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Operations Research (Paper III)
MSc. (Computer Science) Semester III 2022-23

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Practical 1

Aim: Use graphical method to solve the following LPP:

Max Z = 3x + 5y
w.r.t.
x + 2y ≤ 2000,
x + y ≤ 1500,
y ≤ 600, x, y ≥
0

Source   Code:

```
require(lpSolv

e) C <- c(3, 5)

A <- matrix(c(1, 2,
              1, 1,
              0, 1), nrow = 3, byrow =

T) B <- c(2000, 1500, 600)

constraint_direction <- c("<=", "<=",

"<=")

plot.new()
plot.window(xlim = c(0, 2000), ylim = c(0,
2000)) axis(1) axis(2)
title(main = "LPP using graphical method", xlab = "X-axis",
ylab = "Yaxis") box()

segments(x0 = 2000, y0 = 0, x1 = 0, y1 = 1000, col =

"green") segments(x0 = 1500, y0 = 0, x1 = 0, y1 = 1500,

col = "red") segments(x0 = 0, y0 = 0, x1 = 600, y1 = 0,

col = "blue") z <- lp(direction = "max",

        objective.in = C,
const.mat = A,          const.dir =
constraint_direction,
const.rhs = B,          all.int = T
) print(z$status)

best_sol <- z$solution names(best_sol) <-
c("x1", "x2") print(paste("Total cost: ",
z$objval, sep = ""))
```

Output:

```
> # Use graphical method to solve the following LPP:
> # Max z = 3x + 5y
> # w.r.t
> # x + 2y ≤ 2000,
> # x + y ≤ 1500,
> # y ≤ 600,
> # x, y ≥ 0
>
> require(lpSolve)
>
> C ← c(3, 5)
>
> A ← matrix(c(1, 2,
+                1, 1,
+                0, 1), nrow = 3, byrow = T)
>
> B ← c(2000, 1500, 600)
>
> constraint_direction ← c("≤", "≤", "≤")
>
> plot.new()
> plot.window(xlim = c(0, 2000), ylim = c(0, 2000))
> axis(1)
> axis(2)
> title(main = "LPP using graphical method", xlab = "X-axis", ylab = "Y-axis")
> box()
>
> segments(x0 = 2000, y0 = 0, x1 = 0, y1 = 1000, col = "green")
> segments(x0 = 1500, y0 = 0, x1 = 0, y1 = 1500, col = "red")
> segments(x0 = 0, y0 = 0, x1 = 600, y1 = 0, col = "blue")
>
> z ← lp(direction = "max",
+          objective.in = C,
+          const.mat = A,
+          const.dir = constraint_direction,
+          const.rhs = B,
+          all.int = T
+          )
>
> print(z$status)
[1] 0
>
> best_sol ← z$solution
> names(best_sol) ← c("x1", "x2")
```
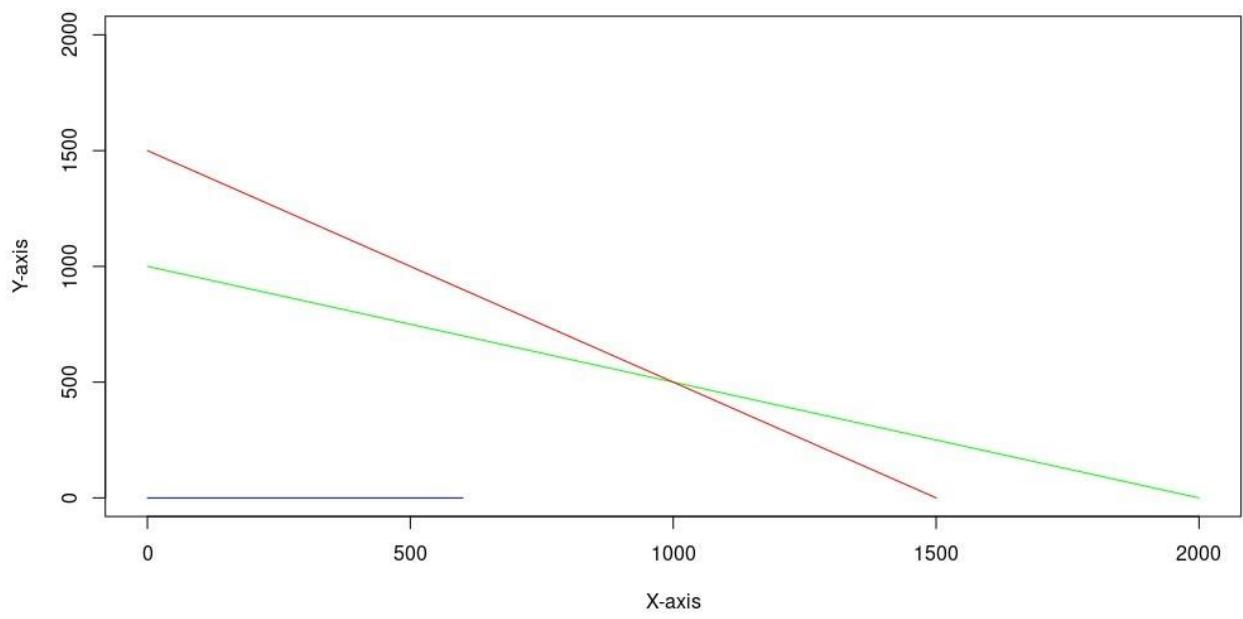
```
> best_sol ← z$solution
> names(best_sol) ← c("x1", "x2")
> print(paste("Total cost: ", z$objval, sep = ""))
[1] "Total cost: 5500"
>
```

LPP using graphical method

Aim: Use simplex method to solve the following LPP:

Practical 2

Max Z = 3x + 2y
w.r.t.
x + y ≤ 4,
x − y ≤ 2,
x, y ≥ 0

Source Code:

```
from scipy.optimize import linprog

obj = [-3, -2] lhs_ineq =
[[1, 1], [1, -1]] In[1]:
rhs_ineq = [4, 2] bound = [(0,

float("inf")), (0, float("inf"))]

z = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
bounds = bound, method = "revised simplex") In[2]:

z

print(z.fun)
In[3]:
print(z.success)
print(z.x)
```

Output:

```
In [1]:    1  from scipy.optimize import linprog
           2
           3  obj = [-3, -2]
           4  lhs_ineq = [[1, 1],
           5              [1, -1]]
           6
           7  rhs_ineq = [4,
           8              2]
           9
          10  bound = [(0, float("inf")),
          11           (0, float("inf"))]
```

```
In [2]:    1  z = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
           2              bounds = bound, method = "revised simplex")
           3
           4  z
```

```
Out[2]:        con: array([], dtype=float64)
               fun: -11.0
           message: 'Optimization terminated successfully.'
               nit: 2
             slack: array([0., 0.])
            status: 0
           success: True
                 x: array([3., 1.])
```

```
In [3]:    1  print(z.fun)
           2  print(z.success)
           3  print(z.x)
```

```
-11.0
True
[3. 1.]
```

Practical 3

Min $Z = x_1 - 3x_2 + 2x_3$
w.r.t
$3x_1 - x_2 + 3x_3 \leq 7$,
$-2x_1 + 4x_2 \leq 12$, $-4x_1$
$+ 3x_2 + 8x_3 \leq 10$, x_1,
x_2, $x_3 \geq 0$

Source Code:

Aim: Use simplex method to solve the following LPP:

```python
from scipy.optimize import linprog

obj = [1, -3, 2]

lhs_ineq = [[3, -1, 3],
            [-2, 4, 0],
            [-4, 3, 8]]
```

```python
rhs_ineq = [7,
            12,
            10]

bound = [(0, float("inf")),
         (0, float("inf")),
         (0, float("inf"))]


z = linprog(c = obj, A_ub = lhs_ineq, b_ub =
rhs_ineq,
```

```python
            bounds = bound, method = "revised
simplex") z
```

Output:

```
In [1]:    1  from scipy.optimize import linprog
           2
           3  obj = [1, -3, 2]
           4
           5  lhs_ineq = [[3, -1, 3],
           6              [-2, 4, 0],
           7              [-4, 3, 8]]
           8
           9  rhs_ineq = [7,
          10              12,
          11              10]
          12
          13  bound = [(0, float("inf")),
          14           (0, float("inf")),
          15           (0, float("inf"))]
```

```
In [2]:    1  z = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
           2              bounds = bound, method = "revised simplex")
           3
           4  z
```

```
Out[2]:        con: array([], dtype=float64)
               fun: -11.0
           message: 'Optimization terminated successfully.'
               nit: 2
             slack: array([ 0.,   0.,  11.])
            status: 0
           success: True
                 x: array([4., 5., 0.])
```

Practical 4

Max $Z = x + 2y$
w.r.t.
$2x + y \leq 20,$
$-4x + 5y \leq 10,$
$-x + 2y \geq -2, -x$
  $+ 5y = 15, x, y \geq$
  0

Source code:

Aim: Use simplex method to solve the following LPP:

```python
from scipy.optimize import linprog

obj = [-1, -2]

lhs_ineq = [[2, 1],
            [-4, 5],
         [1, -2]]

rhs_ineq = [20,

            10,
            2]

lhs_eq = [[-1, 5]]
rhs_eq = [15]

bound =  [(0, float("inf")),
          (0, float("inf"))]

z = linprog(c = obj, A_ub = lhs_ineq, b_ub =
rhs_ineq,
        A_eq = lhs_eq, b_eq = rhs_eq,

            bounds = bound, method = "revised simplex")
z
```

Output:

```
In [1]:    1  from scipy.optimize import linprog
           2
           3  obj = [-1, -2]
           4
           5  lhs_ineq = [[2, 1],
           6              [-4, 5],
           7              [1, -2]]
           8
           9  rhs_ineq = [20,
          10              10,
          11              2]
          12
          13  lhs_eq = [[-1, 5]]
          14  rhs_eq = [15]
          15
          16  bound =   [(0, float("inf")),
          17             (0, float("inf"))]
```

```
In [2]:    1  z = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
           2              A_eq = lhs_eq, b_eq = rhs_eq,
           3              bounds = bound, method = "revised simplex")
           4
           5  z
```

```
Out[2]:       con: array([0.])
              fun: -16.818181818181817
          message: 'Optimization terminated successfully.'
              nit: 3
            slack: array([ 0.        , 18.18181818,  3.36363636])
           status: 0
          success: True
                x: array([7.72727273, 4.54545455])
```

Aim:

Practical 5

Use Big M method to solve the following LPP:

$$\text{Min } Z = 4x_1 + x_2$$
w.r.t.
$$3x_1 + 4x_2 \geq 12,$$
$$x_1 + 5x_2 \geq 15,$$
$$x_1, x_2 \geq 0$$

Source code:

```python
from scipy.optimize import linprog

obj = [4, 1]
lhs_ineq = [[-3, -4],
           [-1, -5]]
```

In [1]:

```python
rhs_ineq = [-20,
           -15]

bound = [(0, float("inf")),
        (0, float("inf"))]
```

```python
opt = linprog(c=obj,A_ub=lhs_ineq,b_ub=rhs_ineq,
bounds=bound,method="interior-point")
```
In [2]:

Output:

opt

```
In [1]:    1  from scipy.optimize import linprog
           2
           3  obj = [4, 1]
           4  lhs_ineq = [[-3, -4],
           5               [-1, -5]]
           6
           7  rhs_ineq = [-20,
           8               -15]
           9
          10  bound = [(0, float("inf")),
          11           (0, float("inf"))]
```

```
In [2]:    1  opt =linprog(c=obj,A_ub=lhs_ineq,b_ub=rhs_ineq,
           2                  bounds=bound,method="interior-point")
           3
           4  opt
```

```
Out[2]:        con: array([], dtype=float64)
               fun: 5.0000000002364455
           message: 'Optimization terminated successfully.'
               nit: 5
             slack: array([1.64270375e-10, 1.00000000e+01])
            status: 0
           success: True
                 x: array([6.01160437e-11, 5.00000000e+00])
```

Practical 6

Use any method to solve the following resource allocation problem:

$$\text{Max } Z = 20x_1 + 12x_2 + 50x_3 + 25x_4 \ldots\ldots\ldots\ldots\ldots(\text{profit})$$
w.r.t. $x_1 + x_2 + x_3 + x_4 \leq 50$
.....................................(manpower) $3x_1 + 2x_2 + x_3 \leq 100$
.....................................(material A) $x_2 + 2x_3 \leq 90,$
.....................................(material B) $x_1, x_2, x_3 \geq 0$

Aim:
Source code:

```
from scipy.optimize import linprog

obj = [-20, -12, -40, -25]

lhs_ineq = [[1, 1, 1, 1],
        [3, 2, 1, 0],

        [0, 1, 2, 3]]

rhs_ineq = [50,
        100,
        90]
```

In [1]:

```
opt = linprog(c = obj, A_ub = lhs_ineq, b_ub =
```

rhs_ineq, In [2]: method="revised simplex") opt

Output:

```
In [1]:  1  from scipy.optimize import linprog
         2
         3  obj = [-20, -12, -40, -25]
         4
         5  lhs_ineq = [[1, 1, 1, 1],
         6              [3, 2, 1, 0],
         7              [0, 1, 2, 3]]
         8
         9  rhs_ineq = [50,
        10              100,
        11              90]
```

```
In [2]:  1  opt = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq, method="revised simplex")
         2
         3  opt
```

```
Out[2]:      con: array([], dtype=float64)
             fun: -1900.0
         message: 'Optimization terminated successfully.'
             nit: 2
           slack: array([ 0., 40.,  0.])
          status: 0
         success: True
               x: array([ 5.,  0., 45.,  0.])
```

Aim:

Practical 7

Use simplex method to solve the following LPP:

Max Z = 200x + 300y
w.r.t.
$2x + 3y \geq 1200,$
$x + y \leq 400, 2x$
$+ 1.5y \geq 900, x,$
$y \geq 0$

Source code:

```
from scipy.optimize import linprog

obj = [-200, 300]

lhs_ineq = [[-2, -3],
        [1, 1],
        [-2, -3/2]] rhs_ineq = [-

1200, 400, -900]

bnd=[(0, float("inf")),
(0, float("inf"))]


opt = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
bounds = bnd,
        method = "revised simplex")

opt
```

In [1]:

In [2]:

Output:

```
In [1]:   1  from scipy.optimize import linprog
          2
          3  obj = [-200, 300]
          4
          5  lhs_ineq = [[-2, -3],
          6              [1, 1],
          7              [-2, -3/2]]
          8
          9  rhs_ineq = [-1200, 400, -900]
         10
         11  bnd=[(0, float("inf")),
         12      (0, float("inf"))]
```

```
In [2]:   1  opt = linprog(c = obj, A_ub = lhs_ineq, b_ub = rhs_ineq,
          2                bounds = bnd,
          3                method = "revised simplex")
          4
          5  opt
```

```
Out[2]:      con: array([], dtype=float64)
             fun: 120000.0
         message: 'The problem appears infeasible, as the phase one auxiliary problem terminated successfully with a residual of
         3.0e+02, greater than the tolerance 1e-12 required for the solution to be considered feasible. Consider increasing the tol
         erance to be greater than 3.0e+02. If this tolerance is unnaceptably large, the problem is likely infeasible.'
             nit: 1
           slack: array([   0.,    0., -300.])
          status: 2
         success: False
               x: array([  0., 400.])
```

Aim:

Practical 8

Use dual simplex method to solve the following LPP:

Max Z = 40x$_1$ + 50x$_2$
w.r.t.
2x$_1$ + 3x$_2$ ≤ 3,
8x$_1$ + 4x$_2$ ≤ 5,
x$_1$, x$_2$ ≥ 0

Source code:

```
require(lpSolve)
f.obj <- c(40, 50)
f.con <- matrix(c(2, 3,
                  8, 4), nrow = 2, byrow = T)
f.dir <- c("<=", "<=")
f.rhs <- c(3, 5)

lp("max", f.obj, f.con, f.dir, f.rhs)$solution
lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens =
T)$sens.coef.from lp("max", f.obj, f.con, f.dir, f.rhs,
compute.sens = T)$sens.coef.to lp("max", f.obj, f.con, f.dir,
f.rhs, compute.sens = T)$duals lp("max", f.obj, f.con, f.dir,
f.rhs, compute.sens = T)$duals.to
```

Output:

```
> # Maximize the following:
> # z = 40x1 + 50x2
> # w.r.t
> # 2x1 + 3x2 ≤ 3
> # 8x1 + 4x2 ≤ 5
> # x1, x2 ≥ 0
>
> require(lpSolve)
Loading required package: lpSolve
> f.obj ← c(40, 50)
> f.con ← matrix(c(2, 3,
+                  8, 4), nrow = 2, byrow = T)
> f.dir ← c("≤", "≤")
> f.rhs ← c(3, 5)
>
> lp("max", f.obj, f.con, f.dir, f.rhs)$solution
[1] 0.1875 0.8750
> lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens = T)$sens.coef.from
[1] 33.33333 20.00000
> lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens = T)$sens.coef.to
[1] 100  60
```

```
> lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens = T)$duals
[1] 15.00  1.25  0.00  0.00
> lp("max", f.obj, f.con, f.dir, f.rhs, compute.sens = T)$duals.to
[1] 3.75e+00 1.20e+01 1.00e+30 1.00e+30
>
```

Practical 9

Solve following transportation problem in which each cell represents unit costs:

		Customers				Supply
		1	**2**	**3**	**4**	
Suppliers		10	2	20	11	15
		12	7	9	20	25
		4	14	16	18	10
Demand		5	15	15	15	

Source code:

```
library(lpSolve)
```

Aim:

```
cost <- matrix(c(10, 2, 20, 11,
                 12, 7, 9, 20,
                 4, 14, 16, 18), nrow = 3, byrow = T)


colnames(cost) <- c("Customer 1", "Customer 2", "Customer 3",
"Customer
4")
rownames(cost) <- c("Supplier 1", "Supplier 2", "Supplier 3")


row.signs <- rep("<=", 3)
row.rhs <- c(15, 25, 10)


col.signs <- rep("<=", 4)
col.rhs <- c(5, 15, 15, 15)


total.cost <- lp.transport(cost, "min", row.signs, row.rhs,
col.signs, col.rhs) total.cost$solution print(total.cost)
```

```
> ##SOLVE FOLLOWING TRANSPORTATION PROBLEM IN WHICH CELL ENTRIES REPRESENT UNIT COSTS USING R PROGRAMMIN
G.
>
> #           "Customer 1", "Customer 2", "Customer 3", "Customer 4"  SUPPLY
> #SUPPLIER 1    10            2            20            11           15
> #SUPPLIER 2    12            7            9             20           25
> #SUPPLIER 3    4             14           16            18           10
> #DEMAND        5             15           15            15
>
> library(lpSolve)
> cost ← matrix(c(10, 2, 20, 11,
+                 12, 7, 9, 20,
+                 4, 14, 16, 18), nrow = 3, byrow = T)
>
> colnames(cost) ← c("Customer 1", "Customer 2", "Customer 3", "Customer 4")
> rownames(cost) ← c("Supplier 1", "Supplier 2", "Supplier 3")
>
> row.signs ← rep("≤", 3)
> row.rhs ← c(15, 25, 10)
>
> col.signs ← rep("≥", 4)
> col.rhs ← c(5, 15, 15, 15)
```

```
> total.cost ← lp.transport(cost, "min", row.signs, row.rhs, col.signs, col.rhs)
> total.cost$solution
     [,1] [,2] [,3] [,4]
[1,]    0    5    0   10
[2,]    0   10   15    0
[3,]    5    0    0    5
> print(total.cost)
Success: the objective function is 435
```

Output:

Practical 10

Solve following assignment problem represented in this matrix:

		Jobs		
		1	**2**	**3**
Workers	**1**	15	10	9
	2	9	15	10
	3	10	12	8

Source Code:

```
library(lpSolve)

cost <- matrix(c(15, 10,
9,              9, 15,
10,
          10, 12, 8), nrow = 3, byrow = T)

cost
answer <- lp.assign(cost)
answer$solution
```

Output:

Aim:

```
> #SOLVE FOLLOWING ASSIGNMENT PROBLEM REPRESENTED IN FOLLOWING MATRIX USING R PROGRAMMING
> # Assignment Problem
> #         JOB1    JOB2    JOB3
> #W1      15       10      9
> #W2      9        15      10
> #W3      10       12      8
>
> library(lpSolve)
>
> cost <- matrix(c(15, 10, 9,
+                  9, 15, 10,
+                  10, 12, 8), nrow = 3, byrow = T)
>
> cost
     [,1] [,2] [,3]
[1,]   15   10    9
[2,]    9   15   10
[3,]   10   12    8
> answer <- lp.assign(cost)
```

```
> answer ← lp.assign(cost)
> answer$solution
     [,1] [,2] [,3]
[1,]    0    1    0
[2,]    1    0    0
[3,]    0    0    1
>
```