# Boost Your Program's Health

by Adding Fibers to your Coroutine

CppCon 2017

#### Thanks

Oliver Kowalke:
 Author of Boost Context, Boost Coroutines and Boost Fiber

Nat Goodspeed:
 Contributor to the libraries and author of proposals to ISO/WG21 for fibers and coroutines and speaker.

### Agenda

- Overview of coroutines
- Two implementations: Stackless and Stackful
- Generators
- Asynchronous APIs
- Threads and Fibers
- The Boost Fiber library
- Questions and Summary

#### More Information

- Presentation and samples at: <a href="https://github.com/david-sackstein/CppCon2017">https://github.com/david-sackstein/CppCon2017</a>
- Boost Fiber documentation
- My email: davids@codeprecise.com

### What are Coroutines?

- Coroutines are a generalization of subroutines.
- Coroutines can be suspended and resumed. The resume at the point of suspension with the same state.

#### Use Cases for Coroutines

- Generators, Parsers, Pulling from Visitors
- Asynchronous APIs without callbacks
- Combinations of the above: Asynchronous generators
- What is common to all of the above?
  - Coroutines help us "Invert Control"
  - We allow the code that is called in a callback behave as if it were in control

#### Inversion of Control with Generators

- Both Producer and Consumer want to be in the driver's seat:
  - Producers want to call a function to transfer data
  - Consumers want to call a function to receive data
- With coroutines:
  - <sup>-</sup> The Consumer pulls data. The Producer is the coroutine (inverted):
  - The producer suspends on entry
  - Then pushes data and suspends.
  - <sup>-</sup> Then resumes only when the consumer pulls again.

### Two Coroutine Implementations

- Coroutines TS:
  - Stackless
  - Suspend by return
- Boost Coroutine2
  - Stackful
  - Suspend by call

```
#include <boost/coroutine2/all.hpp>
template<typename T>
using pull_type = typename boost::coroutines2::asymmetric_coroutine<T>::pull_type;
template<typename T>
using push_type = typename boost::coroutines2::asymmetric_coroutine<T>::push_type;
static pull_type<int> GenerateIntegers()
    pull_type<int> source ([](push_type<int>& sink)
        for (int i = 0; i < 5; i++)
           sink(i);
    });
                                          Generator using Boost Coroutine2
    return source;
```

### **Generator using Coroutine TS**

```
#include <experimental/generator>
template <typename T>
using generator = std::experimental::generator<T>;
static generator<int> GenerateIntegers()
    for (int i = 0; i < 5; i++)
        co_yield i;
```

## First class objects?

- The generator is a first class object
  - Therefore generators can be chained together.
  - This is true for both coroutine implementations

### Chained Generator using Boost Coroutine2

```
static pull_type<int> GenerateSquares(pull_type<int>& anotherSource)
    pull_type<int> source ([&](push_type<int>& sink)
        for (int i : anotherSource)
            sink(i * i);
    return source;
```

### **Chained Generator using Coroutines TS**

```
static generator<int> GenerateSquares(generator<int>& anotherSource)
{
    for (int i : anotherSource)
    {
        co_yield i * i;
    }
}
```

### First class objects?

- The generator is a first class object
  - Therefore generators can be chained together.
  - This is true for both coroutine implementations
- What about the push capability? Can that be passed around?
  - In Boost Coroutine2 the push\_type can be passed around.
  - But in Coroutines TS we do not have access to a push object the coroutine invokes a key word (co\_yield) not an callable object.

#### **Nested Generation with Boost Coroutine 2**

```
static pull_type<int> ExtractedMethod(
    pull type<int>& anotherSource,
    push_type<int>& sink)
    for (int i : anotherSource)
        sink(i * i);
static pull_type<int> GenerateSquares(pull_type<int>& anotherSource)
    return pull_type<int> ([&](push_type<int>& sink)
        ExtractedMethod(anotherSource, sink);
    });
```

### Implications of Stacklessness

 Resumable functions require less memory on initial call and in some cases, the heap allocation can be elided and the code inlined

#### However

- Where generators are nested, nested iterations are required
- As they suspend by return all functions that invoke a coroutine must be aware that the callee may suspend.

### Implications of StackFullness

- Boost Coroutine2 coroutines needs to allocate a stack on the initial call. Still, stack allocation can be customized using the Boost Coroutine2 library.
- Because they suspend by call
  - Suspension is transparent to the caller.
  - This makes it easier to introduce coroutines to legacy code.
  - Nat Goodspeed demonstrates this in his C++Now 2016 talk:
     Pulling Visitors
  - Another example, a SAX puller

### Asynchronous IO

- Not only IO Any operation that takes time.
- Caller should not block the thread. If it does, an expensive context switch occurs.
- Instead we initiate the IO operation, install a callback and go and do something useful.
- When the operation completes the callback is invoked and we pick up where we were upon suspension.

#### Problems with callbacks

- Difficult to explain and to maintain
  - <sup>-</sup> The business logic of the class is split up into disjoint functions.
  - State has to be stored and retrieved each time a callback is called.
- Error handling is difficult.
  - In particular exceptions cannot be used
- The problem requires inversion of control.
  - We would like the function and the callback to behave as they were in control.

#### **Boost Asio**

- Provides a wrapper for synchronous and asynchronous use of sockets (and other OS facilities)
- io\_service implements the Proactor Pattern for asynchronous IO.
- Christopher Kohlhoff, the author of the library, provides a generalized way to invoke asynchronous operations.
- Callable objects are only one method of completion. The compiler can deduce different return types from handler types for coroutines, futures and more.

#### Coroutines and Boost Asio

• The code shows how a boost asio system timer that is invoked asynchronously can be awaited upon.

Coroutine TS
implemented
coroutine\_traits
<future<void>,
\_ArgTypes...>

```
std::future<void> sleepy(io_service &io) {
    io_service::work keep_io_service_alive { io };
    system_timer timer(io);
                                                                   Keeps
   timer.expires_from_now(1000ms);
                                                              io_service busy
    co_await timer.async_wait(boost::asio::use_future);
                                                              so it exits only
    std::cout << "After co_await 1\n";</pre>
                                                              after coroutine
   timer.expires_from_now(1000ms);
                                                                    ends
    co_await timer.async_wait(boost::asio::use_future);
    std::cout << "After co await 2\n";</pre>
   timer.expires_from_now(1000ms);
    co_await timer.async_wait(boost::asio::use_future);
    std::cout << "After co_await 3\n";</pre>
                                                   Indicates to asio that the
                                                   operation should return
int main() {
                                                   a std::future object.
    io service io;
    sleepy(io);
    io.run();
```

### From Threads to Coroutines To Fibers

- The Echo Server Project
- Four Parts
  - A. AsioSyncThreads
  - B. AsioAsyncCallbacks
  - C. AsioAsyncCoroutines
  - D. AsioAsyncFibers

### The Echo Server Project

- Implemented an EchoServer and a few EchoClients
- Clients send a message, Server responds with the same message, Clients send the message they received and so on.
- A Message is defined as a header indicating size and data of the specified size.
- Writing a Message requires to writes and reading a message requires two reads.
- We will zoom in on the Messenger object which reads and writes messages.

## A. AsioSyncThreads

Blocking IO on a thread per connection

# Reading a message synchronously

```
Message Messenger::read()
    size_t size;
    boost::asio::read(
        _socket,
        boost::asio::buffer(&size, sizeof(size)),
        boost::asio::transfer_all());
    Message message (size);
    boost::asio::read(
        _socket,
        boost::asio::buffer(message.data(), message.size()),
        boost::asio::transfer all());
    return message;
```

### A. AsioSyncThreads

- Blocking IO on a thread per connection
- The Good:
  - Main thread listening for connections remains responsive
- The Bad
  - Threads are expensive. Will not scale to thousands.
  - Context switching takes time and will dominate the server for large scales.

### B. AsioAsyncCallbacks

 Asynchronous IO using Boost Asio serviced by three threads (arbitrary number). The completion handlers are callback lambdas.

```
void Messenger::async_read(std::function<void(const error_code&, Message&&)> handler)
    auto callback = [this, handler](const error code& ec, size t bytes transferred)
       if (ec)
           handler(ec, 0);
       else
           _message = Message(_size);
           boost::asio::async_read(
               socket,
               boost::asio::buffer(_message.data(), _message.size()),
               boost::asio::transfer all(),
               [this, handler](const error_code ec, size_t bytes_transferred)
                  handler(ec, std::move( message));
                                                        Reading a message
               });
    };
                                                        asynchronously
    boost::asio::async read(
       socket,
       buffer(&_size, sizeof(_size)),
       transfer_all(),
       callback);
```

### B. AsioAsyncCallbacks

 Asynchronous IO using Boost Asio serviced by three threads (arbitrary number). The completion handlers are callback lambdas.

#### The Good

- Main thread listening for connections remains responsive
- Scales well. The number of threads does not depend on the number of connections.
- The Bad
  - Call back code is difficult to debug. Error handling is difficult

### C. AsioAsyncCoroutines

• Like B only asynchronous IO has been made to look like synchronous IO due to the use of coroutines.

## Asynchronously with Coroutine

```
void EchoConnection::start()
    auto self(shared from this());
    boost::asio::spawn(_strand, [self, this](yield_context yield)
        self->start(yield);
   });
```

## Asynchronously with Coroutine

```
Message Messenger::async_read(yield_context yield)
    size t size;
    size_t bytes_transferred =
        boost::asio::async read(
            socket,
            buffer(&size, sizeof(size)),
            transfer_all(), yield);
    auto message = Message(size);
    bytes transferred = boost::asio::async_read(
        socket,
        boost::asio::buffer(message.data(), message.size()),
        boost::asio::transfer_all(),
        vield);
    return std::move(message);
```

### C. AsioAsyncCoroutines

- Like B only asynchronous IO has been made to look like synchronous IO due to the use of coroutines.
- The Good
  - Main thread listening for connections remains responsive
  - Scales well. The number of threads does not depend on the number of connections.
  - <sup>-</sup> The code is now organized like synchronous code.

## Introducing the Boost Fiber Library

















































### Boost Fiber Library Architecture

- A fiber is a userland thread a thread of execution that is scheduled cooperatively.
- The library is organized as coroutines plus a manager plus a scheduler.
- Each fiber has its own stack.
- Like Boost Coroutine the library uses Boost Context to allocate and switch between stacks.
- You can choose the stack allocation strategy. The default is fixed size. The size itself is configurable.

### Fiber vs Thread

- At most one fiber on a thread can be running
- Therefore a fiber does not need to protect resources from other fibers running on the same thread.
- However, if a fiber on another thread access the resource protection is required.
- Spawning fibers does not distribute your computation across more hardware cores.
- But fibers do help you manage the division between working and waiting on a thread.

### Manager

- A fiber can be in the running, suspended or ready state.
- The running fiber can call the manager to yield or suspend itself.
  - When a fiber yields it moves to the ready state
  - When a fiber suspends it moves to a suspended state.
- In both cases the manager uses a scheduling algorithm to select another ready fiber to run.
- The manager performs a context switch to the selected fiber.
- If there were no ready fibers, the manager blocks the thread.
- Context switching is direct, the manager runs on the source fiber.

### Scheduler Algorithm

- There is one scheduler algorithm for all fibers in a thread
- The scheduler's responsibility is to pick one of the ready fibers that should to run.
- The default is a round robin scheduler among the ready fibers on the thread.
- So, by default a fiber will always be resumed on the thread where it was created.
- A blocked fiber can however be awoken by another thread

### Scheduler Algorithm

- The scheduling algorithm is an extension point. You can also implement and install your own.
- You can also install others provided by the library for instance:
  - shared\_work: ready fibers from all threads are treated equally
  - work\_stealing: local ready fibers are selected if any, otherwise a fiber is stolen from another scheduler
- Note that these algorithms migrate fibers between threads which requires care in protecting shared resources

### Fiber Suspension

- A fiber can yield itself or it can suspend itself (a.k.a. block) in a number of ways:
  - It can request to sleep (until a time or for a specified duration)
  - Use fiber synchronization objects that are defined in the library.
- The semantics of the synchronization objects are are similar to those in the std::thread library, however:
- The fiber types suspend only the current fiber. They do not block the thread (unless there are no other fibers to run)

# Synchronization Object

Туре	Comment
boost::fibers::mutex	Can be used with std::unique_lock
boost::fibers::condition_variable	No spurious wake ups
boost::fibers::barrier	Reusable fiber rendez-vous object
boost::fibers::future <t>, boost::fibers::promise<t></t></t>	
boost::fibers::packaged_task <t></t>	
boost::fibers::buffered_channel <t></t>	Like a future-promise of a sequence
boost::fibers::unbuffered_channel <t></t>	of values

## Context switching is fast\*

Haskell   stack-1.4.0/ghc-8.0.1	Go   go1.8.1	Erlang   erts-8.3
0.05 μs - 0.06 μs	0.42 μs <b>-</b> 0.49 μs	0.63 μs - 0.73 μs

#### Table 1.3. time per thread (average over 10,000 - unable to spawn 1,000,000 threads)

pthread	std::thread	std::async
54 μs - 73 μs	52 μs <b>-</b> 73 μs	106 μs - 122 μs

#### Table 1.4. time per fiber (average over 1.000.000)

fiber (16C/32T, work stealing, tcmalloc)	fiber (1C/1T, round robin, tcmalloc)
0.05 μs - 0.09 μs	1.69 μs <b>-</b> 1.79 μs

### Launch a fiber

```
boost::fibers::fiber _fiber(
    boost::fibers::launch::dispatch, // do not enter now
    []()
    {
        std::cout << "Running\n";
    });

boost::this_fiber::yield();</pre>
```

### Using an unbuffered\_channel

```
char WaitForChar()
   boost::fibers::unbuffered_channel<char> channel;
    std::thread canceller([&] {
        char c = getchar();
        channel.push(c);
    });
    canceller.detach();
    char c;
    channel.pop(c);
    return c;
```

### Using a future and a promise

```
boost::fibers::promise<error_code> pr;
boost::fibers::future<error code> fu = pr.get future();
boost::asio::async_read(
    _socket,
    buffer(data, size),
    transfer_all(),
    [&](const error_code& ec, size_t bytes_transferred)
        pr.set value(ec);
    });
return fu.get();
```

### D. AsioAsyncFibers

AsioAsyncFibers
 Like A only fibers are used instead of threads and asynchronous IO is used in combination with boost::fibers::future

# Asynchronously with Fiber

```
error_code AsyncMessenger::read(char* data, size_t size)
    boost::fibers::promise<error_code> pr;
    boost::fibers::future<error_code> fu = pr.get_future();
    boost::asio::async_read(
       socket,
        buffer(data, size),
        transfer_all(),
                                                                    Blocks the
        [&](const error_code& ec, size_t bytes_transferred)
                                                                   current fiber
            pr.set_value(ec);
                                                                       only
        });
    return fu.get();
```

### D. AsioAsyncFibers

- AsioAsyncFibers
   Like A only fibers are used instead of threads and asynchronous IO is used in combination with boost::fibers::future
- The Good
  - All of the advantages of A-B
- The Bad
  - Need to introduce grouping of connections on multiple threads.

## Questions

### Summary

- We have two implementations of coroutines
  - Stackless (in standardization process) and Stackful (Boost)
- Coroutines enable inversion of control
  - Generators
  - Asynchronous operations
- Threads should be used for parallel computation (or for a small number of background tasks)
- Fibers help organize the execution of asynchronous IO on a thread.