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# **Vector Calculus**

## **Fifth Edition**

### **Chapter 2:**

### **Differentiation**

#### 2.4 Introduction to Paths and Curves

## 2.4 Introduction to Paths

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### Key Points in this Section.

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1. A *path* in  $\mathbb{R}^3$  is a map  $\mathbf{c}$  of an interval  $[a, b]$  to  $\mathbb{R}^3$ . The *endpoints* of the path are the points  $\mathbf{c}(a)$  and  $\mathbf{c}(b)$ . The associated geometric curve  $C$  is the set of image points  $\mathbf{c}(t)$  as  $t$  ranges from  $a$  to  $b$ . We say  $\mathbf{c}$  is a *parametrization* of  $C$ . Paths in the plane are similar (leave off the last component).
2. A particle on the rim of a rolling circle of radius 1 traces out a path called a *cycloid*:

$$\mathbf{c}(t) = (t - \sin t, 1 - \cos t).$$

3. If a path  $\mathbf{c}$  is differentiable, its *velocity* is defined to be

$$\mathbf{c}'(t) = \lim_{h \rightarrow 0} \frac{\mathbf{c}(t+h) - \mathbf{c}(t)}{h} = x'(t)\mathbf{i} + y'(t)\mathbf{j} + z'(t)\mathbf{k},$$

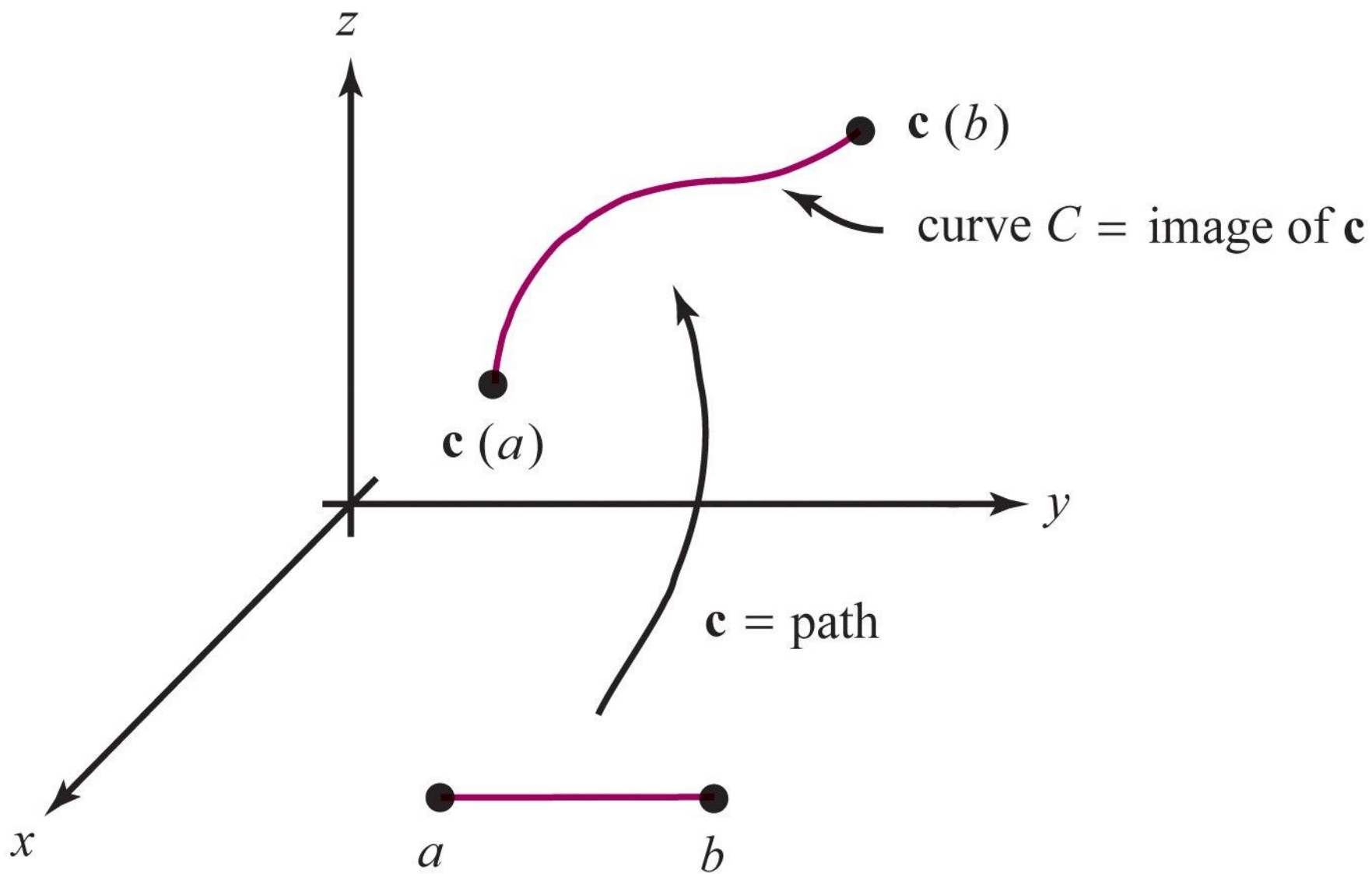
where  $\mathbf{c}(t)$  has components  $(x(t), y(t), z(t))$ .

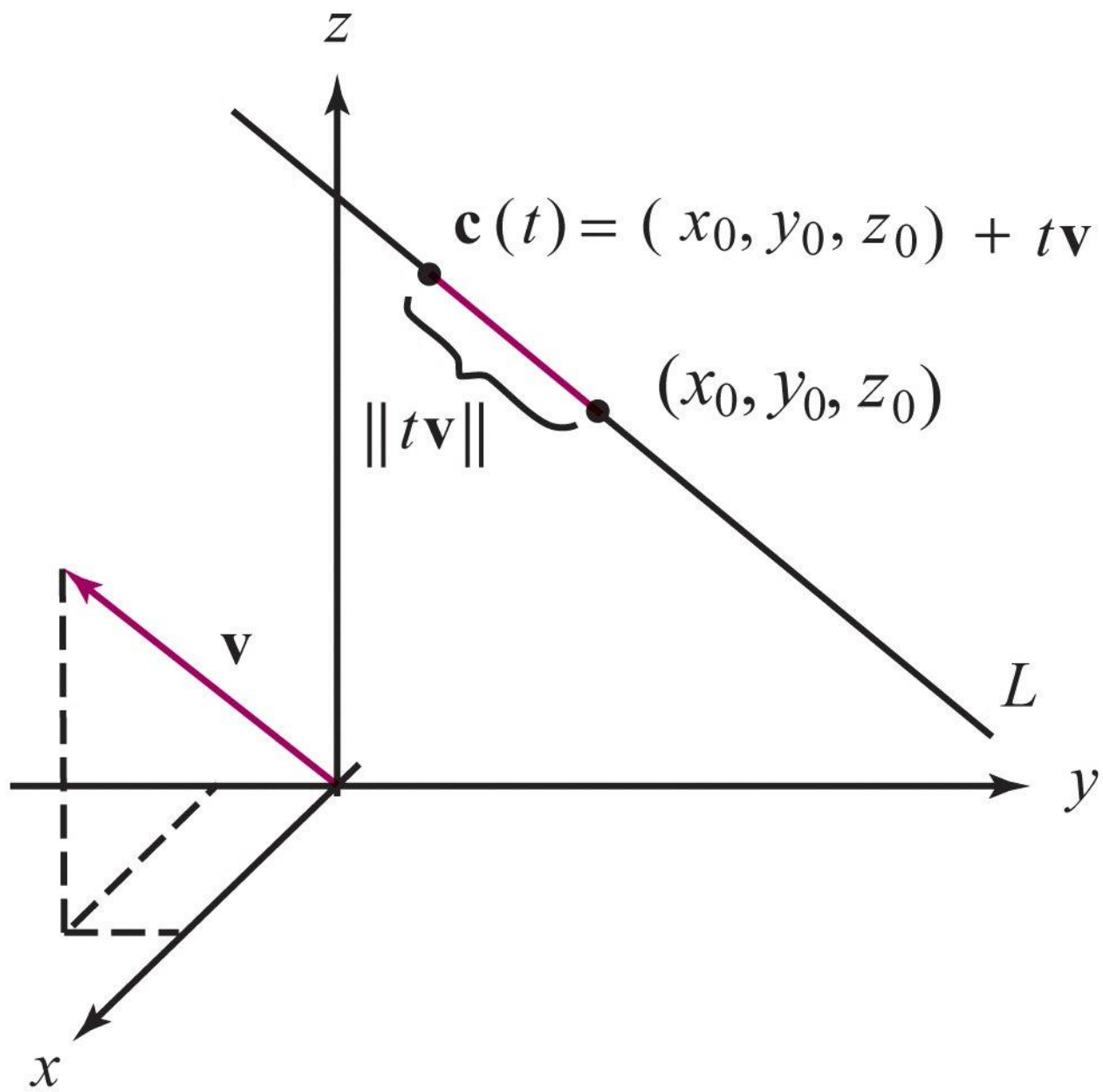
4. The vector  $\mathbf{c}'(t_0)$  is tangent to the path at the point  $\mathbf{c}(t_0)$ . The ***tan-  
gent line*** at this point is

$$\ell(t) = \mathbf{c}(t_0) + (t - t_0)\mathbf{c}'(t_0).$$

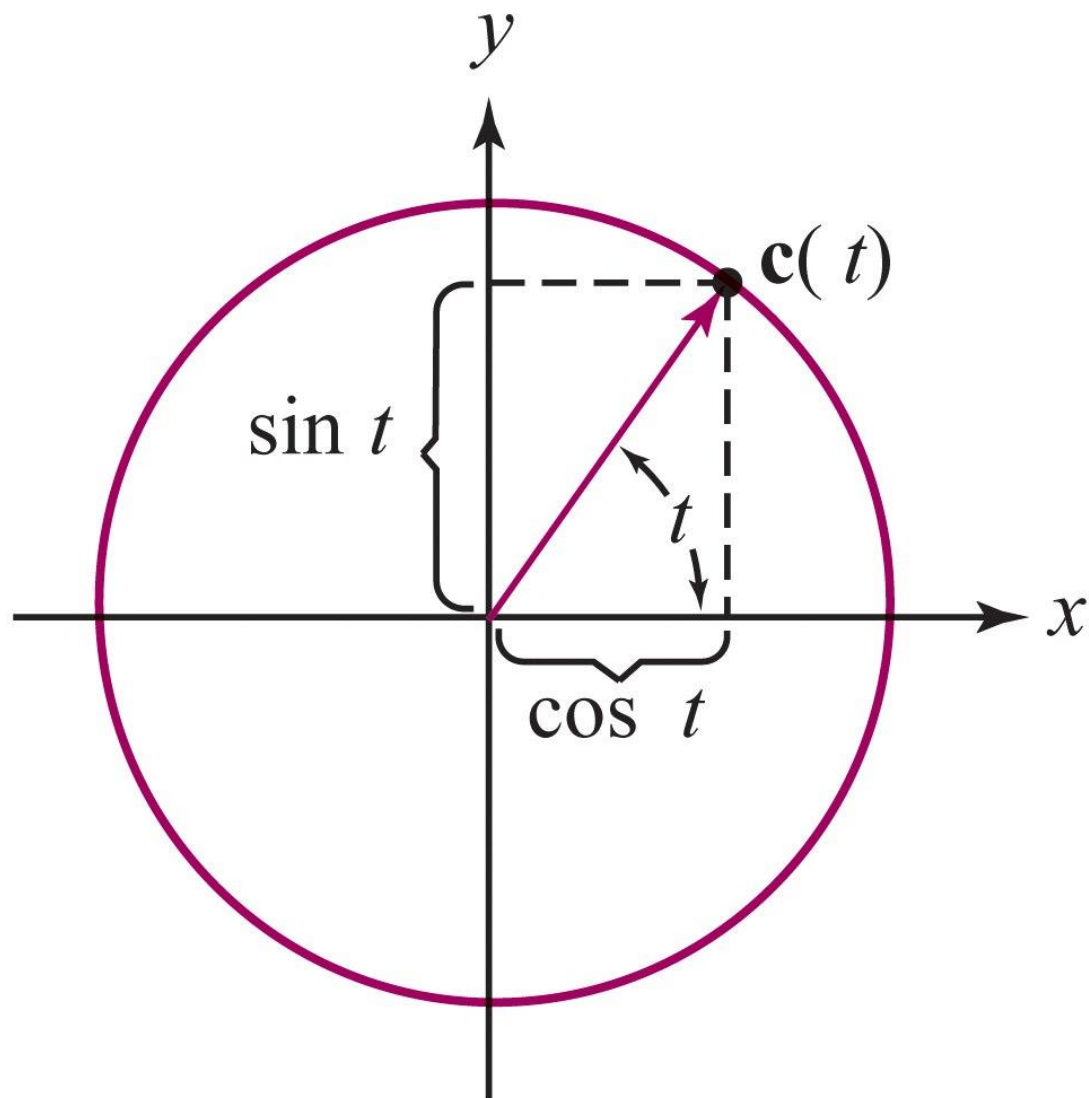
**Paths and Curves** A *path* in  $\mathbb{R}^n$  is a map  $\mathbf{c}: [a, b] \rightarrow \mathbb{R}^n$ ; it is a *path in the plane* if  $n = 2$  and a *path in space* if  $n = 3$ . The collection  $C$  of points  $\mathbf{c}(t)$  as  $t$  varies in  $[a, b]$  is called a *curve*, and  $\mathbf{c}(a)$  and  $\mathbf{c}(b)$  are its *endpoints*. The path  $\mathbf{c}$  is said to *parametrize* the curve  $C$ . We also say  $\mathbf{c}(t)$  *traces out*  $C$  as  $t$  varies.

If  $\mathbf{c}$  is a path in  $\mathbb{R}^3$ , we can write  $\mathbf{c}(t) = (x(t), y(t), z(t))$  and we call  $x(t)$ ,  $y(t)$ , and  $z(t)$  the *component functions* of  $\mathbf{c}$ . We form component functions similarly in  $\mathbb{R}^2$  or, generally, in  $\mathbb{R}^n$ .

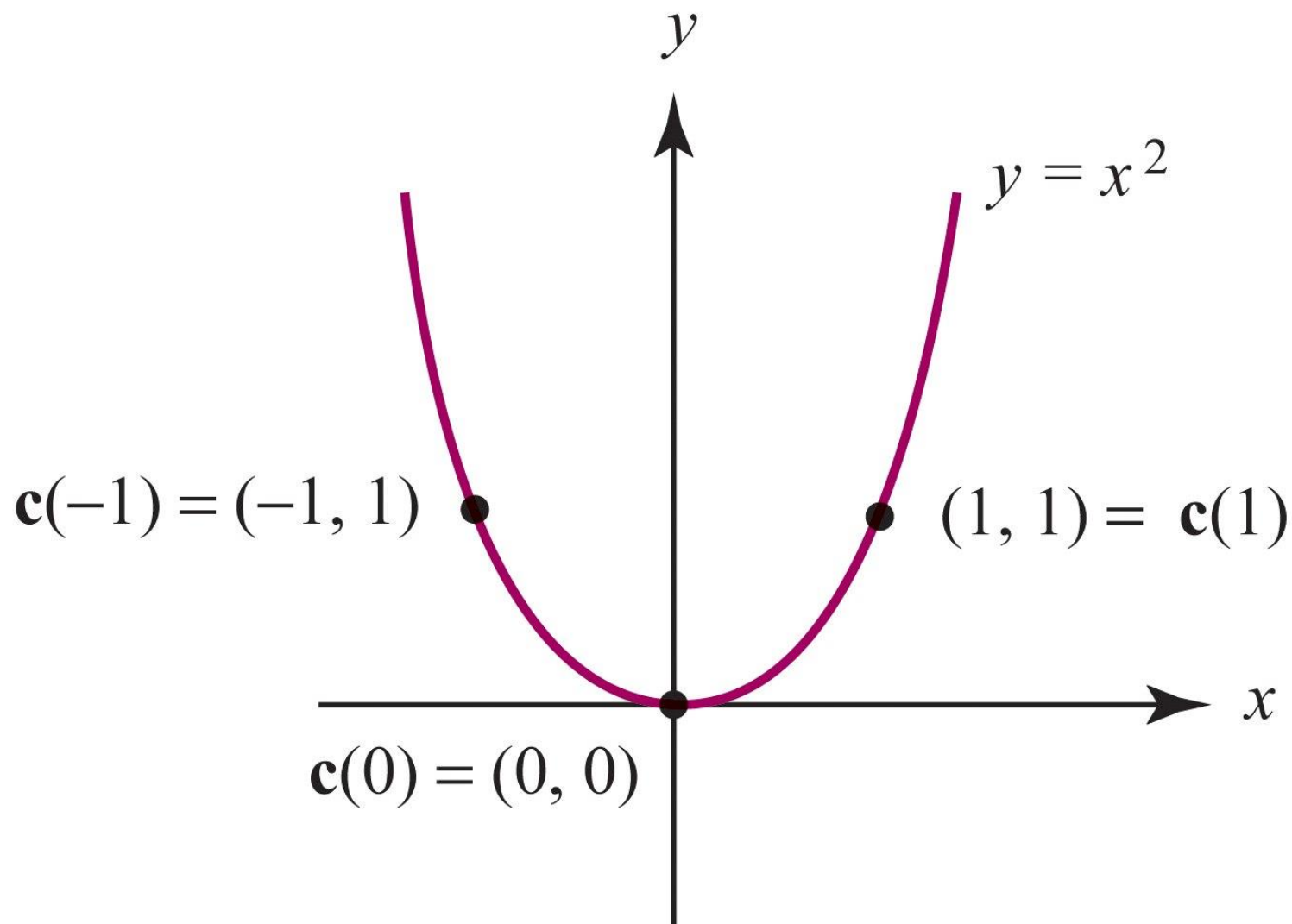




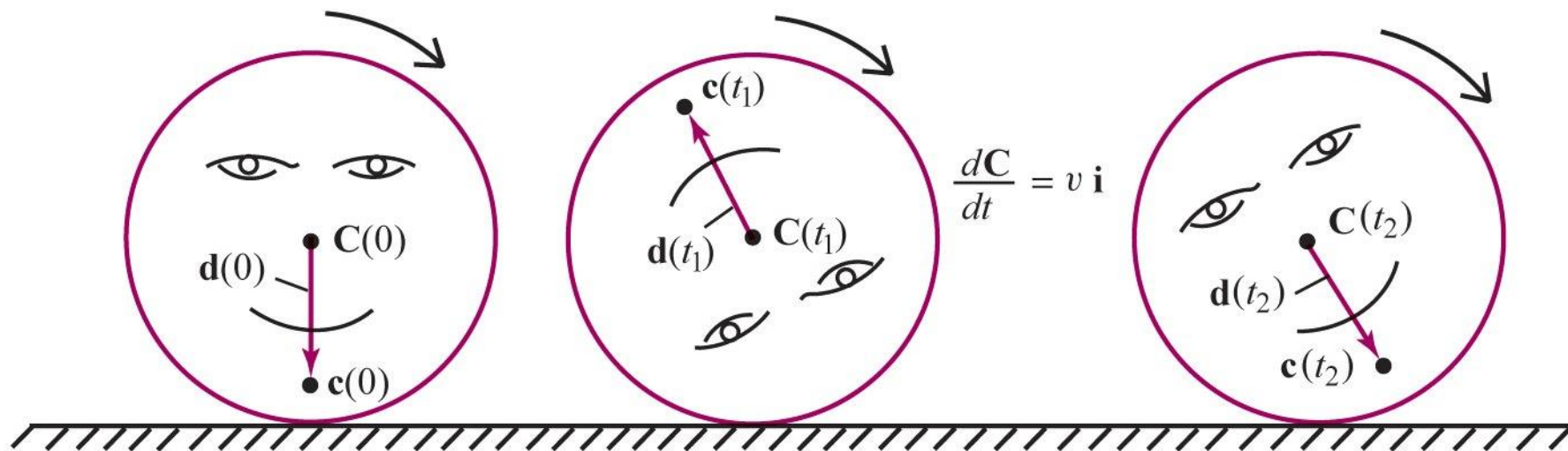
$$\mathbf{c}(t) = (\cos t, \sin t), \quad 0 \leq t \leq 2\pi$$



$$\mathbf{c}(t) = (t, t^2) \quad t \in \mathbb{R}$$





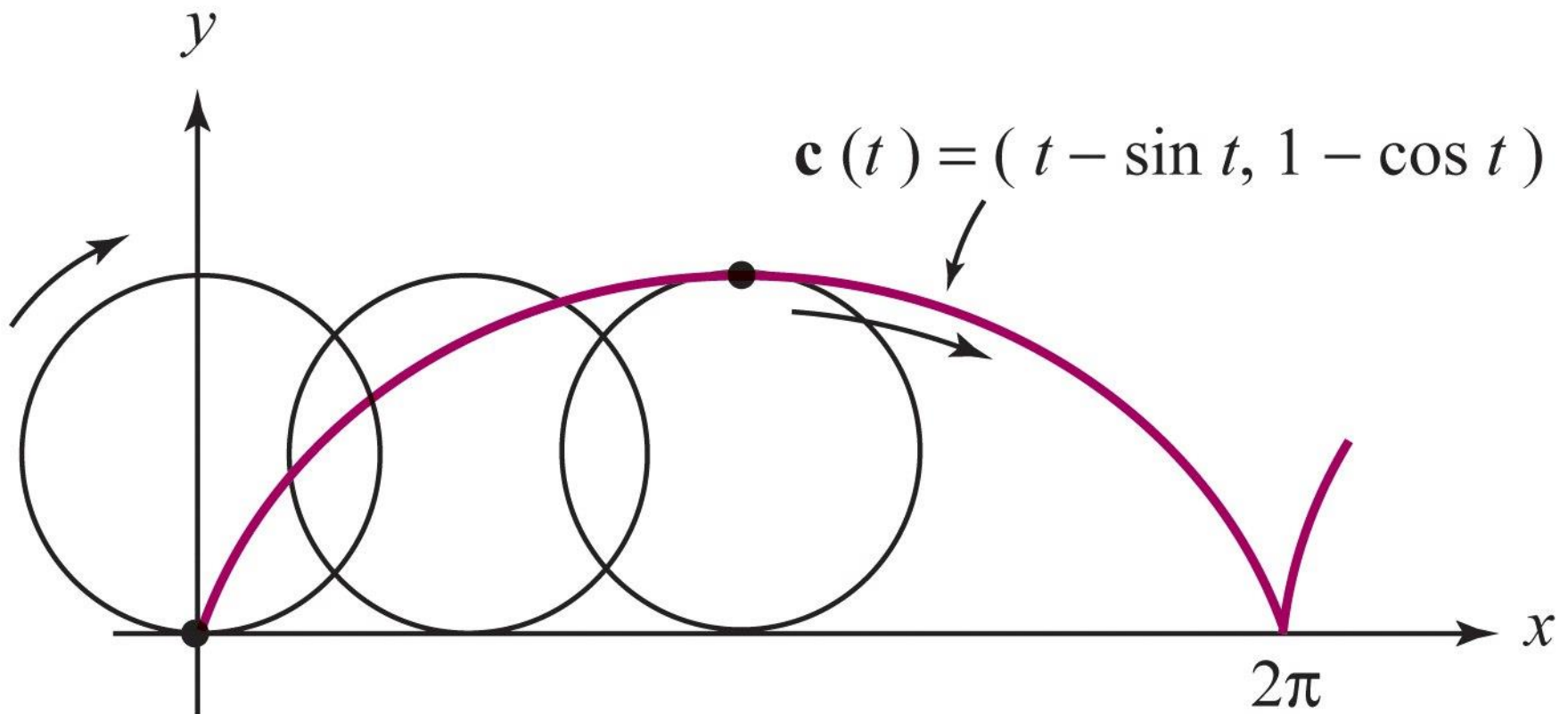


$$\mathbf{C}(t) = (vt, R) \quad \mathbf{d}(t) = r \left( \cos \left[ -\frac{v}{R} t - \frac{\pi}{2} \right] \mathbf{i} + \sin \left[ -\frac{v}{R} t - \frac{\pi}{2} \right] \mathbf{j} \right)$$

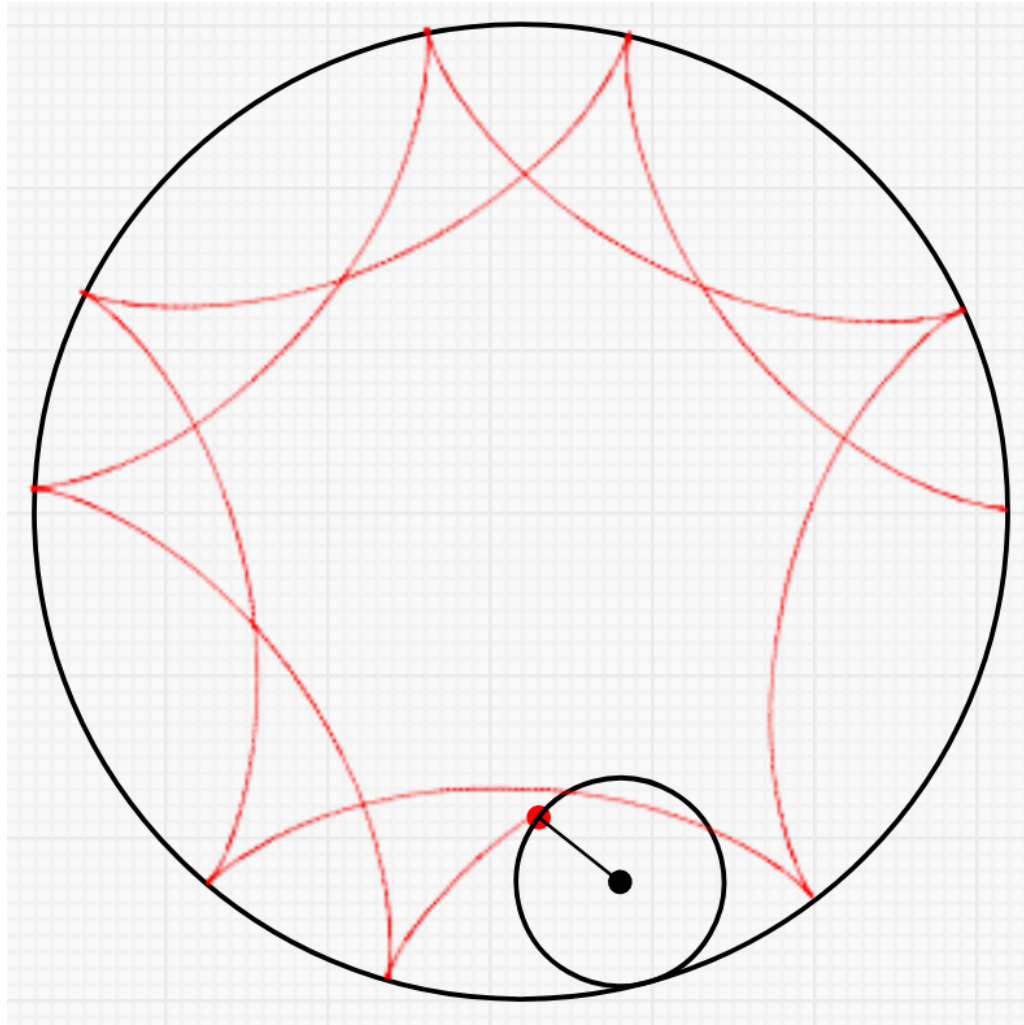
$$\mathbf{d}(t) = r \left( -\sin \frac{vt}{R} \mathbf{i} - \cos \frac{vt}{R} \mathbf{j} \right)$$

$$\mathbf{c}(t) = \left( vt - r \sin \frac{vt}{R}, R - r \cos \frac{vt}{R} \right)$$

# Cycloid



# Hypocycloid



**DEFINITION: Velocity Vector** If  $\mathbf{c}$  is a path and it is differentiable, we say  $\mathbf{c}$  is a *differentiable path*. The *velocity* of  $\mathbf{c}$  at time  $t$  is defined by<sup>3</sup>

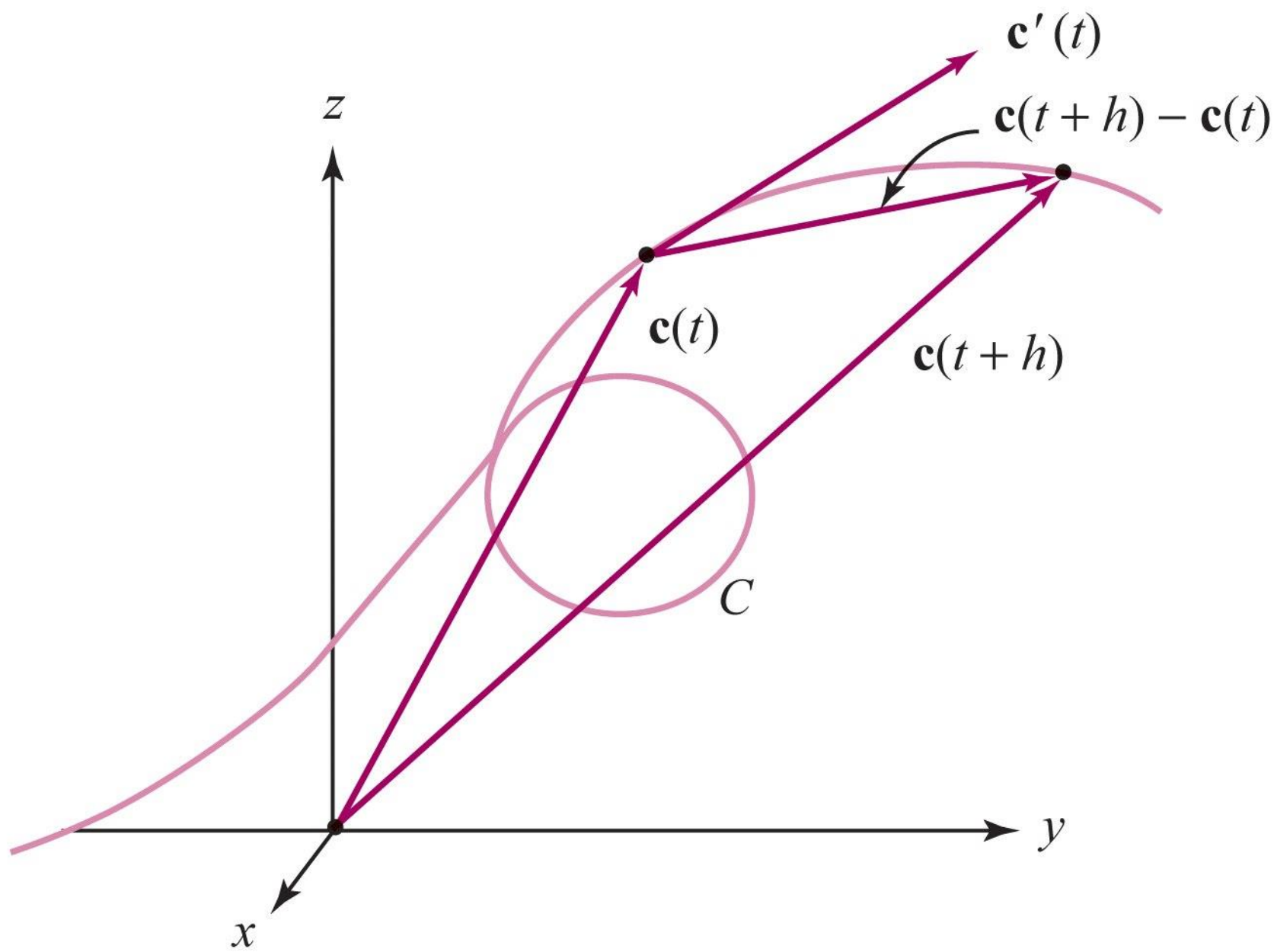
$$\mathbf{c}'(t) = \lim_{h \rightarrow 0} \frac{\mathbf{c}(t+h) - \mathbf{c}(t)}{h}.$$

We normally draw the vector  $\mathbf{c}'(t)$  with its tail at the point  $\mathbf{c}(t)$ . The *speed* of the path  $\mathbf{c}(t)$  is  $s = \|\mathbf{c}'(t)\|$ , the length of the velocity vector. If  $\mathbf{c}(t) = (x(t), y(t))$  in  $\mathbb{R}^2$ , then

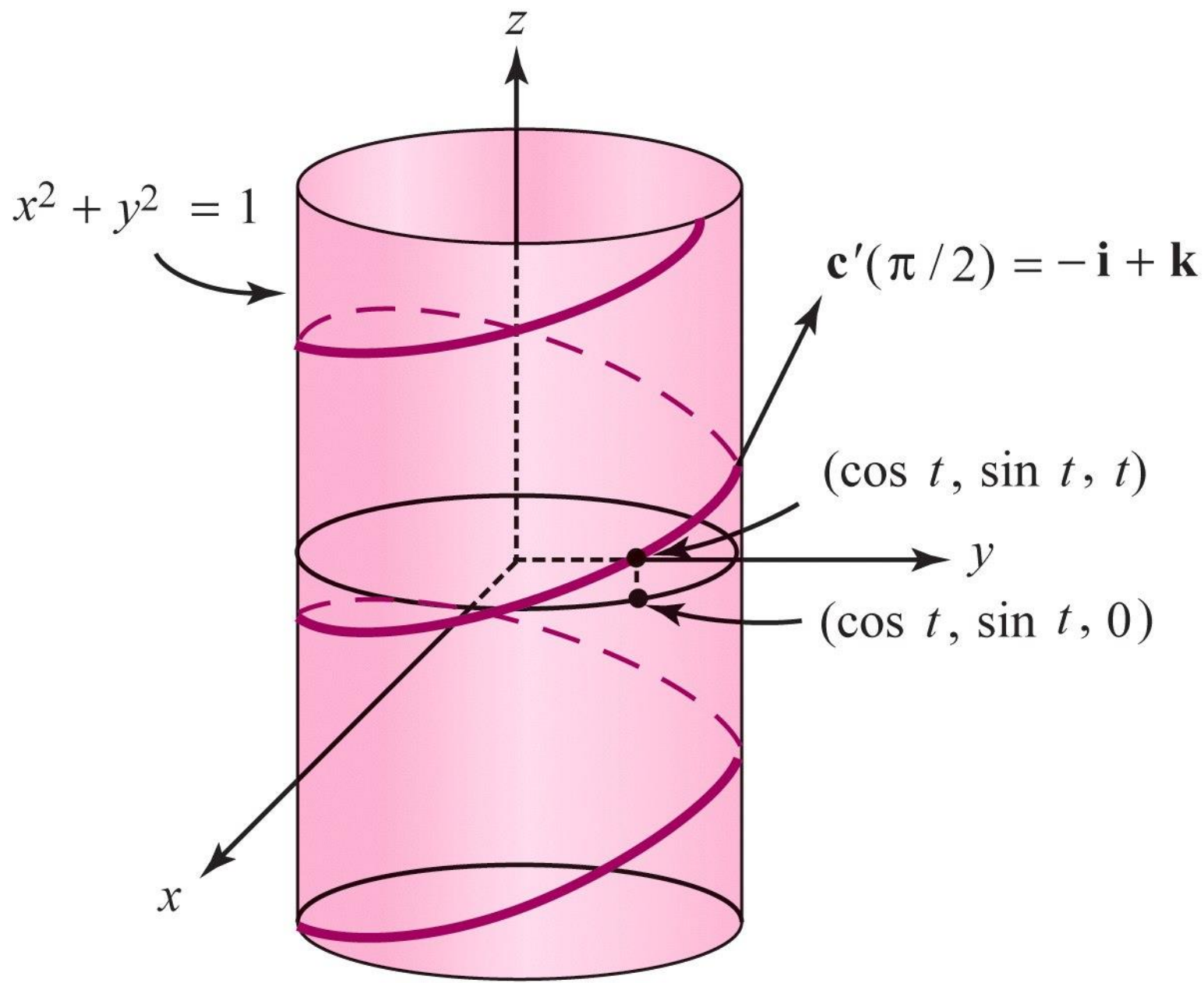
$$\mathbf{c}'(t) = (x'(t), y'(t)) = x'(t)\mathbf{i} + y'(t)\mathbf{j}$$

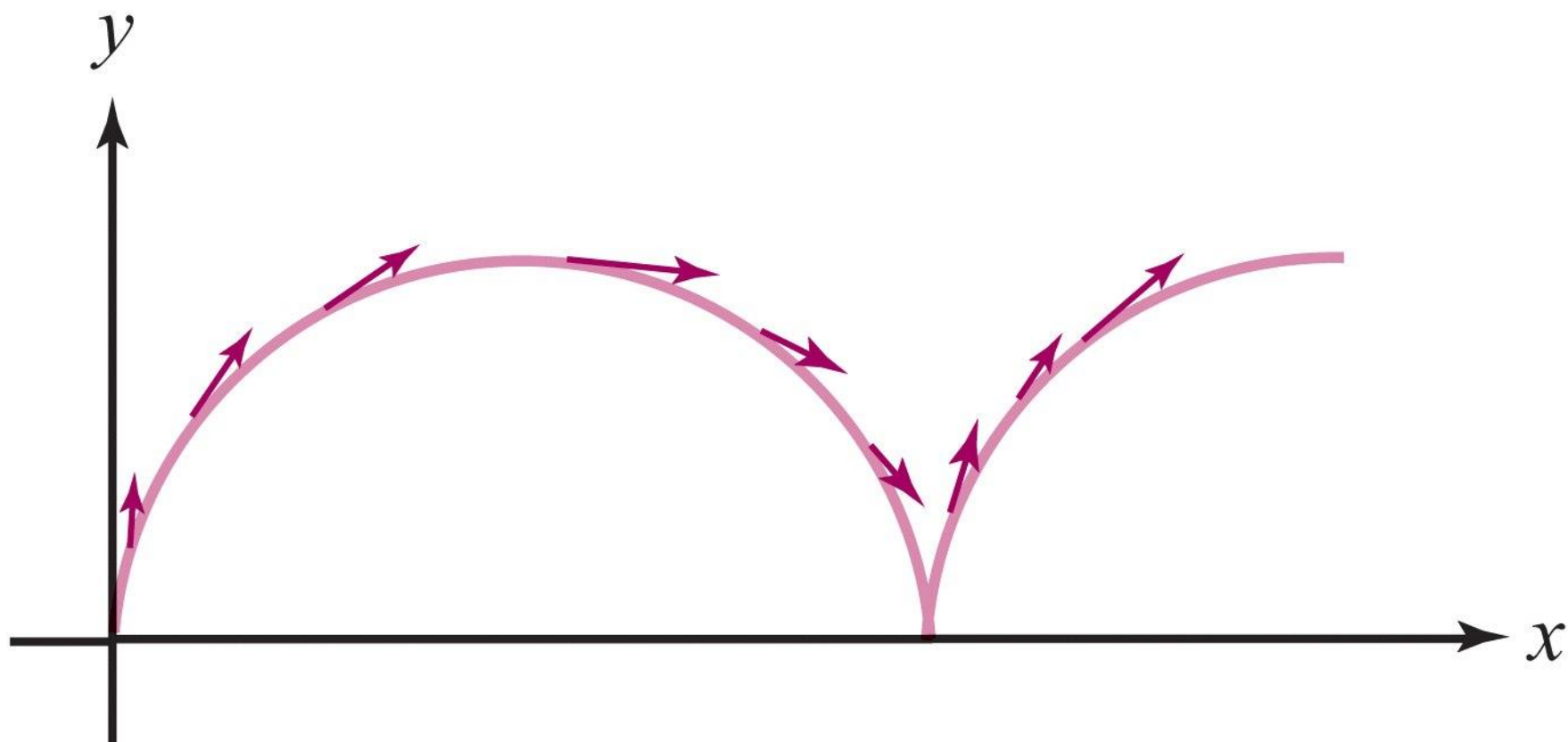
and if  $\mathbf{c}(t) = (x(t), y(t), z(t))$  in  $\mathbb{R}^3$ , then

$$\mathbf{c}'(t) = (x'(t), y'(t), z'(t)) = x'(t)\mathbf{i} + y'(t)\mathbf{j} + z'(t)\mathbf{k}.$$



**Tangent Vector** The velocity  $\mathbf{c}'(t)$  is a vector *tangent* to the path  $\mathbf{c}(t)$  at time  $t$ . If  $C$  is a curve traced out by  $\mathbf{c}$  and if  $\mathbf{c}'(t)$  is not equal to  $\mathbf{0}$ , then  $\mathbf{c}'(t)$  is a vector tangent to the curve  $C$  at the point  $\mathbf{c}(t)$ .







**Tangent Line to a Path** If  $\mathbf{c}(t)$  is a path, and if  $\mathbf{c}'(t_0) \neq \mathbf{0}$ , the equation of its *tangent line* at the point  $\mathbf{c}(t_0)$  is

$$\mathbf{l}(t) = \mathbf{c}(t_0) + (t - t_0)\mathbf{c}'(t_0).$$

If  $C$  is the curve traced out by  $\mathbf{c}$ , then the line traced out by  $\mathbf{l}$  is the tangent line to the curve  $C$  at  $\mathbf{c}(t_0)$ .

