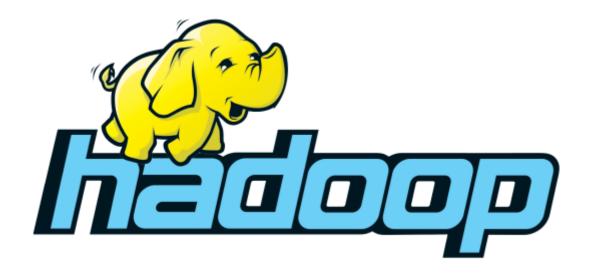
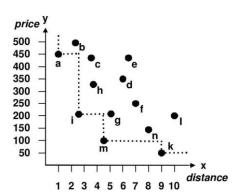
Technical University of Crete School of Electronic and Computer Engineering Parallel Skyline Computation on Map Reduce System







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AM: 2013030016

<u>Abstract</u>

During the last decades, data management and storage have become increasingly distributed. Advanced query operators, such as skyline queries, have become, not just useful, but indispensable, in order to help users handle the huge amount of available data by identifying a set of interesting data objects. Space partition techniques, such as recursive division of the data space, have been used for skyline query processing in centralized, parallel and distributed settings. Unfortunately, such gridbased partitioning is not suitable in the case of a parallel skyline query, where all partitions are examined simultaneously, since many data partitions do not contribute to the overall skyline set, resulting in a lot of redundant processing.

1) Rules

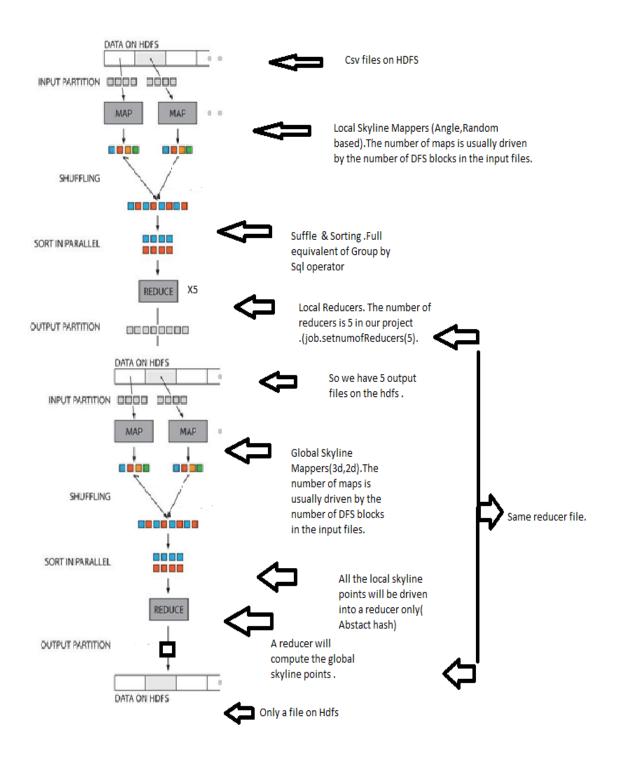
Αρχικά για την υλοποίηση του αλγορίθμου , είναι χρήσιμο να κατανοήσουμε σωστά τους παρακάτω ορισμούς :

Definition 1: (Domination) A point $p \in P$ is said to dominate another point $q \in P$, denoted as p < q, if (1) on every dimension $d_i \in D$, $p_i \le q_i$ and (2) on at least one dimension $d_j \in D$, $p_j < q_j$.

Definition 2: (Skyline) The skyline is a set of points SKY (S) \subseteq S which are not dominated by any other points. The points in SKY (S) will be called skyline points. The notion of skyline queries can be extended to subspaces, where a subspace skyline query only refers to a user-defined subset of attributes.

Definition 3: (Subspace Skyline) The subspace skyline of U is a set of points $SKY_U(S) \subseteq S$ which are not dominated by any other point on subspace Consider for example the two-dimensional dataset S depicted in Figure 2.1b. The skyline points are $SKY(S) = \{a,i,m,k\}$, which are the best possible trade-offs between price and distance from the beach. On the other hand, for the subspace $U = \{x\}$ the subspace skyline is $SKY_U(S) = \{a\}$. Skyline queries have also been studied for the case where constraints exist. Typically, each constraint is expressed as a range along a dimension and the conjunction of all constraints form a hyper-rectangle in the d-dimensional attribute space. Therefore a definition of constrained skyline could be the following.

Αφού μελετήσαμε τους παραπάνω κανόνες ,τότε ήταν εφικτός ο σχεδιασμός ενός block diagram έτσι ώστε να φανεί ξεκάθαρα η δουλεία του κάθε mapper -reducer.



2) Algorithms

Random-Based partitioning

```
-----Grid-Based -----
4 Algorithm Random_mapper [ <key ,value > iterator,partitions ]
   mapper_write( Random_number([0,partitions]) as key ,Text (value) as value )
8
9
   end
10
11
12 Algorithm Reducer [<key ,value > iterator]
13
14 Declare:
15 ArrayList skyline = new ArrayList<>();
16 counter =0;
17
18
19 begin
20
21 if (counter==0) then add the value to the list
22
23 else
24
25 if( iterator.value is canditate skyline point) then add the values to the list
   else if (iterator.value is dominate value) then delete the elemements which are dominated from iterator.value
26
27 and add the iterator.value in the list .
28 else continue
29
30 end
31
32 At the end :write the list in hdfs
33
34
```

Παραπάνω βλέπουμε τον Pseudocode που αφορά την υλοποίηση της τυχαίας διαμερίσης. Είναι φανερό πώς ο Mapper ομαδοποιεί τα δεδομένα με τυχαία σειρά στα hash tables .Δημιουργούνται [0,partitions]τυχαίες διαμερίσεις .Ο reducer υλοποιεί τον BNL αλγόριθμο ,κρατώντας τα candidate skyline points σε List .Στο τέλος ο αλγόριθμος γράφει τα δεδομένα της λίστας στον hdfs .

4

Angle-Based partitioning 2d

```
2 -----Angle-Based 2d |-----
  Algorithm Random_mapper [ <key ,value > iterator,partitions ]
   begin
6 float degrees = 90 /partitions;
           double deg=Math.toDegrees(Math.atan((Double.parseDouble(values[2]))/(Double.parseDouble(values[1]))));
8
9
           double part=deg/degrees;
LØ
           collector.collect(new IntWritable((int) Math.ceil(part)),new TextArrayWritable(values));
11
L2
L3
   end
14
   Algorithm Reducer [<key ,value > iterator]
L7
18
   ArrayList skyline = new ArrayList<>();
19
   counter =0;
21
22
   begin
   if (counter==0) then add the value to the list
27
   else
29
   if( iterator.value is canditate skyline point) then add the values to the list
   else if (iterator.value is dominate value) then delete the elemements which are dominated from iterator.value
   and add the iterator.value in the list .
   else continue
33
   end
35
   At the end :write the list in hdfs
36
37
38
```

$$r = \sqrt{(x_n)^2 + (x_{n-1})^2 + \dots + (x_1)^2}$$

$$\tan \phi_1 = \frac{\sqrt{(x_n)^2 + (x_{n-1})^2 + \dots + (x_2)^2}}{x_1}$$

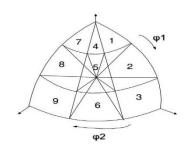
$$\dots$$

$$\tan \phi_{d-2} = \frac{\sqrt{(x_n)^2 + (x_{n-1})^2}}{x_{n-2}}$$

$$\tan \phi_{d-1} = \frac{x_n}{x_{n-1}}$$

Παραπάνω βλέπουμε τον Pseudocode που αφορά την υλοποίηση της γωνιακής διαμερίσης. Είναι φανερό πώς ο Mapper ομαδοποιεί τα δεδομένα σύμφωνα με τα παρακάτω μαθηματικά μοντέλα προσδιορισμού γωνίας .

.O reducer υλοποιεί τον BNL αλγόριθμο ,κρατώντας τα candidate skyline points σε List .Στο τέλος ο αλγόριθμος γράφει τα δεδομένα της λίστας στον hdfs .

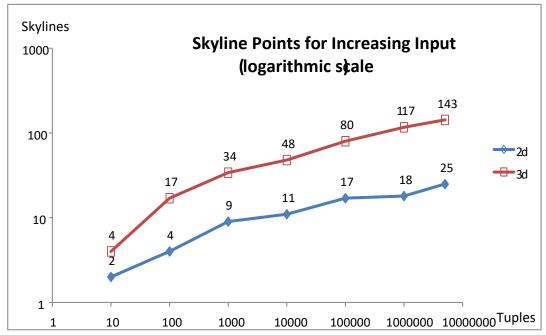


```
-----Angle-Based 2d -----
4
     Algorithm Random_mapper [ <key ,value > iterator,partitions ]
     D7=[ 0,48.24]x[60,90], D4=[0,48.24 ]x[30,60 ], D1=[0,48.24 ]x[0,30 ]
D8=[ 48.24,70.52]x[60,90 ], D5=[ 48.24,70.52]x[ 30,60 ], D2=[ 48.24,70.52]x [ 0,30 ]
D9=[70.52,90 ]x[ 60,90], D6=[ 70.52,90]x[30,60 ], D3=[ 70.52,90]x[0,30 ]
10
     double h1 =Math.pow(Double.parseDouble(values[3]), 2);
     double h2 =Math.pow(Double.parseDouble(values[2]), 2);
     double h3= Math.sqrt(h1+h2);
12
13
14
     \textbf{double} \ \ \text{deg1=Math.toDegrees}(\texttt{Math.atan}(\texttt{h3/Double.parseDouble}(\texttt{values}[1])));\\
     \textbf{double} \ \ \text{deg2=Math.toDegrees} (\texttt{Math.atan}((\texttt{Double.parseDouble}(\texttt{values}[2]))/(\texttt{Double.parseDouble}(\texttt{values}[1])))); \\
15
16
17
18
            for( i=0; i<9;i++){
                   if(deg1 isInFirstVertex and deg2 isInSecondVertex)
22
23
24
25
26
27
28
                       collector.collect(new IntWritable(i+1),new TextArrayWritable(values));
     end
29
31
     Algorithm Reducer [<key ,value > iterator]
     ArrayList skyline = new ArrayList<>();
35
36
37
38
39
40
     counter =0;
     if (counter==0) then add the value to the list
11
     if( iterator.value is canditate skyline point) then add the values to the list
     else if (iterator value is dominate value) then delete the elemements which are dominated from iterator value
16
17
     and add the iterator.value in the list .
     else continue
18
19
51
     At the end :write the list in hdfs
```

Ομοίως με Angle-Based partitioning 2d

3) **TEIPAMATA**

Ο κώδικας μας θα ελεγχθεί με τα παρακάτω αρχεία εισόδου.



ΓράφημαGlobal Skyline σημεία για αυξανόμενα αρχεία εισόδου

Α.1) Σύγκριση Απόδοσης για αυξανόμενο αριθμό

διαμερίσεων

• Διάστασεις: 2-d.

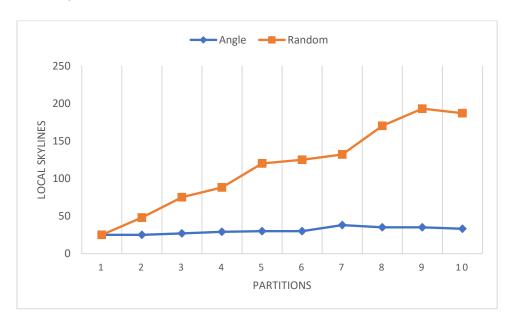
Δεδομένα: input_file_5000000.csv

Τεχνική Διαμέρισης: Τυχαία και Γωνιακή

• Διαμερίσεις: απο 1 εώς 10

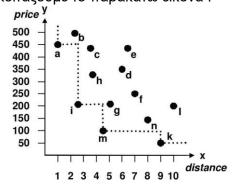
Γράφημα: Άξονας χ – Διαμερίσεις | Άξονας ψ – Ενδιάμεσα skylines |

Γραμμές 2: Τυχαία και Γωνιακή



Παρατηρήσεις :

Είναι φανερό πώς η Angle -based φέρει μικρότερο αριθμό Local Skyline Points .Ο αιτία είναι φανερή ,αν κοιτάξουμε το παρακάτω εικόνα :



Από ότι βλέπουμε όλα τα σημεία έχουν μία θέση μέσα στο χώρο .Χρησιμοποιώντας την Random () είναι ουσιαστικά ,σαν να επανατοποθετούμε τα σημεία σε έναν νέο χώρο ,στον οποίο θα είναι διάσπαρτα .Αυτό όμως έχει ως αποτέλεσμα Skyline points που κάνουν dominate ένα διαγώνιο slice από τον καρντεσιανό χώρο να μην είναι στην ίδια << ομάδα >> με τα σημεία που κάνει dominate .Στην περίπτωση όμως του Ange -based Partitioning όλα τα σημεία κάποιου διαγώνιου slice να βρεθούν μαζί και να ελεγχθούν από τον ίδιο Reducer .Τότε ,είναι προφανές πώς τα Local Skylines σημεία θα είναι λιγότερα ,αφού με μεγάλη πιθανότητα τα Dominate Key θα

βρίσκετε στον ίδιο hash table (Hadoop inner implementation) με τα σημεία που θα κυριαρχεί πάνω τους. Αυτό σημαίνει πώς η διαμέριση την δεδομένων είναι αποτελεσματική όταν εξαρτάται από το ίδιο τα ίδια τα δεδομένα ,αλλά όχι από την <<δίκαιη>> μηχανή Random. Όσο λιγότερα Local Skyline σημεία έχουμε τόσο γρηγορότερα θα βρεθούν τα Global skyline σημεία ,αφού ο BNL αλγόριθμος θα έχει να ελένξει λιγότερες περιπτώσεις . Πρέπει όμως να υπογραμμιστεί ότι η angle -based φέρει ελάχιστα Local Skylines γιατί τα input data έχουν ομοιόμορφη διασπορά .Σε αντίθετη περίπτωση θα είχαμε καθυστέρηση του ολικού χρόνου εκτέλεσης αφού κάποιοι Mappers θα ήταν περισσότερο φορτωμένη από κάποιους άλλους. Επιπροσθέτως παρατηρούμε μια σχεδόν γραμμική αύξηση των Local Partitions στο γράφημα ,στην Random περίπτωση, σε αντίθεση με την Angle -based όπου η άυξηση την Local Skylines ακολουθεί αριθμητική πρόοδο .Ακόμα είναι γεγονός πώς όσο αυξάνονται τα partitions ο αριθμός των Local Skylines αυξάνονται ,κάτι που είναι λογικό αφού δημιουργούνται περισσότερα hash tables στο Hadoop και ο κάθε reducer αναλαμβάνει ένα μικρότερο αριθμό από inputs .Άλλωστε μόνο έτσι ,θα μπορούσαν τα εκτελεστούν οι Reducers παράλληλα ,και ακριβώς αυτή είναι η ιδέα των Cluster και του Parallel Computing .

8

Α.2) Σύγκριση Απόδοσης για αυξανόμενο αριθμό δεδομένων εισόδου

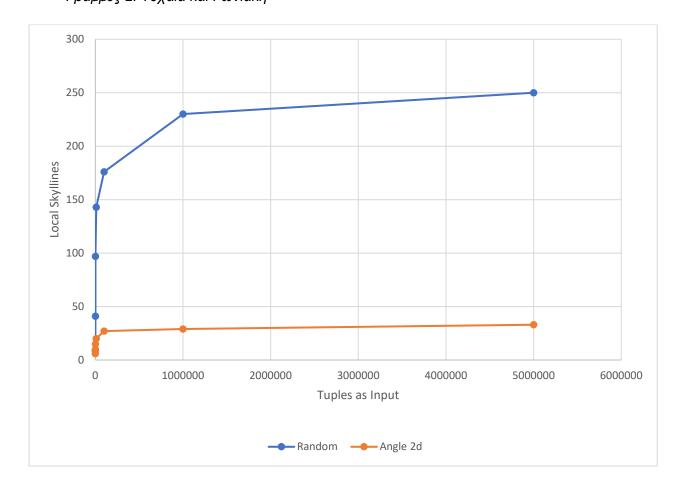
• Διάστασεις: 2-d.

• Δεδομένα: όλα τα αρχεία (απο 10 εώς 5000000)

• Τεχνική Διαμέρισης: Τυχαία και Γωνιακή

• Διαμερίσεις: 10

Γράφημα: Άξονας χ – Αριθμός Tuples | Άξονας ψ – Ενδιάμεσα skylines
 Γραμμές 2: Τυχαία και Γωνιακή



Παρατηρήσεις:

Τώρα πλέον θα εξετάσουμε το Map -Reduce System με 10 partitions σε αυξανόμενο αριθμό Tuples. Αυτό που παρατηρούμε όπως και πρίν είναι ότι, η Random- based τεχνική διαμερίσεις φέρει αισθητά μεγαλύτερο αριθμό από Local Skylines για τους λόγους που αναφέρθηκαν στον Α1.Ακόμα βλέπουμε κάτι αναμενόμενο ,ότι καθώς αυξάνονται τα tuples τα Local Skylines αυξάνονται λογαριθμικά στην περίπτωση <Random -based> σε αντίθεση με στην περίπτωση του <Angle-based 2d>.Και πάλι όμως τα αποτελέσματα στο Angle 2d based είναι τόσο ενθαρρυντικά λόγω της ομοιόμορφης διασποράς των δεδομένων στον χώρο .

Β) Σύγκριση Απόδοσης μεταξύ των 2 και των 3 διαστάσεων

B.1)

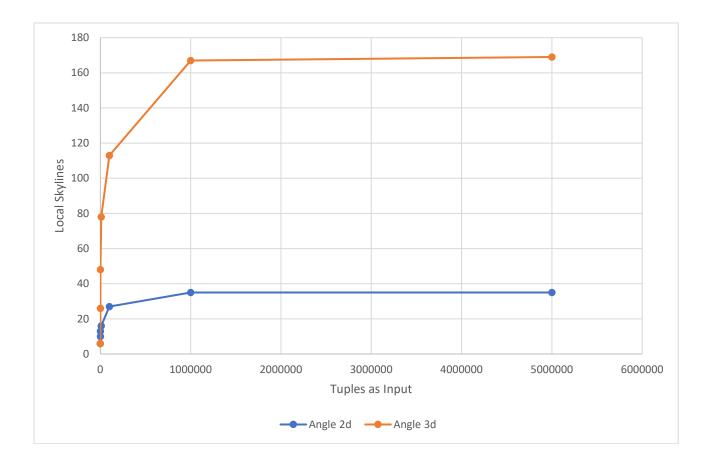
Διάστασεις: 2-d και 3-d

•Δεδομένα: όλα τα αρχεία (απο 10 εώς 5000000)

•Τεχνική Διαμέρισης: Γωνιακή

•Διαμερίσεις: 9

• Γράφημα: Άξονας χ – Αριθμός Tuples | Άξονας ψ – Ενδιάμεσα skylines | Γραμμές 2 : 2-d και 3-d



Παρατηρήσεις:

Τώρα θα εξετάσουμε το Map -Reduce System με 9 partitions σε αυξανόμενο αριθμό Tuples. Αυτό που παρατηρούμε όπως και πρίν είναι ότι, η Angle 3d-based τεχνική διαμερίσεις φέρει αισθητά μεγαλύτερο αριθμό από Local Skylines σε σύγκριση με την Angle 2d-based. Ο λόγος είναι ότι το selectivity του reducer αυξάνεται, αφού ένα Skyline dominate point πρέπει να κυριαρχεί σε 3 παράμετρους και όχι σε 2 .Έτσι η πιθανότητα ένα point να κυριαρχεί πάνω σε 2 άλλα points, είναι μεγαλύτερη από το κυριαρχεί σε 3. Συνεπώς είναι λογική η λογαριθμική συμπεριφορά της 3d διαμέρισης.

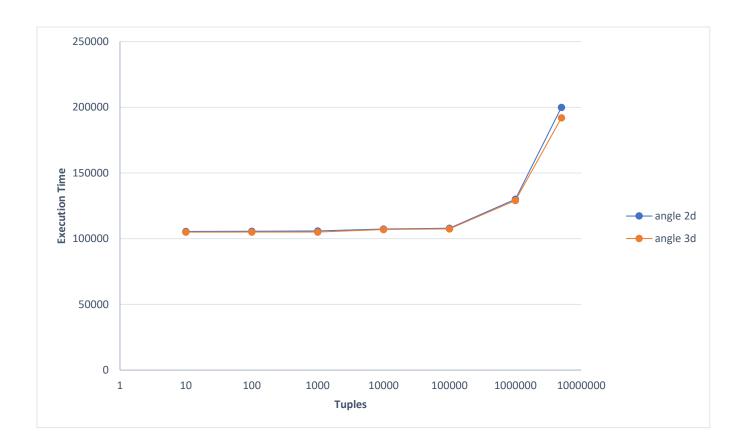
B.2)

Χρόνος Εκτέλεσης

Διάστασεις: 2-d και 3-d •

Δεδομένα: όλα τα αρχεία (απο 10 εώς 5000000) • Τεχνική Διαμέρισης: Γωνιακή • Διαμερίσεις: 9 •

Γράφημα: Άξονας χ – Αριθμός Tuples | Άξονας ψ – Χρονος Εκτέλεσης | Γραμμές 2 : 2-d και 3-d



Παρατηρήσεις :

Ισως η ποίο σημαντική αποτίμηση που πρέπει να κάνουμε είναι το Execution Time του αλγορίθμου μας . Είναι σημαντικό να αναφερθεί ότι ο BNL αλγόριθμος έχει πολυπλοκότητα Ο ((m)²). Αρα περιμένουμε να δούμε μια τετραγωνική πολυωνιμική αύξηση του χρόνου εκτέλεσης σε σχέση με τα αυξανόμενα Tuples.Είναι φανερό πώς αυτό συμβαίνει ,κάτι που μας φανερώνει την ορθότητα του αλγορίθμου μας.Τέλος ο λόγος που ο angle -2d based διαμέριση επιτυγχάνει ελάχιστα ποιο γρήγορο χρόνο εκτέλεσης είναι το μικροτερο selectivity του reducer του σε σύγκριση με το angle 3d-based.

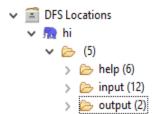
<u>Συμπεράσματα</u>

Random-based τεχνική είναι εργαλείο το οποίο χρησιμοποιείται σε πολλές εφαρμογές των Machine Learning ,Big Data,Deep Learning, Sinopsis of Data Streaming .Ο λόγος είναι ότι η Random ακολουθεί uniform distribution με:

$$\begin{array}{ccc} \text{M\'e}\,\text{sog} & \text{\'o}\,\text{ro}\,\text{g} & = \sum_{i=1}^N \frac{Ri}{N} = \frac{1}{2} \\ \Delta \, \, \text{lagnor}\,\text{fo}\,\text{g} & = \sum_{i=1}^N \frac{(Ri - \mu i \sigma \sigma c) \rho \sigma \rho c_i)^2}{N} = \frac{1}{2} \end{array}$$

Μετά από μελέτη του Skyline Project κατανοούμε ότι για την δική μας περίπτωση ,οπου τα data έχουν ομοιόμορφη διασπορά και κατανομή η Random -Based φέρει σχεδόν γραμμικά περισσότερα Local Skylines,για τους λόγους που αναφέρθηκαν στο A1 . Επιπροσθέτως BNL αλγόριθμος που υλοποιήσαμε, είναι ένας πραγματικά αποτελεσματικός τετραγωνικής πολυπλοκότητας αλγόριθμος. Συνεπαγωγικά για διασδιάστατο πρόβλημα θα επέλεγα Angle 2d partition and BNL Reducer partition αφού ελαχιστοποιεί την δουλεία του Global Reducer . Επιπροσθέτως είδαμε πώς για τρισδιάστατο πρόβλημα ,ότι η Angle 3d based επιτυγχάνει μικρούς χρόνους εκτέλεσης και αρκετά μειωμένα Local Skylines. Συμπερασματικά ,στις 3 διαστάσεις θα επέλεγα Angle 3d based.Τέλος αξίζει να αναφερθεί ότι τα χαμηλά execution times για αυτό το πρόβλημα (5 Mega Data less than < 2.3 minutes) οφείλεται στο MapReduce Framework το οποίο υλοποιώντας εσωτερικά Sorting & Hashing πετυχαίνει πραγματικά Real-time Results σε σύγκριση με το SQL skyline operator ,στο οποίο δοκιμάστηκε το dataset για τα 5 Mega data και βρέθηκαν τα skyline σημεία σε >3.2 minutes .

Δομή HDFS για να γίνει το Testing του κωδικα.



Run command:

>hadoop jar skyline.jar Skyline input_file_100.csv output.csv 8 angle 2d >Hadoop fs -cat /output/output.csv

Τα skyline σημεία για τα αντίστοιχα αρχεία εισόδου για 2 και για 3 διαστάσεις:

```
2d Skylines :
  6,5.493186750629353,35.316270288868346,60.9941748525534
7,46.13193337869227,2.859001782706091,39.50380858155019
 File: input file 100.csv
                                                                            2d Skylines: 4
14 , 2.1334867451946056 , 30.685789876529068 , 88.53889851774092
19 , 2.274040723013895 , 9.61492682707098 , 59.02306897857438
24 , 20.55949805997638 , 2.0261263354183137 , 65.39058956825671
36 , 10.054655701242206 , 6.483857695702772 , 74.98059916603644
                                                                            3d Skylines: 17
1, 3.2974643046230074, 66.32813427602473, 17.28804560789571
12, 2.886828148970545, 10.619378330789388, 28.467768091149473
14 , 2.1334867451946056 , 30.685789876529068 , 88.53889851774092  
19 , 2.274040723013895 , 9.61492682707098 , 59.02306897857438  
23 , 31.113279854622846 , 77.32989919090878 , 3.6805403801999015  
24 , 20.55949805997638 , 2.0261263354183137 , 65.39058956825671
24, 20.55949805997638, 2.0261263354183137, b5.39030920622071

29, 59.500992863148205, 60.233321751188086, 4.060979519883922

32, 41.04941833122222, 2.0910085048509437, 54.451941458954515

36, 10.054655701242206, 6.483857695702772, 74.98059916603644

61, 69.92833855901448, 3.196743745539089, 6.803371188142907
36, 10.054655701242206, 6.483857695702772, 74.98059916603644
61, 69.92833855901448, 3.196743745539089, 6.803371148142907
66, 99.7355998156057, 2.771130298521599, 16.6807276064047
72, 68.17364655984018, 34.84945557826125, 2.2837875203064977
80, 68.96497992892965, 4.451869500504606, 11.188239391294555
81, 88.99036285216613, 9.743527035457896, 5.409563705670457
4, 21.564121434838533, 4.13482822805686, 13.57481037788679
95, 24.792891599366207, 50.244102183569765, 8.229956146522282
96, 54.10405526063253, 94.62284965746069, 1.0864520204372363
  File: input file 1000.csv
2d Skylines: 9
5, 35.43133830094412, 1.4684266346274675, 77.38691228796738
45, 13.6348524293881, 1.7181355653734594, 79.11167827434407
118, 1.136879537827855, 12.043768784732682, 27.5108935321525
397, 1.0112178931820663, 22.558713552545733, 56.65557683213506
441, 9.331597445443565, 1.825739457234871, 93.16702008990497
514, 63.911016211191345, 1.3071928333149168, 27.324612238686353
532, 2.152069374293113, 10.443718811819139, 25.305283417095684
741, 65.9799066153562, 1.1920846590654919, 29.24746348640462
924, 2.6379257336562816, 2.0499504041261716, 18.486761636675073
                                                                            2d Skylines: 9
3d Skylines: 34

5, 35.43133830094412, 1.46684266346274675, 77.38691228796738

45, 13.6348524293881, 1.71813555653734594, 79.11167827434407

118, 1.136879537827855, 12.043768784732682, 27.5108935321525

152, 1.101813243141341, 79.83410983298162, 22.170007043199252

164, 14.033680987116469, 18.755533596847602, 4.23262080736673

182, 12.53947334804277, 25.057618782577993, 2.2996700327665556

243, 2.697466594861871, 46.767230374290754, 1.9059230334794521

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