892. Surface Area of 3D Shapes **Geometry**

Math

Array

Matrix

Problem Description

Easy

contains v cubes, indicated by the value v = grid[i][j]. Each cube is of size $1 \times 1 \times 1$. After placing the cubes, we glue any cubes that are directly next to each other on the grid vertically or horizontally. Our task is to determine the total surface area of the joined 3D shapes created. Each cube on its own has a surface area of 6 units, but when cubes are adjacent, they share walls and reduce the overall surface area. We must account for shared walls between adjacent cubes and also remember that there is an additional bottom surface for

In this problem, we have a square n x n grid representing an overhead view of a collection of 3D cubes where each grid cell (i,

the shape formed by cubes at each grid cell. Intuition

• First, for each tower of cubes, calculate the surface area if it were isolated, i.e., not adjacent to any other cubes. This involves the surface area

of the sides and top of the tower. • Second, subtract the area of the surfaces shared between adjacent towers of cubes.

The intuition behind the solution is to do a two-fold computation:

- To break it down:
- 1. We iterate over each cell in the grid: ∘ For a cell with v cubes (where v > ∅), it has 4 sides, and each will have an area of v, plus the top and bottom, each having an area of 1.
- Hence the total surface area of an isolated tower is 2 + v * 4.
- If there is a neighbor to the left, we find the minimum of v and the height of this neighboring tower. The shared wall's area is this minimum times two (since each shared face between two cubes is equal to 1 × 1 = 1, and we're subtracting from both towers). So we

If there is a neighbor above, perform the same calculation for the shared wall and subtract accordingly.

subtract this value from the total surface area.

2. Sum these adjusted surface area values to get the total surface area of the 3D shape.

grid follows an efficient step-by-step approach. Here is a detailed explanation:

• We then check if there is a neighboring tower to the left (west) and above (north):

external surfaces. Solution Approach

This approach gives us the correct total surface area of the resulting irregular 3D shape after accounting for all internal and

The provided solution to finding the total surface area of the resulting 3D shapes formed by gluing 1 × 1 × 1 cubes together in a

Initialize a variable ans to hold the total surface area count, starting at 0.

Loop through each cell in the grid with a nested for-loop, using i to index rows and j to index columns: For each cell at (i, j) with a value v:

Add the surface area of an isolated tower of v cubes to ans. This is done by adding 2 (for the top and bottom of the tower) plus 4

We ensure the shared walls are only subtracted when there is actually a neighbor. We check that i or j is not at the first row

In terms of data structures, the solution uses the given grid directly and an accumulator for the surface area count. There is no

∘ If the current tower has a neighbor to the left (at (i, j - 1)), the shared wall's area to subtract is twice the minimum height of these two

Next comes the subtraction of shared walls to account for gluing:

- ∘ If the current tower has a neighbor above (at (i 1, j)), similarly, the shared wall's area is also twice the minimum height of these towers: min(v, grid[i - 1][j]) * 2.
- or column by conditionally executing the subtraction only if i or j is greater than 0.

arithmetic involving addition, multiplication, and minimum values.

Continue this process for all cells in the grid.

need for additional data structures.

Subtract these shared wall areas from the ans.

towers: min(v, grid[i][j-1]) * 2.

If v is greater than 0 (indicating there are cubes),

* v for the four vertical sides of the tower.

The algorithmic pattern demonstrated in this solution is straightforward iteration through grid elements, with conditionals within the nested loops to handle edge cases (literally the edges of the grid). The mathematics behind the area calculations is simple

After the loops complete, ans contains the correct total surface area. This value is then returned.

Example Walkthrough

Let's go through a small example to illustrate the solution approach with an $n \times n$ grid where n = 2. Consider the following grid

each cell at least once, and constant space complexity, as no additional space proportional to the input size is used.

The result is a solution with time complexity O(n^2), where n is the dimension of the grid, which is optimal since we must visit

[3, 4] Step 1:

• Initialize ans to 0.

Step 3:

• Loop over each cell (i, j) in grid.

v = 2 + 4 * 1 = 6.

cell is 10 - 2 = 8.

Solution Implementation

surface_area = 0

def surfaceArea(self, grid: List[List[int]]) -> int:

Initialize the surface area to 0

Loop through each cell of the grid

for i, height in enumerate(row):

If the height of the current voxel is not zero

surface_area += 2 + height * 4

Add the surface area of the current voxel

Each voxel contributes to 2 base/top faces and 4 side faces

If we are not in the first column, subtract the overlapping area

// Top and bottom surface area (2) + 4 sides for each cube in the cell

totalSurfaceArea -= Math.min(grid[i][j], grid[i - 1][j]) * 2;

totalSurfaceArea -= Math.min(grid[i][j], grid[i][j - 1]) * 2;

// Subtract the area of the sides that are shared with the adjacent cube on the left

// Subtract the area of the sides that are shared with the adjacent cube behind

with the voxel directly on the left (in the j-1 column)

surface_area -= min(height, grid[i][j - 1]) * 2

for i, row in enumerate(grid):

if height:

if j:

return surface_area

Return the total calculated surface area

if (grid[i][i] > 0) {

if (i > 0) {

if (i > 0) {

// Return the total surface area

// Return the totalSurfaceArea calculated

return totalSurfaceArea;

function surfaceArea(grid: number[][]): number {

// Initialize the total surface area to 0

const gridSize: number = grid.length;

for (let i = 0; i < gridSize; i++) {</pre>

if (i > 0) {

if (j > 0) {

let totalSurfaceArea: number = 0;

if (grid[i][i]) {

// Iterate through the grid

// Get the size of the grid (which is n x n)

for (let j = 0; j < gridSize; j++) {</pre>

totalSurfaceArea += 2;

// If the current cell is non-zero (a block exists)

// Each block also contributes 4 side faces

// If there is a block to the north, subtract the hidden area

// If there is a block to the west, subtract the hidden area

totalSurfaceArea -= Math.min(grid[i][j], grid[i - 1][j]) * 2;

totalSurfaceArea -= Math.min(grid[i][j], grid[i][j - 1]) * 2;

// Each block has a top and bottom face

totalSurfaceArea += grid[i][i] * 4;

def surfaceArea(self. grid: List[List[int]]) -> int:

Initialize the surface area to 0

Loop through each cell of the grid

for j, height in enumerate(row):

If the height of the current voxel is not zero

surface_area += 2 + height * 4

accumulated surface area, aside from the input data structure itself.

Add the surface area of the current voxel

with the voxel directly behind (in the i-1 row)

surface_area -= min(height, grid[i - 1][j]) * 2

with the voxel directly on the left (in the j-1 column)

surface_area -= min(height, grid[i][j - 1]) * 2

for i, row in enumerate(grid):

if height:

if i:

if i:

surface_area = 0

return totalSurfaceArea;

C++

public:

};

TypeScript

#include <vector>

class Solution {

#include <algorithm>

totalSurfaceArea += 2 + grid[i][j] * 4;

Step 2:

Step 4:

Step 5:

configuration:

grid = [

[1, 2],

At (0, 1), value v is 2. No neighbors above but there is one to the left. Surface area with sides is 2 + 4 * v = 2 + 4 * 2 = 010. It shares a wall with (0, 0), so we subtract the shared surface: $\min(2, 1) * 2 = 2$. The surface area contributed by this

At (0, 0), value v is 1. There are no neighbors above or to the left. Surface area added to ans is 2 (top and bottom) + 4 *

At (1, 0), v is 3. There's a neighbor above but not to the left. Surface area with sides is 2 + 4 * v = 2 + 4 * 3 = 14.

At (1, 1), v is 4. There are neighbors both above and to the left. Surface area with sides is 2 + 4 * v = 2 + 4 * 4 = 18. It

shares walls with (0, 1) and (1, 0). Subtractions are min(4, 2) * 2 = 4 and min(4, 3) * 2 = 6. Contribution is 18 - 4 - 46 = 8.

After the final calculation, and is 34, so the total surface area for the shape formed by the cubes in this 2 x 2 grid is 34 units.

• Sum the adjusted surface areas for each cell: 6 (from (0, 0)) + 8 (from (0, 1)) + 12 (from (1, 0)) + 8 (from (1, 1)) = 34.

Shared wall with (0, 0) must be subtracted: min(3, 1) * 2 = 2. The contribution is 14 - 2 = 12.

Python class Solution:

If we are not on the first row, subtract the overlapping area # with the voxel directly behind (in the i-1 row) if i: surface_area -= min(height, grid[i - 1][j]) * 2

Please note that the `List` type hint assumes that you have imported `List` from `typing` module at the beginning of your script like `python from typing import List Java class Solution { // Function to calculate the total surface area of 3D shapes public int surfaceArea(int[][] grid) { // Length of the grid (number of rows/columns in the grid) int n = grid.length; // Initialize surface area to 0 int totalSurfaceArea = 0; // Iterate over each cell in the grid for (int i = 0; i < n; ++i) { for (int i = 0; i < n; ++i) { // If the cell has at least one cube

// Calculate the total surface area of 3D shapes represented by a grid int surfaceArea(std::vector<std::vector<int>>& grid) { // Get the size of the grid (which is $n \times n$) int gridSize = grid.size(); // Initialize the answer to 0 int totalSurfaceArea = 0; // Iterate through the grid for (int i = 0; i < gridSize; ++i) {</pre> for (int i = 0; i < gridSize; ++i) {</pre> // If the current cell is non-zero (a block exists) **if** (arid[i][i]) { // Each block has a top and bottom face totalSurfaceArea += 2; // Each block also contributes 4 side faces totalSurfaceArea += grid[i][i] * 4; // If there is a block to the north, subtract the hidden area if (i > 0) { totalSurfaceArea -= std::min(grid[i][j], grid[i - 1][j]) * 2; // If there is a block to the west, subtract the hidden area if (i > 0) { totalSurfaceArea -= std::min(grid[i][j], grid[i][j - 1]) * 2;

// Return the calculated total surface area return totalSurfaceArea; class Solution:

Each voxel contributes to 2 base/top faces and 4 side faces

If we are not on the first row, subtract the overlapping area

If we are not in the first column, subtract the overlapping area

Return the total calculated surface area return surface_area Please note that the `List` type hint assumes that you have imported `List` from `typing` module at the beginning of your script like `python from typing import List

Time Complexity The given code iterates over each cell in the grid, which has a size n * n where n is the length of a side of the grid. We can

Time and Space Complexity

blocks (if any).

This leads to a time complexity of O(n^2), as it's necessary to visit each cell exactly once, and the amount of work per cell does not depend on the size of the grid. **Space Complexity**

assume that the grid is square-shaped since no other shape is indicated. For each cell, a constant amount of work is done:

checking the cell value, adding the surface area of the top and bottom, and subtracting the areas that are shared with adjacent

The space complexity of the code is 0(1) because no additional space proportional to the size of the input grid is being used. The solution uses a fixed amount of space, as all calculations are done in place, with a single integer ans holding the