

# Build Tutorial for SNR based GNSS Reflectometry (GNSS-R) Project

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# Parts

The parts list can be found here: <https://github.com/AjayACST/grss-ir-nz/tree/main/tutorial/part-list.xlsx>

## 1. Preparing Arduino

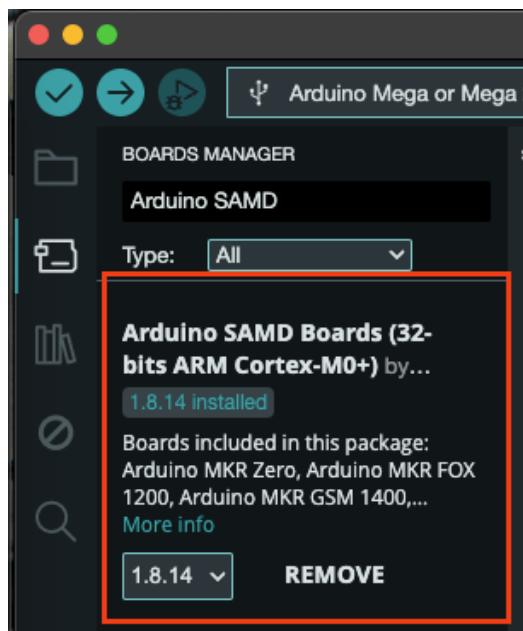
You will need:

1. Arduino MKR NB 1500
2. Micro SD Card

### 1.1 Arduino IDE Setup

Download the latest version of the Arduino IDE from here: <https://www.arduino.cc/en/software>

The first thing to do is install the board group from the Board Manager. To do this click the second icon in the sidebar and search for "Arduino SAMD". The board group you want to install is called "Arduino SAMD Boards (32-bits ARM Cortex-M0+)", install the latest version of this.



You can then install the library that we will need for this project. We will need the SD library which handles communication with the SD Card. To do this click the library icon below the boards manager and search for SD and install it. You will also need to install the ArduinoJSON library which is used to parse the JSON from the Dropbox API. To do this search for "ArduinoJSON" and install the latest version.



## 1.2 Format the SD Card

Before you can use the SD card with the Arduino you will need to format it. The link below has instructions on how to do this for both Windows and macOS. Ensure that the SD card is formatted as FAT32 (just FAT if you are using macOS) so that the Arduino can read it. <https://support.garmin.com/en-NZ/?faq=QqSbC0YZTz57kLm7uRQxZ7>

## 1.3 Get the firmware

Now that we have the board group and library installed we can upload the firmware to the Arduino. To do this create a new sketch and copy the code found [in the main.cpp file here](#) into the sketch. You will also need to copy or download the files `dropbox.cpp`, `dropbox.h`, `main.h`, `arduino_secrets.h.example` (see note below) into their own files as well. You can do this by copying the file in GitHub, then click the three dots near the top right of the arduino IDE and then "New File". Call the file the same as the file you are copying, you can then paste the code into the new file. You will need to do this for all three files.

When copying the `arduino_secrets.h.example` file remove the `.example` so you should have a file called `arduino_secrets.h`. In this file you will need to type in your sim providers APN, if you are using Spark you can leave this as `m2m`. For the dropbox app key and secret follow the guide below. [1.4 Dropbox Key](#).

## 1.4 Dropbox Key

To get a dropbox API key you will need a Dropbox account, and to create an app. To create an app go <https://dropbox.com/developers> and click the "Create App" button and sign in to your account if prompted. Then select "Scoped Access" and "App folder", then give your app a name, you can call this anything you want.

## Create a new app on the DBX Platform

### 1. Choose an API

Scoped access New  
 Select the level of access your app needs to Dropbox data. [Learn more](#)



### 2. Choose the type of access you need

[Learn more about access types](#)

App folder – Access to a single folder created specifically for your app.  
 Full Dropbox – Access to all files and folders in a user's Dropbox.

### 3. Name your app

gnss-ir-nmea

[Create app](#)

Once you have created the app you will be taken to the app, click on "Permissions" in the bar below the app name and add the `file.content.write` and `file.content.read` permissions. Click "Submit" to save the changes.

grss-ir-nmea

Settings Permissions Branding Analytics

Individual Scopes Individual scopes include the ability to view and manage a user's files and folders. [View Documentation](#)

**Account Info** Permissions that allow your app to view and manage Dropbox account info

account\_info.write View and edit basic information about your Dropbox account such as your profile photo  
 account\_info.read View basic information about your Dropbox account such as your username, email, and country

**Files and folders** Permissions that allow your app to view and manage files and folders

files.metadata.write View and edit information about your Dropbox files and folders  
 files.metadata.read View information about your Dropbox files and folders

files.content.write Edit content of your Dropbox files and folders  
 files.content.read View content of your Dropbox files and folders

**Collaboration** Permissions that allow your app to view and manage sharing and collaboration settings

sharing.write View and manage your Dropbox sharing settings and collaborators  
 sharing.read View your Dropbox sharing settings and collaborators

file\_requests.write View and manage your Dropbox file requests  
 file\_requests.read View your Dropbox file requests

contacts.write View and manage your manually added Dropbox contacts  
 contacts.read View your manually added Dropbox contacts

Then go back to the settings page and scroll down to the OAuth 2 section. Here you will find your app key and secret (you will need to click 'show' to copy the app secret). Copy these into the `arduino_secrets.h` file in the `#define DROPBOX_APP_KEY` and `#define DROPBOX_APP_SECRET` lines. You will also need to generate a first time dropbox access token, using the python script found on the GitHub:  
<https://github.com/AjayACST/grss-ir-nz/blob/main/python/dropbox/main.py>

To run this you will need Python 3 installed and the `dropbox` library. You can install this by running

```
pip install dropbox
```

Then run the script by running the command below in the terminal

```
python main.py
```

You may need to call python3 instead of python depending on your system. The script will ask you to paste in your app key and app secret, it will then give you a URL to open in your browser. This will ask you to log in to your dropbox account and will give you a code to copy. Copy this code and paste it into your terminal. If all has worked, after a few seconds you should see a message saying "Dropbox credentials saved to: ..." and a file called dropbox.txt created in the same directory as `main.py`. You will need to copy this file onto your SD card after formatting it.

```
/Users/ajayquirk/Library/Caches/pypoetry/virtualenvs/grss-ir-nz-qSQtWY8-py3.11/bin/python3.11 /Users/ajayquirk/Documents/Restore Labs/grss-ir-nz/python/dropbox/main.py
Enter your app key: 2qz4xi3bzoaige3
Enter your app secret: Access token here

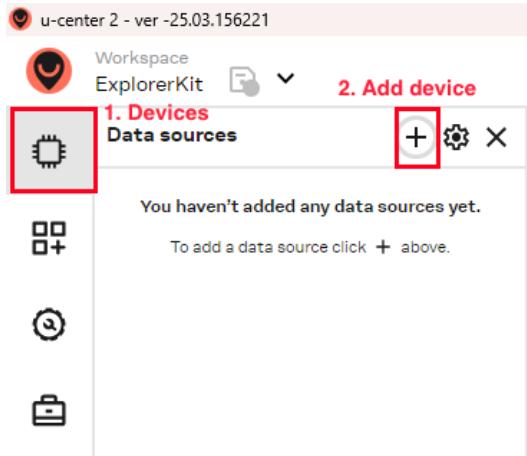
1. Go to: https://www.dropbox.com/oauth2/authorize?response\_type=code&client\_id=2qz4xi3bzoaige3&token\_access\_type=offline Copy this link into your browser
2. Click "Allow" (you might have to log in first).
3. Copy the authorization code.

Enter the authorization code here: SPbHzHEgXcYAAAAAAAAdS-wuuB_PWyEmbPnf1iuw7U
Dropbox credentials saved to dropbox.txt

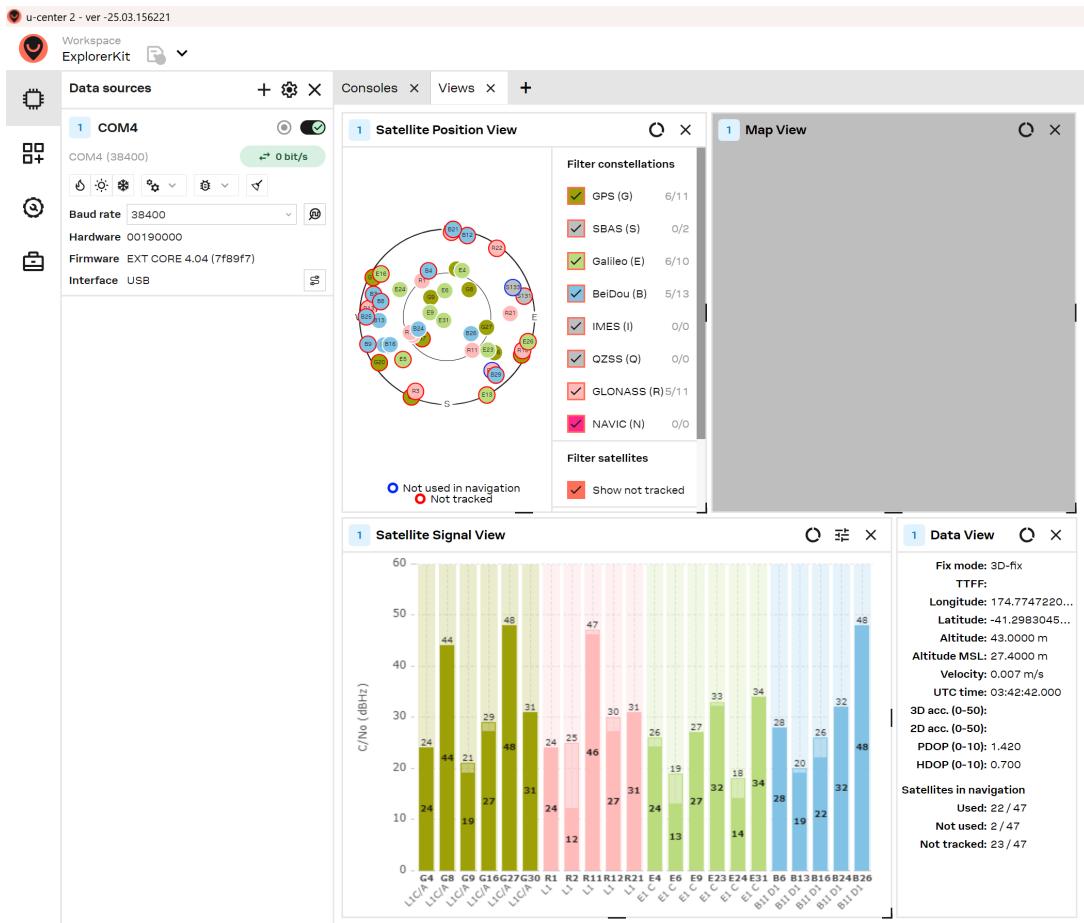
Process finished with exit code 0
```

## 1.5 Change GPS Output Rate

The GPS module will output data at a rate of 1Hz by default. This will create a massive amount of data that is not needed for this project. Therefore we will need to change the output rate to 0.2Hz (5 seconds). To do this you will need a windows computer and the u-Center software. You can download this from the u-Blox website here: <https://u-blox.com/u-center>, download u-Center 2.0. Once you have installed and opened u-Center you will need to connect the GPS module, if you are using the Sparkfun NEO-M9N from the parts list you can do this by plugging a USB-C cable into the module and your computer. Then click the "devices" icon and then the plus button.



Then select the COM port that the GPS module is connected to, this will be the one that is not the Arduino, and click 'Connect'. Assuming everything has connected correctly, and your GPS module has a FIX on some satellites you should see a screen like the one below.

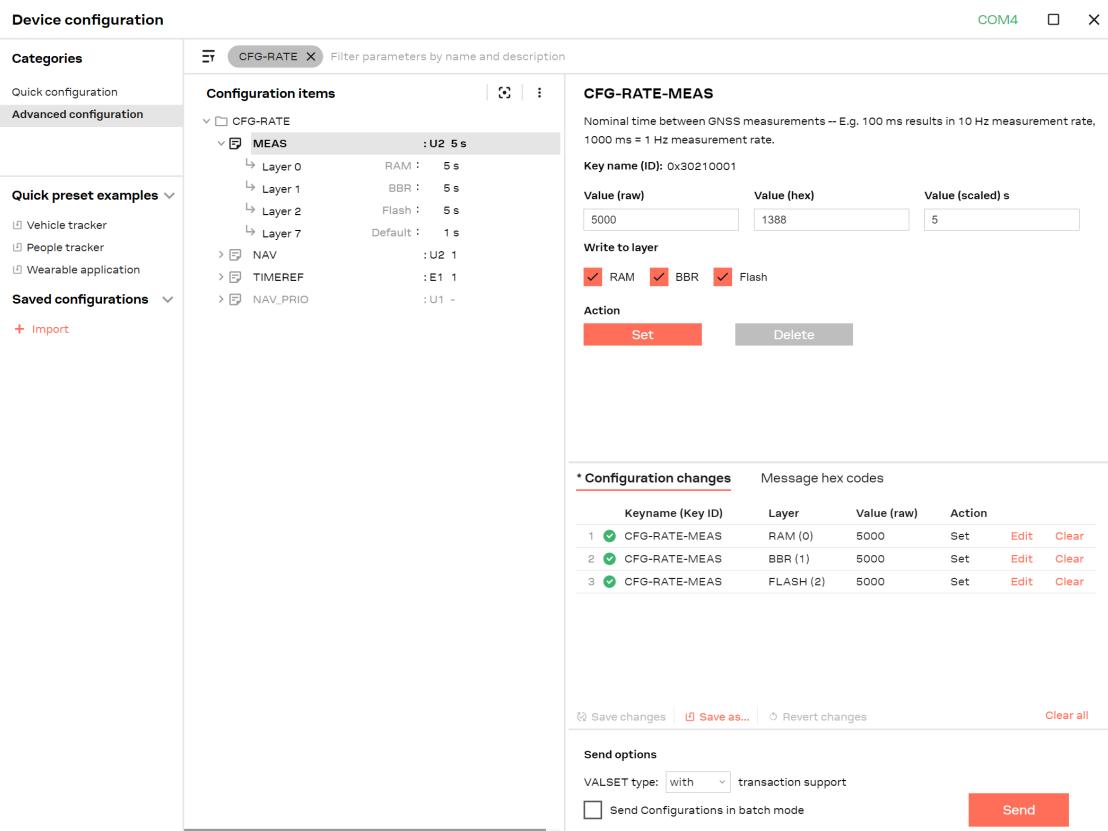


This screen shows all the parsed raw data that is collected from the GPS module. Now click the settings button beside the plus icon you used to add the module. In the window the comes up click the button indicated below to load in the current module configuration. Then search for "CFG-RATE" in the search bar.

The screenshot shows the "Device configuration" window for COM4:

- Categories**: Quick configuration and Advanced configuration are listed. Advanced configuration is selected.
- Quick preset examples**: Vehicle tracker and People tracker are listed.
- Configuration items**: A list of configuration items with checkboxes:
  - CFG-ANA
  - CFG-BATCH
  - CFG-BDS
  - CFG-GAL
  - CFG-GEOFENCE
  - CFG-HW
  - CFG-I2C
- Search Bar**: A search bar with placeholder text "Filter parameters by name and description".
- Buttons**: "Load Config" (highlighted with a red box) and "Configuration changes".
- Table**: A table titled "Configuration changes" with columns: Keyname (Key ID), Layer, Value (raw), and Action. It shows a single row: "No configuration changes added".

Then click the "CFG-RATE" option in the list, then the MEAS command. This will bring up the settings panel on the side, under "Value (scaled) s" change this to 5, then tick the boxes for "RAM", "BBR" and "Flash". Then click the "Set" button and then "Send". Assuming everything has worked you should see 3 green ticks beside the 3 rows added to the table when you clicked "Set".



You can now close out of u-Center and unplug the GPS module from your computer.

## 1.6 Install Cellular Library

You will need to install one more library before uploading the firmware. To do this download this zip file of code: <https://github.com/techstudio-design/SimpleNB/archive/refs/heads/master.zip> and in your Arduino IDE click the "Sketch" button in the toolbar and then "Include Library" -> "Add .ZIP Library". Then select the zip file you just downloaded. This will install the library needed for cellular communication. Once you have done this check everything compiles by clicking the "tick" icon in the top left of the Arduino IDE. If you have done everything correctly it should compile and you can move on to the next step!

## 1.7 Uploading the Firmware

Now plug the Arduino into your computer and select the board group that we installed earlier. Then select the board from the board selector beside the upload button. It should be indicated as "Arduino MKR NB 1500". If it is not go to Tools -> Board -> Arduino SAMD Boards (32-bits ARM Cortex-M0+) and select the Arduino MKR NB 1500. You can then click the Upload button, Right Arrow Icon, to upload the firmware to the Arduino.

## 1.8 C++ Definitions

At the top of the file below the #include directives there are a few definitions that you can change if you have some different configs

- `#define GPS_BAUD 38400` default baud rate for the u-Blox NEO-M9N GPS module, only change if using a different module
- `#define SERIAL_BAUD 9600` baud rate for the serial monitor, only change if you want to change the speed of the serial monitor.

- `#define IDLE_THRESHOLD 10` threshold for no output from GPS module to be considered "idle". In milliseconds.
- `#define SDCard 4` SD card chip select pin, only change if not using the MKR SD Shield.
- `#define WAIT_FOR_VALID_GPS` comment out if you want to start recording data immediately, even if the GPS module is not ready.
- `#define MAX_BASENAME_LEN (8+1)` maximum length of the basename of the log files
- `#define MAX_FILENAME_LEN (MAX_BASENAME_LEN+1+3)` maximum length of the log file name including extension
- `#define DEBUG` comment out if you want to disable debug messages, recommend to comment out when confirmed working.
- `#define GPS_BUFFER_SIZE_TYPICAL 512` typical size of the GPS nmea, used for buffer pre-allocation

## 2. Connecting the Electronics

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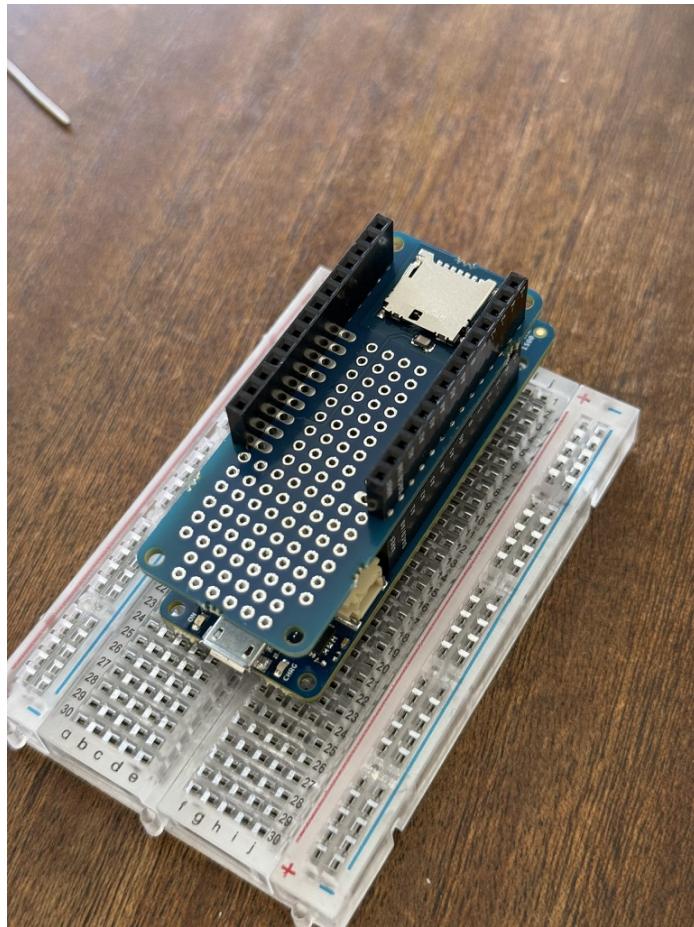
### 2.1 Connecting the Arduino and SD Shield

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You will need:

1. Arduino MKR NB 1500
2. Micro SD Card
3. Arduino MKR SD Shield
4. Header Pins
5. Breadboard

Start by plugging the SD Shield into the Arduino. To do this simply line the pins up on the SD shield to the pins on the NB 1500 and push them together. The pins should line up with the headers on the Arduino as shown below. As a general guide the SD card slot should face away from the micro USB port on the Arduino.



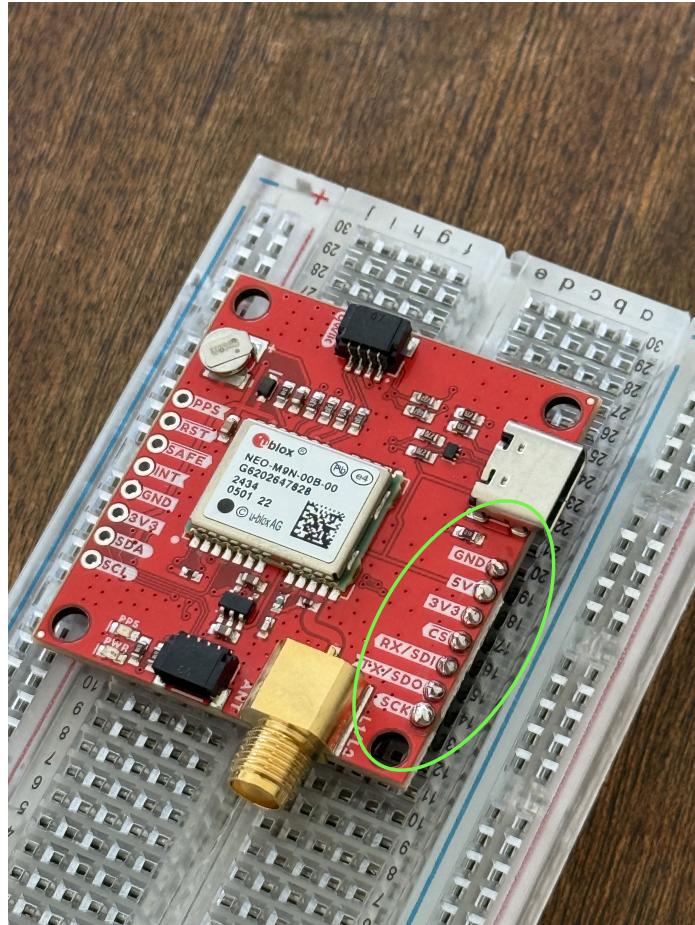
## 2.2 Connecting the Arduino and GPS Module

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You will need:

1. Arduino MKR NB 1500
2. Sparkfun NEO-M9N GPS Module
3. Breadboard
4. Jumper Wires
5. GNSS Antenna

To connect the GPS Module to the Arduino you will first need to solder the header pins to the GPS Module. To do this cut the header pins to the correct length and solder them to the GPS module. The pins should be soldered to the empty row that is on the USB port side of the PCB. Then put the header pins into the breadboard so that the longer side of the pins goes into the breadboard, then place the SD Shield on top of the header pins. You can then solder the header pins to the SD Shield.



Once it has been soldered you can plug the GPS Module and Arduino into the breadboard. To do this place the Arduino on one end of the breadboard and the GPS module on the other end. Ensuring that none of the pins from the GPS Module are connected to the same tracks that the Arduino is on. You can then connect the two devices using jumper wires.





The first image shows an example of bad placement of the board and GPS module.

The connections are as follows:

- GPS Module VCC -> Arduino 3.3V
- GPS Module GND -> Arduino GND
- GPS Module RX -> Arduino TX
- GPS Module TX -> Arduino RX

You can then connect the GNSS Antenna to the GPS Module. To do this plug the GNSS Antenna into the SMA connector on the GPS Module. This is the big gold connector on the side of the board, to connect it simply screw the antenna onto the connector.

## 2.3 Cellular Connection

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Add in info about how to get sim card

To start break the first layer of the sim card off so that you are left with the second-biggest size, the Micro Size. Then plug the sim card into the sim card slot on the back of the Arduino. The sim card slot is on the back of the board at the opposite end to the micro USB port. The sim card should be inserted with the gold contacts facing up.

Then plug the Laird antenna into the U.FL connector on the Arduino. This is the small circle connector on the front of the board, above the Sim card slot. This connector can be a bit tricky to plug in, so be careful when plugging it in. It can also come out easily so we would recommend using a small amount of hot glue or tape to hold it in place once you have confirmed that everything is working. [Add photo of completed board](#)

## 2.4 Preparing the Power System

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Euan to write or give information for me to write this up

# 3. Mounting the system

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Craig to write or give information for me to write this up

## 4. Testing the system

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### 4.1 Activity LEDs

There is a red LED on the Arduino that will blink every time data is written to the SD card. Ensure that this is flashing to make sure that data is saved. There is also a LED on the GPS module that will blink once a second when it has a fix. This means that it has a connection to the satellites and is ready to record data. The red LED on the arduino will only start to blink once the GPS module has a fix.

Add photo highlighting these LEDs

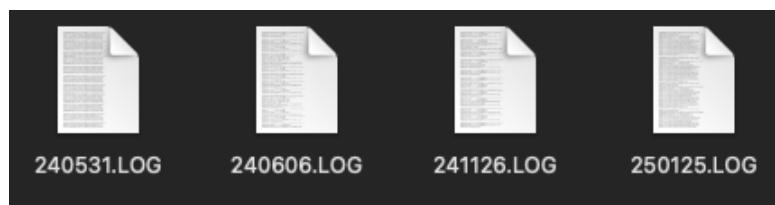
### 4.2 Serial Monitor

You can also check that the NMEA sentences look correct through the serial monitor. To do this follow the steps for plugging the arduino into the computer from [1.3 Uploading the Firmware](#). Then open the serial monitor by clicking the magnifying glass icon in the top right of the Arduino IDE. The baud rate should be set to 9600.

Add photo of serial monitor showing NMEA sentences

### 4.3 Data Files

The files that are saved to the SD Card will have an .log extension. The file names will look like the below photo:



Where the first two digits are the year, the second two digits are the month, and the last two digits are the day. This date is in UTC.

The data in the file should look like the below example

```
$GNGGA,000018.000,4443.0117,S,16910.7100,E,2,17,0.65,345.2,M,6.1,M,,*5E
$GPGSV,3,1,12,03,62,297,48,26,59,075,49,31,58,126,48,04,52,236,43*7D
$GPGSV,3,2,12,16,40,018,44,28,25,119,42,50,23,307,40,09,14,243,40*7A
$GPGSV,3,3,12,06,09,222,46,29,06,131,38,195,06,330,27,194,,,25*45
$GLGSV,2,1,08,80,79,002,43,70,71,203,35,79,40,142,43,69,37,054,46*69
$GLGSV,2,2,08,73,23,330,43,71,20,221,39,87,08,197,24,86,05,244,33*67
$GNRMC,000018.000,A,4443.0117,S,16910.7100,E,0.03,0.00,310524,,,D*6A

$GNGGA,000028.000,4443.0117,S,16910.7099,E,2,17,0.65,345.3,M,6.1,M,,*5D
$GPGSV,3,1,12,03,62,297,48,26,59,075,49,31,58,126,48,04,52,236,43*7D
$GPGSV,3,2,12,16,40,018,44,28,25,119,42,50,23,307,40,09,14,243,38*75
$GPGSV,3,3,12,06,09,222,45,29,06,131,38,195,06,330,24,194,,,25*45
```

\$GLGSV,2,1,08,80,80,003,43,70,71,203,34,79,39,142,43,69,37,054,46\*61  
\$GLGSV,2,2,08,73,24,330,42,71,20,221,33,87,08,197,24,86,05,244,32\*6A  
\$GNRMC,000028.000,A,4443.0117,S,16910.7099,E,0.01,0.00,310524,,,D\*6A