# Team notebook

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# 1 Algorithms

# 1.1 sliding window

```
* Given an array ARR and an integer K, the problem boils down to
     computing for each index i: min(ARR[i], ARR[i-1], ..., ARR[i-K+1]).
* if mx == true, returns the maximun.
* http://people.cs.uct.ac.za/~ksmith/articles/sliding_window_minimum.html
* */
vector<int> sliding_window_minmax(vector<int> & ARR, int K, bool mx) {
 deque< pair<int, int> > window;
 vector<int> ans;
 for (int i = 0; i < ARR.size(); i++) {</pre>
   if (mx) {
     while (!window.empty() && window.back().first <= ARR[i])</pre>
       window.pop_back();
   } else {
     while (!window.empty() && window.back().first >= ARR[i])
       window.pop_back();
   }
   window.push_back(make_pair(ARR[i], i));
   while(window.front().second <= i - K)</pre>
     window.pop_front();
   ans.push_back(window.front().first);
 }
 return ans;
```

## 2 Data structures

#### 2.1 hash table

```
/**
 * Micro hash table, can be used as a set.
 * Very efficient vs std::set
 * */
```

```
const int MN = 1001;
struct ht {
  int _s[(MN + 10) >> 5];
  int len;
  void set(int id) {
    len++;
    _s[id >> 5] |= (1LL << (id & 31));
  }
  bool is_set(int id) {
    return _s[id >> 5] & (1LL << (id & 31));
  }
};</pre>
```

## 2.2 heavy light decomposition

```
// Heavy-Light Decomposition
struct TreeDecomposition {
 vector<int> g[MAXN], c[MAXN];
 int s[MAXN]; // subtree size
 int p[MAXN]; // parent id
 int r[MAXN]; // chain root id
 int t[MAXN]; // index used in segtree/bit/...
 int d[MAXN]; // depht
 int ts;
 void dfs(int v, int f) {
   p[v] = f;
   s[v] = 1;
   if (f != -1) d[v] = d[f] + 1;
   else d[v] = 0;
   for (int i = 0; i < g[v].size(); ++i) {</pre>
     int w = g[v][i];
     if (w != f) {
       dfs(w, v);
       s[v] += s[w];
 void hld(int v, int f, int k) {
   t[v] = ts++:
   c[k].push_back(v);
```

```
r[v] = k:
    int x = 0, y = -1;
    for (int i = 0; i < g[v].size(); ++i) {</pre>
     int w = g[v][i];
     if (w != f) {
       if (s[w] > x) {
         x = s[w]:
         y = w;
       }
     }
    }
    if (y != -1) {
     hld(y, v, k);
    }
    for (int i = 0; i < g[v].size(); ++i) {</pre>
     int w = g[v][i];
     if (w != f && w != y) {
       hld(w, v, w);
     }
   }
 }
  void init(int n) {
   for (int i = 0; i < n; ++i) {</pre>
     g[i].clear();
   }
 }
  void add(int a, int b) {
   g[a].push_back(b);
   g[b].push_back(a);
  void build() {
   ts = 0;
    dfs(0, -1);
   hld(0, 0, 0);
 }
};
```

### 2.3 segment tree

```
/**
 * Taken from: http://codeforces.com/blog/entry/18051
const int N = 1e5; // limit for array size
int n; // array size
int t[2 * N];
void build() { // build the tree
 for (int i = n - 1; i > 0; --i) t[i] = t[i << 1] + t[i << 1|1];
// Single modification, range query.
void modify(int p, int value) { // set value at position p
 for (t[p += n] = value; p > 1; p >>= 1) t[p>>1] = t[p] + t[p^1];
}
int query(int 1, int r) { // sum on interval [1, r)
 int res = 0;
 for (1 += n, r += n; 1 < r; 1 >>= 1, r >>= 1) {
   if (l&1) res += t[l++];
   if (r\&1) res += t[--r];
 return res;
}
// Range modification, single query.
void modify(int 1, int r, int value) {
 for (1 += n, r += n; 1 < r; 1 >>= 1, r >>= 1) {
   if (1&1) t[1++] += value;
   if (r&1) t[--r] += value;
}
int query(int p) {
 int res = 0;
 for (p += n; p > 0; p >>= 1) res += t[p];
 return res;
}
* If at some point after modifications we need to inspect all the
 * elements in the array, we can push all the modifications to the
```

```
* leaves using the following code. After that we can just traverse
 * elements starting with index n. This way we reduce the complexity
 * from O(n \log(n)) to O(n) similarly to using build instead of n
     modifications.
 * */
void push() {
 for (int i = 1; i < n; ++i) {
   t[i<<1] += t[i];
   t[i<<1|1] += t[i];
   t[i] = 0;
 }
}
// Non commutative combiner functions.
void modify(int p, const S& value) {
 for (t[p += n] = value; p >>= 1; ) t[p] = combine(t[p<<1], t[p<<1|1]);
}
S query(int 1, int r) {
 S resl, resr;
 for (1 += n, r += n; 1 < r; 1 >>= 1, r >>= 1) {
   if (l&1) resl = combine(resl, t[l++]);
   if (r&1) resr = combine(t[--r], resr);
 return combine(resl, resr);
}
// To be continued ...
```

## 2.4 sparse table

```
// RMQ.
const int MN = 100000 + 10; // Max number of elements
const int ML = 18; // ceil(log2(MN));

struct st {
  int data[MN];
  int M[MN][ML];
  int n;

void read(int _n) {
```

```
n = _n;
for (int i = 0; i < n; ++i)
    cin >> data[i];
}

void build() {
  for (int i = 0; i < n; ++i)
    M[i][0] = data[i];
  for (int j = 1, p = 2, q = 1; p <= n; ++j, p <<= 1, q <<= 1)
    for (int i = 0; i + p - 1 < n; ++i)
        M[i][j] = max(M[i][j - 1], M[i + q][j - 1]);
}
int query(int b, int e) {
  int k = log2(e - b + 1);
   return max(M[b][k], M[e + 1 - (1<<k)][k]);
}
};</pre>
```

### 2.5 splay tree

```
using namespace std;
#include<bits/stdc++.h>
#define D(x) cout<<x<<endl;

typedef int T;

struct node{
  node *left, *right, *parent;
  T key;
  node (T k) : key(k), left(0), right(0), parent(0) {}
};

struct splay_tree{

  node *root;

void right_rot(node *x) {
   node *p = x->parent;
   if (x->parent = p->parent) {
      if (x->parent->left == p) x->parent->right = x;
      if (x->parent->right == p) x->parent->right = x;
   }
}
```

```
if (p->left = x->right) p->left->parent = p;
 x->right = p;
 p->parent = x;
void left rot(node *x) {
 node *p = x->parent;
 if (x->parent = p->parent) {
   if (x->parent->left == p) x->parent->left = x;
   if (x->parent->right == p) x->parent->right = x;
 if (p->right = x->left) p->right->parent = p;
 x->left = p;
 p->parent = x;
void splay(node *x, node *fa = 0) {
 while( x->parent != fa and x->parent != 0) {
   node *p = x->parent;
   if (p->parent == fa)
     if (p->right == x)
      left_rot(x);
     else
      right_rot(x);
   else {
     node *gp = p->parent; //grand parent
     if (gp->left == p)
      if (p->left == x)
        right_rot(x), right_rot(x);
       else
         left_rot(x),right_rot(x);
     else
       if (p->left == x)
        right_rot(x), left_rot(x);
        left_rot(x), left_rot(x);
   }
 }
 if (fa == 0) root = x;
void insert(T key) {
 node *cur = root;
 node *pcur = 0;
```

```
while (cur) {
     pcur = cur;
     if (key > cur->key) cur = cur->right;
     else cur = cur->left;
   cur = new node(key);
   cur->parent = pcur;
   if (!pcur) root = cur;
   else if (key > pcur->key ) pcur->right = cur;
   else pcur->left = cur;
   splay(cur);
  node *find(T key) {
   node *cur = root;
   while (cur) {
     if (key > cur->key) cur = cur->right;
     else if(key < cur->key) cur = cur->left;
     else return cur;
   }
   return 0;
  splay_tree(){ root = 0;};
};
```

#### 2.6 trie

```
const int MN = 26; // size of alphabet
const int MS = 100010; // Number of states.

struct trie{
    struct node{
        int c;
        int a[MN];
    };

    node tree[MS];
    int nodes;

void clear(){
        tree[nodes].c = 0;
        memset(tree[nodes].a, -1, sizeof tree[nodes].a);
```

```
nodes++;
 }
  void init(){
   nodes = 0;
   clear();
 int add(const string &s, bool query = 0){
   int cur_node = 0;
   for(int i = 0; i < s.size(); ++i){</pre>
     int id = gid(s[i]);
     if(tree[cur_node].a[id] == -1){
       if(query) return 0;
       tree[cur_node].a[id] = nodes;
       clear();
     cur_node = tree[cur_node].a[id];
   if(!query) tree[cur_node].c++;
   return tree[cur_node].c;
 }
};
```

# 3 Geometry

## 3.1 closest pair problem

```
struct point {
  double x, y;
  int id;
  point() {}
  point (double a, double b) : x(a), y(b) {}
};

double dist(const point &o, const point &p) {
  double a = p.x - o.x, b = p.y - o.y;
  return sqrt(a * a + b * b);
}

double cp(vector<point> &p, vector<point> &x, vector<point> &y) {
```

```
if (p.size() < 4) {</pre>
 double best = 1e100;
 for (int i = 0; i < p.size(); ++i)</pre>
   for (int j = i + 1; j < p.size(); ++j)
     best = min(best, dist(p[i], p[j]));
 return best;
int ls = (p.size() + 1) >> 1;
double l = (p[ls - 1].x + p[ls].x) * 0.5;
vector<point> xl(ls), xr(p.size() - ls);
unordered_set<int> left;
for (int i = 0; i < ls; ++i) {</pre>
  xl[i] = x[i]:
 left.insert(x[i].id);
for (int i = ls; i < p.size(); ++i) {</pre>
 xr[i - ls] = x[i];
vector<point> yl, yr;
vector<point> pl, pr;
yl.reserve(ls); yr.reserve(p.size() - ls);
pl.reserve(ls); pr.reserve(p.size() - ls);
for (int i = 0; i < p.size(); ++i) {</pre>
  if (left.count(y[i].id))
   yl.push_back(y[i]);
  else
   yr.push_back(y[i]);
  if (left.count(p[i].id))
   pl.push_back(p[i]);
  else
   pr.push_back(p[i]);
double dl = cp(pl, xl, yl);
double dr = cp(pr, xr, yr);
double d = min(dl, dr);
vector<point> yp; yp.reserve(p.size());
for (int i = 0; i < p.size(); ++i) {</pre>
 if (fabs(y[i].x - 1) < d)
   yp.push_back(y[i]);
for (int i = 0; i < yp.size(); ++i) {</pre>
```

```
for (int j = i + 1; j < yp.size() && j < i + 7; ++j) {
     d = min(d, dist(yp[i], yp[j]));
   }
 }
 return d;
}
double closest_pair(vector<point> &p) {
 vector<point> x(p.begin(), p.end());
 sort(x.begin(), x.end(), [](const point &a, const point &b) {
   return a.x < b.x:</pre>
 });
 vector<point> y(p.begin(), p.end());
  sort(y.begin(), y.end(), [](const point &a, const point &b) {
   return a.y < b.y;</pre>
 }):
 return cp(p, x, y);
}
```

## 3.2 squares

```
typedef long double ld;
const ld eps = 1e-12;
int cmp(ld x, ld y = 0, ld tol = eps) {
   return ( x \le y + tol) ? (x + tol < y) ? -1 : 0 : 1;
}
struct point{
 ld x, y;
 point(ld a, ld b) : x(a), y(b) {}
 point() {}
};
struct square{
 ld x1, x2, y1, y2,
    a, b, c;
 point edges[4];
 square(ld _a, ld _b, ld _c) {
   a = _a, b = _b, c = _c;
   x1 = a - c * 0.5:
   x2 = a + c * 0.5;
```

```
y1 = b - c * 0.5;
   v2 = b + c * 0.5;
   edges[0] = point(x1, y1);
   edges[1] = point(x2, y1);
   edges[2] = point(x2, y2);
   edges[3] = point(x1, y2);
 }
}:
ld min_dist(point &a, point &b) {
 1d x = a.x - b.x,
    y = a.y - b.y;
 return sqrt(x * x + y * y);
bool point_in_box(square s1, point p) {
  if (cmp(s1.x1, p.x) != 1 && cmp(s1.x2, p.x) != -1 &&
     cmp(s1.y1, p.y) != 1 \&\& cmp(s1.y2, p.y) != -1)
   return true:
 return false;
}
bool inside(square &s1, square &s2) {
 for (int i = 0; i < 4; ++i)
   if (point_in_box(s2, s1.edges[i]))
     return true;
 return false;
bool inside_vert(square &s1, square &s2) {
  if ((cmp(s1.y1, s2.y1) != -1 && cmp(s1.y1, s2.y2) != 1) ||
      (cmp(s1.y2, s2.y1) != -1 \&\& cmp(s1.y2, s2.y2) != 1))
   return true:
return false;
bool inside_hori(square &s1, square &s2) {
  if ((cmp(s1.x1, s2.x1) != -1 && cmp(s1.x1, s2.x2) != 1) ||
      (cmp(s1.x2, s2.x1) != -1 \&\& cmp(s1.x2, s2.x2) != 1))
   return true;
return false;
}
ld min_dist(square &s1, square &s2) {
```

```
if (inside(s1, s2) || inside(s2, s1))
  return 0;
ld ans = 1e100;
for (int i = 0; i < 4; ++i)
  for (int j = 0; j < 4; ++j)
   ans = min(ans, min_dist(s1.edges[i], s2.edges[j]));
if (inside_hori(s1, s2) || inside_hori(s2, s1)) {
  if (cmp(s1.y1, s2.y2) != -1)
   ans = min(ans, s1.v1 - s2.v2);
  else
  if (cmp(s2.y1, s1.y2) != -1)
   ans = min(ans, s2.y1 - s1.y2);
}
if (inside_vert(s1, s2) || inside_vert(s2, s1)) {
  if (cmp(s1.x1, s2.x2) != -1)
   ans = min(ans, s1.x1 - s2.x2);
  else
  if (cmp(s2.x1, s1.x2) != -1)
   ans = min(ans, s2.x1 - s1.x2);
}
return ans;
```

## 3.3 triangles

Let a, b, c be length of the three sides of a triangle.

$$p = (a + b + c) * 0.5$$

The inradius is defined by:

$$iR = \sqrt{\frac{(p-a)(p-b)(p-c)}{p}}$$

The radius of its circumcircle is given by the formula:

$$cR = \frac{abc}{\sqrt{(a+b+c)(a+b-c)(a+c-b)(b+c-a)}}$$

# 4 Graphs

## 4.1 bridges

```
struct edge{
 int to, id;
 edge(int a, int b) : to(a), id(b) {}
struct graph {
 vector<vector<edge> > g;
 vector<int> vi, low, d, pi, is_b;
 int ticks, edges;
 graph(int n, int m) {
   g.assign(n, vector<edge>());
   is_b.assign(m, 0);
   vi.resize(n);
   low.resize(n);
   d.resize(n);
   pi.resize(n);
   edges = 0;
 void add_edge(int u, int v) {
   g[u].push_back(edge(v, edges));
   g[v].push_back(edge(u, edges));
   edges++;
 void dfs(int u) {
   vi[u] = true;
   d[u] = low[u] = ticks++;
   for (int i = 0; i < g[u].size(); ++i) {</pre>
     int v = g[u][i].to;
     if (v == pi[u]) continue;
     if (!vi[v]) {
       pi[v] = u;
       dfs(v);
       if (d[u] < low[v])</pre>
         is_b[g[u][i].id] = true;
```

```
low[u] = min(low[u], low[v]);
     } else {
       low[u] = min(low[u], d[v]);
     }
   }
 }
 // Multiple edges from a to b are not allowed.
 // (they could be detected as a bridge).
 // If you need to handle this, just count
 // how many edges there are from a to b.
 void comp_bridges() {
   fill(pi.begin(), pi.end(), -1);
   fill(vi.begin(), vi.end(), 0);
   fill(low.begin(), low.end(), 0);
   fill(d.begin(), d.end(), 0);
   ticks = 0;
   for (int i = 0; i < g.size(); ++i)</pre>
     if (!vi[i]) dfs(i):
 }
};
```

#### 4.2 directed mst

```
const int inf = 1000000 + 10;

struct edge {
  int u, v, w;
  edge() {}
  edge(int a, int b, int c) : u(a), v(b), w(c) {}
};

/**

  * Computes the minimum spanning tree for a directed graph
  * - edges : Graph description in the form of list of edges.
  * each edge is: From node u to node v with cost w
  * - root : Id of the node to start the DMST.
  * - n : Number of nodes in the graph.
  * */

int dmst(vector<edge> &edges, int root, int n) {
  int ans = 0;
  int cur_nodes = n;
}
```

```
while (true) {
 vector<int> lo(cur_nodes, inf), pi(cur_nodes, inf);
 for (int i = 0; i < edges.size(); ++i) {</pre>
   int u = edges[i].u, v = edges[i].v, w = edges[i].w;
   if (w < lo[v] and u != v) {
     lo[v] = w:
     pi[v] = u;
 }
 lo[root] = 0:
 for (int i = 0; i < lo.size(); ++i) {</pre>
   if (i == root) continue;
   if (lo[i] == inf) return -1;
 int cur_id = 0;
 vector<int> id(cur_nodes, -1), mark(cur_nodes, -1);
 for (int i = 0; i < cur_nodes; ++i) {</pre>
   ans += lo[i]:
   int u = i;
   while (u != root and id[u] < 0 and mark[u] != i) {</pre>
     mark[u] = i;
     u = pi[u];
   }
   if (u != root and id[u] < 0) { // Cycle}
      for (int v = pi[u]; v != u; v = pi[v])
        id[v] = cur_id;
      id[u] = cur_id++;
 }
 if (cur_id == 0)
   break:
 for (int i = 0; i < cur_nodes; ++i)</pre>
   if (id[i] < 0) id[i] = cur_id++;</pre>
 for (int i = 0; i < edges.size(); ++i) {</pre>
   int u = edges[i].u, v = edges[i].v, w = edges[i].w;
   edges[i].u = id[u];
   edges[i].v = id[v];
   if (id[u] != id[v])
     edges[i].w -= lo[v];
 cur_nodes = cur_id;
```

```
root = id[root];
}
return ans;
}
```

## 4.3 eulerian path

```
// Taken from https://github.com/lbv/pc-code/blob/master/code/graph.cpp
// Eulerian Trail
struct Euler {
 ELV adj; IV t;
 Euler(ELV Adj) : adj(Adj) {}
 void build(int u) {
   while(! adj[u].empty()) {
     int v = adj[u].front().v;
     adj[u].erase(adj[u].begin());
     build(v);
   t.push_back(u);
 }
}:
bool eulerian_trail(IV &trail) {
 Euler e(adj);
 int odd = 0, s = 0:
    for (int v = 0; v < n; v++) {
    int diff = abs(in[v] - out[v]);
    if (diff > 1) return false;
    if (diff == 1) {
    if (++odd > 2) return false;
    if (out[v] > in[v]) start = v;
    }
    }
    */
  e.build(s);
 reverse(e.t.begin(), e.t.end());
 trail = e.t;
 return true;
```

## 4.4 karp min mean cycle

```
/**
 * Finds the min mean cycle, if you need the max mean cycle
 * just add all the edges with negative cost and print
 * ans * -1
 * test: uva, 11090 - Going in Cycle!!
const int MN = 1000;
struct edge{
 int v;
 long long w;
  edge(){} edge(int v, int w) : v(v), w(w) {}
};
long long d[MN][MN];
// This is a copy of g because increments the size
// pass as reference if this does not matter.
int karp(vector<vector<edge> > g) {
 int n = g.size();
  g.resize(n + 1); // this is important
 for (int i = 0; i < n; ++i)
   if (!g[i].empty())
     g[n].push_back(edge(i,0));
  ++n;
 for(int i = 0;i<n;++i)</pre>
   fill(d[i],d[i]+(n+1),INT_MAX);
 d[n - 1][0] = 0;
  for (int k = 1; k \le n; ++k) for (int u = 0; u \le n; ++u) {
   if (d[u][k - 1] == INT_MAX) continue;
   for (int i = g[u].size() - 1; i >= 0; --i)
     d[g[u][i].v][k] = min(d[g[u][i].v][k], d[u][k-1] + g[u][i].w);
  bool flag = true;
 for (int i = 0; i < n && flag; ++i)</pre>
   if (d[i][n] != INT_MAX)
```

```
flag = false;
 if (flag) {
   return true; // return true if there is no a cycle.
 double ans = 1e15;
 for (int u = 0; u + 1 < n; ++u) {
   if (d[u][n] == INT_MAX) continue;
   double W = -1e15:
   for (int k = 0; k < n; ++k)
     if (d[u][k] != INT_MAX)
       W = max(W, (double)(d[u][n] - d[u][k]) / (n - k));
   ans = min(ans, W);
 }
 // printf("%.21f\n", ans);
  cout << fixed << setprecision(2) << ans << endl;</pre>
  return false;
}
```

## 4.5 konig's theorem

In any bipartite graph, the number of edges in a maximum matching equals the number of vertices in a minimum vertex cover

## 4.6 minimum path cover in DAG

Given a directed acyclic graph G = (V, E), we are to find the minimum number of vertex-disjoint paths to cover each vertex in V.

We can construct a bipartite graph  $G' = (Vout \cup Vin, E')$  from G, where :

```
Vout = \{v \in V : v \text{ has positive out} - degree\}
Vin = \{v \in V : v \text{ has positive in} - degree\}
E' = \{(u, v) \in Vout \times Vin : (u, v) \in E\}
```

Then it can be shown, via König's theorem, that G' has a matching of size m if and only if there exists n-m vertex-disjoint paths that cover each vertex in

G, where n is the number of vertices in G and m is the maximum cardinality bipartite mathching in G'.

Therefore, the problem can be solved by finding the maximum cardinality matching in G' instead.

**NOTE:** If the paths are note necessarily disjoints, find the transitive closure and solve the problem for disjoint paths.

## 4.7 tarjan scc

```
const int MN = 20002;
struct tarjan_scc {
 int scc[MN], low[MN], d[MN], stacked[MN];
 int ticks, current_scc;
 deque<int> s; // used as stack.
 tarjan_scc() {}
 void init () {
   memset(scc, -1, sizeof scc);
   memset(d, -1, sizeof d);
   memset(stacked, 0, sizeof stacked);
   s.clear():
   ticks = current scc = 0:
 void compute(vector<vector<int> > &g, int u) {
   d[u] = low[u] = ticks++;
   s.push_back(u);
   stacked[u] = true;
   for (int i = 0; i < g[u].size(); ++i) {</pre>
     int v = g[u][i];
     if (d[v] == -1)
       compute(g, v);
     if (stacked[v]) {
       low[u] = min(low[u], low[v]);
   if (d[u] == low[u]) { // root
     int v:
     do {
       v = s.back();s.pop_back();
```

```
stacked[v] = false;
    scc[v] = current_scc;
} while (u != v);
    current_scc++;
}
}
```

# 4.8 two sat (with kosaraju)

```
/**
 * Given a set of clauses (a1 v a2)^(a2 v a3)....
 * this algorithm find a solution to it set of clauses.
 * test: http://lightoj.com/volume_showproblem.php?problem=1251
 **/
#include<bits/stdc++.h>
using namespace std;
#define MAX 100000
#define endl '\n'
vector<int> G[MAX];
vector<int> GT[MAX];
vector<int> Ftime:
vector<vector<int> > SCC;
bool visited[MAX];
int n;
void dfs1(int n){
 visited[n] = 1;
 for (int i = 0; i < G[n].size(); ++i) {</pre>
   int curr = G[n][i]:
   if (visited[curr]) continue;
   dfs1(curr);
 }
 Ftime.push_back(n);
}
void dfs2(int n, vector<int> &scc) {
 visited[n] = 1;
```

```
scc.push_back(n);
  for (int i = 0;i < GT[n].size(); ++i) {</pre>
   int curr = GT[n][i];
   if (visited[curr]) continue;
   dfs2(curr, scc);
 }
}
void kosaraju() {
 memset(visited, 0, sizeof visited);
 for (int i = 0; i < 2 * n; ++i) {
   if (!visited[i]) dfs1(i);
 }
  memset(visited, 0, sizeof visited);
  for (int i = Ftime.size() - 1; i >= 0; i--) {
   if (visited[Ftime[i]]) continue;
   vector<int> _scc;
   dfs2(Ftime[i],_scc);
   SCC.push_back(_scc);
}
 * After having the SCC, we must traverse each scc, if in one SCC are -b
     y b, there is not a solution.
 * Otherwise we build a solution, making the first "node" that we find
     truth and its complement false.
 **/
bool two_sat(vector<int> &val) {
 kosaraju();
 for (int i = 0; i < SCC.size(); ++i) {</pre>
   vector<bool> tmpvisited(2 * n, false);
   for (int j = 0; j < SCC[i].size(); ++j) {</pre>
     if (tmpvisited[SCC[i][j] ^ 1]) return 0;
     if (val[SCC[i][j]] != -1) continue;
     else {
       val[SCC[i][j]] = 0;
       val[SCC[i][j] ^ 1] = 1;
```

```
tmpvisited[SCC[i][j]] = 1;
   }
 }
 return 1;
}
// Example of use
int main() {
 int m, u, v, nc = 0, t; cin >> t;
 // n = "nodes" number, m = clauses number
  while (t--) {
   cin >> m >> n;
   Ftime.clear();
   SCC.clear();
   for (int i = 0; i < 2 * n; ++i) {</pre>
     G[i].clear():
     GT[i].clear();
   // (a1 v a2) = (a1 -> a2) = (a2 -> a1)
   for (int i = 0; i < m; ++i) {</pre>
     cin >> u >> v;
     int t1 = abs(u) - 1;
     int t2 = abs(v) - 1:
     int p = t1 * 2 + ((u < 0)? 1 : 0);
     int q = t2 * 2 + ((v < 0)? 1 : 0);
     G[p ^ 1].push_back(q);
     G[q ^ 1].push_back(p);
     GT[p].push_back(q ^ 1);
     GT[q].push_back(p ^ 1);
   vector < int > val(2 * n, -1);
   cout << "Case " << ++nc <<": ";
   if (two_sat(val)) {
     cout << "Yes" << endl;</pre>
     vector<int> sol;
     for (int i = 0; i < 2 * n; ++i)
       if (i % 2 == 0 and val[i] == 1)
         sol.push_back(i / 2 + 1);
     cout << sol.size();</pre>
```

```
for (int i = 0; i < sol.size(); ++i) {
    cout << " " << sol[i];
}
    cout << endl;
} else {
    cout << "No" << endl;
}
return 0;
}</pre>
```

## 5 Math

#### 5.1 fft

```
* Fast Fourier Transform.
 * Useful to compute convolutions.
* computes:
 * C(f \operatorname{star} g)[n] = \operatorname{sum}_m(f[m] * g[n - m])
 * for all n.
 * test: icpc live archive, 6886 - Golf Bot
 * */
using namespace std;
#include<bits/stdc++.h>
#define D(x) cout << #x " = " << (x) << endl
#define endl '\n'
const int MN = 262144 << 1;</pre>
int d[MN + 10], d2[MN + 10];
const double PI = acos(-1.0);
struct cpx {
 double real, image;
  cpx(double _real, double _image) {
   real = _real;
   image = _image;
```

```
cpx(){}
};
cpx operator + (const cpx &c1, const cpx &c2) {
 return cpx(c1.real + c2.real, c1.image + c2.image);
}
cpx operator - (const cpx &c1, const cpx &c2) {
 return cpx(c1.real - c2.real, c1.image - c2.image);
}
cpx operator * (const cpx &c1, const cpx &c2) {
 return cpx(c1.real*c2.real - c1.image*c2.image, c1.real*c2.image +
      c1.image*c2.real);
}
int rev(int id, int len) {
 int ret = 0:
 for (int i = 0; (1 << i) < len; i++) {
   ret <<= 1;
   if (id & (1 << i)) ret |= 1;</pre>
 }
 return ret;
}
cpx A[1 << 20];
void FFT(cpx *a, int len, int DFT) {
 for (int i = 0; i < len; i++)</pre>
   A[rev(i, len)] = a[i];
 for (int s = 1; (1 << s) <= len; s++) {
   int m = (1 << s);
   cpx wm = cpx(cos(DFT * 2 * PI / m), sin(DFT * 2 * PI / m));
   for(int k = 0; k < len; k += m) {
     cpx w = cpx(1, 0);
     for(int j = 0; j < (m >> 1); j++) {
       cpx t = w * A[k + j + (m >> 1)];
       cpx u = A[k + j];
       A[k + j] = u + t;
       A[k + j + (m >> 1)] = u - t;
       w = w * wm;
     }
```

```
if (DFT == -1) for (int i = 0; i < len; i++) A[i].real /= len,
      A[i].image /= len;
 for (int i = 0; i < len; i++) a[i] = A[i];</pre>
 return;
}
cpx in[1 << 20];
void solve(int n) {
 memset(d, 0, sizeof d);
  int t:
  for (int i = 0; i < n; ++i) {</pre>
   cin >> t;
    d[t] = true;
  int m;
  cin >> m;
  vector<int> q(m);
  for (int i = 0; i < m; ++i)</pre>
   cin >> q[i];
  for (int i = 0; i < MN; ++i) {</pre>
   if (d[i])
     in[i] = cpx(1, 0);
    else
     in[i] = cpx(0, 0);
  FFT(in, MN, 1);
  for (int i = 0; i < MN; ++i) {</pre>
   in[i] = in[i] * in[i];
  FFT(in, MN, -1);
  int ans = 0;
  for (int i = 0; i < q.size(); ++i) {</pre>
   if (in[q[i]].real > 0.5 || d[q[i]]) {
     ans++;
   }
  cout << ans << endl;</pre>
int main() {
  ios_base::sync_with_stdio(false);cin.tie(NULL);
```

```
int n;
while (cin >> n)
  solve(n);
return 0;
```

# 5.2 fibonacci properties

Let A, B and n be integer numbers.

$$k = A - B \tag{1}$$

$$F_A F_B = F_{k+1} F_A^2 + F_k F_A F_{A-1} \tag{2}$$

$$\sum_{i=0}^{n} F_i^2 = F_{n+1} F_n \tag{3}$$

ev(n) = returns 1 if n is even.

$$\sum_{i=0}^{n} F_i F_{i+1} = F_{n+1}^2 - ev(n) \tag{4}$$

$$\sum_{i=0}^{n} F_i F_{i-1} = \sum_{i=0}^{n-1} F_i F_{i+1}$$
 (5)

# 6 Matrix

### 6.1 matrix

```
const int MN = 111;
const int mod = 10000;

struct matrix {
  int r, c;
  int m[MN] [MN];

matrix (int _r, int _c) : r (_r), c (_c) {
  memset(m, 0, sizeof m);
}
```

```
void print() {
   for (int i = 0; i < r; ++i) {</pre>
     for (int j = 0; j < c; ++j)
       cout << m[i][j] << " ";
     cout << endl;</pre>
   }
 }
  int x[MN][MN];
  matrix & operator *= (const matrix &o) {
   memset(x, 0, sizeof x);
   for (int i = 0; i < r; ++i)
     for (int k = 0; k < c; ++k)
       if (m[i][k] != 0)
         for (int j = 0; j < c; ++j) {
           x[i][j] = (x[i][j] + ((m[i][k] * o.m[k][j]) % mod)) % mod;
   memcpy(m, x, sizeof(m));
   return *this;
};
void matrix_pow(matrix b, long long e, matrix &res) {
  memset(res.m, 0, sizeof res.m);
 for (int i = 0; i < b.r; ++i)</pre>
   res.m[i][i] = 1;
  if (e == 0) return;
  while (true) {
   if (e & 1) res *= b;
   if ((e >>= 1) == 0) break;
   b *= b:
```

# 7 Misc

## 7.1 Template Java

```
import java.io.*;
import java.util.StringTokenizer;
```

```
public class Template {
   public static void main(String []args) throws IOException {
       Scanner in = new Scanner(System.in);
       OutputWriter out = new OutputWriter(System.out);
       Task solver = new Task();
       solver.solve(in, out);
       out.close();
   }
}
class Task{
   public void solve(Scanner in, OutputWriter out){
}
class Scanner{
   public BufferedReader reader;
   public StringTokenizer st;
   public Scanner(InputStream stream){
       reader = new BufferedReader(new InputStreamReader(stream));
       st = null;
   }
   public String next(){
       while(st == null || !st.hasMoreTokens()){
          trv{
              String line = reader.readLine();
              if(line == null) return null;
              st = new StringTokenizer(line);
          }catch (Exception e){
              throw (new RuntimeException());
          }
       return st.nextToken();
   }
   public int nextInt(){
       return Integer.parseInt(next());
   public long nextLong(){
       return Long.parseLong(next());
```

```
public double nextDouble(){
       return Double.parseDouble(next());
}
class OutputWriter{
   BufferedWriter writer;
   public OutputWriter(OutputStream stream){
       writer = new BufferedWriter(new OutputStreamWriter(stream));
   public void print(int i) throws IOException {
       writer.write(i);
   public void print(String s) throws IOException {
       writer.write(s):
   public void print(char []c) throws IOException {
       writer.write(c);
   public void close() throws IOException {
       writer.close();
```

#### 7.2 fraction

```
struct frac{
  long long x, y;
  frac(long long a, long long b) {
    long long g = __gcd(a, b);
    x = a / g;
    y = b / g;
  }
  bool operator < (const frac &o) const {
    return (x * o.y < y * o.x);
  }
};</pre>
```

#### 7.3 io

```
// taken from :
    https://github.com/lbv/pc-code/blob/master/solved/c-e/diablo/diablo.cpp
// this is very fast as well :
    https://github.com/lbv/pc-code/blob/master/code/input.cpp
typedef unsigned int u32;
#define BUF 524288
struct Reader {
  char buf[BUF]; char b; int bi, bz;
 Reader() { bi=bz=0; read(); }
 void read() {
   if (bi==bz) { bi=0; bz = fread(buf, 1, BUF, stdin); }
   b = bz ? buf[bi++] : 0; }
 void skip() { while (b > 0 && b <= 32) read(); }</pre>
 u32 next_u32() {
   u32 v = 0; for (skip(); b > 32; read()) v = v*10 + b-48; return v; }
 int next_int() {
   int v = 0; bool s = false;
   skip(); if (b == '-') { s = true; read(); }
   for (; 48<=b&&b<=57; read()) v = v*10 + b-48; return s ? -v : v; }</pre>
  char next_char() { skip(); char c = b; read(); return c; }
};
```

# 8 Number theory

#### 8.1 convolution

```
typedef long long int LL;
typedef pair<LL, LL> PLL;

inline bool is_pow2(LL x) {
  return (x & (x-1)) == 0;
}

inline int ceil_log2(LL x) {
  int ans = 0;
  --x;
  while (x != 0) {
    x >>= 1;
    ans++;
}
```

```
return ans;
/* Returns the convolution of the two given vectors in time proportional
    to n*log(n).
* The number of roots of unity to use nroots_unity must be set so that
     the product of the first
* nroots_unity primes of the vector nth_roots_unity is greater than the
     maximum value of the
* convolution. Never use sizes of vectors bigger than 2^24, if you need
     to change the values of
* the nth roots of unity to appropriate primes for those sizes.
vector<LL> convolve(const vector<LL> &a, const vector<LL> &b, int
    nroots_unity = 2) {
 int N = 1 \ll ceil_log2(a.size() + b.size());
 vector<LL> ans(N,0), fA(N), fB(N), fC(N);
 LL modulo = 1:
 for (int times = 0; times < nroots_unity; times++) {</pre>
   fill(fA.begin(), fA.end(), 0);
   fill(fB.begin(), fB.end(), 0);
   for (int i = 0; i < a.size(); i++) fA[i] = a[i];</pre>
   for (int i = 0; i < b.size(); i++) fB[i] = b[i];</pre>
   LL prime = nth_roots_unity[times].first;
   LL inv_modulo = mod_inv(modulo % prime, prime);
   LL normalize = mod_inv(N, prime);
   ntfft(fA, 1, nth_roots_unity[times]);
   ntfft(fB, 1, nth_roots_unity[times]);
   for (int i = 0; i < N; i++) fC[i] = (fA[i] * fB[i]) % prime;</pre>
   ntfft(fC, -1, nth_roots_unity[times]);
   for (int i = 0; i < N; i++) {</pre>
     LL curr = (fC[i] * normalize) % prime;
     LL k = (curr - (ans[i] % prime) + prime) % prime;
     k = (k * inv_modulo) % prime;
     ans[i] += modulo * k;
   modulo *= prime;
 return ans;
```

#### 8.2 crt

```
/**
  * Chinese remainder theorem.
  * Find z such that z % x[i] = a[i] for all i.
  * */
long long crt(vector<long long> &a, vector<long long> &x) {
  long long z = 0;
  long long n = 1;
  for (int i = 0; i < x.size(); ++i)
    n *= x[i];

  for (int i = 0; i < a.size(); ++i) {
    long long tmp = (a[i] * (n / x[i])) % n;
    tmp = (tmp * mod_inv(n / x[i], x[i])) % n;
    z = (z + tmp) % n;
}

  return (z + n) % n;
}</pre>
```

## 8.3 discrete logarithm

```
// Computes x which a \hat{x} = b \mod n.
long long d_log(long long a, long long b, long long n) {
 long long m = ceil(sqrt(n));
 long long aj = 1;
 map<long long, long long> M;
 for (int i = 0; i < m; ++i) {</pre>
   if (!M.count(aj))
     M[ai] = i;
   ai = (ai * a) % n;
 long long coef = mod_pow(a, n - 2, n);
 coef = mod_pow(coef, m, n);
 // coef = a ^ (-m)
 long long gamma = b;
 for (int i = 0; i < m; ++i) {</pre>
   if (M.count(gamma)) {
     return i * m + M[gamma];
   } else {
```

```
gamma = (gamma * coef) % n;
}
return -1;
}
```

#### 8.4 ext euclidean

```
void ext_euclid(long long a, long long b, long long &x, long long &y,
    long long &g) {
    x = 0, y = 1, g = b;
    long long m, n, q, r;
    for (long long u = 1, v = 0; a != 0; g = a, a = r) {
        q = g / a, r = g % a;
        m = x - u * q, n = y - v * q;
        x = u, y = v, u = m, v = n;
    }
}
```

## 8.5 highest exponent factorial

```
int highest_exponent(int p, const int &n){
  int ans = 0;
  int t = p;
  while(t <= n){
    ans += n/t;
    t*=p;
  }
  return ans;
}</pre>
```

#### 8.6 miller rabin

```
const int rounds = 20;

// checks whether a is a witness that n is not prime, 1 < a < n
bool witness(long long a, long long n) {
    // check as in Miller Rabin Primality Test described
    long long u = n - 1;</pre>
```

```
int t = 0:
 while (u % 2 == 0) {
   t++:
   u >>= 1;
 long long next = mod_pow(a, u, n);
 if (next == 1) return false;
 long long last;
 for (int i = 0; i < t; ++i) {</pre>
   last = next;
   next = mod_mul(last, last, n);
   if (next == 1) {
     return last != n - 1;
 }
 return next != 1:
// Checks if a number is prime with prob 1 - 1 / (2 ^it)
// D(miller_rabin(999999999999997LL) == 1);
// D(miller_rabin(999999999971LL) == 1);
// D(miller_rabin(7907) == 1);
bool miller_rabin(long long n, int it = rounds) {
 if (n <= 1) return false;</pre>
 if (n == 2) return true;
 if (n % 2 == 0) return false:
 for (int i = 0; i < it; ++i) {</pre>
   long long a = rand() \% (n - 1) + 1;
   if (witness(a, n)) {
     return false;
   }
 }
 return true;
```

#### 8.7 mod inv

```
long long mod_inv(long long n, long long m) {
  long long x, y, gcd;
  ext_euclid(n, m, x, y, gcd);
  if (gcd != 1)
   return 0;
```

```
return (x + m) % m;
```

#### 8.8 mod mul

```
// Computes (a * b) % mod
long long mod_mul(long long a, long long b, long long mod) {
  long long x = 0, y = a % mod;
  while (b > 0) {
    if (b & 1)
        x = (x + y) % mod;
        y = (y * 2) % mod;
        b /= 2;
  }
  return x % mod;
}
```

## 8.9 mod pow

```
// Computes ( a ^ exp ) % mod.
long long mod_pow(long long a, long long exp, long long mod) {
  long long ans = 1;
  while (exp > 0) {
    if (exp & 1)
      ans = mod_mul(ans, a, mod);
    a = mod_mul(a, a, mod);
    exp >>= 1;
  }
  return ans;
}
```

#### 8.10 number theoretic transform

```
typedef long long int LL;
typedef pair<LL, LL> PLL;

/* The following vector of pairs contains pairs (prime, generator)
  * where the prime has an Nth root of unity for N being a power of two.
  * The generator is a number g s.t g^(p-1)=1 (mod p)
```

```
* but is different from 1 for all smaller powers */
vector<PLL> nth_roots_unity {
 \{1224736769, 330732430\}, \{1711276033, 927759239\}, \{167772161, 167489322\}.
  {469762049,343261969},{754974721,643797295},{1107296257,883865065}};
PLL ext_euclid(LL a, LL b) {
 if (b == 0)
   return make_pair(1,0);
 pair<LL,LL> rc = ext_euclid(b, a % b);
 return make_pair(rc.second, rc.first - (a / b) * rc.second);
}
//returns -1 if there is no unique modular inverse
LL mod_inv(LL x, LL modulo) {
 PLL p = ext_euclid(x, modulo);
 if ((p.first * x + p.second * modulo) != 1)
   return -1;
 return (p.first+modulo) % modulo;
}
//Number theory fft. The size of a must be a power of 2
void ntfft(vector<LL> &a, int dir, const PLL &root_unity) {
 int n = a.size():
 LL prime = root_unity.first;
 LL basew = mod_pow(root_unity.second, (prime-1) / n, prime);
 if (dir < 0) basew = mod_inv(basew, prime);</pre>
 for (int m = n; m >= 2; m >>= 1) {
   int mh = m >> 1;
   LL w = 1:
   for (int i = 0; i < mh; i++) {</pre>
     for (int j = i; j < n; j += m) {</pre>
       int k = j + mh;
       LL x = (a[j] - a[k] + prime) \% prime;
       a[j] = (a[j] + a[k]) \% prime;
       a[k] = (w * x) \% prime;
     w = (w * basew) % prime;
   basew = (basew * basew) % prime;
 int i = 0:
 for (int j = 1; j < n - 1; j++) {
   for (int k = n >> 1; k > (i ^= k); k >>= 1);
   if (j < i) swap(a[i], a[j]);</pre>
```

```
}
}
```

#### 8.11 pollard rho factorize

```
long long pollard_rho(long long n) {
 long long x, y, i = 1, k = 2, d;
 x = y = rand() \% n;
  while (1) {
   ++i:
   x = mod_mul(x, x, n);
   x += 2:
   if (x \ge n) x -= n;
   if (x == y) return 1;
   d = \_gcd(abs(x - y), n);
   if (d != 1) return d;
   if (i == k) {
     v = x;
     k *= 2;
 }
 return 1;
}
// Returns a list with the prime divisors of n
vector<long long> factorize(long long n) {
 vector<long long> ans;
 if (n == 1)
   return ans:
 if (miller_rabin(n)) {
   ans.push_back(n);
 } else {
   long long d = 1;
   while (d == 1)
     d = pollard_rho(n);
   vector<long long> dd = factorize(d);
   ans = factorize(n / d);
   for (int i = 0; i < dd.size(); ++i)</pre>
     ans.push_back(dd[i]);
 return ans;
```

#### 8.12 totient sieve

```
for (int i = 1; i < MN; i++)
   phi[i] = i;

for (int i = 1; i < MN; i++)
   if (!sieve[i]) // is prime
   for (int j = i; j < MN; j += i)
      phi[j] -= phi[j] / i;</pre>
```

#### 8.13 totient

```
long long totient(long long n) {
  if (n == 1) return 0;
  long long ans = n;
  for (int i = 0; primes[i] * primes[i] <= n; ++i) {
    if ((n % primes[i]) == 0) {
      while ((n % primes[i]) == 0) n /= primes[i];
      ans -= ans / primes[i];
    }
  }
  if (n > 1) {
    ans -= ans / n;
  }
  return ans;
}
```

# 9 Strings

# 9.1 minimal string rotation

```
// Lexicographically minimal string rotation
int lmsr() {
   string s;
   cin >> s;
   int n = s.size();
   s += s;
   vector<int> f(s.size(), -1);
   int k = 0;
   for (int j = 1; j < 2 * n; ++j) {</pre>
```

```
int i = f[j - k - 1];
while (i != -1 && s[j] != s[k + i + 1]) {
    if (s[j] < s[k + i + 1])
        k = j - i - 1;
    i = f[i];
}
if (i == -1 && s[j] != s[k + i + 1]) {
    if (s[j] < s[k + i + 1]) {
        k = j;
    }
    f[j - k] = -1;
} else {
    f[j - k] = i + 1;
}
return k;
}</pre>
```

# 9.2 suffix array

```
/**
 * 0 (n log^2 (n))
 * See http://web.stanford.edu/class/cs97si/suffix-array.pdf for reference
 * */
struct entry{
 int a, b, p;
  entry(){}
  entry(int x, int y, int z): a(x), b(y), p(z){}
  bool operator < (const entry &o) const {</pre>
   return (a == o.a) ? (b == o.b) ? (p < o.p) : (b < o.b) : (a < o.a);
 }
};
struct SuffixArray{
 const int N;
 string s;
 vector<vector<int> > P;
 vector<entry> M;
  SuffixArray(const string &s) : N(s.length()) , s(s), P(1, vector<int>
      (N, 0)), M(N) {
   for (int i = 0; i < N; ++i)</pre>
```

```
P[0][i] = (int) s[i];
    for (int skip = 1, level = 1; skip < N; skip *= 2, level++) {</pre>
     P.push_back(vector<int>(N, 0));
     for (int i = 0 ; i < N; ++i) {</pre>
       int next = ((i + skip) < N) ? P[level - 1][i + skip] : -10000;
       M[i] = entry(P[level - 1][i], next, i);
     sort(M.begin(), M.end());
     for (int i = 0; i < N; ++i)</pre>
       P[level][M[i].p] = (i > 0 \text{ and } M[i].a == M[i - 1].a \text{ and } M[i].b ==
            M[i - 1].b) ? P[level][M[i - 1].p] : i;
   }
  }
  vector<int> getSuffixArray(){
    vector<int> &rank = P.back();
    vector<pair<int, int> > inv(rank.size());
    for (int i = 0; i < rank.size(); ++i)</pre>
     inv[i] = make_pair(rank[i], i);
    sort(inv.begin(), inv.end());
    vector<int> sa(rank.size());
    for (int i = 0; i < rank.size(); ++i)</pre>
     sa[i] = inv[i].second:
    return sa;
 }
  // returns the length of the longest common prefix of s[i...L-1] and
      s[j...L-1]
  int lcp(int i, int j) {
    int len = 0;
   if (i == j) return N - i;
    for (int k = P.size() - 1; k \ge 0 && i < N && j < N; --k) {
     if (P[k][i] == P[k][j]) {
       i += 1 << k;
       i += 1 << k;
       len += 1 << k;
     }
   }
    return len;
 }
};
```

#### 9.3 suffix automaton

```
* Suffix automaton:
 * This implementation was extended to maintain (online) the
 * number of different substrings. This is equivalent to compute
 * the number of paths from the initial state to all the other
 * states.
 * The overall complexity is O(n)
 * can be tested here:
     https://www.urionlinejudge.com.br/judge/en/problems/view/1530
struct state {
 int len, link;
 long long num_paths;
 map<int, int> next;
};
const int MN = 200011;
state sa[MN << 1];
int sz, last;
long long tot_paths;
void sa init() {
  sz = 1;
 last = 0:
  sa[0].len = 0;
  sa[0].link = -1;
  sa[0].next.clear();
  sa[0].num_paths = 1;
 tot_paths = 0;
void sa extend(int c) {
 int cur = sz++;
  sa[cur].len = sa[last].len + 1;
  sa[cur].next.clear();
  sa[cur].num_paths = 0;
  int p;
  for (p = last; p != -1 \&\& !sa[p].next.count(c); p = sa[p].link) {
   sa[p].next[c] = cur;
   sa[cur].num_paths += sa[p].num_paths;
   tot_paths += sa[p].num_paths;
```

```
}
 if (p == -1) {
   sa[cur].link = 0;
 } else {
   int q = sa[p].next[c];
   if (sa[p].len + 1 == sa[q].len) {
     sa[cur].link = q;
   } else {
     int clone = sz++;
     sa[clone].len = sa[p].len + 1;
     sa[clone].next = sa[q].next;
     sa[clone].num_paths = 0;
     sa[clone].link = sa[q].link;
     for (; p!= -1 && sa[p].next[c] == q; p = sa[p].link) {
       sa[p].next[c] = clone;
       sa[q].num_paths -= sa[p].num_paths;
       sa[clone].num_paths += sa[p].num_paths;
     sa[q].link = sa[cur].link = clone;
 }
 last = cur;
}
```

# 9.4 z algorithm

```
using namespace std;
#include<bits/stdc++.h>

vector<int> compute_z(const string &s){
   int n = s.size();
   vector<int> z(n,0);
   int l,r;
   r = l = 0;
   for(int i = 1; i < n; ++i){
      if(i > r) {
        l = r = i;
      while(r < n and s[r - l] == s[r])r++;
      z[i] = r - l;r--;
   }else{
      int k = i-l;
      if(z[k] < r - i +1) z[i] = z[k];</pre>
```

```
else {
       l = i;
       while (r < n \text{ and } s[r - 1] == s[r])r++;
       z[i] = r - 1;r--;
   }
 }
 return z;
int main(){
 //string line;cin>>line;
  string line = "alfalfa";
 vector<int> z = compute_z(line);
 for(int i = 0; i < z.size(); ++i ){</pre>
   if(i)cout<<" ";</pre>
    cout<<z[i];
  cout<<endl;</pre>
 // must print "0 0 0 4 0 0 1"
 return 0;
```