

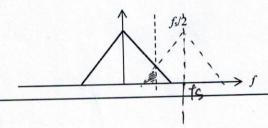
Name: Review Card 3 Vrey - Word

1. If an ADC has a resolution of 12 bit and a reference voltage of 5 volts, the digital output for an analog input of

1.56 volts will be = 1278 (in decimal form)

2. If we want to digitize an analog signal with frequency of interest not higher than 8 kHz, the minimal sampling frequency should be by the anti-aliasing filter prior to digitizing is a more analog or digital manalog or digital (low- or high- pass) filter with a cut-off frequency of 8 kH2

3. Draw the side effect if an analog signal is sampled as follows:





Name: 表情

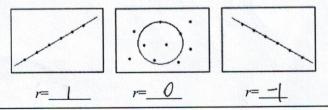
1. For a random signal {2 3 1 5 3 4 3 1}, calculate the

following descriptive statistics:

Mean=\_\_2.75, Median=\_\_3\_\_\_, Mode=\_\_7\_\_

Standard Deviation= 1,588

2. Determine the following correlation coefficients (r):



Name: 基春春

**Review Card 4** 

Read the datasheet of a DAC chip from Texas Instruments below and answer the following questions:

## DESCRIPTION

The DAC161S997 is a very low power 16-bit ΣΔ digital-to-analog converter (DAC) for transmitting an analog output current over an industry standard 4-20mA current loop. The DAC161S997 has a simple 4-wire <u>SPI</u> for data transfer and configuration of the DAC functions. To reduce power and component count in compact loop-powered applications, the DAC161S997 contains an internal ultra-low power voltage reference and an internal ultra-low power voltage reference and an internal oscillator. The low power consumption of the DAC161S997 results in additional current being available for the remaining portion of the system. The loop drive of the DAC161S997 interfaces to a Highway Addressable Remote Transducer (HART) modulator, allowing injection of FSK modulated digital data into the 4-20mA current loop. This combination of specifications and features makes the DAC161S997 ideal for 2- and 4-wire industrial transmitters. The DAC161S997 is available in a 16-pin 4 mm × 4 mm WQFN package and is specified over the extended industrial temperature range of -40°C to +105°C.

Name: Review Card 5
1. Complete the number conversion between different bases:
(1101.0111)2=(13.4375)10
$(4F.6E)_{16} = (79, 4)9687 \pm )_{10}$
$(87.35)_{10} = (110101011011011011011011011011011011011$
$(CD.6A)_{16} = (100[10], 0[1010])_2$
$(99.025)_{10} = ( b), 0666 \cdots $
$(111\underline{00110},\underline{0111}1001)_2 = (\underline{E6},\underline{79})_{16}$
@11100110.011110010=( 346,762 )8
3 4 6 3 6 7
2. The range of a signed char (8-bit) is: -128 v+127
3. Represent the negative number (-13) <sub>10</sub> in different ways:
Sign-and-Magnitude: 100010
1s Complement: 11/10010
2s Complement:         0

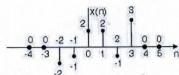
2 * 2 Review Card 7	
Name: 1 - Londof Huish	
1. A linear time-invariant system should have the following	
three properties: 13 76 th, 713 70 th and 14 7 3 th	2
(time-invariant)	
2. Decide whether the system described by the following	
formula is a linear time-invariant system:	
y(n) = nx(n)	
♦ Linear? A . Yes	
♦ Time-invariant?	

Name: Review Card 6
1. For an 8-bit binary number 1001 1101,
(A) If it represents an <b>unsigned</b> number, the decimal value is;
(B) If it represents an <b>signed</b> number, the decimal value is:
a) if it is in sign-and-magnitude form;
b) $-9\%$ if it is in 1s complement form;
c) if it is in 2s complement form;
2. The three parts of a float number is: Sign, mantiss 9
and byponent The advantage of float number is: In
IEEE standard, it uses $\frac{3\nu}{2}$ bits to represent a number
of single precision, and $\psi$ bits for double
precision.
3. Rewrite the following number in base-2 normalized form
and represent it by a 10 digit float number (4 digit for
exponent part):
(A) (13.25) <sub>10</sub> a) normalized form: (110   ) 2   10   0   X 2
a) normalized form:
b) float-number representation:
0 1 1 0 1 0 0 1 0 0
(B) (-0.1325) <sub>10</sub>
a) normalized form: 1, 1700 7 X
b) float-number representation (2s complement):
110000011110

**Review Card 8** 

1. There are usually three ways to uniquely characterize a LTI system: nomogeneity, and the and time - inveniount (Z)

**2.** Please rewrite x(n) by the form of impulse decomposition:



 $x(n) = -2 \delta(n+1) - \int (n+1) + 2\delta(n) + 2\delta(n+1) - \delta(n+1) + 3\delta(n+3)$ 

- 3. If the length of an input x(n) is 8 points and the length of the system impulse response h(n) is 7 points, then the convolution of x(n) and h(n) would be y points.
- 4. Please calculate the convolution of the following two discrete signals through both the input and output side algorithms:

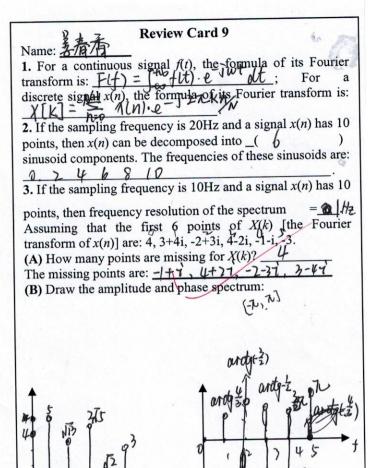
$$x(n) = \{1,3,4,2,5\}$$
  
 $h(n) = \{6,5,7\}$ 

(A) The input side algorithm:

$$y_{0}(n) = \{ \begin{array}{c|cccc} b & b & \\ \hline & y_{1}(n) = \\ \hline & y_{2}(n) = \\ \hline & y_{2}(n) = \\ \hline & y_{3}(n) = \\ \hline & y_{4}(n) = \\ \hline & \\$$

(B) Draw the steps as h(n) moved along x(n), as well as the

corresponding element of y(n) for each step:



## Name: Review Card 10

1. If the sampling frequency is 1000Hz and the length of x(n) is 500, then frequency resolution  $\triangle f$  of the Fourier transform of x(n) is:  $2 \frac{1}{12}$ .

Is it possible to separate 80Hz and 82Hz?

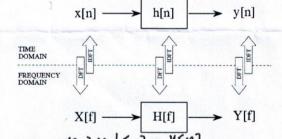
Is it possible to separate 79Hz and 81Hz?

Is it possible to separate 1000Hz and 1002Hz? A/O

2. For frequencies of 10Hz, 30Hz, 40Hz and 50Hz, what is the fundamental frequency? 10Hz The third harmonic is 22Hz The second harmonic of the power line frequency in China is 22Hz 140Hz

3. If the length of h(n) is 500 and the sampling frequency is 1000Hz, what is the frequency resolution of H[f]?

4. For a system below, list two methods to calculate y[n]



Method (1): A[n] \* h[n] = Y[n]Method (2):  $X[f] \times H[f] = Y[f]$ IDFT Y[n]

If both x[n] and h[n] have 100 points, y[n] will have 190 points and Y[f] will have points. In this case, will the y[n] be the same for the two methods?

If no, what can you do to make the y[n] results the same? Attack M[n] h[n] h[n]

Name: A State

If the amplitude spectrum of a system is as flows:

dB

-3dB point

fc Frequency (Hz)

(1) Describe the system:

High part filter. The Lamb to

**Review Card 11** 

(2) If the sampling frequency is 10Hz and the system always delays the input signal by one point, please draw the phase spectrum of the system:

## **Review Card 12** Name: 1. Which type of filter is better in performance, analog or digital? digital 2. There are two ways to evaluate the performance of a digital filter: in time domain and in frequency domain. Time Domain (A) What type of system response is used? M 块面龙 (B) What parameters are used? Military linear share (C) The responses of several filters are as follows, which filter do you think is best? (Mark the curve) Frequency Domain (A) What type of system response is used? (B) What parameters are used? <u>tout</u> (C) The responses of several filters are as follows, which filter do you think is best? (Mark the curve) Butterworth Response Order = 2 Order = 5 Order = 20 0.2 low-payl What type of filter is above? Q=0.1 What type of filter is above? band - reject filter

Review Card 14
Name: ATEME
The Moving Average Filter (MAF)
1. For a four-point MAF, draw the impulse response h(n):
2 Is it a high-pass or low-pass filter? (Au) -Pous.
2. Is it a might pass of low pass titler.
3. The aim we use the MAF is to AR PAP.
4. See figure below of MAF's with different averaging
points. The advantage of using more points (such as 31 points) is 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
The Windowed-Sinc Filter (WSF)  1. How do we get the filter kernel of WSF from its frequency response (see below)?
Frequency Domain Time Domain
a. Ideal frequency response  1.5  a. Ideal frequency response  1.0  5. Ideal filter kernel  1.0  0.0  0.0  0.0  0.0  Sample number
2. The actual frequency response is different from its
ideal response (see below), why?  d. Truncated-sinc frequency response  1.0  d. Truncated-sinc frequency response  0.0  0.0

3. We see that the response above is poor, how to solve the problem?

4. What's the two parameters when designing WSF?

4. What's the two parameters when designing WSF?

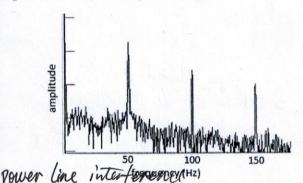
cut of frequency M [number of points

1: be used in moving av

**Review Card 15** 

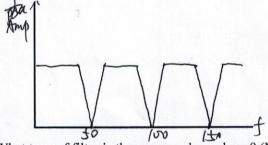
Name: A

When measuring ECG signals, Xiaoming found that the recorded signal was not as what he expected. After performing a FFT, he found that there were large spikes in the spectrum, which were so large that it was impossible for him to observe the actual ECG signals. Please help him to find a solution to extract the ECG signals from such a noisy recording.



1. Where did the interferences come from?

2. Please draw the frequency response of the filter that can remove the interferences.



3. What type of filter is the one you draw above? (Moving average, Windowed-Sinc, or Custom filter) wstom filter

- 4. Please describe the steps to get the h(n) of this filter?
- (1). Given a frequency response needed by you.

  (5) Took the IDFT of the frequency response to get the impulse response.

- I truncated the impulse responsites M+1 Samples.
- and shifted ito the right by Mr. samples.
- @ Multiplied the truncated impulse response by a Hamming or Blackman window to get the filter bernel.

@ Took the DFT of the bernel to get the actual frequency regionse

**Review Card 16** 

Name: 3

1. Compare FIR and IIR filter:

	FIR	IIR
冲击响应 (是/否)有 限长度	是	否
负反馈(有/ 无)	礼	有
输出 y(n)与 (输入/输 出)有关	输入.	输入额头
需要计算的 参数	h(n)	A-B.
计算量	大	N'
线性相位(是/否)	是	否 (信被務

2. Assume that the input and output of a filter satisfies the following equation:

 $= \prod_{n=1}^{\infty} fittly_{(n)} + 4y_{(n-1)} + 6y_{(n-2)} = 7x_{(n)} + 8x_{(n-2)}$ 

(1). Please calculate the H(z) of the system:  

$$H(z) = \frac{7 + 4 + 2}{1 + 2 + 3 + 2}$$

(2). The recursive coefficients of the filter is:

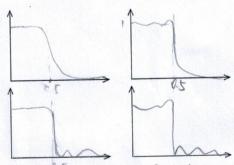
$$A = \{3, 5, 0, 4\}$$

$$B = \{1, 2, 3\}$$

(3) What Matlab function can be used to plot the frequency. response of a filter, given coefficients A and B? freqz

Review Card 17 188時 > 188時 Name: (0)

Draw the typical frequency responses of the following low-pass IIR filters: Butterworth, Chebyshev Type I, Checbyshev Type II and Elliptic filters (assuming a cut-off of 0.5)



A. Which has the flattest response? Butterwart

B. Which has the fastest roll-off? Zuptu

C. Which has ripples in pass-band? Cheby L Hubtic

D. What are the Matlab functions for the four types of filters, respectively? butter, chebyl, cheby, ellip

E. After getting the A and B coefficients by using one of the above functions, Xiaming used them to filter input signal x immediately, do you think it is OK? 100

F. If no, what step do you think Xiaoming missed?