

## Programming with C++ Constraints: Background, Utility, and Gotchas

WALTER E. BROWN, PH.D.

< webrown.cpp @ gmail.com >



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### A little about me


- B.A. (math's); M.S., Ph.D. (computer science).
- Professional programmer for over 50 years, programming in C++ since 1982.
- Experienced in industry, academia, consulting, and research:
  - Founded a Computer Science Dept.; served as Professor and Dept. Head; taught and mentored at all levels.
  - Managed and mentored the programming staff for a reseller.
  - Lectured internationally as a software consultant and commercial trainer.
  - Retired from the Scientific Computing Division at Fermilab, specializing in C++ programming and in-house consulting.
- **Not dead — still doing training & consulting. (Email me!)**



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### Emeritus participant in C++ standardization

- Written 125+ papers for WG21, proposing such now-standard C++ library features as `gcd/lcm`, `cbegin/cend`, and `common_type`, as well as the entirety of headers `<random>` and `<ratio>`. 
- Influenced such core language features as *alias templates*, *contextual conversions*, and *variable templates*; working on *requires-expressions*, comparison operators, and more!
- Conceived and served as Project Editor for *Int'l Standard on Mathematical Special Functions in C++* (ISO/IEC 29124 ), now incorporated into C++17's `<cmath>`.
- Be forewarned: Based on my training and experience, I hold some rather strong opinions about computer software and programming methodology — these opinions are not shared by all programmers, but they should be! 😊

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### Coming soon to a compiler near you! 😊

- Compile-time **constraints** will soon be part of our routine C++ programming vocabulary:
  - Mainly due to `requires`, an expected new C++20 keyword ...
  - That introduces *requires-clauses* and *requires-expressions*.
- While this syntax is new to C++, the ideas are not, so ...
- This talk will explore:
  - What these ideas mean for us at a technical level, and ...
  - How they affect our past, present, and future C++ code.
  - (Some material is adapted from my recent WG21 paper “`enable_if` vs. `requires`: A Case Study” [wg21.link/p0552].)

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## std::disclaimer

- Code samples in this talk:
  - Freely use color and other highlighting techniques, ...
  - Mostly ignore proper headers and namespaces, and ...
  - May ignore (or subvert) a few other coding niceties.
- Why? In the interests of:
  - Clarity of exposition (my foremost concern), ...
  - Coping with screen real estate (a secondary concern), and ...
  - Emphasizing my main point(s).

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## 1. The Bigger Picture

*Instead of freaking out about these constraints, embrace them [and] use them to your advantage.*

— JASON FRIED

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### Nomenclature

- What's common to these terms?
  - Precondition
  - Constraint
  - Narrow contract
  - *requires-clause*
  - Wide contract
  - *requires-expression*
- All deal with requirements:
  - That a function or other component imposes, and ...
  - That are expected/assumed to be met before use.
- How do they differ?
  - Some requirements affect a component's correct use.
  - Other requirements affect a component's very existence.

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### Preconditions and contracts

- A function's **precondition** is a predicate:
  - Expected/assumed **true** each time the function is called:
    - Typically at run time, but at compile time if **constexpr** applies.
    - A function that checks its precondition doesn't really have one.
  - If its precondition is **false**, a function's behavior is undefined; the program (by definition) has a bug (see [res.on.required]/1).
- Preconditions are part of a function's **contract** with clients:
  - No preconditions  $\Rightarrow$  **wide** contract.
  - Any preconditions  $\Rightarrow$  **narrow** contract.
- Tangential to **constraints**, so not further discussed today:
  - (But keep an eye out for **[[expects: ]]**, etc., in a future C++.)

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### How are constraints different?

- A **constraint** is a **compile**-time predicate associated with some program component (e.g., a function or a template):
  - The constraint must be **satisfied** (evaluated as **true**), or else!
  - Else the associated component **WON'T/MUSTN'T BE COMPILED**:
    - But that doesn't always imply that something is wrong!
    - Like preprocessor directives **#if**, **#ifdef**, etc., in this regard.
- C++ has always had certain innate constraints:
  - Types impose constraints: e.g., arg's must initialize parm's.
  - Template specialization imposes constraints on its arg's.
- The C++98 era limited us to such implicit techniques.

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### Newer technologies

- C++11 gave us tools for explicit constraint programming:
  - Via `static_assert` to force a diagnostic when constraint is `false`.
  - Via `std::enable_if` metafunction in a `SFINAE` context to prevent a template's instantiation (and thus to prevent its compilation).
  - Via *expression SFINAE*, additional contexts in which deduction failures do not result in hard errors.
- Most recently, WG21 added:
  - C++17: `std::void_t` to support the *detection idiom*.
  - C++17: *constexpr if* and *discarded statements*.
  - C++20 WD: the *Concepts [Lite] TS requires* keyword.

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## 2. Pre-Modern Constraints

*There are no constraints ...  
except those we ourselves erect.*

— RONALD REAGAN

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### Statically asserting à la C++98

- Declare something that might, but needn't, be valid:
  - Let the validity depend on the truth of the constraint.
  - Guarantees a diagnostic when the constraint isn't satisfied.
  - Example: `int ensure[ 2 · int(constraint) - 1 ];`
- Or can apply **tag dispatch** for this purpose:
  - `template< bool b > struct ensure { };`
  - `int g_impl( T x, ensure<true> ) { return ... ; }`
  - `int g( T x ) { return g_impl( x, ensure<constraint>( ) ); }`

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### Using constraints à la C++98

- ②  $O(\log N)$  helper (a primary template with 2 partial spec's):

```

▪ template< unsigned N, class T, bool = (N % 2 == 0) >
  struct p { // primary template handles only odd N (see below)
    T operator ( ) ( T x ) { return x · p<N-1, T>{ }( x ); } };

▪ template< unsigned N, class T >
  struct p< N, T, true > { // constrains N to be even
    T operator ( ) ( T x ) { return p<N/2, T>{ }( x · x ); } };

▪ template< class T >
  struct p< 0, T, true > { // constrains N to be 0 (and even)
    T operator ( ) ( T ) { return T(1); } };
    
```

- ① Raise a value  $x$  (of type  $T$ ) to the  $N^{\text{th}}$  power:

```

▪ template< unsigned N, class T >
  T power( T x ) { return p<N, T>{ }( x ); } // dispatch to helper
    
```

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### Constraints à la C++11: the `enable_if` type trait metafunction

- If `true`, alias a given type; otherwise, provide `no alias`:
  - *// primary template assumes the bool value is true:*  
`template< bool, class T = void > // default is useful, not essential`  
`struct enable_if { using type = T; };`
  - *// partial specialization recognizes a false value, so no alias:*  
`template< class T >`  
`struct enable_if<false, T> { }; // no member named type!`
- Now consider a meta-call `enable_if< false, ... >::type` :
  - Refers to a non-existent member named `type`.
  - Always an error, right?
  - No, only sometimes an error: **SFINAE**!

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### Mechanics of SFINAE 1: instantiation

- To instantiate a template's declaration, the compiler:
  - ① Obtains (or figures out) each template argument:
    - a) Take verbatim if explicitly supplied at template's point of use.
    - b) Else **deduce** from function arguments, if any, at point of call.
    - c) Else rely on (C++17) class template's **deduction guide**(s), if any.
    - d) Else take from the declaration's **default template arguments**, if any.
  - ② Replaces each occurrence of a template parameter by its corresponding template argument. (**Substitution** step.)
- This process has one of two possible outcomes.

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## Mechanics of SFINAE 2: outcomes

- An instantiation attempt may succeed or may fail:
  - ① If substitution produces a well-formed declaration, the instantiation is **viable** (succeeds), but ...
  - ② If the resulting declaration is ill-formed, it is **not viable** (due to **substitution failure**) and is discarded w/ no diagnostic.
- In other words:
 

**SFINAE: Substitution Failure Is Not An Error!**
- But what is it good for?

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## Constraints à la C++11: explicit overload set management

- At most one of the following overloads will be instantiated:
  - Why? At most one of the predicates can be **true** and ...
  - The **false** predicates lead to ill-formed code that's discarded.
- 3 overloads to raise **x** (of type **T**) to the **N<sup>th</sup>** power:
 

```
template< unsigned N, class T >
enable_if_t< N == 0u, T >
power( T ) { return T(1); }
```

```
template< unsigned N, class T >
enable_if_t< (N != 0u) and N % 2u == 0u, T > // even, non-0 N
power( T x ) { return power<N/2u, T>{ }( x · x ); }
```

```
template< unsigned N, class T >
enable_if_t< N % 2u != 0u, T > // odd N
power( T x ) { return x · power<N-1u, T>{ }( x ); }
```

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### What's wrong with `enable_if` and `SFINAE`?

- Nothing at all. But ...
- The idiom does have limitations:
  - It requires a template context.
  - It's more challenging to use when a constructor is involved.
- And the resulting code tends to be verbose/wordy:
  - It's often not very transparent to read/understand.
  - Newer techniques for expressing constraints can be both easier to write and easier to read.

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## 3. Modern & Post-Modern Constraints

*We are so Post-Modern that we don't realize  
how Post-Modern we are anymore.*

— LARRY WALL

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### Constraints à la C++17: *constexpr if*

- An ordinary *if*, but evaluated at compile-time:
  - Branches not taken become **discarded statements**.
  - Each branch, even if discarded, must be parsable.
- Raise *x* to the *N*<sup>th</sup> power — no dispatching, no overloading:
  - ```
template< unsigned N, class T >
T power( T x ) {
    if constexpr( N == 0u ) return T(1);
    else if constexpr( N % 2u == 0u )
        return power<N/2>( x · x );    // O(log N) multiplications
    else    // N is odd
        return x · power<N-1>( x );
}
```
- While very useful, *constexpr if* doesn't fit all situations.

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### Constraints à la Concepts [Lite]

- *Concepts [Lite]* TS was published in late 2015:
  - Concepts parts weren't quite ready for C++17 integration.
  - Other parts specify syntax/semantics for a **requires-clause**.
- A *requires-clause* may be applied:
  - To any kind of template declaration, but ...
  - Also to an ordinary (non-template) function declaration:
    - In which case it's termed a **trailing requires-clause**.

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### Technical details of `requires`

- A *requires-clause* induces **constraints** on its component:
  - These must be **satisfied** (**true** at compile time) ...
  - To permit the component to be (instantiated and) compiled.
  - An unsatisfied constraint causes its associated component (an instantiation or a function) to be ignored à la SFINAE.
  - Mustn't use any component whose constraint is unsatisfied.
- **Subsumption** is a new consideration:
  - Applies when one constraint subsumes a second constraint.
  - Gives us the notion of **more constrained**.
  - Akin to templates' notion of *more specialized*.
- None of this machinery depends on any **concept** keyword.

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### Constraints are useful even without templates

- *E.g.*, overloaded functions:
  - `void xmit( char buffer[ ] ) requires local == endian::big;`
  - `void xmit( char buffer[ ] ) requires local == endian::little;`
  - `void xmit( char buffer[ ] ) requires local == endian::native;`
  - Each function implements, say, the transmission protocol appropriate to its supported environment.
- How can overloading work with identical argument lists?
  - The *requires-clause* is now part of the *signature*, so that ...
  - Only declarations whose constraint is satisfied will go into a call's set of viable candidates, and ...
  - As usual, the other declarations won't be further considered.

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### A *requires*-clause has several forms

- Can take any compile-time predicate, *e.g.*, a type trait.
- Or can refer to a named set of requirements (a *concept*):
  - *E.g.*, using a concept *C*, can write `... requires C<T> ...`.
  - The assoc. constraint is satisfied iff *T* meets *C*'s specification.
- Or can use an equivalent shorter form:
  - Instead of `template< class T > requires C<T> ...`,
  - Can write `template< C T > ...` (Stepanov/*Concepts TS* syntax).
- Or can use a *requires-expression* within a *requires-clause*:
  - *E.g.*, `... requires requires { e1; e2; ...; } ...`.
  - The associated constraint is satisfied iff each expression *e<sub>i</sub>* is well-formed.

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## 4. A Case Study: Implementing `std::swap`

*Every man lives by exchanging.*

— ADAM SMITH

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### Overview of the experiment

- Implemented `std::swap`'s specification twice:
  - Once with only `enable_if` technology, and then ...
  - Separately with only `requires` technology.
  - Identical function bodies; different function introductions.
- Validated each, identically, to ensure conformance:
  - Used established test cases from well-respected public and private sources.
  - Unexpectedly, testing showed a somewhat subtle difference in the two implementations' behavior!

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### `std::swap`'s specification

- Salient excerpts (from `[utility.swap]`):
  - `template < class T >`  
`void swap( T&, T& ) noexcept( ... );`
  - This function “shall not participate in overload resolution unless `T` is a movable type.”
- The highlighted formulaic words specify a constraint:
  - Namely, they require SFINAE-like behavior.
  - In this case, conforming implementers must tell the compiler to instantiate `std::swap<T>` only when `T` is a movable type.

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## ① Satisfying the spec via `enable_if` technology

- Declaration:
  - `template< typename T >`  
`enable_if_t< is_movable_v<T>, void >`  
`swap( T&, T& ) noexcept( ... );`
  - The `enable_if` result is positioned as `swap`'s return type.
- Two possibilities:
  - When the movability requirement holds, the metafunction call yields `void` (which is taken as `swap`'s return type) and so the resulting function declaration is well-formed and viable.
  - But when that predicate does not hold, `swap` has no return type, thus forming an ill-formed (hence non-viable) declaration that's discarded due to SFINAE.

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## ② Satisfying the spec via `requires` technology

- Declaration:
  - `template< typename T >`  
`requires is_movable_v<T>`  
`void`  
`swap( T&, T& ) noexcept( ... );`
  - Has an ordinary return type (namely `void`), because ...
  - Now the `requires` clause induces the specified constraint.
- Again, two possibilities:
  - When the moveability constraint is satisfied, the (well-formed) declaration will be a viable candidate.
  - But when the constraint is not satisfied, the declaration is considered non-viable and is silently discarded à la SFINAE.

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### Then came validation

- Consisted of several public and private test program suites.
- All went well, until ...
- When tested against `is_swappable.pass.cpp` (from libc++):
  - ✓ The `enable_if`-based implementation passed, but ...
  - ✗ The `requires`-based implementation failed!
- So what went wrong?

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### The failing test probes the `is_swappable` trait

- Relevant excerpt (names shortened):
  - ```
namespace ns {  
    struct A { };  
    template< class T > void swap( T&, T& ) { }  
}
```
- Consider `ns::A a, b; using std::swap; swap( a, b );`:
  - Ordinary (unqualified) name lookup finds `std::swap`, and ...
  - Argument-dependent lookup (ADL) finds `ns::swap`.
  - Which is better to call? Classic partial ordering says neither!
- `static_assert( ! std::is_swappable_v< ns::A > );`
  - The test passes if `A` is not swappable — which it isn't, here, due to the expected ambiguity re which function to call.
  - This works fine for `enable_if`, but not for `requires`!

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### So what's different about a *requires-clause*?

- It comes with a new rule (a tie-breaker of sorts):
  - When partial ordering considers two viable candidates, ...
  - The more constrained (by a *requires-clause*) candidate wins.
- In the second implementation:
  - `std::swap` was constrained by a *requires-clause*, so ...
  - The new rule applies (even though `ns::swap` was unconstrained).
- Result? The test code is no longer ambiguous:
  - `std::swap` is now the more constrained overload, and wins.
  - And the test's assertion, expecting ambiguity, now fails!

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### A caveat

- This talk uses the *requires* syntax and semantics as formulated in the *Concepts [Lite] TS*:
  - And as implemented by `gcc -fconcepts` for several years now.
- Much of that wording has been recently absorbed into the *C++20 Working Draft*, but:
  - That wording has already been considerably tweaked, and ...
  - WG21 discussions will continue, and so ...
  - Further technical adjustments seem likely.
- Therefore, what we actually get in C++20 may be slightly (or not-so-slightly 😊) different from today's exposition.
- But the thrust of today's talk will hold up, namely the ...

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## 5. Lessons Learned

*Ultimately there is no such thing  
as failure. There are lessons learned  
in different ways.*

— TWYLA THARP

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### About language constraints

- C++ constraints via *requires-clauses* are more than just a language solution for the ugliness of `enable_if`.
- If present, a constraint comes into play:
  - Whenever instantiating a template, or even when just using a template name.
  - As part of overload resolution, when compared during partial ordering.
- E.g., given `void g() requires false { }` *// not overloaded*
  - `g();` *// no; can't call g*
  - `void (*p)() = g;` *// no; can't take g's address*
  - `decltype(g)* p = nullptr;` *// no; decltype(g) is an invalid type*

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### The big picture

- Core language constraints (*requires-clauses*, etc.) become an integral part of a declaration.
- Traditional declarations, not constrained in this way, just aren't quite the same!
- With *requires-clauses* come an additional set of rules for overload resolution.
- We programmers must be cognizant of those new rules in our coding.
  - Most of these details seem not yet widely well-understood.
  - Sample misleading advice: "If an implementation turns `enable_if` constraints into concepts, you won't be able to tell the difference, programmatically." — NAME WITHHELD

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### Consequences

- "You potentially change overload resolutions every time you add constrained overloads [to] a set containing [only] unconstrained templates with equivalent types."  
— Andrew Sutton
- "`enable_if` cannot be directly replaced with `requires` without a semantic difference."  
— David Sankel
- Vendors are already free to meet today's standard library specifications via this new technology:
  - Doing so can (greatly!) simplify some implementations, ...
  - But, as shown, this (a) is detectable, (b) can affect user code in edge cases, and (c) affects the ABI (due to name mangling).

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## 6. Addendum

*He who never made a mistake,  
never made a discovery.*

— SAMUEL SMILES

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### Test your understanding

- How do these declarations differ?
  - a) `void f ( ); // unconstrained`
  - b) `void f ( ) requires true;`
- What about these?
  - c) `void g ( ) = delete;`
  - d) `void g ( ) requires false { }`
- And these?
  - e) `template< ... > requires true and false  
void h ( );`
  - f) `template< ... > requires true  
void h ( ) requires false;`

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### When you train/consult/discuss

- I respectfully suggest that only experienced programmers (journeymen and masters) should learn these details in the order I've presented them, namely bottom-up.
- Novices and apprentices should likely best approach this material from first principles, namely top-down.
- As you pass on this information, please keep in mind your various listeners' level of experience.

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FIN

WALTER E. BROWN, PH.D.

< webrown.cpp @ gmail.com >



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