1030. Matrix Cells in Distance Order

Geometry Sorting Array Math Matrix Easy

Problem Description

distance from the center cell.

You are tasked with finding the coordinates of all cells in a given matrix, ordered by their distance from a specified center cell. Given four integers (row, cols, rCenter, cCenter), the problem defines a matrix of size rows x cols. Your position in the matrix is initially at the cell with coordinates (rCenter, cCenter). The goal is to return a list of coordinates of all cells in the matrix, sorted based on their Manhattan distance from the center cell

(rCenter, cCenter). The Manhattan distance between two points (r1, c1) and (r2, c2) is calculated as |r1 - r2| + |c1 - c2|. In

Leetcode Link

other words, it's the sum of the absolute differences of their corresponding coordinates. You have the flexibility to provide the sorted coordinates in any order as long as they are arranged from the nearest to the farthest

Intuition

The intuition behind the solution to this problem lies in the properties of the Manhattan distance and an algorithmic technique known

as Breadth-First Search (BFS).

time.

when graphed on the matrix. Since the problem asks us to order the cells by their distance from a center cell, using the BFS algorithm, we can ensure that we process cells in layers - starting with the center cell and moving outwards one distance unit at a

Manhattan distance has an interesting property where cells that are an equal distance from a given point form a diamond shape

front of the queue, add it to our answer list, and then add all its unvisited neighboring cells that are one unit away. To avoid adding the same cell multiple times, we also keep track of all visited cells using a boolean matrix called vis. This method ensures that we add cells to our answer list in increasing distance order without explicitly calculating the distance for every cell from the center. Once there are no more cells to add, we have processed the whole matrix, and our answer list contains all

Therefore, the approach is to create a queue and start from the center cell, adding it to the queue. We repeatedly take a cell from the

cells in the required sorted order. Solution Approach

The implementation of the solution uses Breadth-First Search (BFS) to explore the matrix starting from the given center. Here's a step-by-step walkthrough explaining how the given Python code achieves this: 1. Initialize Data Structures: A queue q is used to store cells for exploration, and it's implemented using a deque to allow efficient

popping from the front. A 2-dimensional list vis keeps track of visited cells; initially, all cells are marked as unvisited (False).

2. Queue Starting Cell: The starting cell, given by the coordinates (rCenter, cCenter), is added to the queue and marked as

cols.

returned as the final output.

Example Walkthrough

visited in the vis matrix. 3. Process Cells in Queue: The algorithm enters a while-loop that continues until the queue is empty. At each step, we process all

cells currently in the queue, ensuring that all neighbors one unit away are considered before moving to a larger distance.

- 4. Explore Neighbors: Within the loop, for each cell (p) taken from the queue, its neighbors are determined by iterating over the relative positions represented by (-1, 0, 1, 0, -1) using the pairwise function which gives us pairs of relative coordinates for
- the four directions (up, right, down, left). These are used to calculate the neighboring cells' coordinates (x, y). 5. Boundary and Visit Checks: Before a neighboring cell is added to the queue, there are two checks:
- added to the growing result set ans. 7. Return Results: After the while loop exits (when the queue is empty), it means that all cells have been explored according to their distance from the center, and the ans list contains them in the order of increasing Manhattan distance. The list ans is

The algorithm efficiently traverses the matrix in a manner that naturally sorts the cells by their Manhattan distance, eliminating the

need for an explicit sort operation, and is a classic example of BFS applied to grid traversal problems.

Queue q is initialized and contains the starting cell coordinates (1, 1).

Visited matrix vis is initialized with all values set to False.

Boundary Check: The coordinates (x, y) must be inside the matrix, which is checked with 0 <= x < rows and 0 <= y <

Visit Check: The vis matrix is checked to ensure the cell has not been visited before. If it hasn't, it is marked as visited.

6. Enqueue and Store Results: If a neighbor passes these checks, it is appended to the queue for subsequent exploration and also

Let's illustrate the solution approach using a small example. Suppose our matrix size is defined by rows = 3 and cols = 3, creating a 3×3 grid. The center cell is given by rCenter = 1 and cCenter = 1. The matrix with Manhattan distance from the center cell looks like this:

Initialization:

• Starting cell (1, 1) is marked as visited in vis and added to q.

Queue Starting Cell:

3 1 1 1

Process Cells in Queue: We begin processing by popping (1, 1) from the queue.

All neighbors are within the boundaries of the matrix and none of them are visited. They are marked as visited and added to the

queue q.

Return Results:

Explore Neighbors:

Boundary and Visit Checks:

Enqueue and Store Results:

• The order of neighbors being added to q and result set ans may vary, but let's assume they're added in the sequence (1, 0), (2, 1), (1, 2), (0, 1).

The neighbors of (1, 1) are (1, 0), (2, 1), (1, 2), (0, 1).

The process continues until all cells have been added to ans.

sequence that preserves the non-decreasing Manhattan distance order.

center cell, until all cells have been visited and added to the result in the required sorted order.

Python Solution from collections import deque

class Solution:

16

17

18

19

20

21

22

23

24

25

26

27

34

35

36

37

38

6

8

9

10

11

12

13

14

15

16

17

18

19

20

21

22

23

24

30

31

32

19

20

21

22

23

24

25

26

28

29

30

31

32

33

34

35

36

37

38

39

40

41

42

43

44

45

46

47

from typing import List

while queue:

return result

1 import java.util.ArrayDeque;

2 import java.util.Deque;

class Solution {

Java Solution

Initialize a queue with the starting cell, which is the center cell queue = deque([[r_center, c_center]]) # Create a 2D list to keep track of visited cells visited = [[False] * cols for _ in range(rows)] visited[r_center][c_center] = True 10

def allCellsDistOrder(self, rows: int, cols: int, r_center: int, c_center: int) -> List[List[int]]:

• The next level of neighbors would be the corners, (0, 0), (0, 2), (2, 0), (2, 2), each with Manhattan distance of 2.

In the end, ans would look like [(1, 1), (1, 0), (2, 1), (1, 2), (0, 1), (0, 0), (0, 2), (2, 0), (2, 2)] or any other such

This demonstrates how the BFS approach efficiently processes each layer of cells, grouped by their Manhattan distance to the

11 12 # List to store the cells in the order of increasing distance from the center result = [] 14 15 # Directions for moving up, right, down, and left

directions = [(-1, 0), (0, 1), (1, 0), (0, -1)]

Dequeue the front cell of the queue

for delta_row, delta_col in directions:

new_row = current_cell[0] + delta_row

new_col = current_cell[1] + delta_col

queue.append([new_row, new_col])

Return the cells in the order they were visited

current_cell = queue.popleft()

result.append(current_cell)

Perform a Breadth-First Search (BFS) starting from the center cell

Try moving in all four directions from the current cell

```
28
29
                    # Check if the new cell is within grid bounds and hasn't been visited
30
                    if 0 <= new_row < rows and 0 <= new_col < cols and not visited[new_row][new_col]:</pre>
                        # Mark the new cell as visited
31
32
                        visited[new_row][new_col] = True
33
                        # Add the new cell to the queue to explore its neighbors later
```

// Method to return the coordinates of all cells in the matrix, sorted by their distance from (rCenter, cCenter)

public int[][] allCellsDistOrder(int rows, int cols, int rCenter, int cCenter) {

// Initialize a queue to perform the breadth-first search

// Create a visited matrix to keep track of visited cells

// Use the `dirs` array to explore in all four directions

// Get the current cell from the queue

// Explore the neighbors of the current cell

// Create a result array to hold all cells in the required order

// Assign the current cell's coordinates to the result array

// Array to easily access all 4 surrounding cells (up, right, down, left)

int queueSize = queue.size(); // Number of elements at current level

auto [currentRow, currentCol] = queue.front();

answer.push_back({currentRow, currentCol});

int newRow = currentRow + directions[k];

int newCol = currentCol + directions[k + 1];

// Check if the new cell is within bounds and not visited

visited[newRow][newCol] = true; // Mark cell as visited

// Add the current cell to the answer

// Explore the neighboring cells

for (int k = 0; k < 4; ++k) {

int directions $[5] = \{-1, 0, 1, 0, -1\};$

// Perform BFS

while (!queue.empty()) {

while (queueSize--) {

queue.pop();

Deque<int[]> queue = new ArrayDeque<>();

queue.offer(new int[] {rCenter, cCenter});

int[][] result = new int[rows * cols][2];

// Index to insert the next point in `result`

int[] point = queue.poll();

result[index++] = point;

boolean[][] visited = new boolean[rows][cols];

// Start from the center cell

// Mark the center cell as visited

visited[rCenter][cCenter] = true;

int[] dirs = $\{-1, 0, 1, 0, -1\}$;

// Perform breadth-first search

int index = 0;

```
25
           while (!queue.isEmpty()) {
26
                for (int size = queue.size(); size > 0; size--) {
27
28
29
```

```
33
                     for (int k = 0; k < 4; ++k) {
 34
                         int x = point[0] + dirs[k], y = point[1] + dirs[k + 1];
 35
                         // Check for valid boundary conditions and unvisited state
                         if (x >= 0 \&\& x < rows \&\& y >= 0 \&\& y < cols \&\& !visited[x][y]) {
 36
 37
                             // Mark the new cell as visited
 38
                             visited[x][y] = true;
 39
                             // Add new cell's coordinates to the queue
 40
                             queue.offer(new int[] {x, y});
 41
 42
 43
 45
             // Return the result array containing all cell coordinates
 46
             return result;
 47
 48
 49
C++ Solution
    #include <vector>
  2 #include <queue>
     #include <cstring>
    class Solution {
    public:
         vector<vector<int>> allCellsDistOrder(int rows, int cols, int rCenter, int cCenter) {
             // Queue to perform BFS
             queue<pair<int, int>> queue;
  9
             queue.emplace(rCenter, cCenter); // Start from the center cell
 10
 11
 12
             // Initialize answer vector
 13
             vector<vector<int>> answer;
 14
 15
             // Visited matrix to keep track of visited cells
 16
             bool visited[rows][cols];
             memset(visited, false, sizeof(visited)); // Set all cells to unvisited
 17
 18
             visited[rCenter][cCenter] = true; // Mark the center cell as visited
```

return answer; // Return the cells sorted by their distance from the center 48 **}**; 49 50

```
Typescript Solution
    type Cell = [number, number]; // Defines a type for cells
    // Define a function to calculate all cells in distance order
    function allCellsDistOrder(rows: number, cols: number, rCenter: number, cCenter: number): Cell[] {
         // Queue to perform BFS
         const queue: Cell[] = [[rCenter, cCenter]];
  8
         // Initialize answer array
         const answer: Cell[] = [];
  9
 10
         // Visited matrix to keep track of visited cells. Initialize with false values.
 11
         const visited: boolean[][] = Array.from({ length: rows }, () => Array(cols).fill(false));
 12
 13
 14
         // Mark the center cell as visited
         visited[rCenter][cCenter] = true;
 15
 16
 17
         // Array to easily access all 4 adjacent cells (up, right, down, left)
 18
         const directions: number[] = [-1, 0, 1, 0, -1];
 19
 20
         // Perform BFS
         while (queue.length > 0) {
 21
 22
             const [currentRow, currentCol] = queue.shift()!; // Get the first cell in the queue ! non-null assertion operator since Arr
 23
 24
             // Add the current cell to the answer
 25
             answer.push([currentRow, currentCol]);
 26
 27
             // Explore the neighboring cells
 28
             for (let k = 0; k < 4; k++) {
                 const newRow: number = currentRow + directions[k];
 29
                 const newCol: number = currentCol + directions[k + 1];
 30
 31
 32
                 // Check if the new cell is within bounds and not visited
 33
                 if (newRow >= 0 && newRow < rows && newCol >= 0 && newCol < cols && !visited[newRow][newCol]) {</pre>
 34
                     visited[newRow][newCol] = true; // Mark cell as visited
 35
                     queue.push([newRow, newCol]); // Add the cell to the queue for further BFS
 36
 37
 38
 39
 40
         // Return the cells sorted by their distance from the center
 41
         return answer;
 42 }
 43
```

if (newRow >= 0 && newRow < rows && newCol >= 0 && newCol < cols && !visited[newRow][newCol]) {</pre>

queue.emplace(newRow, newCol); // Add the cell to the queue for further BFS

Time Complexity

Time and Space Complexity

The time complexity of this approach is O(R * C), where R is the number of rows and C is the number of columns in the matrix. This is

the number of cells.

The given code uses a BFS (Breadth-First Search) approach to traverse the matrix starting from the center cell (rCenter, cCenter). For each cell, it checks all four adjacent cells (up, down, left, right), which are represented by the pairwise combinations (-1, 0, 1, 0, -1).

because each cell is visited exactly once. The check 0 <= x < rows and 0 <= y < cols happens for 4 neighbors for each of the R *

c cells, but since each neighbor is only enqueued once (guarded by vis[x][y]), the total number of operations is still proportional to

Space Complexity The space complexity of the code is also O(R * C). The main factors contributing to the space complexity are:

- 1. The vis array, which is a 2D array used to keep track of visited cells, consuming R * C space. 2. The queue q, which in the worst case may contain all cells before being dequeued, thus also requiring up to R * C space.
- 3. The ans array, which will eventually hold all R * C cells in the order they were visited. Therefore, the space required is proportional to the number of cells in the matrix.