect to a device with address of "aa,bb,cc,dd,ee,ff"

4. Bluetooth module requests inputting PINCODE

 $\r\n+INPIN\r\n$

5. Input PINCODE

\r\n+RTPIN=code\r\n

Example: RTPIN=0000 Input PINCODE which is four zero

6. Disconnect device

Pulling PIO0 high will disconnect current working Bluetooth device.

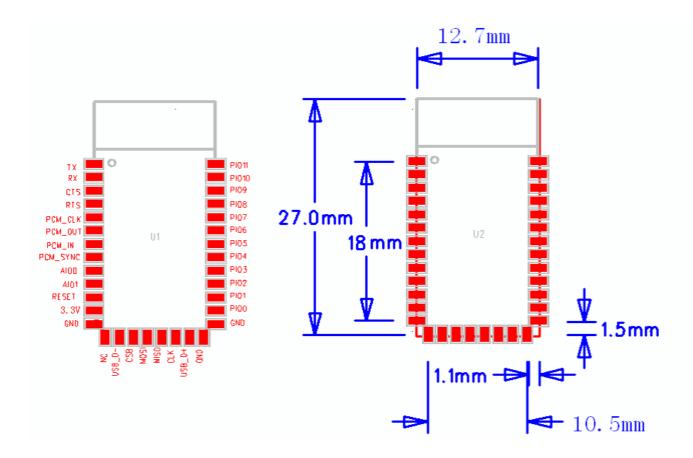
7. Return status

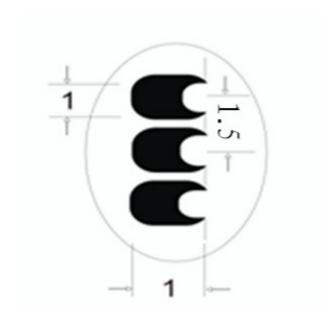
 $\r\n+RTSTA:xx\r\n$

xx status:

- 0, Initializing
- 1, Ready
- 2, Inquiring
- 3, Connecting
- 4, Connected

Pinout







Pin Function

PIN Name	PIN	Pad type	Description	Note
	#			
	13			
GND	21	VSS	Ground pot	
	22			
3.3 VCC	12	3.3V	Integrated 3.3V (+) supply with On-chip linear regulator output within 3.15-3.3V	
AIO0	9	Bi-Directional	Programmable input/output line	
AIO1	10	Bi-Directional	Programmable input/output line	
PIO0	23	Bi-Directional RX EN	Programmable input/output line, control output for LNA(if fitted)	
PIO1	24	Bi-Directional TX EN	Programmable input/output line, control output for PA(if fitted)	

PIO2	25	Bi-Directional	Programmable input/output line	
PIO3	26	Bi-Directional	Programmable input/output line	
PIO4	27	Bi-Directional	Programmable input/output line	
PIO5	28	Bi-Directional	Programmable input/output line	
PIO6	29	Bi-Directional	Programmable input/output line	
PIO7	30	Bi-Directional	Programmable input/output line	
PIO8	31	Bi-Directional	Programmable input/output line	
PIO9	32	Bi-Directional	Programmable input/output line	
PIO10	33	Bi-Directional	Programmable input/output line	
PIO11	34	Bi-Directional	Programmable input/output line	



RESETB	11	CMOS input with weak internal pull-up	Reset if low.input debouncde so must be low for >5MS to cause a reset	
UART_RTS	4	CMOS output, tri-stable with weak internal pull-up	UART request to send, active low	
UART_CTS	3	CMOS input with weak internal pull-down	UART clear to send, active low	
UART_RX	2	CMOS input with weak internal pull-down	UART Data input	
UART_TX	1	CMOS output, Tri-stable with weak internal pull-up	UART Data output	
SPI_MOSI	17	CMOS input with weak internal pull-down	Serial peripheral interface data input	
SPI_CSB	16	CMOS input with weak internal pull-up	Chip select for serial peripheral interface, active low	
SPI_CLK	19	CMOS input with weak internal pull-down	Serial peripheral interface clock	
SPI_MISO	18	CMOS input with weak internal	Serial peripheral interface data Output	

pull-down

Bi-Directional

15

USB_-



USB_+	20	Bi-Directional		
NC	14			
PCM_CLK	5	Bi-Directional	Synchronous PCM data clock	
PCM_OUT	6	CMOS output	Synchronous PCM data output	
PCM_IN	7	CMOS Input	Synchronous PCM data input	
PCM_SYNC	8	Bi-Directional	Synchronous PCM data strobe	

Revision History

Rev.	Descriptions	Release date
1.0	Initial release	2010.1.8