

(5.1) $F(\vec{q}, \vec{p})$, $G(\vec{q}, \vec{p})$ constants of motion \Rightarrow
 $\Rightarrow [F, H] = 0$, $[G, H] = 0$

$\frac{d}{dt} [F, G] \stackrel{?}{=} 0$

Jacobi's identity

\downarrow
 $\frac{d}{dt} [F, G] = [[F, G], H] = -[H, [F, G]] =$
 $= [F, \overset{\circ}{\cancel{[G, H]}}] + [\overset{\circ}{\cancel{G}}, [H, F]] = 0 \quad \square$

5.2 (1)

$$H = p_1^2 + \frac{p_2^2}{q_1} + \frac{(p_4 - q_4)^2}{q_1 \cos q_2} + \frac{p_3^2}{q_1 q_4 \cos q_2} - \frac{\sin^2 q_2}{q_1} + q_1^2$$

(1.1) q_3 cyclic $\Rightarrow p_3 = \text{constant} \equiv a_3$

$$H = p_1^2 + q_1^2 + \frac{1}{q_1} \left[p_2^2 - \sin^2 q_2 + \frac{1}{\cos q_2} \left((p_4 - q_4)^2 + \frac{a_3^2}{q_4} \right) \right]$$

$\underbrace{\hspace{15em}}_{a_1}$
 $\underbrace{\hspace{10em}}_{a_2}$
 $\underbrace{\hspace{5em}}_{a_4}$

• $[a_1, a_3] = \sum_k \left(\frac{\partial a_1}{\partial q_k} \frac{\partial a_3}{\partial p_k} - \frac{\partial a_1}{\partial p_k} \frac{\partial a_3}{\partial q_k} \right) \stackrel{0 \text{ for } k \neq 3}{=} 0$

$= \frac{\partial q_1}{\partial q_3} \frac{\partial a_1}{\partial p_3} - \frac{\partial q_1}{\partial p_3} \frac{\partial a_1}{\partial q_3} = 0$ Trivial

• $[a_2, a_3] = 0$ trivial

• $[a_1, a_3] = 0$ trivial

⋮

We cannot find any new non-trivial constants

$$(1.2) \quad H = \frac{1}{2} \left(\underbrace{\frac{p_1}{q_1^2} + k q_1}_{a_1 = \text{constant}} \right)^2 + \left(\frac{p_1}{q_1^2} + k q_1 \right) q_3 t + \frac{p_3^2}{2} + (p_2 + B q_3)^2$$

$$H = \frac{1}{2} a_1^2 + a_1 q_3 t + \frac{p_3^2}{2} + (p_2 + B q_3)^2$$

q_2 is cyclic $\Rightarrow p_2 = \text{constant} \equiv a_2$

$$H = \frac{a_1^2}{2} + a_1 q_3 t + \frac{p_3^2}{2} + (a_2 + B q_3)^2$$

Let's try to use Poisson's theorem:

$$[a_1, a_2] = \sum_k \left(\frac{\partial a_1}{\partial q_k} \frac{\partial a_2}{\partial p_k} - \frac{\partial a_2}{\partial q_k} \frac{\partial a_1}{\partial p_k} \right) = 0 \quad \text{trivial}$$

No new constants.

5.3

$$T = \sum_{i=1}^n f_i(q_i) \dot{q}_i^2$$

$$V = \sum_{i=1}^n V_i(q_i)$$

a) \mathcal{L} ?

$$\mathcal{L} = \sum_i \left(f_i(q_i) \dot{q}_i^2 - V_i(q_i) \right)$$

b) H ?

$$p_i = \frac{\partial \mathcal{L}}{\partial \dot{q}_i} = 2 f_i(q_i) \dot{q}_i \Rightarrow \dot{q}_i = \frac{p_i}{2 f_i(q_i)}$$

$$H = \sum_i p_i \dot{q}_i - \mathcal{L} = \sum_i \left[\frac{p_i^2}{2 f_i(q_i)} - f_i(q_i) \frac{p_i^2}{4 f_i^2(q_i)} + V_i(q_i) \right] =$$

$$= \sum_i \left[\frac{p_i^2}{4 f_i(q_i)} + V_i(q_i) \right] = \sum_i H_i$$

$$H_i = \frac{p_i^2}{4 f_i(q_i)} + V_i(q_i)$$

c) Each H_i is conserved separately. H is also conserved.

5.4

$$u(q, p, t) = \ln(p + im\omega q) - i\omega t, \quad \omega = \sqrt{\frac{k}{m}}$$

$$\parallel \\ k = \omega^2 m$$

$$H = \frac{p^2}{2m} + \frac{1}{2} k q^2$$

$$[u, H] = \frac{\partial u}{\partial q} \frac{\partial H}{\partial p} - \frac{\partial H}{\partial q} \frac{\partial u}{\partial p} =$$

$$= \frac{im\omega}{p + im\omega q} \cdot \frac{p}{m} - kq \frac{1}{p + im\omega q} =$$

$$= \frac{i\omega p - kq}{p + im\omega q} = \frac{i\omega p - \omega^2 m q}{p + im\omega q} =$$

$$= i\omega \frac{p - \frac{\omega m q}{i}}{p + im\omega q} = i\omega \frac{p + im\omega q}{p + im\omega q} =$$

$$= i\omega$$

$$\frac{du}{dt} = [u, H] + \frac{\partial u}{\partial t} = i\omega - i\omega = 0 \quad \square$$

5.5

$$Q = p + i a q \quad ; \quad P = \frac{p - i a q}{2 i a}$$

$$a) [Q, P] = \frac{\partial Q}{\partial q} \frac{\partial P}{\partial p} - \frac{\partial P}{\partial q} \frac{\partial Q}{\partial p} = \frac{i a}{2 i a} - \left(-\frac{1}{2} \cdot 1 \right) = 1 \hbar$$

$$b) F_2(q, P, t) ?$$

$$p = \frac{\partial F_2}{\partial q} \quad Q = \frac{\partial F_2}{\partial P} \quad \text{Implicit transformation eq.s.}$$

We write p & Q as a function of q & P .

$$\textcircled{1} \quad \frac{\partial F_2}{\partial q} = p = 2 i a P + i a q = i a (2 P + q)$$

$$\textcircled{2} \quad \frac{\partial F_2}{\partial P} = Q = p + i a q = 2 i a P + i a q + i a q = 2 i a (P + q)$$

$$\textcircled{1} \Rightarrow F_2 = i a \left(2 P q + \frac{q^2}{2} \right) + f(P) \Rightarrow$$

$$\Rightarrow \frac{\partial F_2}{\partial P} = i a (2 q) + \frac{d f(P)}{d P} \stackrel{\textcircled{2}}{=} 2 i a P + 2 i a q$$

$$\Rightarrow \frac{d f}{d P} = 2 i a P \Rightarrow f = i a P^2$$

$$\Rightarrow \boxed{F_2 = i a \left(\frac{q^2}{2} + P^2 + 2 P q \right)}$$

$$c) \quad H = \frac{p^2}{2m} + \frac{1}{2} k q^2$$

We set Q & P as functions of q, p .

$$① \quad Q = p + i a q \Rightarrow Q = p + i a q$$

$$② \quad P = \frac{p - i a q}{2 i a} \Rightarrow 2 i a P = p - i a q$$

$$① + ② \Rightarrow p = \frac{Q}{2} + i a P$$

$$① - ② \Rightarrow Q - 2 i a P = 2 i a q \Rightarrow q = \frac{Q}{2 i a} - P$$

$$p^2 = \frac{Q^2}{4} - a^2 P^2 + i a Q P$$

$$q^2 = -\frac{Q^2}{4 a^2} + P^2 - \frac{Q P}{i a}$$

$$\boxed{\tilde{H} = \frac{1}{2m} \left(\frac{Q^2}{4} - a^2 P^2 + i a Q P \right) + \frac{k}{2} \left(P^2 - \frac{Q^2}{2 a^2} - \frac{Q P}{i a} \right)}$$

$$d) \quad a = \sqrt{m k}$$

$$\boxed{\tilde{H}} = \frac{\cancel{Q^2}}{\cancel{8m}} - \frac{\cancel{m k} P^2}{2m} + \frac{i \sqrt{m k} Q P}{2m} + \frac{\cancel{k} P^2}{2} - \frac{\cancel{k} Q^2}{\cancel{8 m k}} - \frac{k}{2} \frac{Q P}{i \sqrt{m k}}$$

$$= i \sqrt{\frac{k}{m}} \frac{Q P}{2} + i \sqrt{\frac{k}{m}} \frac{Q P}{2} = i \sqrt{\frac{k}{m}} Q P$$

$$\left. \begin{aligned} \dot{P} &= -\frac{\partial \tilde{H}}{\partial Q} = -i\sqrt{\frac{k}{m}} P \\ \dot{Q} &= \frac{\partial \tilde{H}}{\partial P} = i\sqrt{\frac{k}{m}} Q \end{aligned} \right\} \sqrt{\frac{k}{m}} \equiv \omega$$

$$\frac{dP}{dt} = -i\omega P \Rightarrow \int \frac{dP}{P} = \int -i\omega dt \Rightarrow \log \frac{P}{P_0} = -i\omega(t-t_0)$$

$$\Rightarrow P = P_0 e^{-i\omega(t-t_0)}$$

$$\dots \Rightarrow Q = Q_0 e^{i\omega(t-t_0)}$$

5.6

$$Q = \alpha \frac{p}{x}$$

$$P = \beta x^2$$

necessary & sufficient

when is it canonical? We impose $[Q, P] = 1$

$$[Q, P] = \frac{\partial Q}{\partial x} \frac{\partial P}{\partial p} - \frac{\partial P}{\partial x} \frac{\partial Q}{\partial p} = -\frac{\alpha \beta}{x^2} \cdot 0 - 2\beta x \frac{\alpha}{x} = 1$$

$$\Rightarrow \boxed{\alpha \beta = -\frac{1}{2}} \Leftrightarrow \beta = -\frac{1}{2\alpha} \Rightarrow$$

$$\Rightarrow \boxed{Q = \alpha \frac{p}{x}, P = -\frac{x^2}{2\alpha}}$$

Generating function:

$$\rightarrow F_1(q, Q)? \quad p = \frac{Qx}{\alpha}, \quad P = -\frac{x^2}{2\alpha}$$

$$p = \frac{\partial F_1}{\partial x} = \frac{Qx}{\alpha} \Rightarrow F_1 = \frac{Qx^2}{2\alpha} + f(Q)$$

$$P = -\frac{\partial F_1}{\partial Q} = -\frac{x^2}{2\alpha} - \frac{\partial f}{\partial Q} = -\frac{x^2}{2\alpha} \Rightarrow f = 0 \text{ is OK}$$

$$\boxed{F_1 = \frac{Qx^2}{2\alpha}}$$

5.6

$$H = \frac{p_\phi^2}{4ma^2(1-\cos\phi)} - m a g (1-\cos\phi)$$

$$a) \quad s = -4a \cos(\phi/2) \quad p_s = \frac{p_\phi}{2a \sin(\phi/2)}$$

$$\begin{aligned} [s, p_s] &= \frac{\partial s}{\partial \phi} \frac{\partial p_s}{\partial p_\phi} - \frac{\partial p_s}{\partial \phi} \frac{\partial s}{\partial p_\phi} = \\ &= 4a \sin \frac{\phi}{2} \cdot \frac{1}{2} - \frac{1}{2a \sin \frac{\phi}{2}} = 0 = \\ &= 1 \quad \square. \end{aligned}$$

$$b) \quad F_2(\phi, p_s)?$$

$$p_\phi = \frac{\partial F_2}{\partial \phi} \quad s = \frac{\partial F_2}{\partial p_s}$$

$$\begin{aligned} \frac{\partial F_2}{\partial \phi} = p_\phi &= 2a p_s \sin \frac{\phi}{2} \Rightarrow F_2 = \int d\phi \, 2a p_s \sin \frac{\phi}{2} + f(p_s) \\ &= -4a p_s \cos \frac{\phi}{2} + f(p_s) \end{aligned}$$

$$s = \frac{\partial F_2}{\partial p_s} = -4a \cos \frac{\phi}{2} + \frac{df}{dp_s} = -4a \cos \frac{\phi}{2} \Rightarrow$$

$$\Rightarrow f(p_s) = \text{constant (or 0)}.$$

$$\boxed{F_2 = -4a p_s \cos \frac{\phi}{2}}$$

$$b2) F_1(s, \phi)$$

$$p_\phi = \frac{\partial F_1}{\partial \phi}$$

$$p_s = - \frac{\partial F_1}{\partial s}$$

$$p_\phi = 2a \underline{p_s} \sin \frac{\phi}{2} \quad \text{but this not expressed as a function of } s!!$$

$$c) H(s, p_s) ?$$

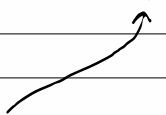
$$p_\phi = 2a p_s \sin \frac{\phi}{2} \Rightarrow p_\phi^2 = 4a^2 p_s^2 \sin^2 \frac{\phi}{2}$$

$$\text{Remember! } \sin \frac{\phi}{2} = \pm \sqrt{\frac{1 - \cos \phi}{2}} \Rightarrow 1 - \cos \phi = 2 \sin^2 \frac{\phi}{2}$$

$$H = \frac{p_\phi^2}{4ma^2(1 - \cos \phi)} - m a g (1 - \cos \phi) =$$

$$= \frac{4a^2 p_s^2 \sin^2 \frac{\phi}{2}}{4m a^2 2 \sin^2 \frac{\phi}{2}} - m a g \frac{2 \sin^2 \phi}{2} =$$

$$= \frac{p_s^2}{2m} - m a g 2 \left(1 - \frac{s^2}{4^2 a^2}\right) = \frac{p_s^2}{2m} + \frac{m g s^2}{8a} + C$$



$$\cos \frac{\phi}{2} = \frac{s}{-4a} \Rightarrow \cos^2 \frac{\phi}{2} = \frac{s^2}{4^2 a^2} \Rightarrow \sin^2 \frac{\phi}{2} = 1 - \frac{s^2}{4^2 a^2}$$

↳ from the given transformation