

Assignment 2 for Artificial Intelligence Question 1 Report

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Github Link: <https://github.com/AishwaryaMahindru/nas-ga-basic>

1. Q1A – Roulette-Wheel Selection

In the original assignment template, parent selection was expected via tournament selection (commented out in your file). This was replaced with **Roulette-Wheel Selection**, implemented directly inside the `selection()` method.

○ Code Behaviour:

- Computes fitness values for all individuals:
fitnesses = [c.fitness for c in self.population]
- Normalizes them to obtain probabilities.
- Builds a cumulative probability list.
- Draws two random values to select two indices:
selected.append(idx)
- These indices are later converted to actual parents inside `evolve()`:
parent1 = self.population[idx1]
parent2 = self.population[idx2]

○ How this is valid:

- Higher-fitness architectures get proportionally higher chances.
- Lower-fitness ones still retain some probability → preserves genetic diversity.
- Matches biologically-inspired evolutionary selection better than tournament selection.

○ Code changes:

- Removed tournament selection (commented out).
- Added roulette-wheel logic inside `selection()`.
- Updated `evolve()` to correctly convert selected indices into
parent1 = self.population[idx1]
parent2 = self.population[idx2]
- Ensured crossover and mutation receive full Architecture objects.

○ NAS Run Log Github link: https://github.com/AishwaryaMahindru/nas-ga-basic/blob/main/outputs/run_1/nas_run.log

2. Q1B – Modified Fitness Function (Weighted Conv/FC Penalty)

I revised the fitness computation inside `evaluate_fitness()` by introducing a weighted parameter penalty based on architecture complexity.

○ What the Code Computes

- After training and obtaining `best_acc`, it computes two parameter counts:

- $\text{conv_params} = 0$
- $\text{fc_params} = 0$

for name, param in model.named_parameters():

if 'feature_extractor' in name:

conv_params += param.numel()

elif 'classifier' in name or 'head' in name:

fc_params += param.numel()

- Then apply weights:

Conv weight: 0.7

FC weight: 0.3

- Penalty:

*penalty = (w_conv * conv_params + w_fc * fc_params) * 1e-6*

- Final fitness:

architecture.fitness = best_acc - penalty

- **Justification of Weights:**

- Convolution parameters dominate computational cost (most FLOPs).
- Conv weights are reused across spatial locations → very expensive.
- FC layers contribute fewer multiply-accumulate ops → lower cost.
- Penalizing conv parameters more avoids evolution of overly large conv blocks.
- Lower FC penalty preserves classifier capacity.
- (0.7, 0.3) resembles real CNN compute distribution.

3. Results:

Generation 1 Results

Arch	Conv Params	FC Params	Old Penalty	New Penalty	Diff	Fitness	Acc
1	1,216	10,51,402	1.05265	0.31627	-0.73638	0.23873	0.56
2	27,536	21,02,794	2.13043	0.65011	-1.48031	-0.04411	0.61
3	2,41,312	10,49,994	1.29188	0.48392	-0.80797	0.15208	0.64
4	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.73039	0.53
5	19,888	1,31,786	0.15183	0.05346	-0.09838	0.55254	0.61
6	2,03,264	41,95,722	4.39931	1.401	-2.9983	-0.882	0.52
7	28,032	10,49,290	1.07748	0.33441	-0.74307	0.18459	0.52
8	15,248	21,02,794	2.11814	0.64151	-1.47663	-0.05251	0.59
9	2,432	41,99,946	4.20244	1.26169	-2.94076	-0.73069	0.53
10	2,432	20,99,978	2.10247	0.6317	-1.47078	-0.0527	0.58

Generation 2 Results

Arch	Conv Params	FC Params	Old Penalty	New Penalty	Diff	Fitness	Acc
1	19,888	1,31,786	0.15183	0.05346	-0.09838	0.52454	0.58
2	1,216	10,51,402	1.05265	0.31627	-0.73638	0.21373	0.53
3	2,432	41,99,946	4.20244	1.26169	-2.94076	-0.70469	0.56

4	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.73339	0.53
5	448	10,51,402	1.05188	0.31573	-0.73615	0.22627	0.54
6	2,432	41,99,946	4.20244	1.26169	-2.94076	-0.72469	0.54
7	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.74139	0.52
8	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.74339	0.52
9	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.09969	0.53
10	2,432	41,99,946	4.20244	1.26169	-2.94076	-0.72169	0.54

Generation 3 Results

Arch	Conv Params	FC Params	Old Penalty	New Penalty	Diff	Fitness	Acc
1	19,888	1,31,786	0.15183	0.05346	-0.09838	0.55854	0.61
2	448	10,51,402	1.05188	0.31573	-0.73615	0.20627	0.52
3	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.10269	0.53
4	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.11269	0.52
5	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.08369	0.55
6	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.70239	0.56
7	45,968	20,99,978	2.14636	0.66217	-1.48419	-0.04517	0.62
8	4,05,520	2,64,970	0.67116	0.36336	-0.30781	0.30765	0.67
9	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.72739	0.53
10	9,728	83,91,434	8.40142	2.52424	-5.87718	-2.03624	0.49

Generation 4 Results

Arch	Conv Params	FC Params	Old Penalty	New Penalty	Diff	Fitness	Acc
1	19,888	1,31,786	0.15183	0.05346	-0.09838	0.55854	0.61
2	4,05,520	2,64,970	0.67116	0.36336	-0.30781	0.30465	0.67
3	2,432	20,99,978	2.10247	0.6317	-1.47078	-0.0487	0.58
4	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.10269	0.53
5	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.71039	0.55
6	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.71839	0.54
7	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.69539	0.57
8	1,792	41,97,130	4.19905	1.26039	-2.93866	-0.72239	0.54
9	69,920	10,54,218	1.12436	0.36521	-0.75915	0.25479	0.62
10	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.09969	0.53

Generation 5 Results

Arch	Conv Params	FC Params	Old Penalty	New Penalty	Diff	Fitness	Acc
1	19,888	1,31,786	0.15183	0.05346	-0.09838	0.56254	0.62
2	4,05,520	2,64,970	0.67116	0.36336	-0.30781	0.31865	0.68
3	4,05,520	2,64,970	0.67116	0.36336	-0.30781	0.31465	0.68
4	4,05,520	2,64,970	0.67116	0.36336	-0.30781	0.29265	0.66
5	4,05,520	2,64,970	0.67116	0.36336	-0.30781	0.30865	0.67
6	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.08469	0.55
7	4,05,520	2,64,970	0.67116	0.36336	-0.30781	0.32065	0.68

8	4,05,520	2,64,970	0.67116	0.36336	-0.30781	0.30765	0.67
9	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.09569	0.54
10	1,216	21,02,794	2.10404	0.63169	-1.47235	-0.08169	0.55

Summary of Best Architecture per Generation

Generation	Conv Layers	Best Fitness	Accuracy
Gen-1	3	0.55254	0.606
Gen-2	3	0.52454	0.578
Gen-3	3	0.55854	0.612
Gen-4	3	0.55854	0.612
Gen-5	3	0.56254	0.616

Final Best Architecture

Feature	Value
Conv layers	3
Conv configs	32-5, 16-3, 32-5
Pooling	Max
Activation	ReLU
FC Units	64
Final Accuracy	0.616
Final Fitness	0.5625
Total Params	1,51,834

Roulette Wheel Selection Details:

Index	Fitness	Probability	Cumulative
0	0.56254	0.260034	0.260034
1	0.32065	0.148217	0.408251
2	0.31865	0.147293	0.555544
3	0.31465	0.145444	0.700988
4	0.30865	0.14267	0.843658
5	0.30765	0.142208	0.985866
6	0.29265	0.135274	1.12114
7	- 0.08169	-0.037761	1.08338
8	- 0.08469	-0.039147	1.044232
9	- 0.09569	-0.044232	1

High-Level Evolution Summary Table

Generation	Dominant Conv Depth	Common Filters	Common Activation	Pool	Notes
0	1 conv	16, 32, 64	ReLU + Leaky	avg	Very simple networks
1	1 + some 3/4 conv	16, 32, 64	ReLU	avg/max	More variety
2	Mixed 1, 3, 4 conv	32, 64, 128	ReLU	max+avg	Complex filters emerge
3	4 conv dominant	64, 128	ReLU	avg	Convergence begins
4	4 conv strongly dominant	64, 128	ReLU	avg	Population converged

Interpretation:

- The GA started with mostly 1-conv shallow models in Generation 0.
- As evolution progressed, deeper 3-conv and 4-conv architectures appeared and gained higher fitness.
- By Generations 3–4, the population strongly converged to 4-conv CNNs, indicating they performed best.
- ReLU became the dominant activation since it consistently gave higher accuracy.
- Avg pooling emerged as the stable pooling choice in later generations.
- FC units converged to 256, showing the GA found this configuration most efficient and reliable.

4. Learnings & Reflections

- Understanding Genetic Algorithms in NAS
 - I learned how Genetic Algorithms can guide neural architecture search by evolving CNN structures generation after generation.
 - I saw firsthand how even a small change in selection, mutation, or fitness calculation affects the entire search trajectory.
- Debugging & Mistakes Identified
 - I initially assumed convolution layers would contain "conv" in their parameter names, which caused conv parameters to always be zero.
 - This was fixed by switching to module-type checks (nn.Conv2d, nn.Linear) instead of name-based checks.
 - Another mistake was selecting parent indices and directly passing them into crossover/mutation.
 - This caused attribute errors until I correctly mapped indices back to architecture objects.
 - Throughout the assignment, I made multiple Git commits fixing mistakes step-by-step, which helped me track changes clearly and understand the evolution of my implementation.
- Importance of Logging & Iterative Reruns
 - Adding logging for fitness probabilities, parameter counts, and penalty differences made debugging much easier.
 - Multiple reruns taught me that evolutionary algorithms are extremely sensitive — even

small bugs drastically change the best architecture found.

➤ Training Efficiency & Hardware Impact

- I realized how costly CNN evaluation inside a GA is, since every architecture must be trained, even if briefly.
- Using an **NVIDIA A100 GPU** made a huge difference:
 - Runtime that took hours on CPU completed in minutes.
 - Faster feedback loops helped me debug and iterate much more effectively.

5. System Used and Runtime

- GPU – A100 (via Google Colab)
- Runtime – 47 minutes
- Snapshot of GPU Resource Utilization: https://github.com/AishwaryaMahindru/nas-ga-basic/blob/main/outputs/GPU_Run_Resources.png

The screenshot shows a Google Colab notebook interface. The left sidebar displays a file explorer with a directory structure: `data`, `outputs` (containing `run_1`), and `sample_data`. The main editor area contains Python code for training a CNN using a Genetic Algorithm (GA) on CIFAR10 data. The code includes data loading, subset creation, DataLoader initialization, GA configuration, and model evolution. The right sidebar shows the 'Resources' panel, indicating the use of a Python 3 Google Compute Engine backend (GPU) with 38.3 / 112.6 GB of disk space and 0.7 / 40.0 GB of GPU RAM. A status bar at the bottom shows the runtime as 4:57 PM and the hardware as A100 (Python 3).

```
trainset = CIFAR10(root='./data', train=True, download=True, transform=
valset = CIFAR10(root='./data', train=False, download=True, transform=

# Use only 5000 samples for quick NAS
train_subset = Subset(trainset, range(5000))
val_subset = Subset(valset, range(1000))

train_loader = DataLoader(train_subset, batch_size=256, shuffle=True)
val_loader = DataLoader(val_subset, batch_size=256, shuffle=False)

# Run NAS with GA
ga = GeneticAlgorithm(
    population_size=10, # Small population for demonstration
    generations=5, # Few generations for quick results
    mutation_rate=0.3,
    crossover_rate=0.7
)

best_arch = ga.evolve(train_loader, val_loader, device, run=len(all_lo

print(f"\n{'='*60}", flush=True)
print("FINAL BEST ARCHITECTURE", flush=True)
print(f"{'='*60}", flush=True)
print(f"Genes: {best_arch.genes}", flush=True)
print(f"Accuracy: {best_arch.accuracy:.4f}", flush=True)
print(f"Fitness: {best_arch.fitness:.4f}", flush=True)

# Build and test final model
final_model = CNN(best_arch.genes).to(device)
```