818. Race Car

Description

Your car starts at position and speed +1 on an infinite number line. Your car can go into negative positions. Your car drives automatically according to a sequence of instructions 'A' (accelerate) and 'R' (reverse):

When you get an instruction 'A', your car does the following:

```
position += speedspeed *= 2
```

- When you get an instruction 'R', your car does the following:
 - If your speed is positive then speed = -1
 - otherwise speed = 1

Your position stays the same.

For example, after commands "AAR", your car goes to positions 0 --> 1 --> 3 --> 3, and your speed goes to 1 --> 2 --> 4 --> --> 1.

Given a target position [target], return the length of the shortest sequence of instructions to get there.

Example 1:

```
Input: target = 3
Output: 2
Explanation:
The shortest instruction sequence is "AA".
Your position goes from 0 --> 1 --> 3.
```

Example 2:

```
Input: target = 6
Output: 5
Explanation:
The shortest instruction sequence is "AAARA".
Your position goes from 0 --> 1 --> 3 --> 7 --> 6.
```

Constraints:

• 1 <= target <= 10 ⁴