Q1: What is the Curse of Dimensionality?

Answer

The curse of dimensionality refers to various phenomena that arise when analyzing and organizing data in high-dimensional spaces that do not occur in lowdimensional settings. The common theme of these problems is that when the dimensionality increases, the volume of the space increases so fast that the available data become sparse.

Now let's say you have a square 100 yards on each side and you dropped a penny somewhere on it. It would be pretty hard, like searching across two football fields stuck together. It could take days.

The difficulty of searching through the space gets a lot harder as you have more dimensions. You might not realize this intuitively when it's just stated in mathematical

Now a cube 100 yards across. That's like searching a 30-story building the size of a football stadium. Ugh.

formulas, since they all have the same "width". That's the curse of dimensionality.

What is the Curse of Dimensionality and how can Unsupervised Learning help with it?

Source: en.wikipedia.org

Answer

the machine learning process, the more difficult the training becomes. • In very high-dimensional space, supervised algorithms learn to separate points and build function approximations to make good predictions.

• As the amount of data required to train a model increases, it becomes harder and harder for machine learning algorithms to handle. As more features are added to

- When the number of features increases, this search becomes expensive, both from a time and compute perspective. It might become impossible to find a good
- solution fast enough. This is the curse of dimensionality. • Using dimensionality reduction of unsupervised learning, the most salient features can be discovered in the original feature set. Then the dimension of this feature set can be reduced to a more manageable number while losing very little information in the process. This will help supervised learning find the optimum function to
- approximate the dataset. Source: www.amazon.com

Answer

If we increase dimensions or features, we are giving our data a higher chance to differentiate itself from other data points.

Q3: Why is data more *sparse* in a high-dimensional space?

The previous example illustrates that more dimensions give our data a higher chance of being different, of being unique, and that is why it becomes more sparse.

This also tells us that the distance between two random points increases with more dimensions: every data point is becoming increasingly separate and different from the rest.

Source: towardsdatascience.com

Answer

• As we increase the number of dimensions, our data becomes more sparse; every new dimension increases the volume of the feature space, giving our data a higher differentiation chance and therefore, the possibility of it becoming more spread out in a higher dimensional space than in a lower one. This means that if we

How does the Curse of Dimensionality affect Machine Learning models?

need more training samples of a kind for our model to be able to learn about them and be able to predict them well, generalizing, in the future.

- As we increase the number of dimensions, especially for parametric models, we increase the time it takes to train them. • Introducing features that don't add much value to our models and therefore increasing the number of dimensions, makes our model learn from these noisy or irrelevant features and can lead to a reduction in its performance.
- More features and thus dimensions lead to models that are more complex and harder to interpret than those with a low number of features.
- How does High Dimensionality affect Distance-Based Mining Applications?

Many distance-based data mining applications lose their effectiveness as the dimensionality of the data increases.

Source: towardsdatascience.com

distances between data points with increasing dimensionality. • As a result, distance-based models of clustering, classification, and outlier detection are often qualitatively ineffective. This phenomenon is referred to as the curse

of dimensionality.

Answer

- Source: www.amazon.com
- Q6: How does the Curse of Dimensionality affect Privacy Preservation? **Answer**

Anonymization is the process of modifying data before it is given for data analytics so that de-identification is not possible (so privacy is preserved) and will lead to K

• For example, a distance-based clustering algorithm may group unrelated data points because the distance function may poorly reflect the intrinsic semantic

indistinguishable records if an attempt is made to de identify by mapping the anonymized data with external data sources.

1. Computational challenges: Optimal k-anonymization is NP-hard. This implies that with increasing dimensionality, it becomes more difficult to perform privacy preservation.

2. Qualitative challenges: The qualitative challenges to privacy preservation are even more fundamental. Recently, it has been shown that it may be difficult to

perform effective privacy preservation without losing the utility of the anonymized data records. This is an even more fundamental challenge because it makes the privacy-preservation process less practical.

- Q7: Does kNN suffer from the Curse of Dimensionality and if it why?
- **Answer** Yes, very much so, K-Nearest Neighbors operates on the distance between the data points. The distance of the data points is inversely proportional to the exponential

Source: www.quora.com

we choose as a practitioner:

Source: www.amazon.com

What are some trade-offs when using *Embeddings* in Machine Learning?

increase in the number of data points that leads to the curse of dimensionality.

Answer

An embedding is a relatively low-dimensional space into which you can translate high-dimensional vectors. Embeddings make it easier to do machine learning on large inputs like sparse vectors representing words. The lossiness of the representation is controlled by the size of the embedding layer. In practice, the exact dimensionality of the embedding space is something that

However, if we're in a hurry, there are two rules of thumb that we could take: 1. Use the fourth root of the total number of unique categorical elements as the embedding dimension.

2. The embedding dimension should be approximate 1.6 times the square root of the number of unique elements in the category, and no less than 600.

For example, suppose we wanted to use an embedding layer to encode a feature that has 625 unique values:

• By choosing a very small output dimension of an embedding layer, too much information is forced into a small vector space and context can be lost.

• The optimal embedding dimension is often found through experimentation, similar to choosing the number of neurons in a deep neural network layer.

• On the other hand, when the embedding dimension is too large, the embedding loses the learned contextual importance of the features.

• Using the second rule of thumb, we'd choose 40. • If we are doing hyperparameter tuning, it might be worth searching within this range.

Explain Curse of Dimensionality to a child Answer

• To hunt birds, which now have an extra dimension they can move in

• To hunt a dog and maybe catch it if it were running around on the plain (two dimensions)

Q10: How does the Curse of Dimensionality affect k-Means Clustering?

• Using the first rule of thumb, we would choose an embedding dimension for a plurality of 5.

Source: stats.stackexchange.com

• To catch a caterpillar moving along the branch

Source: www.oreilly.com

Answer • k-Means is a search strategy to minimize the squared Euclidean distance. • As the number of dimensions increase, the objects become approximately equidistant (at equal distances) from each other given that the data is distributed

process of learning in machine learning (ML) algorithms finds that smaller dimensional representation space in the large raw vector v.

The analogy I like to use for the curse of dimensionality is a bit more on the geometric side, but I hope it's still sufficiently useful for your kid.

uniformly throughout the space. • What matters is not necessarily the number of variables, but the effective dimensionality of the data. It is quite common that most of the variation exists in a couple of dimensions. If this is the case then there will be fewer problems with k-means in the sense that the effective dimensionality is much smaller.

relevant features during learning.

For simplicity let's consider a single node,

So we can further write

Source: www.quora.com

increasing complexity.

Answer

After learning,

Answer

Source: stats.stackexchange.com

dimensions that maximize variation. The clusters might be in the lower-variation dimensions.

Q11: How does a Deep Neural Network escape/resist the Curse of Dimensionality?

Answer The curse of dimensionality normally comes about because in data there are relevant and too many irrelevant (noise) features. The neurons in deep learning (DL) architectures, use lots of data in order to model a problem and thereby a DL system reduces the influence of irrelevant features while increasing the influence of

 $v=[v_1,v_2,\cdots,v_n]$

For n very large number such as an image n = width × height, we know that the actual information exists in a much lower dimensional space than n. That is why

dimensionality reduction works well because it eliminates the curse of dimensionality by projecting the data into a much lower relevant representational space. The

 $y=\psi(\sum_{i=1}^n v_i w_i+b)$

The node makes a decision by weighing each feature vi thus after training the weights for corresponding relevant features will be high. Further, consider v is a

• Therefore, under the assumption that there are meaningful latent groupings in the data, they do not necessarily exist in all of the dimensions or in constructed

 $v = \left[v_{relevant}, v_{irrelevant}
ight]$ The weight vector can also be seen as a concatenated vector: $w = \left[w_{relevant}, w_{irrelevant}
ight]$

concatenation of the relevant feature vector and the irrelevant feature vector such as

 $w_{irrelevant} pprox 0$

 $egin{aligned} y = & \psi(v^Tw + b) \ y = & \psi(v^T_{relevant}w_{relevant} + v^T_{irrelevant}w_{irrelevant} + b) \end{aligned}$

The performance bounds on which the maximal margin classifier is based in linear SVM are independent of the input vector, but instead, depending on the margin of **separation** which is defined with the **hyperparameter** *C*. • For large values of C, the optimization will choose a smaller-margin hyperplane if that hyperplane does a better job of getting all the training points classified

correctly. • A very small value of C, will cause the optimizer to look for a larger-margin separating hyperplane, even if that hyperplane misclassifies more points.

Q12: Does linear SVMs suffer from the Curse of Dimensionality?

Source: stats.stackexchange.com

Instead of the complexity of the model being defined in terms of the number of model parameters, the parameter C is used to define a nested set of classes of models of

 $w^*(\alpha, \beta) = \arg\min_{w} P(w, \alpha, \beta, S_{train})$ Now we use this w* to predict on the validation sample to get validation error. We can view this scenario in terms of a validation error function: the function takes

So the goal of hyperparameter optimization is to find the set of values of α and β, that minimize this validation error function. Therefore, we resort to grid search: pick

a bunch of values of α : (α 1, α 2,...), pick a bunch of values of β : (β 1, β 2,...) and for each pair of values, evaluate the **validation error function**. Then pick the pair that

number of hyperparameters (d) increase a little, the procedure quickly becomes much more expensive.

Source: www.quora.com Q14: Does Random Forest suffer from the Curse of Dimensionality?

Answer

Source: stats.stackexchange.com

Random Forests use a collection of decision trees to make their predictions, but instead of using all the features of the problem, individual trees only use a subset of

Now, the dimension of the space we're looking at or the dimension of the grid we're working with is 2 here (one dimension is α and the other one is β). So if we have n values to try for α and values to try for β , the total number of pairs would be $n \times n$. Generalizing from here, if we have d parameters, the number of pairs (or ordered sets) would be n^d. That d in the exponent is the curse of dimensionality, as the

gives the minimum value of the validation error function.

Just to have some numbers, it is typical to have n = 5 or around that. So d = 2 hyperparameters require solving $5^2 = 25$ optimization problems, which is doable. But if we have d = 5 hyperparameters, we now need to solve 5⁵ = 3125 optimization problems, which is basically **too expensive** for most practical purposes.

the features. Since they use bootstrapped data and a random set of features, they ensure diversity and robust performance they are immune to the curse of dimensionality as they do not consider all the features at one time for individual trees. The main disadvantage is that they are complex and computationally expensive.

This is the reason that the SVM with an infinite-dimensional feature space (e.g. that induced by the radial basis function kernel) can still give good generalisation performance. However, this requires careful tuning of the regularisation parameter. In other words, the linear SVM is robust to the curse of dimensionality when the C parameter is tuned very carefully.

Q13: Why does the hyperparameter optimisation method *GridSearch* suffer from the *Curse of Dimensionality*?

Consider the standard classification framework, we have a sample which we divide into training sample and validation sample. We are solving an optimization problem P (which would usually be something like minimize training error plus a regularization term), which is a function of the model parameters, say w, the training **sample** and some **hyperparameters**, say α and β .

as inputs the hyperparameters α and β , and returns the validation error corresponding to $w*(\alpha,\beta)$.