# Team notebook

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## 1 Algorithms

## 1.1 sliding window

```
* Given an array ARR and an integer K, the problem boils down to
     computing for each index i: min(ARR[i], ARR[i-1], ..., ARR[i-K+1]).
* if mx == true, returns the maximun.
* http://people.cs.uct.ac.za/~ksmith/articles/sliding_window_minimum.html
vector<int> sliding_window_minmax(vector<int> & ARR, int K, bool mx) {
 deque< pair<int, int> > window;
 vector<int> ans;
 for (int i = 0; i < ARR.size(); i++) {</pre>
   if (mx) {
     while (!window.empty() && window.back().first <= ARR[i])</pre>
       window.pop_back();
   } else {
     while (!window.empty() && window.back().first >= ARR[i])
       window.pop_back();
   }
   window.push_back(make_pair(ARR[i], i));
   while(window.front().second <= i - K)</pre>
     window.pop_front();
   ans.push_back(window.front().first);
 }
 return ans;
```

## 2 Data structures

#### 2.1 hash table

```
/**
 * Micro hash table, can be used as a set.
```

```
* Very efficient vs std::set
* */

const int MN = 1001;
struct ht {
  int _s[(MN + 10) >> 5];
  int len;
  void set(int id) {
    len++;
    _s[id >> 5] |= (1LL << (id & 31));
  }
  bool is_set(int id) {
    return _s[id >> 5] & (1LL << (id & 31));
  }
};</pre>
```

### 2.2 heavy light decomposition

```
// Heavy-Light Decomposition
struct TreeDecomposition {
 vector<int> g[MAXN], c[MAXN];
 int s[MAXN]; // subtree size
 int p[MAXN]; // parent id
 int r[MAXN]; // chain root id
 int t[MAXN]; // index used in segtree/bit/...
 int d[MAXN]; // depht
 int ts;
 void dfs(int v, int f) {
   p[v] = f;
   s[v] = 1;
   if (f != -1) d[v] = d[f] + 1;
   else d[v] = 0;
   for (int i = 0; i < g[v].size(); ++i) {</pre>
     int w = g[v][i];
     if (w != f) {
       dfs(w, v);
       s[v] += s[w];
```

```
void hld(int v, int f, int k) {
   t[v] = ts++;
   c[k].push_back(v);
   r[v] = k;
   int x = 0, y = -1;
   for (int i = 0; i < g[v].size(); ++i) {</pre>
     int w = g[v][i];
     if (w != f) {
       if (s[w] > x) {
        x = s[w]:
        y = w;
       }
     }
   }
   if (y != -1) {
     hld(y, v, k);
   for (int i = 0; i < g[v].size(); ++i) {</pre>
     int w = g[v][i];
     if (w != f && w != y) {
       hld(w, v, w);
     }
   }
 }
 void init(int n) {
   for (int i = 0; i < n; ++i) {</pre>
     g[i].clear();
   }
 }
 void add(int a, int b) {
   g[a].push_back(b);
   g[b].push_back(a);
 void build() {
   ts = 0;
   dfs(0, -1);
   hld(0, 0, 0);
 }
};
```

## 2.3 persistent array

```
struct node {
 node *1, *r;
 int val;
 node (int x) : 1(NULL), r(NULL), val(x) {}
 node (): l(NULL), r(NULL), val(-1) {}
typedef node* pnode;
pnode update(pnode cur, int 1, int r, int at, int what) {
 pnode ans = new node();
 if (cur != NULL) {
   *ans = *cur;
 if (1 == r) {
   ans-> val = what;
   return ans;
 int m = (1 + r) >> 1;
 if (at <= m) ans-> 1 = update(ans-> 1, 1, m, at, what);
 else ans-> r = update(ans-> r, m + 1, r, at, what);
 return ans:
int get(pnode cur, int 1, int r, int at) {
 if (cur == NULL) return 0;
 if (1 == r) return cur-> val;
 int m = (1 + r) >> 1;
 if (at <= m) return get(cur-> 1, 1, m, at);
 else
             return get(cur-> r, m + 1, r, at);
```

#### 2.4 persistent seg tree

```
/**
 * Important:
 * When using lazy propagation remembert to create new
 * versions for each push_down operation!!!
 * */
```

```
struct node {
 node *1. *r:
 long long acc;
 int flip;
 node (int x) : 1(NULL), r(NULL), acc(x), flip(0) {}
 node () : 1(NULL), r(NULL), acc(0), flip(0) {}
};
typedef node* pnode;
pnode create(int 1, int r) {
 if (1 == r) return new node();
 pnode cur = new node();
 int m = (1 + r) >> 1;
 cur \rightarrow 1 = create(1, m);
 cur \rightarrow r = create(m + 1, r);
 return cur:
}
pnode copy_node(pnode cur) {
 pnode ans = new node();
 *ans = *cur;
 return ans;
}
void push_down(pnode cur, int 1, int r) {
  assert(cur);
  if (cur-> flip) {
    int len = r - 1 + 1;
    cur-> acc = len - cur-> acc;
    if (cur-> 1) {
     cur \rightarrow 1 = copy_node(cur \rightarrow 1);
     cur-> 1 -> flip ^= 1;
    if (cur-> r) {
     cur-> r = copy_node(cur-> r);
     cur-> r -> flip ^= 1;
    cur-> flip = 0;
 }
}
int get_val(pnode cur) {
```

```
assert(cur):
  assert((cur-> flip) == 0);
 if (cur) return cur-> acc;
 return 0;
pnode update(pnode cur, int 1, int r, int at, int what) {
 pnode ans = copy_node(cur);
 if (1 == r) {
   assert(1 == at);
   ans-> acc = what:
   ans-> flip = 0;
   return ans;
 int m = (1 + r) >> 1;
 push_down(ans, 1, r);
 if (at <= m) ans-> 1 = update(ans-> 1, 1, m, at, what);
 else ans-> r = update(ans-> r, m + 1, r, at, what);
 push_down(ans-> 1, 1, m);
 push_down(ans-> r, m + 1, r);
 ans-> acc = get_val(ans-> 1) + get_val(ans-> r);
 return ans;
}
pnode flip(pnode cur, int 1, int r, int a, int b) {
 pnode ans = new node();
 if (cur != NULL) {
   *ans = *cur;
 if (1 > b | | r < a)
   return ans;
 if (1 >= a && r <= b) {</pre>
   ans-> flip ^= 1;
   push_down(ans, 1, r);
   return ans;
  int m = (1 + r) >> 1;
  ans-> 1 = flip(ans-> 1, 1, m, a, b);
  ans-> r = flip(ans-> r, m + 1, r, a, b);
 push_down(ans-> 1, 1, m);
  push_down(ans-> r, m + 1, r);
```

#### 2.5 segment tree

```
* Taken from: http://codeforces.com/blog/entry/18051
const int N = 1e5; // limit for array size
int n; // array size
int t[2 * N];
void build() { // build the tree
 for (int i = n - 1; i > 0; --i) t[i] = t[i << 1] + t[i << 1|1];
}
// Single modification, range query.
void modify(int p, int value) { // set value at position p
 for (t[p += n] = value; p > 1; p >>= 1) t[p>>1] = t[p] + t[p^1];
}
int query(int 1, int r) { // sum on interval [1, r)
 int res = 0:
 for (1 += n, r += n; 1 < r; 1 >>= 1, r >>= 1) {
   if (1&1) res += t[1++]:
   if (r\&1) res += t[--r]:
 }
```

```
return res;
}
// Range modification, single query.
void modify(int 1, int r, int value) {
 for (1 += n, r += n; 1 < r; 1 >>= 1, r >>= 1) {
   if (1&1) t[1++] += value:
   if (r&1) t[--r] += value;
 }
}
int query(int p) {
  int res = 0;
 for (p += n; p > 0; p >>= 1) res += t[p];
 return res:
 * If at some point after modifications we need to inspect all the
 * elements in the array, we can push all the modifications to the
 * leaves using the following code. After that we can just traverse
 * elements starting with index n. This way we reduce the complexity
 * from O(n \log(n)) to O(n) similarly to using build instead of n
     modifications.
 * */
void push() {
 for (int i = 1; i < n; ++i) {
   t[i<<1] += t[i];
   t[i<<1|1] += t[i];
   t[i] = 0:
 }
}
// Non commutative combiner functions.
void modify(int p, const S& value) {
 for (t[p += n] = value; p >>= 1; ) t[p] = combine(t[p<<1], t[p<<1|1]);
S query(int 1, int r) {
 S resl, resr;
 for (1 += n, r += n; 1 < r; 1 >>= 1, r >>= 1) {
   if (l&1) resl = combine(resl, t[l++]);
```

```
if (r&1) resr = combine(t[--r], resr);
}
return combine(resl, resr);
}
// To be continued ...
```

#### 2.6 sparse table

```
// RMQ.
const int MN = 100000 + 10; // Max number of elements
const int ML = 18; // ceil(log2(MN));
struct st {
 int data[MN];
 int M[MN][ML];
 int n;
 void read(int _n) {
   n = _n;
   for (int i = 0; i < n; ++i)</pre>
     cin >> data[i];
 }
 void build() {
   for (int i = 0; i < n; ++i)
     M[i][0] = data[i];
   for (int j = 1, p = 2, q = 1; p \le n; ++j, p \le 1, q \le 1)
     for (int i = 0; i + p - 1 < n; ++i)</pre>
       M[i][j] = max(M[i][j-1], M[i+q][j-1]);
 int query(int b, int e) {
   int k = log2(e - b + 1);
   return max(M[b][k], M[e + 1 - (1<<k)][k]);</pre>
 }
};
```

## 2.7 splay tree

```
using namespace std;
#include<bits/stdc++.h>
```

```
#define D(x) cout<<x<<endl;</pre>
typedef int T;
struct node{
 node *left, *right, *parent;
 T key;
 node (T k) : key(k), left(0), right(0), parent(0) {}
};
struct splay_tree{
 node *root;
  void right_rot(node *x) {
   node *p = x->parent;
   if (x->parent = p->parent) {
     if (x->parent->left == p) x->parent->left = x;
     if (x->parent->right == p) x->parent->right = x;
   if (p->left = x->right) p->left->parent = p;
   x->right = p;
   p->parent = x;
  void left rot(node *x) {
   node *p = x->parent;
   if (x->parent = p->parent) {
     if (x->parent->left == p) x->parent->left = x;
     if (x->parent->right == p) x->parent->right = x;
   if (p->right = x->left) p->right->parent = p;
   x->left = p;
   p->parent = x;
  void splay(node *x, node *fa = 0) {
   while( x->parent != fa and x->parent != 0) {
     node *p = x->parent;
     if (p->parent == fa)
       if (p->right == x)
        left_rot(x);
       else
```

```
right_rot(x);
   else {
     node *gp = p->parent; //grand parent
     if (gp->left == p)
       if (p->left == x)
         right_rot(x), right_rot(x);
         left_rot(x),right_rot(x);
     else
       if (p->left == x)
         right_rot(x), left_rot(x);
       else
         left_rot(x), left_rot(x);
   }
  }
  if (fa == 0) root = x;
void insert(T key) {
  node *cur = root;
  node *pcur = 0;
  while (cur) {
   pcur = cur;
   if (key > cur->key) cur = cur->right;
   else cur = cur->left;
  cur = new node(key);
  cur->parent = pcur;
  if (!pcur) root = cur;
  else if (key > pcur->key ) pcur->right = cur;
  else pcur->left = cur;
  splay(cur);
}
node *find(T key) {
  node *cur = root;
  while (cur) {
   if (key > cur->key) cur = cur->right;
   else if(key < cur->key) cur = cur->left;
   else return cur;
  return 0;
}
splay_tree(){ root = 0;};
```

#### 2.8 trie

};

```
const int MN = 26; // size of alphabet
const int MS = 100010; // Number of states.
struct trie{
 struct node{
   int c:
   int a[MN];
 };
 node tree[MS];
 int nodes;
 void clear(){
   tree[nodes].c = 0;
   memset(tree[nodes].a, -1, sizeof tree[nodes].a);
   nodes++;
 void init(){
   nodes = 0;
   clear();
 }
 int add(const string &s, bool query = 0){
   int cur_node = 0;
   for(int i = 0; i < s.size(); ++i){</pre>
     int id = gid(s[i]);
     if(tree[cur_node].a[id] == -1){
       if(query) return 0;
       tree[cur_node].a[id] = nodes;
       clear();
     cur_node = tree[cur_node].a[id];
   if(!query) tree[cur_node].c++;
   return tree[cur_node].c;
```

## 3 Geometry

#### 3.1 closest pair problem

```
struct point {
 double x, y;
 int id;
 point() {}
 point (double a, double b) : x(a), y(b) {}
};
double dist(const point &o, const point &p) {
 double a = p.x - o.x, b = p.y - o.y;
 return sqrt(a * a + b * b);
}
double cp(vector<point> &p, vector<point> &x, vector<point> &y) {
  if (p.size() < 4) {</pre>
    double best = 1e100;
    for (int i = 0; i < p.size(); ++i)</pre>
     for (int j = i + 1; j < p.size(); ++j)</pre>
       best = min(best, dist(p[i], p[j]));
    return best;
 }
  int ls = (p.size() + 1) >> 1;
  double l = (p[ls - 1].x + p[ls].x) * 0.5;
  vector<point> xl(ls), xr(p.size() - ls);
  unordered_set<int> left;
  for (int i = 0; i < ls; ++i) {</pre>
   xl[i] = x[i];
    left.insert(x[i].id);
 for (int i = ls; i < p.size(); ++i) {</pre>
    xr[i - ls] = x[i];
  vector<point> yl, yr;
  vector<point> pl, pr;
  yl.reserve(ls); yr.reserve(p.size() - ls);
 pl.reserve(ls); pr.reserve(p.size() - ls);
 for (int i = 0; i < p.size(); ++i) {</pre>
    if (left.count(y[i].id))
     yl.push_back(y[i]);
```

```
else
     yr.push_back(y[i]);
   if (left.count(p[i].id))
     pl.push_back(p[i]);
   else
     pr.push_back(p[i]);
  double dl = cp(pl, xl, yl);
  double dr = cp(pr, xr, yr);
  double d = min(dl, dr);
  vector<point> yp; yp.reserve(p.size());
  for (int i = 0; i < p.size(); ++i) {</pre>
   if (fabs(y[i].x - 1) < d)
     yp.push_back(y[i]);
 for (int i = 0; i < yp.size(); ++i) {</pre>
   for (int j = i + 1; j < yp.size() && j < i + 7; ++j) {
     d = min(d, dist(yp[i], yp[j]));
 }
 return d;
}
double closest_pair(vector<point> &p) {
  vector<point> x(p.begin(), p.end());
  sort(x.begin(), x.end(), [](const point &a, const point &b) {
   return a.x < b.x;</pre>
 });
  vector<point> y(p.begin(), p.end());
  sort(y.begin(), y.end(), [](const point &a, const point &b) {
   return a.y < b.y;</pre>
 });
 return cp(p, x, y);
```

## 3.2 squares

```
typedef long double ld;
const ld eps = 1e-12;
```

```
int cmp(ld x, ld y = 0, ld tol = eps) {
   return ( x \le y + tol) ? (x + tol < y) ? -1 : 0 : 1;
}
struct point{
 ld x, y;
 point(ld a, ld b) : x(a), y(b) {}
 point() {}
};
struct square{
 ld x1, x2, y1, y2,
    a, b, c;
 point edges[4];
 square(ld _a, ld _b, ld _c) {
   a = _a, b = _b, c = _c;
   x1 = a - c * 0.5;
   x2 = a + c * 0.5;
   y1 = b - c * 0.5;
   v2 = b + c * 0.5;
   edges[0] = point(x1, y1);
   edges[1] = point(x2, y1);
   edges[2] = point(x2, y2);
   edges[3] = point(x1, y2);
 }
}:
ld min_dist(point &a, point &b) {
 1d x = a.x - b.x,
    y = a.y - b.y;
 return sqrt(x * x + y * y);
}
bool point_in_box(square s1, point p) {
 if (cmp(s1.x1, p.x) != 1 && cmp(s1.x2, p.x) != -1 &&
     cmp(s1.y1, p.y) != 1 \&\& cmp(s1.y2, p.y) != -1)
   return true;
 return false;
}
bool inside(square &s1, square &s2) {
 for (int i = 0; i < 4; ++i)
   if (point_in_box(s2, s1.edges[i]))
     return true:
```

```
return false:
}
bool inside_vert(square &s1, square &s2) {
 if ((cmp(s1.v1, s2.v1) != -1 && cmp(s1.v1, s2.v2) != 1) ||
      (cmp(s1.y2, s2.y1) != -1 \&\& cmp(s1.y2, s2.y2) != 1))
   return true;
return false:
bool inside_hori(square &s1, square &s2) {
 if ((cmp(s1.x1, s2.x1) != -1 && cmp(s1.x1, s2.x2) != 1) ||
      (cmp(s1.x2, s2.x1) != -1 \&\& cmp(s1.x2, s2.x2) != 1))
   return true:
return false;
}
ld min_dist(square &s1, square &s2) {
  if (inside(s1, s2) || inside(s2, s1))
   return 0;
 1d ans = 1e100;
 for (int i = 0; i < 4; ++i)</pre>
   for (int j = 0; j < 4; ++j)
     ans = min(ans, min_dist(s1.edges[i], s2.edges[j]));
  if (inside_hori(s1, s2) || inside_hori(s2, s1)) {
   if (cmp(s1.y1, s2.y2) != -1)
     ans = min(ans, s1.y1 - s2.y2);
   else
   if (cmp(s2.y1, s1.y2) != -1)
     ans = min(ans, s2.y1 - s1.y2);
 }
 if (inside_vert(s1, s2) || inside_vert(s2, s1)) {
   if (cmp(s1.x1, s2.x2) != -1)
     ans = min(ans, s1.x1 - s2.x2);
   else
   if (cmp(s2.x1, s1.x2) != -1)
     ans = min(ans, s2.x1 - s1.x2);
 return ans;
```

### 3.3 triangles

Let a, b, c be length of the three sides of a triangle.

$$p = (a + b + c) * 0.5$$

The inradius is defined by:

$$iR = \sqrt{\frac{(p-a)(p-b)(p-c)}{p}}$$

The radius of its circumcircle is given by the formula:

$$cR = \frac{abc}{\sqrt{(a+b+c)(a+b-c)(a+c-b)(b+c-a)}}$$

## 4 Graphs

#### 4.1 bridges

```
struct edge{
 int to, id;
 edge(int a, int b) : to(a), id(b) {}
};
struct graph {
 vector<vector<edge> > g;
 vector<int> vi, low, d, pi, is_b;
 int ticks, edges;
  graph(int n, int m) {
   g.assign(n, vector<edge>());
   is_b.assign(m, 0);
   vi.resize(n):
   low.resize(n);
   d.resize(n);
   pi.resize(n);
   edges = 0;
 }
  void add_edge(int u, int v) {
   g[u].push_back(edge(v, edges));
   g[v].push_back(edge(u, edges));
```

```
edges++;
  void dfs(int u) {
   vi[u] = true;
   d[u] = low[u] = ticks++;
   for (int i = 0; i < g[u].size(); ++i) {</pre>
     int v = g[u][i].to;
     if (v == pi[u]) continue;
     if (!vi[v]) {
       pi[v] = u;
       dfs(v);
       if (d[u] < low[v])</pre>
         is_b[g[u][i].id] = true;
       low[u] = min(low[u], low[v]);
     } else {
       low[u] = min(low[u], d[v]);
   }
 // Multiple edges from a to b are not allowed.
 // (they could be detected as a bridge).
 // If you need to handle this, just count
 // how many edges there are from a to b.
 void comp_bridges() {
   fill(pi.begin(), pi.end(), -1);
   fill(vi.begin(), vi.end(), 0);
   fill(low.begin(), low.end(), 0);
   fill(d.begin(), d.end(), 0);
   ticks = 0;
   for (int i = 0; i < g.size(); ++i)</pre>
     if (!vi[i]) dfs(i);
};
```

#### 4.2 directed mst

```
const int inf = 1000000 + 10;
struct edge {
```

```
int u, v, w;
 edge() {}
 edge(int a,int b,int c) : u(a), v(b), w(c) {}
};
* Computes the minimum spanning tree for a directed graph
 * - edges : Graph description in the form of list of edges.
     each edge is: From node u to node v with cost w
 * - root : Id of the node to start the DMST.
        : Number of nodes in the graph.
 * */
int dmst(vector<edge> &edges, int root, int n) {
 int ans = 0;
 int cur_nodes = n;
 while (true) {
   vector<int> lo(cur_nodes, inf), pi(cur_nodes, inf);
   for (int i = 0; i < edges.size(); ++i) {</pre>
     int u = edges[i].u, v = edges[i].v, w = edges[i].w;
     if (w < lo[v] and u != v) {</pre>
       lo[v] = w;
       pi[v] = u;
     }
   }
   lo[root] = 0:
   for (int i = 0; i < lo.size(); ++i) {</pre>
     if (i == root) continue;
     if (lo[i] == inf) return -1;
   }
   int cur id = 0:
   vector<int> id(cur_nodes, -1), mark(cur_nodes, -1);
   for (int i = 0; i < cur_nodes; ++i) {</pre>
     ans += lo[i];
     int u = i;
     while (u != root and id[u] < 0 and mark[u] != i) {</pre>
       mark[u] = i;
       u = pi[u];
     if (u != root and id[u] < 0) { // Cycle</pre>
        for (int v = pi[u]; v != u; v = pi[v])
          id[v] = cur_id;
        id[u] = cur_id++;
     }
```

```
if (cur_id == 0)
    break;

for (int i = 0; i < cur_nodes; ++i)
    if (id[i] < 0) id[i] = cur_id++;

for (int i = 0; i < edges.size(); ++i) {
    int u = edges[i].u, v = edges[i].v, w = edges[i].w;
    edges[i].u = id[u];
    edges[i].v = id[v];
    if (id[u] != id[v])
        edges[i].w -= lo[v];
}

cur_nodes = cur_id;
root = id[root];
}

return ans;
}</pre>
```

## 4.3 eulerian path

```
// Taken from https://github.com/lbv/pc-code/blob/master/code/graph.cpp
// Eulerian Trail
struct Euler {
 ELV adj; IV t;
 Euler(ELV Adj) : adj(Adj) {}
 void build(int u) {
   while(! adj[u].empty()) {
     int v = adj[u].front().v;
     adj[u].erase(adj[u].begin());
     build(v);
   t.push_back(u);
};
bool eulerian_trail(IV &trail) {
 Euler e(adi):
 int odd = 0, s = 0;
 /*
```

```
for (int v = 0; v < n; v++) {
  int diff = abs(in[v] - out[v]);
  if (diff > 1) return false;
  if (diff == 1) {
    if (++odd > 2) return false;
    if (out[v] > in[v]) start = v;
    }
  }
  */
e.build(s);
reverse(e.t.begin(), e.t.end());
trail = e.t;
return true;
```

#### 4.4 karp min mean cycle

```
* Finds the min mean cycle, if you need the max mean cycle
 * just add all the edges with negative cost and print
 * ans * -1
 * test: uva, 11090 - Going in Cycle!!
 * */
const int MN = 1000;
struct edge{
 int v;
 long long w;
 edge(){} edge(int v, int w) : v(v), w(w) {}
};
long long d[MN][MN];
// This is a copy of g because increments the size
// pass as reference if this does not matter.
int karp(vector<vector<edge> > g) {
 int n = g.size();
 g.resize(n + 1); // this is important
 for (int i = 0; i < n; ++i)
   if (!g[i].empty())
     g[n].push_back(edge(i,0));
```

```
++n;
for(int i = 0;i<n;++i)</pre>
 fill(d[i],d[i]+(n+1),INT_MAX);
d[n - 1][0] = 0:
for (int k = 1; k \le n; ++k) for (int u = 0; u \le n; ++u) {
  if (d[u][k - 1] == INT_MAX) continue;
 for (int i = g[u].size() - 1; i >= 0; --i)
   d[g[u][i].v][k] = min(d[g[u][i].v][k], d[u][k-1] + g[u][i].w);
bool flag = true;
for (int i = 0; i < n && flag; ++i)</pre>
 if (d[i][n] != INT_MAX)
   flag = false;
if (flag) {
 return true; // return true if there is no a cycle.
double ans = 1e15;
for (int u = 0; u + 1 < n; ++u) {
  if (d[u][n] == INT_MAX) continue;
  double W = -1e15;
  for (int k = 0; k < n; ++k)
   if (d[u][k] != INT_MAX)
     W = max(W, (double)(d[u][n] - d[u][k]) / (n - k));
  ans = min(ans, W);
// printf("%.21f\n", ans);
cout << fixed << setprecision(2) << ans << endl;</pre>
return false;
```

### 4.5 konig's theorem

In any bipartite graph, the number of edges in a maximum matching equals the number of vertices in a minimum vertex cover

#### 4.6 minimum path cover in DAG

Given a directed acyclic graph G = (V, E), we are to find the minimum number of vertex-disjoint paths to cover each vertex in V.

We can construct a bipartite graph  $G' = (Vout \cup Vin, E')$  from G, where :

$$Vout = \{v \in V : v \text{ has positive out} - degree\}$$
 
$$Vin = \{v \in V : v \text{ has positive } in - degree\}$$
 
$$E' = \{(u, v) \in Vout \times Vin : (u, v) \in E\}$$

Then it can be shown, via König's theorem, that G' has a matching of size m if and only if there exists n-m vertex-disjoint paths that cover each vertex in G, where n is the number of vertices in G and m is the maximum cardinality bipartite mathching in G'.

Therefore, the problem can be solved by finding the maximum cardinality matching in G' instead.

**NOTE:** If the paths are note necesarily disjoints, find the transitive closure and solve the problem for disjoint paths.

## 4.7 planar graph (euler)

Euler's formula states that if a finite, connected, planar graph is drawn in the plane without any edge intersections, and v is the number of vertices, e is the number of edges and f is the number of faces (regions bounded by edges, including the outer, infinitely large region), then:

$$f + v = e + 2$$

It can be extended to non connected planar graphs with c connected components:

$$f + v = e + c + 1$$

#### 4.8 tarjan scc

```
const int MN = 20002;
struct tarjan_scc {
 int scc[MN], low[MN], d[MN], stacked[MN];
 int ticks, current_scc;
 deque<int> s; // used as stack.
 tarjan_scc() {}
  void init () {
   memset(scc. -1, sizeof scc):
   memset(d, -1, sizeof d);
   memset(stacked, 0, sizeof stacked);
   s.clear();
   ticks = current_scc = 0;
  void compute(vector<vector<int> > &g, int u) {
   d[u] = low[u] = ticks++;
   s.push_back(u);
   stacked[u] = true;
   for (int i = 0; i < g[u].size(); ++i) {</pre>
     int v = g[u][i];
     if (d[v] == -1)
       compute(g, v);
     if (stacked[v]) {
       low[u] = min(low[u], low[v]);
   }
   if (d[u] == low[u]) { // root
     int v;
     do {
       v = s.back();s.pop_back();
       stacked[v] = false;
       scc[v] = current_scc;
     } while (u != v);
     current_scc++;
   }
 }
};
```

## 4.9 two sat (with kosaraju)

```
/**
 * Given a set of clauses (a1 v a2)^(a2 v a3)....
 * this algorithm find a solution to it set of clauses.
 * test: http://lightoj.com/volume_showproblem.php?problem=1251
 **/
#include<bits/stdc++.h>
using namespace std;
#define MAX 100000
#define endl '\n'
vector<int> G[MAX];
vector<int> GT[MAX];
vector<int> Ftime;
vector<vector<int> > SCC;
bool visited[MAX]:
int n;
void dfs1(int n){
 visited[n] = 1;
 for (int i = 0; i < G[n].size(); ++i) {</pre>
   int curr = G[n][i]:
   if (visited[curr]) continue;
   dfs1(curr);
 }
 Ftime.push_back(n);
}
void dfs2(int n, vector<int> &scc) {
 visited[n] = 1;
 scc.push_back(n);
 for (int i = 0;i < GT[n].size(); ++i) {</pre>
   int curr = GT[n][i];
   if (visited[curr]) continue;
   dfs2(curr, scc);
 }
}
```

```
void kosaraju() {
 memset(visited, 0, sizeof visited);
 for (int i = 0; i < 2 * n; ++i) {
   if (!visited[i]) dfs1(i);
  memset(visited, 0, sizeof visited);
  for (int i = Ftime.size() - 1; i >= 0; i--) {
   if (visited[Ftime[i]]) continue;
   vector<int> scc:
   dfs2(Ftime[i],_scc);
   SCC.push_back(_scc);
}
 * After having the SCC, we must traverse each scc, if in one SCC are -b
     y b, there is not a solution.
 * Otherwise we build a solution, making the first "node" that we find
     truth and its complement false.
bool two_sat(vector<int> &val) {
 kosaraju();
 for (int i = 0; i < SCC.size(); ++i) {</pre>
   vector<bool> tmpvisited(2 * n, false);
   for (int j = 0; j < SCC[i].size(); ++j) {</pre>
     if (tmpvisited[SCC[i][j] ^ 1]) return 0;
     if (val[SCC[i][j]] != -1) continue;
     else {
       val[SCC[i][j]] = 0;
       val[SCC[i][j] ^ 1] = 1;
     tmpvisited[SCC[i][j]] = 1;
 return 1;
// Example of use
int main() {
```

```
int m, u, v, nc = 0, t; cin >> t;
// n = "nodes" number, m = clauses number
while (t--) {
  cin >> m >> n;
  Ftime.clear();
  SCC.clear();
  for (int i = 0; i < 2 * n; ++i) {
    G[i].clear();
    GT[i].clear();
  // (a1 v a2) = (a1 -> a2) = (a2 -> a1)
  for (int i = 0; i < m ; ++i) {</pre>
    cin >> u >> v;
    int t1 = abs(u) - 1;
    int t2 = abs(v) - 1;
    int p = t1 * 2 + ((u < 0)? 1 : 0);
    int q = t2 * 2 + ((v < 0)? 1 : 0);
    G[p ^ 1].push_back(q);
    G[q ^ 1].push_back(p);
    GT[p].push_back(q ^ 1);
    GT[q].push_back(p ^ 1);
  vector < int > val(2 * n, -1);
  cout << "Case " << ++nc <<": ":
  if (two_sat(val)) {
    cout << "Yes" << endl;</pre>
    vector<int> sol;
    for (int i = 0; i < 2 * n; ++i)
     if (i % 2 == 0 and val[i] == 1)
        sol.push_back(i / 2 + 1);
    cout << sol.size();</pre>
    for (int i = 0; i < sol.size(); ++i) {</pre>
      cout << " " << sol[i];</pre>
    cout << endl;</pre>
  } else {
    cout << "No" << endl;</pre>
  }
}
return 0;
```

#### 5 Math

#### 5.1 cumulative sum of divisors

```
/**
The function SOD(n) (sum of divisors) is defined
as the summation of all the actual divisors of
an integer number n. For example,
 SOD(24) = 2+3+4+6+8+12 = 35.
The function CSOD(n) (cumulative SOD) of an integer n, is defined as
    below:
  csod(n) = \sum_{i=1}^{n} sod(i)
It can be computed in O(sqrt(n)):
long long csod(long long n) {
 long long ans = 0;
 for (long long i = 2; i * i <= n; ++i) {
   long long j = n / i;
   ans += (i + j) * (j - i + 1) / 2;
   ans += i * (j - i);
 return ans;
```

#### 5.2 fft

```
/**
 * Fast Fourier Transform.
 * Useful to compute convolutions.
 * computes:
 * C(f star g)[n] = sum_m(f[m] * g[n - m])
 * for all n.
 * test: icpc live archive, 6886 - Golf Bot
 * */
using namespace std;
```

```
#include<bits/stdc++.h>
\#define D(x) cout << \#x " = " << (x) << endl
#define endl '\n'
const int MN = 262144 << 1;</pre>
int d[MN + 10], d2[MN + 10];
const double PI = acos(-1.0);
struct cpx {
 double real, image;
 cpx(double _real, double _image) {
   real = _real;
   image = _image;
 }
 cpx(){}
};
cpx operator + (const cpx &c1, const cpx &c2) {
 return cpx(c1.real + c2.real, c1.image + c2.image);
}
cpx operator - (const cpx &c1, const cpx &c2) {
 return cpx(c1.real - c2.real, c1.image - c2.image);
}
cpx operator * (const cpx &c1, const cpx &c2) {
 return cpx(c1.real*c2.real - c1.image*c2.image, c1.real*c2.image +
      c1.image*c2.real);
}
int rev(int id, int len) {
 int ret = 0:
 for (int i = 0; (1 << i) < len; i++) {
   ret <<= 1;
   if (id & (1 << i)) ret |= 1;</pre>
 }
 return ret;
}
cpx A[1 << 20];
void FFT(cpx *a, int len, int DFT) {
 for (int i = 0; i < len; i++)</pre>
```

```
A[rev(i, len)] = a[i];
 for (int s = 1; (1 << s) <= len; s++) {
   int m = (1 << s);
   cpx wm = cpx(cos(DFT * 2 * PI / m), sin(DFT * 2 * PI / m));
   for(int k = 0; k < len; k += m) {</pre>
     cpx w = cpx(1, 0);
     for(int j = 0; j < (m >> 1); j++) {
       cpx t = w * A[k + j + (m >> 1)];
       cpx u = A[k + j];
       A[k + j] = u + t;
       A[k + j + (m >> 1)] = u - t;
       w = w * wm;
     }
   }
 if (DFT == -1) for (int i = 0; i < len; i++) A[i].real /= len,
      A[i].image /= len;
 for (int i = 0; i < len; i++) a[i] = A[i];</pre>
 return:
cpx in[1 << 20];
void solve(int n) {
 memset(d, 0, sizeof d);
 int t:
 for (int i = 0; i < n; ++i) {</pre>
   cin >> t;
   d[t] = true;
 int m;
 cin >> m;
 vector<int> q(m);
 for (int i = 0; i < m; ++i)</pre>
   cin >> q[i];
 for (int i = 0; i < MN; ++i) {</pre>
   if (d[i])
     in[i] = cpx(1, 0);
   else
     in[i] = cpx(0, 0);
 FFT(in, MN, 1);
 for (int i = 0; i < MN; ++i) {</pre>
```

```
in[i] = in[i] * in[i];
 }
 FFT(in, MN, -1);
 int ans = 0;
 for (int i = 0; i < q.size(); ++i) {</pre>
   if (in[q[i]].real > 0.5 || d[q[i]]) {
     ans++;
    }
 }
  cout << ans << endl;</pre>
}
int main() {
 ios_base::sync_with_stdio(false);cin.tie(NULL);
  int n;
  while (cin >> n)
    solve(n);
 return 0;
}
```

### 5.3 fibonacci properties

Let A, B and n be integer numbers.

$$k = A - B \tag{1}$$

$$F_A F_B = F_{k+1} F_A^2 + F_k F_A F_{A-1} \tag{2}$$

$$\sum_{i=0}^{n} F_i^2 = F_{n+1} F_n \tag{3}$$

ev(n) = returns 1 if n is even.

$$\sum_{i=0}^{n} F_i F_{i+1} = F_{n+1}^2 - ev(n) \tag{4}$$

$$\sum_{i=0}^{n} F_i F_{i-1} = \sum_{i=0}^{n-1} F_i F_{i+1}$$
 (5)

## 6 Matrix

#### 6.1 matrix

```
const int MN = 111;
const int mod = 10000;
struct matrix {
 int r, c;
 int m[MN][MN];
 matrix (int _r, int _c) : r (_r), c (_c) {
   memset(m, 0, sizeof m);
  void print() {
   for (int i = 0; i < r; ++i) {</pre>
     for (int j = 0; j < c; ++j)
       cout << m[i][j] << " ";
     cout << endl;</pre>
   }
 }
  int x[MN][MN];
  matrix & operator *= (const matrix &o) {
   memset(x, 0, sizeof x);
   for (int i = 0; i < r; ++i)
     for (int k = 0; k < c; ++k)
       if (m[i][k] != 0)
         for (int j = 0; j < c; ++j) {
           x[i][j] = (x[i][j] + ((m[i][k] * o.m[k][j]) % mod)) % mod;
   memcpy(m, x, sizeof(m));
   return *this;
};
void matrix_pow(matrix b, long long e, matrix &res) {
  memset(res.m, 0, sizeof res.m);
 for (int i = 0; i < b.r; ++i)</pre>
   res.m[i][i] = 1;
  if (e == 0) return;
  while (true) {
```

```
if (e & 1) res *= b;
if ((e >>= 1) == 0) break;
b *= b;
}
```

## 7 Misc

#### 7.1 Template Java

```
import java.io.*;
import java.util.StringTokenizer;
public class Template {
   public static void main(String []args) throws IOException {
       Scanner in = new Scanner(System.in);
       OutputWriter out = new OutputWriter(System.out);
       Task solver = new Task();
       solver.solve(in, out);
       out.close();
}
class Task{
   public void solve(Scanner in, OutputWriter out){
class Scanner{
   public BufferedReader reader;
   public StringTokenizer st;
   public Scanner(InputStream stream){
       reader = new BufferedReader(new InputStreamReader(stream));
       st = null:
   }
   public String next(){
       while(st == null || !st.hasMoreTokens()){
```

```
try{
              String line = reader.readLine();
              if(line == null) return null:
              st = new StringTokenizer(line);
          }catch (Exception e){
              throw (new RuntimeException());
       return st.nextToken();
   public int nextInt(){
       return Integer.parseInt(next());
   public long nextLong(){
       return Long.parseLong(next());
   public double nextDouble(){
       return Double.parseDouble(next());
}
class OutputWriter{
   BufferedWriter writer;
   public OutputWriter(OutputStream stream){
       writer = new BufferedWriter(new OutputStreamWriter(stream));
   public void print(int i) throws IOException {
       writer.write(i);
   public void print(String s) throws IOException {
       writer.write(s);
   public void print(char []c) throws IOException {
       writer.write(c);
   public void close() throws IOException {
       writer.close();
```

#### 7.2 fraction

```
struct frac{
  long long x, y;
  frac(long long a, long long b) {
    long long g = __gcd(a, b);
    x = a / g;
    y = b / g;
}
bool operator < (const frac &o) const {
    return (x * o.y < y * o.x);
}
};</pre>
```

#### 7.3 io

```
// taken from :
    https://github.com/lbv/pc-code/blob/master/solved/c-e/diablo/diablo.cpp
// this is very fast as well :
    https://github.com/lbv/pc-code/blob/master/code/input.cpp
typedef unsigned int u32;
#define BUF 524288
struct Reader {
  char buf[BUF]; char b; int bi, bz;
 Reader() { bi=bz=0; read(); }
 void read() {
   if (bi==bz) { bi=0; bz = fread(buf, 1, BUF, stdin); }
   b = bz ? buf[bi++] : 0; }
 void skip() { while (b > 0 && b <= 32) read(); }</pre>
 u32 next u32() {
   u32 v = 0; for (skip(); b > 32; read()) v = v*10 + b-48; return v; }
  int next_int() {
   int v = 0; bool s = false;
   skip(); if (b == '-') { s = true; read(); }
   for (; 48<=b&&b<=57; read()) v = v*10 + b-48; return s ? -v : v; }</pre>
  char next_char() { skip(); char c = b; read(); return c; }
};
```

## 8 Number theory

#### 8.1 convolution

```
typedef long long int LL;
typedef pair<LL, LL> PLL;
inline bool is_pow2(LL x) {
 return (x & (x-1)) == 0;
inline int ceil_log2(LL x) {
 int ans = 0;
 --x;
 while (x != 0) {
   x >>= 1;
   ans++:
 return ans;
/* Returns the convolution of the two given vectors in time proportional
* The number of roots of unity to use nroots_unity must be set so that
     the product of the first
* nroots_unity primes of the vector nth_roots_unity is greater than the
     maximum value of the
* convolution. Never use sizes of vectors bigger than 2^24, if you need
     to change the values of
* the nth roots of unity to appropriate primes for those sizes.
vector<LL> convolve(const vector<LL> &a, const vector<LL> &b, int
    nroots_unity = 2) {
 int N = 1 \ll ceil_log2(a.size() + b.size());
 vector<LL> ans(N,0), fA(N), fB(N), fC(N);
 LL modulo = 1;
 for (int times = 0; times < nroots_unity; times++) {</pre>
   fill(fA.begin(), fA.end(), 0);
   fill(fB.begin(), fB.end(), 0);
   for (int i = 0; i < a.size(); i++) fA[i] = a[i];</pre>
   for (int i = 0; i < b.size(); i++) fB[i] = b[i];</pre>
   LL prime = nth_roots_unity[times].first;
   LL inv_modulo = mod_inv(modulo % prime, prime);
   LL normalize = mod_inv(N, prime);
```

```
ntfft(fA, 1, nth_roots_unity[times]);
ntfft(fB, 1, nth_roots_unity[times]);
for (int i = 0; i < N; i++) fC[i] = (fA[i] * fB[i]) % prime;
ntfft(fC, -1, nth_roots_unity[times]);
for (int i = 0; i < N; i++) {
   LL curr = (fC[i] * normalize) % prime;
   LL k = (curr - (ans[i] % prime) + prime) % prime;
   k = (k * inv_modulo) % prime;
   ans[i] += modulo * k;
}
modulo *= prime;
}
return ans;</pre>
```

#### 8.2 crt

```
/**
 * Chinese remainder theorem.
 * Find z such that z % x[i] = a[i] for all i.
 * */
long long crt(vector<long long> &a, vector<long long> &x) {
  long long z = 0;
  long long n = 1;
  for (int i = 0; i < x.size(); ++i)
    n *= x[i];

  for (int i = 0; i < a.size(); ++i) {
    long long tmp = (a[i] * (n / x[i])) % n;
    tmp = (tmp * mod_inv(n / x[i], x[i])) % n;
    z = (z + tmp) % n;
  }

  return (z + n) % n;
}</pre>
```

#### 8.3 discrete logarithm

```
// Computes x which a \hat{x} = b \mod n.
```

```
long long d_log(long long a, long long b, long long n) {
 long long m = ceil(sqrt(n));
 long long aj = 1;
 map<long long, long long> M;
 for (int i = 0; i < m; ++i) {</pre>
   if (!M.count(aj))
     M[aj] = i;
   aj = (aj * a) % n;
 long long coef = mod_pow(a, n - 2, n);
  coef = mod_pow(coef, m, n);
 // coef = a ^ (-m)
 long long gamma = b;
 for (int i = 0; i < m; ++i) {</pre>
   if (M.count(gamma)) {
     return i * m + M[gamma];
   } else {
     gamma = (gamma * coef) % n;
 }
 return -1;
```

#### 8.4 ext euclidean

```
void ext_euclid(long long a, long long b, long long &x, long long &y,
    long long &g) {
    x = 0, y = 1, g = b;
    long long m, n, q, r;
    for (long long u = 1, v = 0; a != 0; g = a, a = r) {
        q = g / a, r = g % a;
        m = x - u * q, n = y - v * q;
        x = u, y = v, u = m, v = n;
    }
}
```

## 8.5 highest exponent factorial

```
int highest_exponent(int p, const int &n){
  int ans = 0;
```

```
int t = p;
while(t <= n){
    ans += n/t;
    t*=p;
}
return ans;
}</pre>
```

#### 8.6 miller rabin

```
const int rounds = 20;
// checks whether a is a witness that n is not prime, 1 < a < n
bool witness(long long a, long long n) {
 // check as in Miller Rabin Primality Test described
 long long u = n - 1;
 int t = 0;
 while (u % 2 == 0) {
   t++;
   u >>= 1;
 long long next = mod_pow(a, u, n);
 if (next == 1) return false;
 long long last;
 for (int i = 0; i < t; ++i) {</pre>
   last = next;
   next = mod_mul(last, last, n);
   if (next == 1) {
     return last != n - 1;
   }
 return next != 1;
}
// Checks if a number is prime with prob 1 - 1 / (2 ^ it)
// D(miller_rabin(999999999999997LL) == 1);
// D(miller_rabin(999999999971LL) == 1);
// D(miller_rabin(7907) == 1);
bool miller_rabin(long long n, int it = rounds) {
 if (n <= 1) return false;</pre>
 if (n == 2) return true:
 if (n % 2 == 0) return false;
```

```
for (int i = 0; i < it; ++i) {
   long long a = rand() % (n - 1) + 1;
   if (witness(a, n)) {
      return false;
   }
}
return true;
}</pre>
```

#### 8.7 mod inv

```
long long mod_inv(long long n, long long m) {
  long long x, y, gcd;
  ext_euclid(n, m, x, y, gcd);
  if (gcd != 1)
   return 0;
  return (x + m) % m;
}
```

#### 8.8 mod mul

```
// Computes (a * b) % mod
long long mod_mul(long long a, long long b, long long mod) {
  long long x = 0, y = a % mod;
  while (b > 0) {
    if (b & 1)
        x = (x + y) % mod;
        y = (y * 2) % mod;
        b /= 2;
    }
  return x % mod;
}
```

## $8.9 \mod pow$

```
// Computes ( a ^ exp ) % mod.
long long mod_pow(long long a, long long exp, long long mod) {
  long long ans = 1;
  while (exp > 0) {
```

```
if (exp & 1)
    ans = mod_mul(ans, a, mod);
a = mod_mul(a, a, mod);
exp >>= 1;
}
return ans;
```

#### 8.10 number theoretic transform

```
typedef long long int LL;
typedef pair<LL, LL> PLL;
/* The following vector of pairs contains pairs (prime, generator)
 * where the prime has an Nth root of unity for N being a power of two.
 * The generator is a number g s.t g^(p-1)=1 (mod p)
 * but is different from 1 for all smaller powers */
vector<PLL> nth_roots_unity {
 {1224736769,330732430},{1711276033,927759239},{167772161,167489322},
  {469762049,343261969},{754974721,643797295},{1107296257,883865065}};
PLL ext_euclid(LL a, LL b) {
 if (b == 0)
   return make_pair(1,0);
 pair<LL,LL> rc = ext_euclid(b, a % b);
 return make_pair(rc.second, rc.first - (a / b) * rc.second);
}
//returns -1 if there is no unique modular inverse
LL mod_inv(LL x, LL modulo) {
 PLL p = ext_euclid(x, modulo);
 if ( (p.first * x + p.second * modulo) != 1 )
   return -1;
 return (p.first+modulo) % modulo;
}
//Number theory fft. The size of a must be a power of 2
void ntfft(vector<LL> &a, int dir, const PLL &root_unity) {
 int n = a.size();
 LL prime = root_unity.first;
 LL basew = mod_pow(root_unity.second, (prime-1) / n, prime);
 if (dir < 0) basew = mod_inv(basew, prime);</pre>
```

```
for (int m = n; m \ge 2; m \ge 1) {
   int mh = m >> 1;
   LL w = 1;
   for (int i = 0; i < mh; i++) {</pre>
     for (int j = i; j < n; j += m) {
       int k = j + mh;
       LL x = (a[j] - a[k] + prime) % prime;
       a[j] = (a[j] + a[k]) % prime;
       a[k] = (w * x) % prime;
     w = (w * basew) % prime;
   basew = (basew * basew) % prime;
 int i = 0;
 for (int j = 1; j < n - 1; j++) {
   for (int k = n >> 1; k > (i ^= k); k >>= 1);
   if (j < i) swap(a[i], a[j]);</pre>
 }
}
```

#### 8.11 pollard rho factorize

```
long long pollard_rho(long long n) {
 long long x, y, i = 1, k = 2, d;
 x = y = rand() \% n;
  while (1) {
   ++i:
   x = mod_mul(x, x, n);
   x += 2:
   if (x \ge n) x -= n;
   if (x == y) return 1;
   d = \_gcd(abs(x - y), n);
   if (d != 1) return d;
   if (i == k) {
     y = x;
     k *= 2;
 }
 return 1;
}
```

```
// Returns a list with the prime divisors of n
vector<long long> factorize(long long n) {
 vector<long long> ans;
 if (n == 1)
   return ans;
 if (miller_rabin(n)) {
   ans.push_back(n);
 } else {
   long long d = 1;
   while (d == 1)
     d = pollard_rho(n);
   vector<long long> dd = factorize(d);
   ans = factorize(n / d);
   for (int i = 0; i < dd.size(); ++i)</pre>
     ans.push_back(dd[i]);
 }
 return ans;
}
```

#### 8.12 totient sieve

```
for (int i = 1; i < MN; i++)
  phi[i] = i;

for (int i = 1; i < MN; i++)
  if (!sieve[i]) // is prime
  for (int j = i; j < MN; j += i)
    phi[j] -= phi[j] / i;</pre>
```

#### 8.13 totient

```
long long totient(long long n) {
   if (n == 1) return 0;
   long long ans = n;
   for (int i = 0; primes[i] * primes[i] <= n; ++i) {
      if ((n % primes[i]) == 0) {
       while ((n % primes[i]) == 0) n /= primes[i];
      ans -= ans / primes[i];
   }
   }
   if (n > 1) {
```

```
ans -= ans / n;
}
return ans;
```

## 9 Strings

#### 9.1 minimal string rotation

```
// Lexicographically minimal string rotation
int lmsr() {
 string s;
 cin >> s;
 int n = s.size();
 s += s;
 vector<int> f(s.size(), -1);
 int k = 0;
 for (int j = 1; j < 2 * n; ++j) {
   int i = f[j - k - 1];
   while (i != -1 && s[j] != s[k + i + 1]) {
     if (s[j] < s[k + i + 1])
       k = j - i - 1;
     i = f[i];
   if (i == -1 \&\& s[j] != s[k + i + 1]) {
     if (s[j] < s[k + i + 1]) {
       k = j;
     f[j - k] = -1;
   } else {
     f[j - k] = i + 1;
 }
 return k;
```

## 9.2 suffix array

```
/**
 * 0 (n log^2 (n))
```

```
* See http://web.stanford.edu/class/cs97si/suffix-array.pdf for reference
 * */
struct entry{
 int a, b, p;
  entry(){}
  entry(int x, int y, int z): a(x), b(y), p(z){}
 bool operator < (const entry &o) const {</pre>
    return (a == o.a) ? (b == o.b) ? (p < o.p) : (b < o.b) : (a < o.a);
 }
}:
struct SuffixArray{
  const int N;
  string s;
  vector<vector<int> > P;
  vector<entry> M;
  SuffixArray(const string &s): N(s.length()), s(s), P(1, vector<int>
      (N, O)), M(N) {
    for (int i = 0; i < N; ++i)</pre>
     P[0][i] = (int) s[i];
    for (int skip = 1, level = 1; skip < N; skip *= 2, level++) {</pre>
     P.push_back(vector<int>(N, 0));
     for (int i = 0 ; i < N; ++i) {</pre>
       int next = ((i + skip) < N) ? P[level - 1][i + skip] : -10000;
       M[i] = entry(P[level - 1][i], next, i);
     sort(M.begin(), M.end());
     for (int i = 0; i < N; ++i)</pre>
       P[level][M[i].p] = (i > 0 \text{ and } M[i].a == M[i - 1].a \text{ and } M[i].b ==
            M[i - 1].b) ? P[level][M[i - 1].p] : i;
    }
 }
  vector<int> getSuffixArray(){
    vector<int> &rank = P.back();
    vector<pair<int, int> > inv(rank.size());
    for (int i = 0; i < rank.size(); ++i)</pre>
     inv[i] = make_pair(rank[i], i);
    sort(inv.begin(), inv.end());
    vector<int> sa(rank.size());
    for (int i = 0; i < rank.size(); ++i)</pre>
     sa[i] = inv[i].second;
```

```
return sa;
}

// returns the length of the longest common prefix of s[i...L-1] and
        s[j...L-1]
int lcp(int i, int j) {
    int len = 0;
    if (i == j) return N - i;
    for (int k = P.size() - 1; k >= 0 && i < N && j < N; --k) {
        if (P[k][i] == P[k][j]) {
            i += 1 << k;
            j += 1 << k;
            len += 1 << k;
        }
    }
    return len;
}
</pre>
```

#### 9.3 suffix automaton

```
* Suffix automaton:
 * This implementation was extended to maintain (online) the
 * number of different substrings. This is equivalent to compute
 * the number of paths from the initial state to all the other
 * states.
 * The overall complexity is O(n)
 * can be tested here:
     https://www.urionlinejudge.com.br/judge/en/problems/view/1530
 * */
struct state {
  int len, link;
 long long num_paths;
 map<int, int> next;
const int MN = 200011;
state sa[MN << 1]:
int sz, last;
long long tot_paths;
```

```
void sa_init() {
 sz = 1;
 last = 0;
 sa[0].len = 0;
 sa[0].link = -1;
 sa[0].next.clear();
 sa[0].num_paths = 1;
 tot_paths = 0;
}
void sa_extend(int c) {
 int cur = sz++;
 sa[cur].len = sa[last].len + 1;
 sa[cur].next.clear();
  sa[cur].num_paths = 0;
  int p;
 for (p = last; p != -1 && !sa[p].next.count(c); p = sa[p].link) {
   sa[p].next[c] = cur;
   sa[cur].num_paths += sa[p].num_paths;
   tot_paths += sa[p].num_paths;
 }
 if (p == -1) {
   sa[cur].link = 0;
 } else {
   int q = sa[p].next[c];
   if (sa[p].len + 1 == sa[q].len) {
     sa[cur].link = q;
   } else {
     int clone = sz++;
     sa[clone].len = sa[p].len + 1;
     sa[clone].next = sa[q].next;
     sa[clone].num_paths = 0;
     sa[clone].link = sa[q].link;
     for (; p!= -1 && sa[p].next[c] == q; p = sa[p].link) {
       sa[p].next[c] = clone;
       sa[q].num_paths -= sa[p].num_paths;
       sa[clone].num_paths += sa[p].num_paths;
     sa[q].link = sa[cur].link = clone;
   }
 }
 last = cur;
```

## 9.4 z algorithm

```
using namespace std;
#include<bits/stdc++.h>
vector<int> compute_z(const string &s){
 int n = s.size();
 vector<int> z(n.0):
 int 1,r;
 r = 1 = 0;
 for(int i = 1; i < n; ++i){</pre>
   if(i > r) {
     l = r = i:
     while (r < n \text{ and } s[r - 1] == s[r])r++;
     z[i] = r - 1;r--;
   }else{
     int k = i-1;
     if(z[k] < r - i +1) z[i] = z[k];
     else {
       l = i;
       while (r < n \text{ and } s[r - 1] == s[r])r++;
       z[i] = r - 1;r--;
     }
   }
 }
 return z;
int main(){
 //string line;cin>>line;
  string line = "alfalfa";
 vector<int> z = compute_z(line);
  for(int i = 0; i < z.size(); ++i ){</pre>
   if(i)cout<<" ";</pre>
   cout<<z[i];
  cout << endl;
  // must print "0 0 0 4 0 0 1"
 return 0;
```