

## Exercises - Hamiltonian mechanics - Hamilton's equations

4.1 LEGENDRE TRANSFORMATION. Consider the function  $A(x, y) = (1 + x^2)y^2$ .

(a) Prove that its Legendre transformation of  $A(x, y)$  gives

$$B(x, z) = \frac{z^2}{4(1 + x^2)}.$$

(b) Use the inverse Legendre transformation to find  $y(x, z)$  and  $A(x, y)$  from  $B(x, z)$ .

4.2 PARTICLE ON A PARABOLIC WIRE. Consider a particle of mass  $m$  sliding, under the action of gravity and without friction, on a parabolic wire whose shape is given by the equation  $y = x^2/2$  (Fig. 1).

(a) Write the Lagrangian  $\mathcal{L}(x, x')$  of the system (in terms of the  $x$  coordinate and its velocity  $x'$ ).

(b) Obtain the generalized conjugate momentum  $p_x$ .

(c) Obtain the Hamiltonian of the system as a function of  $x$  and  $p_x$ .

(d) Obtain the equations of motion of  $x$  and  $p_x$  using Hamilton's equations.

(e) Considering that  $H = E$  is the total energy and is conserved,<sup>1</sup> use your favorite software to plot the trajectories of the system in phase space (**Hint**: Given that  $H = E = \text{constant}$ , you do not need to integrate the equations of motion to get the trajectory in phase space!).

4.3 PENDULUM HANGING FROM A TILTED WIRE. A pendulum is comprised of a mass  $m$  and a rigid rod of length  $l$ . The support of the pendulum can slide, without friction, on a straight wire described by the equation  $y = ax$  (Fig. 2).

(a) Write the Lagrangian of the system in terms of the horizontal position  $X$  of the support of the pendulum and the angle  $\theta$ .

(b) Obtain the generalized momenta  $p_X$  and  $p_\theta$ , and the expressions of the velocities  $X'$  and  $\theta'$  as a function of  $p_X$  and  $p_\theta$ .

**Hint**: Use the following shorthands to write less:

$$A \equiv ml^2 \quad B \equiv m(1 + a^2) \quad C \equiv ml(\cos \theta + a \sin \theta).$$

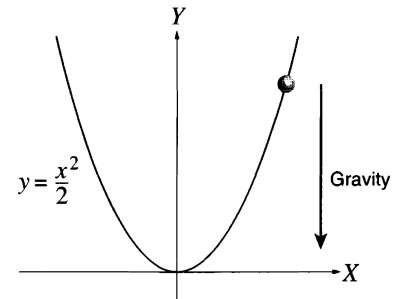


Figure 1: Spherical pendulum (Exercise 2).

<sup>1</sup> Why?

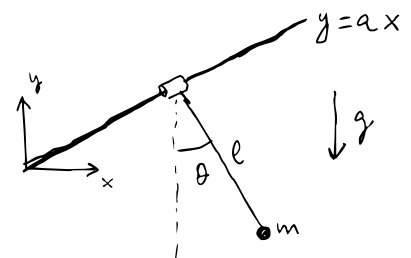


Figure 2: Pendulum hanging from a slope (Exercise 3).

(c) Proof that the Hamiltonian of the system is

$$H = \frac{1}{AB - C^2} \left[ \frac{A}{2} p_X^2 + \frac{B}{2} p_\theta^2 - C p_X p_\theta \right] + mg(aX - l \cos \theta).$$

4.4 SPHERICAL PENDULUM. A pendulum of length  $R$  is connected to the center of a sphere as shown in Fig. 3; it is subject to gravity in the  $z$  direction as depicted.

- Write the Lagrangian  $\mathcal{L}(\theta, \phi)$  of the system.
- Obtain the generalized conjugate momenta  $p_\theta$  and  $p_\phi$ .
- Obtain the Hamiltonian of the system.
- Obtain the equations of motion using Hamilton's equations.
- Differentiate the equation for  $\theta'$  and substitute into the equation for  $p'_\theta$  to obtain a 2nd-order differential equation for  $\theta$ .

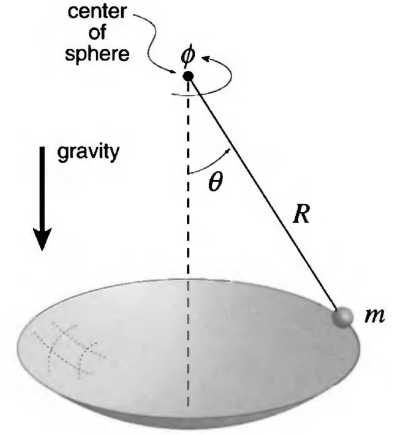


Figure 3: Spherical pendulum (Exercise 4).

4.5 HAMILTONIAN DYNAMICS IN AN ACCELERATED SYSTEM. Consider a mass  $m$  sitting on a turntable that rotates at constant angular velocity  $\omega$  (Fig. 4). The mass is subject to a potential  $V(x, y)$ , where  $x$  and  $y$  are the coordinates in the rotating frame. Obtain the Lagrangian and the generalized momenta from the rotating reference frame. Prove that the Hamiltonian in the rotating frame is<sup>2</sup>

$$H_\omega = \frac{p_x^2 + p_y^2}{2m} + V(x, y) + \omega(y p_x - x p_y).$$

4.6 MOMENTUM SPACE LAGRANGIAN. Consider the momentum space Lagrangian  $\mathcal{K}$ , which is defined as the double Legendre transform of the (coordinate space) Lagrangian

$$\mathcal{K}(p, p', t) = \mathcal{L}(q, q', t) - p q' - q p'.$$

- Prove that  $\mathcal{K}$  and  $\mathcal{L}$  are dynamically equivalent, that is, that the Euler-Lagrange equations for  $\mathcal{K}$  are the same as for  $\mathcal{L}$  (**Hint:**  $d(pq)/dt = p q' + q p'$ ).
- Consider a harmonic oscillator with Hamiltonian

$$H = \frac{1}{2} (p^2 + \omega^2 q^2)$$

and obtain the corresponding Lagrangian  $\mathcal{L}(q, q')$ .

- Obtain  $p = \partial \mathcal{L} / \partial q'$  and  $p' = -\partial H / \partial q$ .
- Obtain the momentum space Lagrangian  $\mathcal{K}$  for this system, and show that it has the same functional form as the coordinate space Lagrangian  $\mathcal{L}$ .

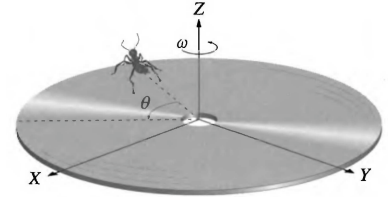


Figure 4: Bug of mass  $m$  on a rotating frame (Exercise 5).

<sup>2</sup> Notice that  $H_\omega = H_{\omega=0} - \omega L_z$ , where  $L_z = (x p_y - y p_x)$  is the  $z$  component of the angular momentum. This means that, to get the Hamiltonian from the perspective of the rotating frame, we just need to subtract  $\omega L_z$  from the Hamiltonian we would have had if there was no rotation. This is one scenario in which the Hamiltonian approach does simplify things!