Segment Trees

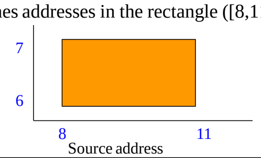
- Basic data structure in computational geometry.
- Computational geometry.
  - Computations with geometric objects.
  - Points in 1-, 2-, 3-, d-space.
    - Closest pair of points.
    - Nearest neighbor of given point.
  - Lines in 1-, 2-, 3-, d-space.
    - Machine busy intervals.

Examples

- Closest pair of points in 3D → track aircraft.
- 2D →Objects on earth (longitude and latitude).
- Nearest neighbor → find nearest gas station to current location.
- Nearest ship (longitude and latitude).

Segment Trees

- Rectangles or more general polygons in 2-space.
  - VLSI mask verification:Sufficient overlap between rectangles that represent wires and contact points on components of a VLSI design.
  - Finding most-specific matching rule requires finding the smallest rectangle that contains the point given by the packet's (source,dest).
  - Detect conflicting 2-d filters requires rectangle intersection detection. Filter matches addresses in the rectangle ([8,11], [6,7])



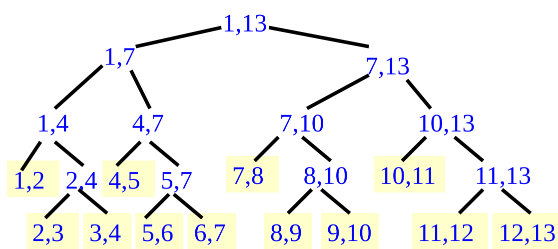
Segment Tree Application

- Store intervals of the form [i,j], i < j, i and j are integers.
  - [i,j] may, for example represent the fact that a machine is busy from time i to time j.
- Answer queries of the form: which intervals intersect/overlap with a given unit interval [a,a+1].
  - List all machines that are busy from 2 to 3.

Segment Tree – Definition

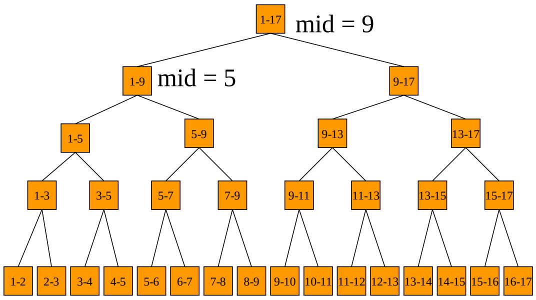
- Binary tree.
- Each node, v, represents a closed interval.
  - s(v) = **start** of v's range.
  - e(v) = **end** of v's range.
  - s(v) < e(v).
  - s(v) and e(v) are **integers**.
  - Root range = **[1,n].**
- e(v) = s(v) + 1 => v is a leaf node (unit interval).
- e(v) > s(v) + 1 =>
  - Left child range is **[s(v), (s(v) + e(v))/2].**
  - Right child range is **[(s(v) + e(v))/2, e(v)].**

Example – Root range = [1,13]

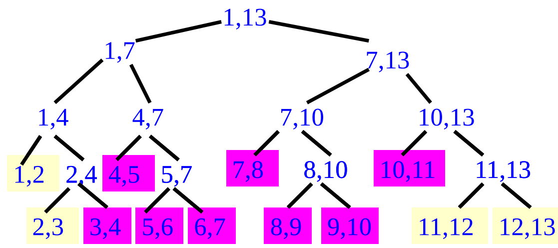


Cream colored boxes are leaves/unit intervals.

The Segment Tree T(1,17)



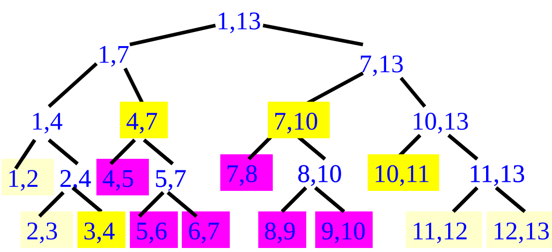
Store Interval [3,11]



Unit intervals of [3,11] highlighted.

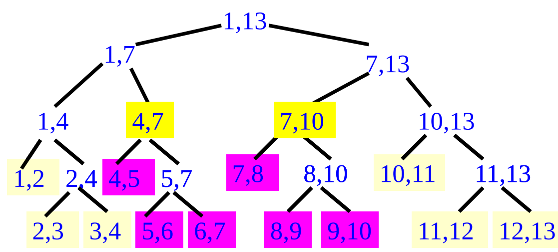
Each interval [i,j], i < j, is stored in one or more nodes of the segment tree.

Store Interval [3,11]



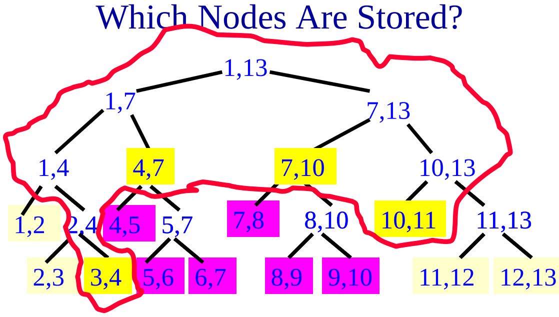
[3,11] is stored in node p iff all leaves in the subtree rooted at p are highlighted and no ancestor of p satisfies this property.

Store Interval [4,10]



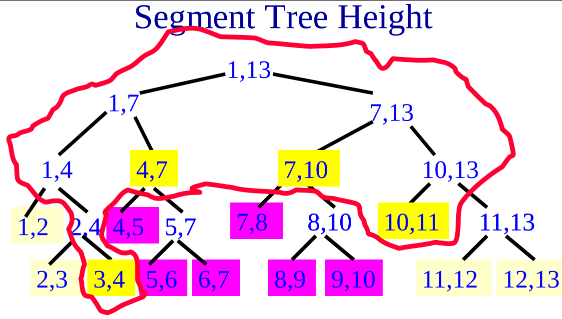
Each node of a segment tree contains **0 or more intervals**.

Which Nodes Are Stored?



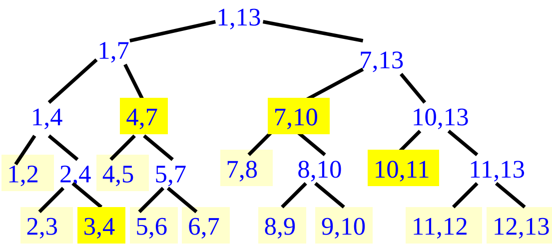
Need to store only those nodes that contain intervals plus the ancestors of these nodes.

Segment Tree Height



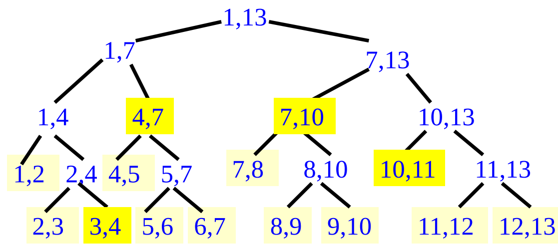
Range = [1,n] => Height <= ceil($\log_2$ (n-1)) + 1.

Properties



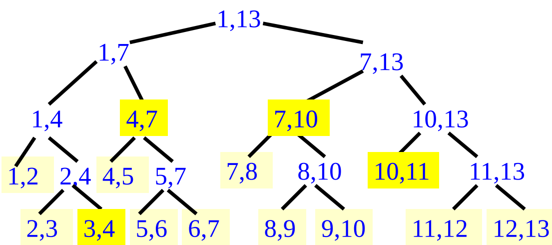
[i,j] in node v => [i,j] not in any ancestor of v .

Properties



[i,j] in node v => [i,j] not in sibling of v .

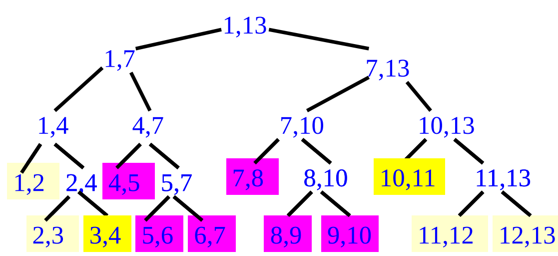
Top-Down Insert — [3,11]



Top-Down Insert

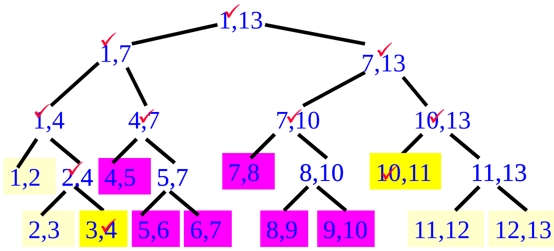
```
insert(s, e, v)
{// insert [s,e] into subtree rooted at v
    if (s <= s(v) && e(v) <= e)
        add [s,e] to v; // interval spans node range
    else {
            if (s < (s(v) + e(v))/2)
                insert(s,e,v.leftChild);
            if (e > (s(v) + e(v))/2)
                insert(s,e,v.rightChild);
        }
}
```

Complexity Of Insert



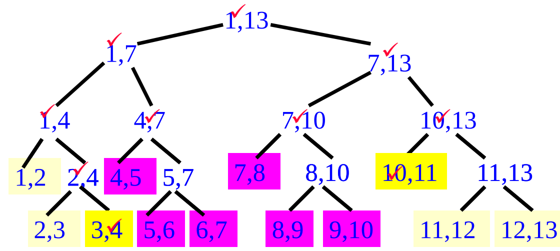
Let L and R, respectively, be the leaves for [s,s+1] and [e – 1,e].

Complexity Of Insert



In the worst-case, L, R, all ancestors of L and R, and possibly the other child of each of these ancestors are reached.

Complexity Of Insert



Complexity is O(log n).

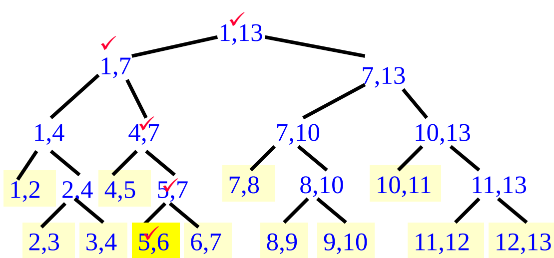
Top-Down Delete

```
delete(s, e, v)
{// delete [s,e] from subtree rooted at v
    if (s <= s(v) && e(v) <= e)
        delete [s,e] from v; // interval spans node range
    else {
            if (s < (s(v) + e(v))/2)
                delete(s,e,v.leftChild);
            if (e > (s(v) + e(v))/2)
                delete(s,e,v.rightChild);
          }
}
```

Search [a,a+1]

- Follow the unique path from the root to the leaf node for the interval [a,a+1].
- Report all segments stored in the nodes on this unique path.
- No segment is reported twice, because no segment is stored in both a node and the ancestor of this node.

Search – [5,6]



O(log n + s), where s is the # of segments in the answer.