

Problem Description

The problem deals with an integer array nums and an integer k. We're tasked with partitioning the array into at most k non-empty adjacent subarrays. Our goal is to maximize the 'score' of the partition, where the score is defined as the sum of the averages of each subarray. Important to note is that we must use every integer in nums and that the partitions we create will affect the score. We need to find the best possible way to split the array to achieve the maximum score.

The core of this problem lies in dynamic programming, particularly in finding the best partition at each stage to maximize the score.

Intuition

A naïve approach might try every possible partition, but this would be prohibitively slow. Instead, we need an efficient way to solve smaller subproblems and combine their solutions to solve the larger problem. The intuition behind the dynamic programming solution is that if we know the best score we can get from the first i elements with k

subarrays, we can use this to compute the best score for the first i+1 elements with k subarrays, and so on. The recursive function

dfs represents this notion, where dfs(i, k) returns the best score we can get starting from index i with k subarrays left to form. The solution uses a top-down approach with memoization (caching) to avoid re-computing the scores for the same i and k values more than once. It also uses a prefix sum array s to quickly compute the sum of elements for any given subarray, which is used to

calculate the averages needed to compute the scores for the partitions. By caching results and avoiding repetition of work, we arrive at the best solution in a much faster and more efficient way than bruteforce methods.

Solution Approach The solution uses several algorithms and concepts:

Dynamic Programming:

Dynamic programming is utilized to break the problem down into smaller, manageable subproblems. A function dfs recursively computes the maximum score obtainable from a given starting index i and a certain number of partitions k. The essence of dynamic

Memoization:

To optimize the dynamic programming solution, memoization is used. The @cache decorator in Python automatically memorizes the result of the dfs function calls with particular arguments, so when the function is called again with the same arguments, the result is retrieved from the cache instead of re-computing it.

To efficiently calculate the average of any subarray within nums, a prefix sum array s is created using the accumulate function from

programming is apparent as dfs computes the scores based on previously solved smaller problems.

Python's itertools module, with initial=0 to include the starting point. This data structure allows constant-time retrieval of the sum of elements between any two indices.

Prefix Sums:

Implementation Details: The main function largestSumOfAverages first computes the cumulative sums of nums. Then it defines the dfs function with parameters \mathbf{i} (the starting index for considering partitions) and \mathbf{k} (the number of remaining partitions).

• If i == n, where n is the length of nums, it means we've considered all elements and there is no score to be added, so it returns 0. • If k == 1, we can only make one more partition, so the best score is the average of all remaining elements, calculated by (s[-1]

-s[i]) / (n - i).

The dfs function works as follows:

and calculating its average. It then recursively calls dfs(j + 1, k - 1) to compute the score of the remaining array with one less partition. The max function keeps track of the highest score found during the iteration.

At the end of the dfs calls, dfs(0, k) provides the maximum score for the entire array with k partitions.

• For other cases, the function iterates through the elements starting from i up to the last element, creating a subarray from i to j

The implementation takes advantage of Python's concise syntax and powerful standard library functions like itertools.accumulate and functools. cache to create an elegant and efficient solution. Example Walkthrough

Let's assume we have nums = [9, 1, 2, 3, 9] and k = 3. We want to find the maximum score by partitioning the array into at most

k adjacent subarrays. First, let's calculate the prefix sums to efficiently compute the sums of subarrays:

Partition after index 0: average of first part [9] is 9, now call dfs(1, 2).

Partition after index 3: average of first part [9, 1, 2, 3] is 3.75, now call dfs(4, 2).

Step 7: Finally, dfs(0, k) returns the maximum score for the entire array with k partitions.

def largestSumOfAverages(self, nums: List[int], k: int) -> float:

Prefix sum array including an initial 0 for convenience

Base case: when we have considered all elements

Update the maximum average sum encountered

Launch depth-first search with initial position and group count

When only one group is left, return the average of the remaining elements

Try to form a group ending at each element from the current index

max_average_sum = max(max_average_sum, total_average_sum)

return (prefix_sums[-1] - prefix_sums[index]) / (num_elements - index)

Recursively calculate the sum of averages for the remaining groups

total_average_sum = current_average + dfs(j + 1, remaining_groups - 1)

current_average = (prefix_sums[j + 1] - prefix_sums[index]) / (j - index + 1)

Total number of elements in nums

if index == num_elements:

if remaining_groups == 1:

for j in range(index, num_elements):

Current group average sum

num_elements = len(nums)

return 0

max_average_sum = 0

return max_average_sum

return dfs(0, k)

Now, let's walk through the solution: Step 1: Call dfs(0, 3) for the full array with 3 partitions allowed.

Step 2: dfs(0, 3) explores partitioning the array from index 0. It tries partitioning after every index to find the maximum score:

 Partition after index 1: average of first part [9, 1] is 5, now call dfs(2, 2). Partition after index 2: average of first part [9, 1, 2] is 4, now call dfs(3, 2).

nums = [9, 1, 2, 3, 9] prefix_sums = [0, 9, 10, 12, 15, 24] (include a 0 at the beginning for easy calculation)

Here's the Python function dfs(i, k) that will compute the maximum score starting from index i with k partitions left.

simply takes the average of the remaining elements since it has to be one partition.

state is not recomputed.

- partitions. The maximum value from these recursive calls is the answer for the current dfs.
- partition the array into [9], [1, 2, 3], [9] with scores 9 + 2 + 9 = 20.

Step 6: Once all possibilities for dfs(0, 3) are evaluated, the maximum score that can be returned is cached to ensure that the same

The recursive and memoizing nature of the dfs function allows us to efficiently explore all possibilities, while the prefix sums provide

a quick way to calculate averages as needed without repeated summation. By combining these techniques, the algorithm efficiently

Step 4: Each time the score is computed, we take the average of the current partition plus the result of dfs for the remaining

Step 5: Following the steps recursively will lead us to find the maximum score. For instance, one of the optimal solutions is to

Step 3: For each of the above calls to dfs(i, 2), it again divides the remaining part of the array and calls dfs(j, 1). When k == 1, it

finds the solution.

Python Solution from functools import lru_cache from itertools import accumulate from typing import List

prefix_sums = list(accumulate(nums, initial=0)) 13 # Memoization function for our depth-first search 14 @lru_cache(maxsize=None) 15 def dfs(index, remaining_groups):

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class Solution:

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Java Solution
  1 class Solution {
         private Double[][] memoization; // 2D array for memoization to store intermediate results
         private int[] prefixSums; // 1D array to store the prefix sums of the input array
         private int length; // Length of the input array
  5
         // Calculates the largest sum of averages
         public double largestSumOfAverages(int[] nums, int k) {
             length = nums.length;
             prefixSums = new int[length + 1]; // Array size is length+1 because we start from 1 for easy calculations
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             memoization = new Double[length + 1][k + 1]; // using Double wrapper class to store null initially
             for (int i = 0; i < length; ++i) {</pre>
 11
 12
                 prefixSums[i + 1] = prefixSums[i] + nums[i]; // Compute prefix sums
 13
 14
             return dfs(0, k); // Begin depth-first search
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 17
         // Performs depth-first search to find the maximum sum of averages
 18
         private double dfs(int startIndex, int groups) {
 19
             if (startIndex == length) {
                 return 0; // Base case: when we've considered all elements
 20
 21
 22
             if (groups == 1) {
 23
                 // If only one group left, return the average of the remaining elements
 24
                 return (double)(prefixSums[length] - prefixSums[startIndex]) / (length - startIndex);
 25
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             if (memoization[startIndex][groups] != null) {
 27
                 return memoization[startIndex][groups]; // Return cached result if available
 28
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             double maxAverage = 0;
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             for (int i = startIndex; i < length; ++i) {</pre>
 31
                 // Choose different points to split the array
                 double current = (double)(prefixSums[i + 1] - prefixSums[startIndex]) / (i - startIndex + 1) + dfs(i + 1, groups - 1);
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                 maxAverage = Math.max(maxAverage, current); // Keep the maximum average found
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             memoization[startIndex][groups] = maxAverage; // Store the result in memoization array
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             return maxAverage;
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C++ Solution

1 #include <vector>

7 class Solution {

public:

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2 #include <cstring>

3 #include <functional>

using namespace std;

int n = nums.size();

// Calculate the prefix sums

for (int i = 0; i < n; ++i) {

double largestSumOfAverages(vector<int>& nums, int k) {

prefix_sum[i + 1] = prefix_sum[i] + nums[i];

// Recursive lambda function for depth-first search

vector<int> prefix_sum(n + 1, 0); // Create a vector to store the prefix sums

vector<vector<double>> memo(n, vector<double>(k + 1, 0)); // Create a 2D vector for memoization

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function<double(int, int)> dfs = [&](int start, int partitions) -> double {
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                if (start == n) return 0; // Base case: no more elements to partition
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 22
                if (partitions == 1) // Base case: only one partition is left
                    return static_cast<double>(prefix_sum[n] - prefix_sum[start]) / (n - start);
                if (memo[start][partitions] > 0) return memo[start][partitions]; // If value already computed return it
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27
                double max_average = 0;
                for (int end = start; end < n; ++end) {</pre>
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                    double current_average = static_cast<double>(prefix_sum[end + 1] - prefix_sum[start]) / (end - start + 1);
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                    double rest_average = dfs(end + 1, partitions - 1);
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                    max_average = max(max_average, current_average + rest_average); // Update max_average if the sum of averages is lar
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 34
                return memo[start][partitions] = max_average; // Memoize and return the result
 35
            };
 36
37
            return dfs(0, k); // Initiate the recursive search with the entire array and k partitions
 38
 39 };
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Typescript Solution
  1 // Import required packages for utility functions if needed (TypeScript doesn't use imports in a similar way, but you may need exte
    // Define the type alias for 2D array of numbers
    type NumberMatrix = number[][];
  6 // Define the function to calculate the largest sum of averages
    function largestSumOfAverages(nums: number[], k: number): number {
        const n: number = nums.length;
        const prefixSum: number[] = new Array(n + 1).fill(0); // Create an array to store the prefix sums
  9
        const memo: NumberMatrix = Array.from({length: n}, () => new Array(k + 1).fill(0)); // Create a 2D array for memoization
 10
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12
        // Calculate the prefix sums
13
        for (let i = 0; i < n; ++i) {
14
           prefixSum[i + 1] = prefixSum[i] + nums[i];
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        // Recursive function for depth-first search
18
        const dfs: (start: number, partitions: number) => number = (start, partitions) => {
19
            if (start === n) return 0; // Base case: no more elements to partition
            if (partitions === 1) // Base case: only one partition is left
 20
                return (prefixSum[n] - prefixSum[start]) / (n - start);
 21
 22
            if (memo[start][partitions] > 0) return memo[start][partitions]; // If value already computed, return it
 23
```

let nums = [9, 1, 2, 3, 9];console.log(largestSumOfAverages(nums, k)); // Output will be the result of the function 42

Time and Space Complexity

// Example usage:

Time Complexity

let maxAverage: number = 0;

for (let end = start; end < n; ++end) {</pre>

const restAverage: number = dfs(end + 1, partitions - 1);

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maxAverage = Math.max(maxAverage, currentAverage + restAverage); // Update maxAverage if the sum of averages is larger return memo[start][partitions] = maxAverage; // Memoize and return the result **}**; 33 34 35 return dfs(0, k); // Initiate the recursive search with the entire array and k partitions 36 } 37

const currentAverage: number = (prefixSum[end + 1] - prefixSum[start]) / (end - start + 1);

The time complexity of the given recursive algorithm involves analyzing the number of subproblems solved and the time it takes to solve each subproblem. Here, n represents the length of the nums array, and k represents the number of partitions.

There are at most n * k subproblems because for each starting index i in nums, there are at most k partitions possible.

• For each subproblem defined by a starting index i and a remaining partition count k, the algorithm iterates from i to n-1 to consider all possible partition points.

The time taken for each subproblem is 0(n) because of the for-loop from i to n-1. Therefore, the overall time complexity is $0(n^2 *$

k).

partition.

Space Complexity The space complexity consists of the space required by the recursion stack and the caching of subproblem results.

- The maximum depth of the recursion stack is k, because the algorithm makes a recursive call with k-1 whenever it makes a The cache stores results for the n * k subproblems.
- Therefore, the space complexity is 0(n * k) due to caching, plus 0(k) for the recursion stack, which simplifies to 0(n * k).