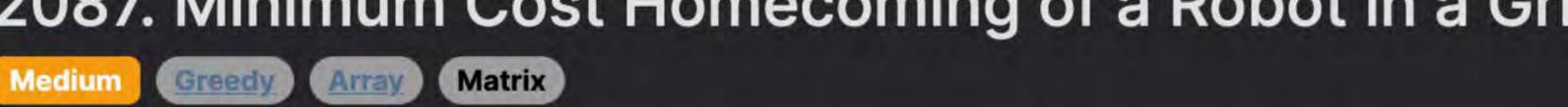
2087. Minimum Cost Homecoming of a Robot in a Grid



In this LeetCode problem, we are given a grid of size m x n, with the top-left cell at (0, 0) and the bottom-right cell at (m - 1, n -1). A robot is initially located at the cell startPos = [start_row, start_col], and its goal is to reach its home located at homePos = [home_row, home_col]. The robot can move in four directions from any cell - left, right, up, or down - while staying inside the grid

Leetcode Link

boundaries. The crux of the problem is to calculate the minimum total cost for the robot to return home. The costs of moving through the grid are

destination row, and moving to a cell in a different column incurs a cost from collosts equal to the value of the destination column. The task is to find and return this minimum cost.

given by two arrays: rowCosts and colCosts. Moving to a cell in a different row incurs a cost from rowCosts equal to the value of the

Intuition

only on the cells it passes through, particularly their row and column indices.

Problem Description

Hence, determining the minimum total cost can be done by separately calculating the cost for moving in the vertical direction (up or down, whichever is required to reach home_row) and the cost for moving in the horizontal direction (left or right, to reach home_col).

For the vertical movement, if startPos[0] (the start row) is less than homePos[0] (the home row), the robot needs to move down,

incurring the sum of rowCosts between these two rows. Conversely, if it is greater, the robot moves up, summing up the corresponding rowCosts in reverse order.

indicating a move to the right with the sum of colcosts between these columns. If greater, the robot moves left, summing the colCosts from home to start. The solution approach consists of two sums in each necessary direction – one for row movement and one for column movement.

Similarly, for the horizontal movement, we check if startPos[1] (the start column) is less than homePos[1] (the home column),

Finally, adding both sums gives us the total minimum cost required by the robot to reach its home. Solution Approach

concepts, relying on direct access to array elements and summing up slices of the arrays based on certain conditions. No complex data structures or patterns are needed for this approach, making it a perfect example of an efficient brute-force solution. Here's a step-by-step explanation of the code:

The provided solution approach is straightforward and directly translates the intuition into code. It utilizes simple algorithmic

home positions.

3. For vertical movement: o If the robot is below its home row (start_row < home_row), we sum rowCosts from the row just below the start row up to and including the home row, as the robot needs to move down.

- Otherwise (start_row >= home_row), we sum rowCosts from the home row up to but not including the start row, as the robot moves up.
- the start column up to and including the home column, as the robot needs to move right.

ans += sum(colCosts[j + 1 : y + 1])

at 0), and wants to move to its home at (2, 2).

ans += sum(colCosts[y:j])

including the start column, as the robot moves left.

- 6. We return the value computed in ans as this is the minimum cost for the robot to reach its home position. The essential algorithmic concepts used here are conditionals to determine the direction of the robot's movement and array slicing
 - ans += sum(rowCosts[i + 1 : x + 1]) ans += sum(rowCosts[x:i])
- This block of code succinctly captures the logic required to solve the problem. The use of array slicing in Python makes for an

Example Walkthrough Let's walk through a small example to illustrate the solution approach. Assume we have a grid represented by its size m x n, and for

The robot starts at position (1, 1), which corresponds to the second row and second column of the grid (since the grid indices start

\circ i, j for start position: i = 1, j = 1 \circ x, y for home position: x = 2, y = 2

Following the solution approach:

3. For vertical movement: i < x: This is true (1 < 2), so the robot moves down.</p>

• We sum up the rowCosts from the row just below the start row up to the home row, which is rowCosts[2] since we don't

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    j < y: This is also true (1 < 2), which means the robot moves to the right.</li>

• We sum up the colCosts from the column just to the right of the start column up to the home column, which again, is
  colCosts[2], with no range to sum.
o ans += colCosts[2], which is ans += 6.
```

need to sum a range here.

4. For horizontal movement:

o ans += rowCosts[2], which is ans += 3.

- In conclusion, the robot would incur a cost of 9 to move from [1, 1] to [2, 2], with a rowCosts of [1, 2, 3] and colCosts of [4, 5, 6]. The simplicity of this algorithm lies in its straightforward calculation of moving costs: we only consider the costs along the robot's
 - # Calculate the row movement cost if i < x: # If start row is less than home row, sum the costs from next of start row to home row total_cost += sum(row_costs[i + 1 : x + 1]) else:

If start row is greater than or equal to home row, sum the costs from home row to the row before start row

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else:
    # If start column is greater than or equal to home column, sum the costs from home column to the column before start colu
    total_cost += sum(col_costs[y:j])
return total_cost # Return the calculated total cost
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If start column is less than home column, sum the costs from next of start column to home column

C++ Solution

```
class Solution {
   public:
       // Method to calculate the minimum cost to move from the start position to the home position.
 6
       int minCost(std::vector<int>& startPos, std::vector<int>& homePos, std::vector<int>& rowCosts, std::vector<int>& colCosts) {
           // Extract start and home positions into readable variables
 8
           int currentRow = startPos[0], currentCol = startPos[1];
           int targetRow = homePos[0], targetCol = homePos[1];
10
            int totalCost = 0; // Initialize total cost to be accumulated
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           // Move vertically and accumulate row costs
           if (currentRow < targetRow) {</pre>
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               // Moving down: sum the costs from the row just below the current row to the target row (inclusive)
16
                totalCost += std::accumulate(rowCosts.begin() + currentRow + 1, rowCosts.begin() + targetRow + 1, 0);
           } else {
17
               // Moving up: sum the costs from the target row to the row just above the current row (exclusive)
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                totalCost += std::accumulate(rowCosts.begin() + targetRow, rowCosts.begin() + currentRow, 0);
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           // Move horizontally and accumulate column costs
           if (currentCol < targetCol) {</pre>
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               // Moving right: sum the costs from the column just right of the current column to the target column (inclusive)
25
               totalCost += std::accumulate(colCosts.begin() + currentCol + 1, colCosts.begin() + targetCol + 1, 0);
26
           } else {
27
               // Moving left: sum the costs from the target column to the column just left of the current column (exclusive)
28
                totalCost += std::accumulate(colCosts.begin() + targetCol, colCosts.begin() + currentCol, 0);
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           // Return the total calculated cost
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           return totalCost;
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34 };
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Typescript Solution
 1 // Import array manipulation functions, since std is not available in TypeScript
 2 // We would typically rely on native array methods in TypeScript
   // Function to calculate the minimum cost to move from the start position to the home position
   function minCost(startPos: number[], homePos: number[], rowCosts: number[], colCosts: number[]): number {
```

} else { 36 // Moving left: sum the costs from the target column to the column just left of the start column (exclusive) 37 totalCost += sumRange(colCosts, targetColumn, startColumn - 1); 38 39

return totalCost;

Time and Space Complexity The given Python function computes the minimum cost to move from a starting position to a home position on a grid, given the costs

// Moving right: sum the costs from the column just right of the start column to the target column (inclusive)

// Moving down: sum the costs from the row just below the start row to the target row (inclusive)

// Moving up: sum the costs from the target row to the row just above the start row (exclusive)

The time complexity of the code is determined primarily by the sum calls for row and column movements. • The first sum operation to calculate the row costs is 0(n) if x > i or 0(m) if x < i, where n is the number of rows from i + 1 to x

Time Complexity

+ 1 and m is the number of rows from x to i. • The second sum operation to calculate the column costs is O(p) if y > j or O(q) if y < j, where p is the number of columns from j + 1 to y + 1 and q is the number of columns from y to j.

- However, since each row and each column is found in the rowCosts and colCosts lists respectively only once, at most, we would
- perform a single pass through each list. Consequently, the overall time complexity is O(R + C), where R is the number of rows (length of rowCosts) and C is the number of columns (length of colCosts).

The space complexity of the function is 0(1) (or constant space) because the space usage does not grow with the size of the input. The function only uses a fixed number of integer variables to compute the result, and there are no data structures that grow with the input size.

The key insight to solve this problem is realizing that the robot can move in a straight line to its destination, without any detours, because there are no obstacles or restrictions on its path other than the grid boundaries. The cost incurred by the robot depends

1. First, we destructure the starting and home positions into their respective row and column indices: i, j for starting and x, y for 2. We initialize ans to zero to accumulate the total cost.

4. For horizontal movement: If the robot is to the left of its home column (start_col < home_col), we sum colCosts from the column just to the right of Conversely, if the robot is to the right (start_col >= home_col), we sum colCosts from the home column up to but not

5. We add the two sums from step 3 and step 4 to get the total cost, which we assign to ans. with the built-in sum() function to calculate the movement's cost.

elegant solution that is not only efficient but also easy to read and understand. our example, let's take m = 3 and n = 3, so we have a 3×3 grid. Let's say the startPos is [1, 1], and the homePos is [2, 2]. Also, let's say rowCosts = [1, 2, 3] and colCosts = [4, 5, 6].

1. We destructure the positions into their indices: 2. Initialize ans to zero.

5. Now, we add the two sums to get ans = 3 (from rowCosts) + 6 (from colCosts) = 9. 6. We return this ans value, which is the minimum total cost for the robot to move from its starting position to its home position on this grid. The minimum cost is 9.

path to its destination.

Python Solution

class Solution:

1 from typing import List

def minCost(self,

if j < y:

class Solution {

i, j = start_pos

 $x, y = home_pos$

start_pos: List[int],

row_costs: List[int],

total_cost += sum(row_costs[x:i])

Calculate the column movement cost

col_costs: List[int]) -> int:

total_cost = 0 # Variable to store the total cost

total_cost += sum(col_costs[j + 1 : y + 1])

// Initialize variables with starting positions.

int targetRow = homePos[0], targetCol = homePos[1];

// If currentRow is less than targetRow, move down.

// If currentRow is more than targetRow, move up.

// If currentCol is less than targetCol, move right.

// Extract start and home positions into readable variables

let totalCost = 0; // Initialize total cost to be accumulated

// Function to sum the elements of an array within a specified range

totalCost += sumRange(rowCosts, startRow + 1, targetRow);

totalCost += sumRange(rowCosts, targetRow, startRow - 1);

totalCost += sumRange(colCosts, startColumn + 1, targetColumn);

// Usage of the minCost function would involve calling it with appropriate arguments:

// const cost = minCost([startX, startY], [homeX, homeY], rowCostsArray, colCostsArray)

const sumRange = (costs: number[], start: number, end: number): number => {

const startRow = startPos[0];

const targetRow = homePos[0];

let sum = 0;

return sum;

const startColumn = startPos[1];

const targetColumn = homePos[1];

sum += costs[i];

if (startColumn < targetColumn) {</pre>

// Return the total calculated cost

if (startRow < targetRow) {</pre>

for (let i = start; i <= end; i++) {</pre>

// Move vertically and accumulate row costs

// Move horizontally and accumulate column costs

for (int row = targetRow; row < currentRow; ++row) {</pre>

for (int row = currentRow + 1; row <= targetRow; ++row) {</pre>

for (int col = currentCol + 1; col <= targetCol; ++col) {</pre>

// If currentCol is more than targetCol, move left.

for (int col = targetCol; col < currentCol; ++col) {</pre>

// Variable to keep track of the total minimum cost.

// Destination positions.

if (currentRow < targetRow) {</pre>

if (currentCol < targetCol) {</pre>

// Return the accumulated total cost.

int totalCost = 0;

} else {

} else {

return totalCost;

int currentRow = startPos[0], currentCol = startPos[1];

Initialize start position (i, j) and target home position (x, y)

public int minCost(int[] startPos, int[] homePos, int[] rowCosts, int[] colCosts) {

totalCost += rowCosts[row]; // Add cost for each row moved.

totalCost += rowCosts[row]; // Add cost for each row moved.

totalCost += colCosts[col]; // Add cost for each column moved.

totalCost += colCosts[col]; // Add cost for each column moved.

home_pos: List[int],

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1 #include <vector> 2 #include <numeric> // include necessary library for std::accumulate

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};

} else {

of moving through each row and column.

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Space Complexity