Free Your Functions!

Encapsulation Abstraction / Polymorphism Cohesion Flexibility / Extensibility Reuse / Generality **Testability Performance**

Hypothesis:

Prefer non-member, non-friend functions

The SOLID Principles

- Single Responsibility Principle (SRP)
- Open-Closed Principle (OCP)
- Liskov Substitution Principle (LSP)
- Interface Segregation Principle (ISP)
- Dependency Inversion Principle (DIP)

Encapsulation

```
class WebBrowser
                               class WebBrowser
                                public:
 public:
  void clearCache();
                                  void clearCache();
  void clearHistory();
                                  void clearHistory();
  void removeCookies();
                                  void removeCookies();
                                private:
  void clearEverything()
                                  // ... the state
   {
                               };
      clearCache();
      clearHistory();
                               void clearEverything( WebBrowser& wb )
      removeCookies();
                                  wb.clearCache();
                                  wb.clearHistory();
 private:
   // ... the state
                                  wb.removeCookies();
};
```

"Object-oriented principles dictate that data and the functions that operate on them should be bundled together, and that suggests that the member function is the better choice. Unfortunately, this suggestion is incorrect. It's based on a misunderstanding of what being object-oriented means. Object-oriented principles dictate that data should be as encapsulated as possible. Counterintuitively, the member function [...] actually yields less encapsulation than the non-member [...]."

(Scott Meyers, Effective C++, 3rd edition)

Coupling

```
class X
public:
 private:
   std::vector<int> values_;
};
```

```
class X
 public:
   void doSomething( ... ) {
      // Reset values
 private:
   std::vector<int> values_;
};
```

```
class X
 public:
   void doSomething( ... ) {
      resetValues();
 private:
   void resetValues() {
      for( int& value : values_ )
         value = 0;
   std::vector<int> values_;
};
```

```
class X
 public:
   void doSomething( ... ) {
      resetValues( values_ );
 private:
   std::vector<int> values_;
};
void resetValues( std::vector<int>& vec )
{
   for( int& value : vec )
      value = 0;
}
```

Cohesion (SRP)

```
class X
{
  public:
  private:
    void resetValues() {
      for( int& value : values_ )
         value = 0;
    }
  std::vector<int> values_;
};
```

```
class X
 public:
 private:
   std::vector<int> values_;
};
void resetValues( std::vector<int>& vec )
   for( int& value : vec )
     value = 0;
```

Flexibility & Extensibility (OCP)

```
class X
 public:
 private:
   std::vector<int> values_;
};
void resetValues( std::vector<int>& vec )
   for( int& value : vec )
     value = 0;
```

Reuse (DRY)

```
class X
};
class Y
 public:
 private:
   std::vector<int> indices_;
};
void resetValues( std::vector<int>& vec )
   for( int& value : vec )
      value = 0;
```

```
class X
};
class Y
 public:
 private:
   std::vector<int> indices_;
};
void reset( std::vector<int>& vec )
   for( int& value : vec )
      value = 0;
```

Overloading

(Polymorphism)

```
class X
{
};
class Y
{
};
```

```
void reset( std::vector<int>& vec )
{
   for( int& value : vec )
    value = 0;
}
```

```
class X
   . . .
};
class Y
};
void reset( int& i )
  i = 0;
void reset( std::vector<int>& vec )
{
   for( int& value : vec )
      reset( value );
```

Generic Programming

```
class X
   . . .
};
class Y
};
void reset( int& i )
   i = 0;
template< typename T >
void reset( std::vector<T>& vec )
   for( T& value : vec )
      reset( value );
```

Abstraction

```
class X
   . . .
class Y
};
void reset( int& i )
   i = 0;
template< typename T >
void reset( std::vector<T>& vec )
   for( T& value : vec )
      reset( value );
```

Testability

```
class X
public:
 private:
   void reset() {
      for( int& value : values_ )
         value = 0;
   std::vector<int> values_;
};
```

```
class X
public:
 private:
   void reset() {
      for( int& value : values_ )
         value = 0;
   std::vector<int> values_;
   friend int testReset(...);
};
```

```
#define private public
class X
public:
 private:
   void reset() {
      for( int& value : values_ )
         value = 0;
   std::vector<int> values_;
};
```

```
class X
public:
 private:
   std::vector<int> values_;
};
template< typename T >
void reset( std::vector<T>& vec )
   for( T& value : vec )
      reset( value );
```

Performance

```
struct S {
   float x, y, z;
   double delta;

   double compute();
};
```

```
double f() {
    S s;
    s.x = /* expensive compute */;
    s.y = /* expensive compute */;
    s.z = /* expensive compute */;
    s.delta = s.x - s.y - s.z;
    return s.compute();
};
```

```
struct S {
    float x, y, z;
    double delta;
};

double compute( S s );
```

```
double f() {
    S s;
    s.x = /* expensive compute */;
    s.y = /* expensive compute */;
    s.z = /* expensive compute */;
    s.delta = s.x - s.y - s.z;
    return compute( s );
};
```

Encapsulation

Cohesion (SRP)

Flexibility / Extensibility (OCP)

Reuse (DRY)

Overloading (Polymorphism)

Generic Programming

Abstraction

Testability

Performance

"Is this even a real idea? Is it used anywhere?"

std::begin, std::cbegin

```
Defined in header <iterator>
                                                                          (since C++11)
template< class C >
auto begin( C& c ) -> decltype(c.begin());
                                                                          (until C++17)
                                                                      (1)
template< class C >
                                                                          (since C++17)
constexpr auto begin( C& c ) -> decltype(c.begin());
                                                                          (since C++11)
template< class C >
auto begin( const C& c ) -> decltype(c.begin());
                                                                          (until C++17)
                                                                      (1)
template< class C >
                                                                          (since C++17)
constexpr auto begin( const C& c ) -> decltype(c.begin());
template< class T, std::size_t N >
                                                                          (since C++11)
T* begin( T (&array)[N] );
                                                                          (until C++14)
                                                                      -(2)
template< class T, std::size t N >
                                                                          (since C++14)
constexpr T* begin( T (&array)[N] ) noexcept;
template< class C >
constexpr auto cbegin( const C& c ) noexcept(/* see below */)
                                                                     (3) (since C++14)
    -> decltype(std::begin(c));
```

std::real(std::complex)

```
Defined in header <complex>
template< class T >
                                                (1)
                                                     (until C++14)
T real( const complex<T>& z );
template< class T >
                                                (1)
                                                     (since C++14)
constexpr T real( const complex<T>& z );
long double real( long double z );
                                                (2)
                                                     (since C++11)
template< class DoubleOrInteger >
                                                (3)
                                                     (since C++11)
double real( DoubleOrInteger z );
float real( float z );
                                                (4)
                                                     (since C++11)
```

Returns the real component of the complex number z, i.e. z.real().

"Come on, this is just a reset() function!"

```
class X
{
  public:
  private:
    std::vector<int> values_;
};

template< typename T >
  void reset( std::vector<T> ) {
    for( T& value : values_ )
        reset( value );
}
```

```
class X
{
  public:
  private:
    std::vector<int> values_;
};

template< typename T >
  void reset( std::vector<T> ) {
    ...
}
```

"This is just a 'reset()' function!"

"Functions should be encapsulated!"

```
class X
 public:
   void doSomething( ... ) {
      resetValues();
 private:
   void resetValues() {
      for( int& value : values_ )
         value = 0;
   std::vector<int> values_;
};
```

```
class X
 public:
   void doSomething( ... ) {
      resetValues( values_ );
 private:
   std::vector<int> values_;
};
void resetValues( std::vector<int>& vec )
{
   for( int& value : vec )
      value = 0;
}
```

```
class X
 public:
   void doSomething( ... );
 private:
   std::vector<int> values_;
};
```

"Functions should be encapsulated!"

"IDEs don't help with free functions, but with member functions!"

"Note begin(c) and c.begin() for range-for loops and in general code. Why do we/someone have to write both? If c.begin() exists, begin(c) should find it, just as x+y finds the right implementation. ... In early 2014, Herb Sutter and I each independently decided to propose a unified syntax. ... To my surprise, many people came out strongly against x.f(y) finding f(x,y) – even if member functions were preferred over free-standing functions by the lookup rules. I received email accusing me of "selling out to the OO crowd"."

(Bjarne Stroustrup)

"Programmers cannot find free functions as easily as member functions!"

"In combination with ADL free functions mean trouble!"

std::complex<double> a, b;

```
std::complex<double> a, b;
min( a, b );
```

"In combination with ADL free functions mean trouble!"

"I'm using virtual functions, so I cannot use this idea!"

```
class X
{
  public:
    virtual void print( std::ostream& os ) {
        ...
};

std::ostream& operator<<( std::ostream& os, const X& x )
{
        x.print( os );
}</pre>
```

Use free functions in order to ...

- ... wrap virtual function calls
- ... get a homogeneous interface

"Does this mean we should convert to functional programming?"

```
class X
   . . .
class Y
};
void reset( int& i )
   i = 0;
template< typename T >
void reset( std::vector<T>& vec )
   for( T& value : vec )
      reset( value );
```

Multiparadigm

"Should we avoid member functions entirely?"

```
if (f needs to be virtual)
  make f a member function of C;
else if (f is operator>> or operator<< or
       f needs type conversions on its left-most argument)
 make f a non-member function;
 if (f needs access to non-public members of C)
   make f a friend of C;
else if (f can be implemented via C's public interface)
 make f a non-member function;
else
 make f a member function of C;
```

"But I have learned the opposite!"

"Free functions are just backward and C-style programming!"

copy() adheres to the ...

- · ... Single Responsibility Principle (SRP)
- · ... Open-Closed Principle (OCP)
- · ... Interface Segregation Principle (ISP)
- · ... Dependency Inversion Principle (DIP)

"There was never any question that the [standard template] library represented a breakthrough in efficient and extensible design."

(Scott Meyers, Effective STL)

"Free functions are just backward and C-style programming!"

Hypothesis:

Prefer non-member, non-friend functions

Guideline:

Prefer non-member, non-friend functions

Free Your Functions!