#### 1959. Minimum Total Space Wasted With K Resizing Operations **Leetcode Link**

### **Dynamic Programming** Medium Array

## **Problem Description**

array is an array that can change its size during the execution of a program. We have an array called nums where nums [i] represents the number of elements in the array at time i. Additionally, the array can be resized up to k times. A resize operation can change the array's size to any number, and the size after each resize or at each time needs to be at least as

The problem involves designing a dynamic array that can accommodate a varying number of elements at different times. A dynamic

large as the number of elements specified at that time (i.e., nums [t]). The efficiency of our dynamic array design is measured by the amount of "space wasted," which is the unused capacity at each point in time. The goal is to minimize the total space wasted after all the insertions, given the constraint that the array can be resized at most k times. Intuition

### keeping track of the space wasted. Dynamic programming is a method for solving complex problems by breaking them down into

Firstly, the concept of precomputing the space wasted for all possible subarray lengths is employed. This calculation is stored in a 2D array (matrix g), where g[i][j] gives the space wasted for a subarray starting at index i and ending at index j. This is done by iterating over each subarray, tracking the maximum element (mx) within that subarray, and calculating the cumulative sum (s) of elements. The space wasted is then the maximum element times the length of the subarray minus the sum of elements in the

simpler sub-problems. It is applicable when the problem can be divided into overlapping sub-problems with the optimal structure.

The intuition behind the solution is to use dynamic programming to explore different ways of resizing the dynamic array while

subarray. After calculating the space wasted for all subarrays, dynamic programming is used to find the minimum total space wasted with exactly j resizes (j <= k+1). To do this, another 2D array (matrix f) is used, where f[i][j] represents the minimum space wasted for the first i elements with j resizes. The transition function for dynamic programming is the core part that gradually builds up the solution. It iterates over all possible

combinations of array sizes and resizes and computes the minimum possible space wasted. In the end, f[n] [k+1] holds the answer to the problem – the minimum total space wasted after optimizing the resizing operations, given the constraints provided by the nums array and the k value.

**Solution Approach** The implemented solution follows a dynamic programming approach that consists of the following steps: 1. Pre-compute wasted space for subarrays: We start by creating a 2D array (matrix g) of size n x n (n being the length of the

nums array). g[i][j] represents the space wasted for a continuous subarray starting at index i and ending at index j. To fill in

the matrix, we iterate through all possible starting and ending indices. For each subarray defined by (i, j), we calculate the

accumulated sum s of all elements and keep track of the maximum element mx. Using these values, we calculate the wasted

with i elements and j resizes. The matrix is initialized with inf, representing a large number since we want to minimize the

space wasted. The first row of the matrix is initialized to 0 because no space is wasted before any elements are added.

### space as mx \* (j - i + 1) - s.

2. Dynamic programming (DP) to minimize total wasted space: Next, we create a 2D DP array (matrix f) with n + 1 rows (for n elements) and k + 1 columns (for k resize operations allowed). Each cell f[i][j] represents the minimum total space wasted

- 3. Building the solution from sub-problems: The solution iterates over each possible number of elements (i, from 1 to n) and each possible number of resizes (j, from 1 to k + 1). For each pair (i, j), it explores the possibility of making a resize at every previous position h (from 0 to i - 1). It then uses the pre-computed g[h][i - 1] to find the total wasted space if we did the last resize at position h. We determine the minimum space wasted as: 1 f[i][j] = min(f[i][j], f[h][j-1] + g[h][i-1])
- In summary, the solution employs dynamic programming with pre-computation and iteration over sub-problems to find the minimum space wasted given a set of constraints. By breaking down the problem in this way, it effectively handles the complexity of determining when and how to resize the dynamic array optimally. Example Walkthrough

4. Finding the result: After filling the f matrix using the above relation, the minimum space wasted with n elements and k resizes is

Step 1: Pre-compute wasted space for subarrays

element mx is 5, and the total number of elements s sum to 9. The space wasted will be 5 \* 3 - 9 = 6.

found at f[n] [k + 1], which is then returned as the result.

Let's apply the solution approach to a small example to illustrate it better.

also given that we can resize the dynamic array up to k = 2 times.

We begin by creating a matrix g with the dimensions 4x4 (n x n, where n is the length of the nums array). The matrix g will help us know the wasted space for any subarray (i, j). • We calculate the wasted space for all subarrays. For example, g[0][2] corresponds to the subarray [3, 1, 5]. The maximum

Suppose we have the following array nums: [3, 1, 5, 4], which indicates the number of elements in the array at each time i. We are

### Step 2: Dynamic programming to minimize total wasted space

This step is repeated to fill out the entire matrix g.

are added. Step 3: Building the solution from sub-problems

Now, we create a matrix f with dimensions 5x3 ( $n+1 \times k+1$ ) to store the minimum total space wasted for i elements with j resizes.

Initially, f is filled with a large value (e.g., inf), except f [0] [\*], which is filled with 0 since no space is wasted before any elements

point h: Consider f[4][2]: we explore h = 0, h = 1, h = 2, and h = 3.

Using the previous state f[h][j-1] and adding the wasted space of the subarray from h to i-1 (obtained from g[h][i-1]), we

• Consider the resize at h = 2, we take f[2][1] (the best case of no resizes up to 2 elements) and add the waste from resizing at

As an example, let's look at the case when j = 2 (meaning one resize has already been done) and i = 4:

We populate the f matrix based on the previously calculated values in g. For each i and j, we look back at each possible 'last resize'

#### **Step 4: Finding the result** After completing the f matrix, we find the minimum space wasted with n = 4 elements and k = 2 resizes at f[4][3] since we

indexed our resizes starting from 1 up to k+1.

from typing import List

k += 1

n = len(nums)

from math import inf

that point for the rest of the elements: g[2][3].

update f[i][j] to the minimum of these values.

Without any previous resizes, f[4][2] would initially be inf.

We do this for all h and keep the minimum value in f[4][2].

def min\_space\_wasted\_k\_resizing(self, nums: List[int], k: int) -> int:

# Initialize a grid to store the wasted space between every pair of indices

wasted\_space = max\_element \* segment\_length - total\_segment\_sum

wasted\_space\_grid[start\_index][end\_index] = wasted\_space

# Return the minimum wasted space after n elements and k resizings

// Calculating the amount of space wasted if we resize from i to j

wastedSpace[start][end] = maxElement \* (end - start + 1) - sum;

// f will store the minimum wasted space for subarrays with different numbers of resizing operations

minWastedSpace[previousIndex][operations - 1] + wastedSpace[previousIndex][i - 1]

minWastedSpace[0][0] = 0; // Base case: no numbers and no operations equals zero wasted space

int infinity = 0x3f3f3f3f; // Using a large number to represent infinity

vector<vector<int>> minWastedSpace(n + 1, vector<int>(k + 1, infinity));

for (int operations = 1; operations <= k; ++operations) {</pre>

minWastedSpace[i][operations] = min(

minWastedSpace[i][operations],

// Calculating the minimum wasted space for each subarray with j operations

for (int previousIndex = 0; previousIndex < i; ++previousIndex) {</pre>

for (int start = 0; start < n; ++start) {</pre>

for (int end = start; end < n; ++end) {</pre>

maxElement = max(maxElement, nums[end]);

int sum = 0, maxElement = 0;

sum += nums[end];

for (int i = 1;  $i \le n$ ; ++i) {

);

# Allow k resizings (plus one to account for zero indexing)

segment\_length = end\_index - start\_index + 1

# Initialize a DP table for the minimum wasted space

return min\_waste\_dp[-1][-1]

43 # print(solution.min\_space\_wasted\_k\_resizing(nums=[10, 20], k=0))

 $min_waste_dp = [[inf] * (k + 1) for _ in range(n + 1)]$ 

wasted\_space\_grid = [[0] \* n for \_ in range(n)]

- By iterating over the sub-problems and combining their results, we are able to establish the entire space wasted and then select the minimum. The result in f[4][3] gives us the minimum total space wasted for our nums array with k = 2 resizes. This demonstrates the application of dynamic programming to efficiently solve the problem.
- max\_element = 0 15 # Max element in the current segment 16 17 for end\_index in range(start\_index, n): 18 total\_segment\_sum += nums[end\_index] 19 max\_element = max(max\_element, nums[end\_index]) 20 # Calculate the wasted space for the current segment

## **Python Solution**

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11 12 # Pre-calculate the wasted space for all possible segments 13 for start\_index in range(n): 14 total\_segment\_sum = 0 # Sum of elements in the current segment

```
27
            min_waste_dp[0][0] = 0
28
29
            # DP to find the minimum wasted space with up to k resizings
30
           for i in range(1, n + 1):
                for resizing_count in range(1, k + 1):
31
32
                    for prev_partition_end in range(i):
                        # Update the DP table entry with the minimum wasted space
33
34
                        waste_with_prev_partition = min_waste_dp[prev_partition_end][resizing_count - 1]
```

current\_waste = waste\_with\_prev\_partition + wasted\_space\_grid[prev\_partition\_end][i - 1]

min\_waste\_dp[i][resizing\_count] = min(min\_waste\_dp[i][resizing\_count], current\_waste)

#### public int minSpaceWastedKResizing(int[] nums, int k) { k++; // Increment k because we can make "k+1" partitions int n = nums.length; // Length of the nums array int[][] wastedSpaceGrid = new int[n][n]; // 2D array to record wasted space for segments 6

1 class Solution {

Java Solution

41 # Example usage:

42 # solution = Solution()

```
// Pre-compute wasted space for each segment [i, j]
             for (int i = 0; i < n; ++i) {
  8
                 int sum = 0, maxNum = 0;
  9
                 for (int j = i; j < n; ++j) {
 10
                     sum += nums[j];
 11
 12
                     maxNum = Math.max(maxNum, nums[j]);
 13
                     wastedSpaceGrid[i][j] = \max Num * (j - i + 1) - sum;
 14
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             // f[i][j] represents the minimum wasted space using j resizings up to the i-th element
 18
             int[][] dp = new int[n + 1][k + 1];
 19
             int infinity = Integer.MAX_VALUE; // Using a large number to represent infinity
 20
             // Initialize the dp array with infinity
 21
 22
             for (int i = 0; i < dp.length; ++i) {</pre>
 23
                 Arrays.fill(dp[i], infinity);
 24
 25
             dp[0][0] = 0; // Base case: 0 wasted space with 0 elements and 0 resizings
 26
 27
             // Fill up the DP table
 28
             for (int i = 1; i \le n; ++i) {
                 for (int j = 1; j \le k; ++j) {
 29
 30
                     for (int h = 0; h < i; ++h) {
 31
                         // Calculate minimum wasted space for dp[i][j]
 32
                         dp[i][j] = Math.min(dp[i][j], dp[h][j - 1] + wastedSpaceGrid[h][i - 1]);
 33
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 37
             // Return minimum wasted space with n elements and k resizings
 38
             return dp[n][k];
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C++ Solution
  1 class Solution {
    public:
         int minSpaceWastedKResizing(vector<int>& nums, int k) {
             ++k; // Incrementing k because we can perform k+1 operations
             int n = nums.size(); // n is the size of the input array nums
  6
             // g will store the extra space wasted for each subarray
  8
             vector<vector<int>> wastedSpace(n, vector<int>(n));
  9
```

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             // The answer is the minimum wasted space for the whole array with k operations
 38
             return minWastedSpace[n][k];
 39
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    };
 41
Typescript Solution
     function minSpaceWastedKResizing(nums: number[], k: number): number {
         k++; // Incrementing k because we can perform k+1 operations
         const n: number = nums.length; // n is the size of the input array nums
  5
         // wastedSpace will store the extra space wasted for each subarray
         let wastedSpace: number[][] = Array.from({ length: n }, () => Array(n).fill(0));
  6
         // Calculating the amount of space wasted if we resize from i to j
  8
         for (let start = 0; start < n; ++start) {</pre>
  9
 10
             let sum: number = 0, maxElement: number = 0;
 11
             for (let end = start; end < n; ++end) {</pre>
 12
                 maxElement = Math.max(maxElement, nums[end]);
 13
                 sum += nums[end];
                 wastedSpace[start][end] = maxElement * (end - start + 1) - sum;
 14
 15
 16
 17
         const infinity: number = Infinity; // Using Infinity to represent a very large number
 18
 19
         // minWastedSpace will store the minimum wasted space for subarrays with different numbers of resizing operations
         let minWastedSpace: number[][] = Array.from({ length: n + 1 }, () => Array(k + 1).fill(infinity));
 20
 21
         minWastedSpace[0][0] = 0; // Base case: no numbers and no operations equals zero wasted space
 22
 23
         // Calculating the minimum wasted space for each subarray with j operations
 24
         for (let i = 1; i <= n; ++i) {
 25
             for (let operations = 1; operations <= k; ++operations) {</pre>
 26
                 for (let previousIndex = 0; previousIndex < i; ++previousIndex) {</pre>
                     minWastedSpace[i][operations] = Math.min(
 27
                         minWastedSpace[i][operations],
 28
                         minWastedSpace[previousIndex][operations - 1] + wastedSpace[previousIndex][i - 1]
 29
 30
 31
 32
 33
 34
 35
         // The answer is the minimum wasted space for the whole array with k operations
 36
         return minWastedSpace[n][k];
 37 }
```

# Time and Space Complexity

**Time Complexity** 

**Space Complexity** 

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The time complexity of the code is determined by several nested loops:

runs n times, and the inner loop runs at most n times in the worst case, resulting in a time complexity of  $0(n^2)$  for this part. There are three loops used to calculate the minimum space wasted with k resizings in matrix f:

• There are two loops used to fill in the g matrix, which stores the space wasted if we resize the array from i to j. The outer loop

- The outermost loop runs n + 1 times (accounting for i from 1 to n).  $\circ$  The middle loop runs k + 1 times, since k is incremented at the beginning (k += 1).
- The innermost loop runs up to i times, which in the worst case would be n times. Combining these loops, we get a time complexity of  $0(n^2 * (k + 1))$  for this second part.

Combining both parts, the total time complexity is  $0(n^2 + n^2 * (k + 1))$ , which simplifies to  $0(n^2 * k)$ .

- The space complexity is determined by the space needed to store the matrices g and f: The g matrix is n by n, so it requires 0(n^2) space.
  - The f matrix is (n + 1) by (k + 1), so it requires 0(n \* k) space.

The total space complexity is  $0(n^2 + n * k)$ . Since in most cases k would be less than n, this simplifies to  $0(n^2)$ .