

# Practical Performance Practices

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- <http://github.com/lefticus/presentations>
- <http://cppcast.com>
- <http://chaiscript.com>
- <http://cppbestpractices.com>
- C++ Weekly - YouTube Series
- @lefticus
- Independent Contractor

I prefer an interactive session - please ask questions

# Optimizing Compilers Are Amazing

```
#include <string>

int main()
{
    std::string s("a");
    return s.size();
}
```

# Optimizing Compilers Are Amazing

## g++ 5.1+

```
main:
    mov     eax, 1
    ret
```

# Optimizing Compilers Are Amazing

```
#include <string>

int main()
{
    return std::string("a").size() + std::string("b").size();
}
```

# Optimizing Compilers Are Amazing

```
.LC0:
    .string "basic_string::_M_construct null not valid"
void std::__cxx11::basic_string<char, std::char_traits<char>, std::allocator<char> >::
    push    r12
    push    rbp
    mov     r12, rsi
    push    rbx
    mov     rbp, rdi
    sub     rsp, 16
    test    rsi, rsi
    jne     .L4
    test    rdx, rdx
    je      .L4
    mov     edi, OFFSET FLAT:.LC0
    call    std::__throw_logic_error(char const*)
.L4:
    mov     rbx, rdx
    sub     rbx, r12
    cmp     rbx, 15
    mov     QWORD PTR [rsp+8], rbx
    ja      .L17
    cmp     rbx, 1
    mov     rdi, QWORD PTR [rbp+0]
    jne     .L5
    movzx   eax, BYTE PTR [r12]
    mov     BYTE PTR [rdi], al
    jmp     .L6
```

# Optimizing Compilers Are Amazing

```
.L17:
    lea     rsi, [rsp+8]
    xor     edx, edx
    mov     rdi, rbp
    call    std::__cxx11::basic_string<char, std::char_traits<char>, std::allocato
    mov     rdx, QWORD PTR [rsp+8]
    mov     QWORD PTR [rbp+0], rax
    mov     rdi, rax
    mov     QWORD PTR [rbp+16], rdx

.L5:
    mov     rdx, rbx
    mov     rsi, r12
    call    memcpy

.L6:
    mov     rax, QWORD PTR [rsp+8]
    mov     rdx, QWORD PTR [rbp+0]
    mov     QWORD PTR [rbp+8], rax
    mov     BYTE PTR [rdx+rax], 0
    add     rsp, 16
    pop     rbx
    pop     rbp
    pop     r12
    ret

.LC2:
    .string "a"

.LC3:
    .string "b"
```

# Optimizing Compilers Are Amazing

```
main:
    push    rbx
    mov     edx, OFFSET FLAT:.LC2+1
    mov     esi, OFFSET FLAT:.LC2
    sub     rsp, 64
    lea     rax, [rsp+16]
    mov     rdi, rsp
    mov     QWORD PTR [rsp], rax
    call    void std::__cxx11::basic_string<char, std::char_traits<char>, std::all
    lea     rax, [rsp+48]
    lea     rdi, [rsp+32]
    mov     edx, OFFSET FLAT:.LC3+1
    mov     esi, OFFSET FLAT:.LC3
    mov     rbx, QWORD PTR [rsp+8]
    mov     QWORD PTR [rsp+32], rax
    call    void std::__cxx11::basic_string<char, std::char_traits<char>, std::all
    mov     rdi, QWORD PTR [rsp+32]
    lea     rax, [rsp+48]
    add     ebx, DWORD PTR [rsp+40]
    cmp     rdi, rax
    je      .L19
    call    operator delete(void*)
.L19:
    mov     rdi, QWORD PTR [rsp]
    lea     rax, [rsp+16]
    cmp     rdi, rax
    je      .L24
    call    operator delete(void*)
```



# Optimizing Compilers Are Amazing

```
.L24:
    add     rsp, 64
    mov     eax, ebx
    pop     rbx
    ret
    mov     rdi, QWORD PTR [rsp]
    lea     rdx, [rsp+16]
    mov     rbx, rax
    cmp     rdi, rdx
    je      .L22
    call    operator delete(void*)
.L22:
    mov     rdi, rbx
    call    _Unwind_Resume
```

# Optimizing Compilers Are Amazing

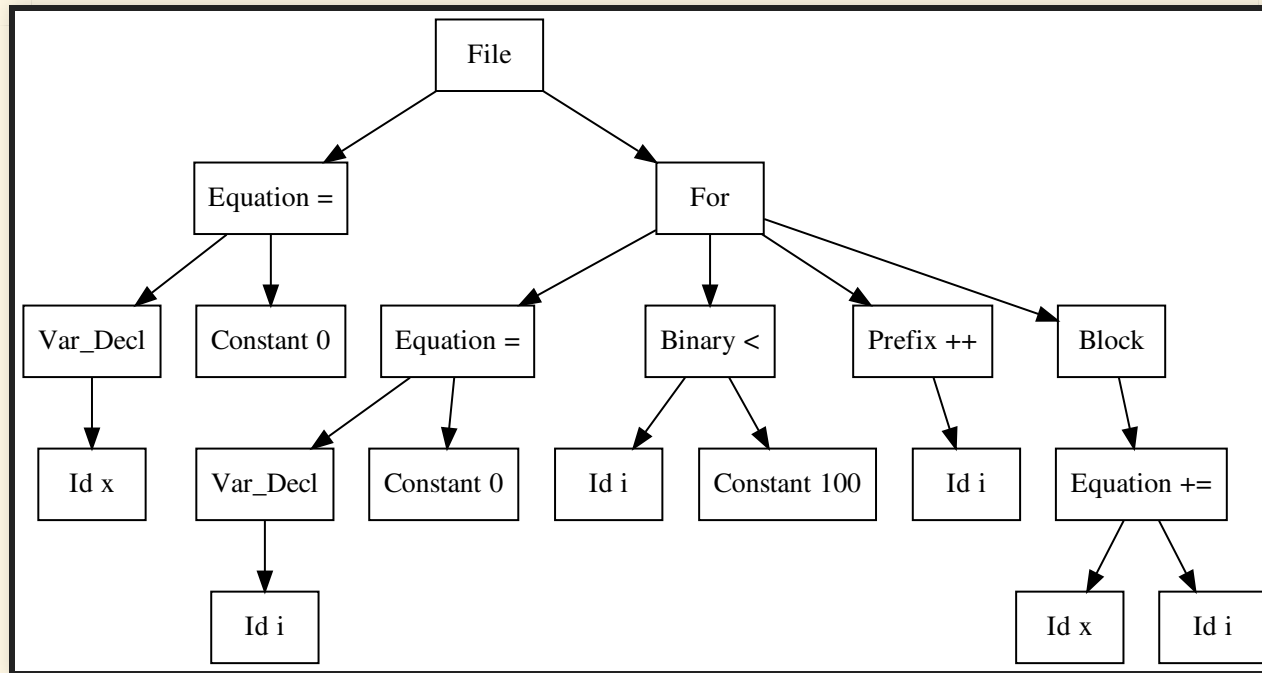
- But trying to predict what the compiler can optimize is a risky game

# Profiling ChaiScript

- Performance measuring ChaiScript is difficult
- Great number of template instantiations
- Nature of scripting means execution is spread over many similar functions

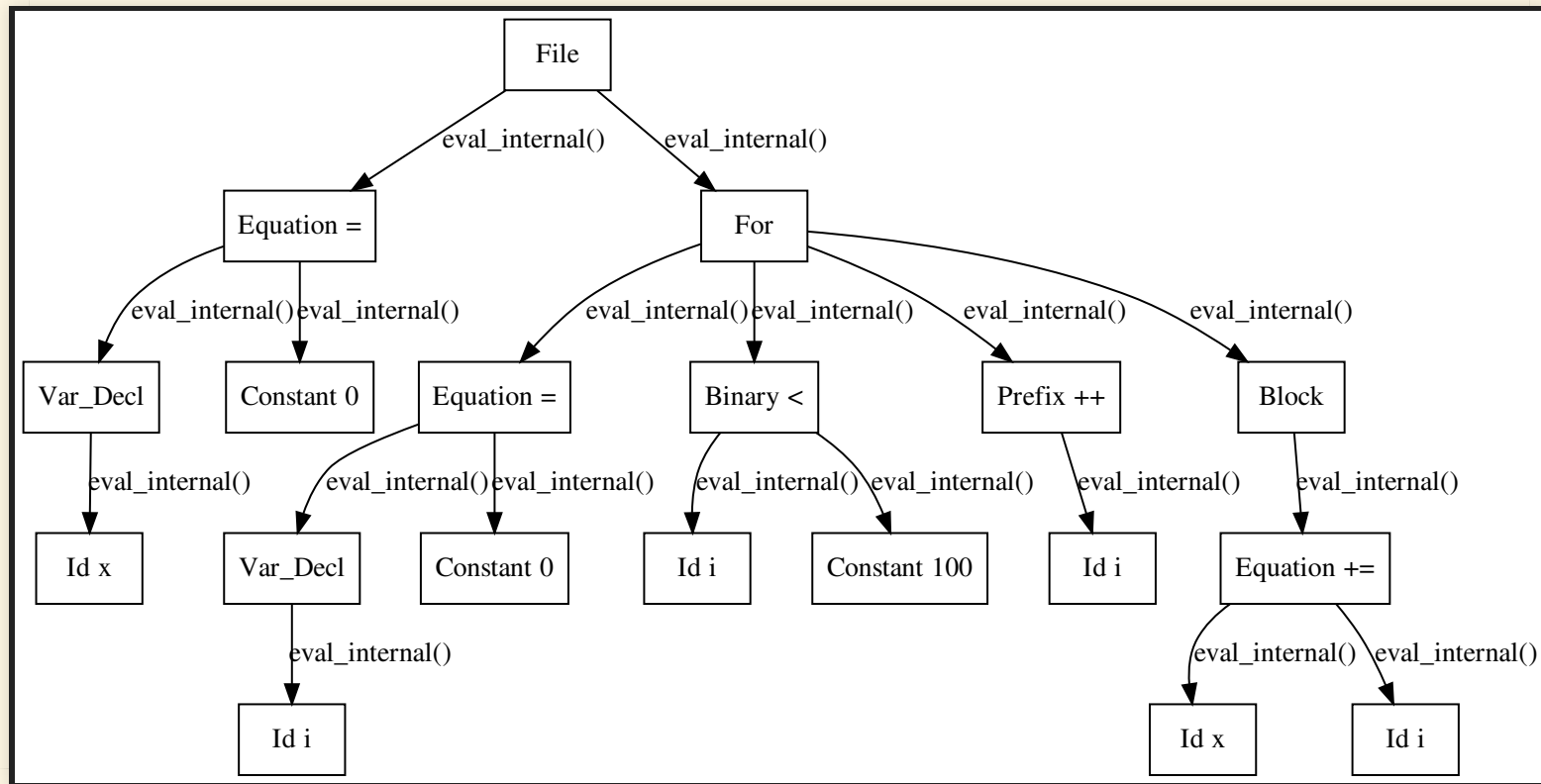
# Parsed Nodes

```
var x = 0;  
for (var i = 0; i < 100; ++i) {  
    x += i;  
}
```

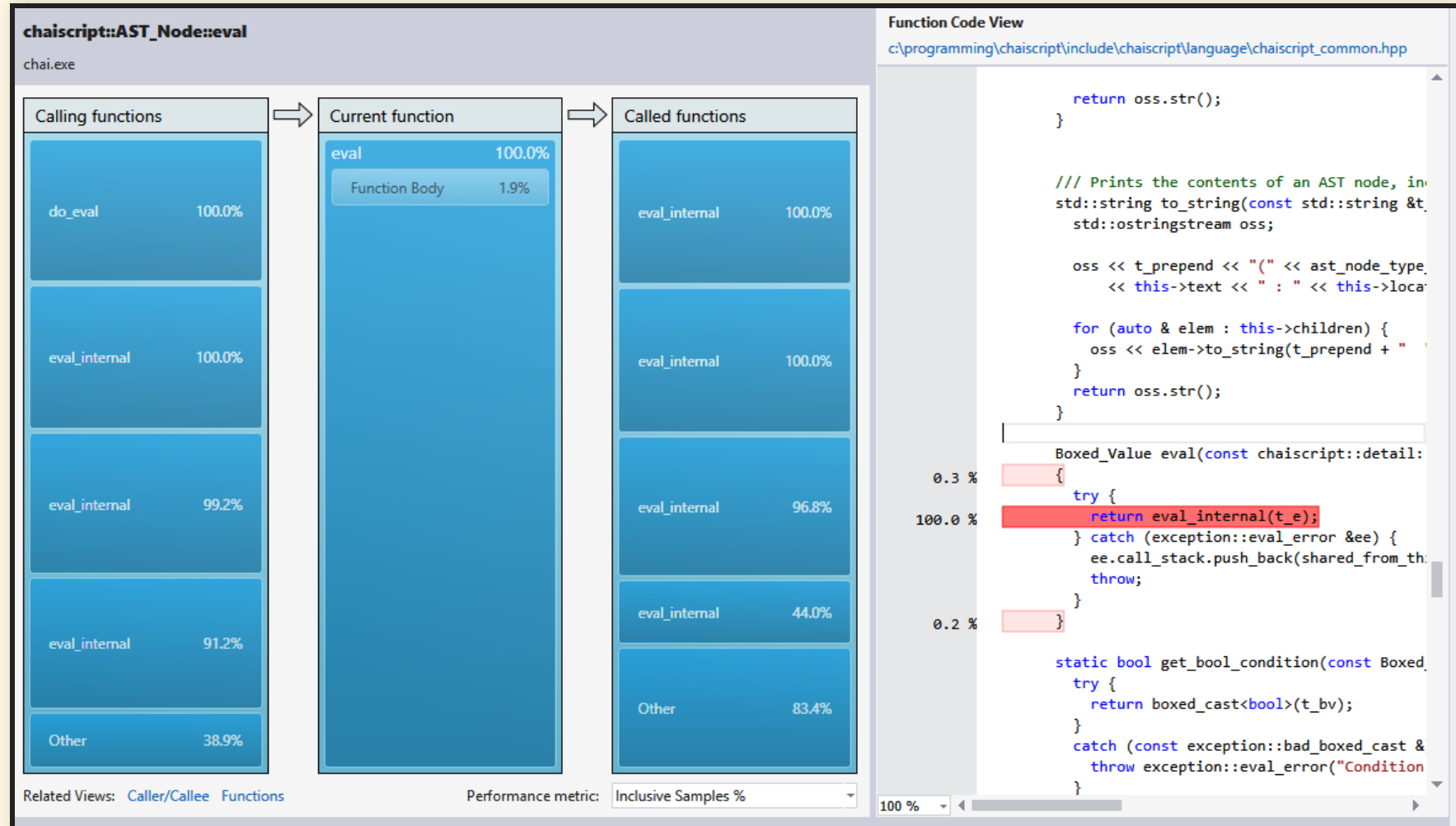


# Parsed Nodes

```
var x = 0;  
  
for (var i = 0; i < 100; ++i) {  
    x += i;  
}
```



# Performance Profiling



# Performance Practices

This led to the creation of several rules and practices that I follow to make well-performing code 'by default'

# Which Is Better In Normal Use?

```
std::vector
```

- or -

```
std::list
```

- WHY?



# `std::list`

# std::list

```
int main()
{
    std::list<int> v{1};
}
```

- What has to happen here?

# std::list

```
main:
    pushq    %r12
    pushq    %rbp
    movl     $24, %edi
    pushq    %rbx
    subq     $32, %rsp
    movq     $0, 16(%rsp)
    movq     %rsp, %rbp
    movq     %rsp, (%rsp)
    movq     %rsp, 8(%rsp)
    call     operator new(unsigned long)
    movq     %rax, %rdi
    movq     $0, (%rax)
    movq     $0, 8(%rax)
    movl     $1, 16(%rax)
    movq     %rsp, %rsi
    call     std::__detail::_List_node_base::_M_hook(std::__detail::_List_node_base
    movq     (%rsp), %rdi
    addq     $1, 16(%rsp)
    cmpq     %rsp, %rdi
    je       .L9
```

# std::list

```
.L10:
    movq    (%rdi), %rbp
    call    operator delete(void*)
    cmpq    %rbx, %rbp
    movq    %rbp, %rdi
    jne     .L10
.L9:
    addq    $32, %rsp
    xorl    %eax, %eax
    popq    %rbx
    popq    %rbp
    popq    %r12
    ret
    movq    (%rsp), %rdi
    movq    %rax, %rbp
```

# std::list

```
.L5:      cmpq    %rbx, %rdi
        je     .L4
        movq   (%rdi), %r12
        call   operator delete(void*)
        movq   %r12, %rdi
        jmp    .L5
.L4:      movq   %rbp, %rdi
        call   _Unwind_Resume
```

# `std::list`

- Allocate a new node
- Handle exception thrown during node allocation?
- Assign the value
- Hook up some pointers
- Delete node
- etc?

# `std::vector`

# std::vector

```
int main()
{
    std::vector<int> v{1};
}
```

- What has to happen here?



# std::vector

```
main:
    subq    $8, %rsp
    movl    $4, %edi
    call    operator new(unsigned long)
    movl    $1, (%rax)
    movq    %rax, %rdi
    call    operator delete(void*)
    xorl    %eax, %eax
    addq    $8, %rsp
    ret
```

- Allocate a buffer
- Assign a value in the buffer
- Delete the buffer

# What about `std::array`?

```
int main()
{
    std::array<int, 1> v{1};
}
```

# What about `std::array`?

```
int main()
{
    std::array<int, 1> v{1};
}
```

```
main:
    xorl    %eax, %eax
    ret
```

- Code is completely compiled away

# Part 1: Don't Do More Work Than You Have To

# Don't Do More Work Than You Have To

## Container Practices

- Always prefer `std::array`
- Then `std::vector`
- Then only differ if you need specific behavior
- Make sure you understand what the library has to do

# Don't Do More Work Than You Have To

```
int main()
{
    std::string s;
    s = "A Somewhat Rather Long String";
}
```

- Construct a string object
- Reassign string object

# Don't Do More Work Than You Have To

*Always* `const`

```
int main()
{
    const std::string s = "A Somewhat Rather Long String";
}
```

- Construct and initialize in one step
- ~32% more efficient

# Don't Do More Work Than You Have To

Always `const` - Complex Initialization

```
int main()
{
    const int i = std::rand();
    std::string s;
    switch (i % 4) {
        case 0:
            s = "long string is mod 0";
            break;
        case 1:
            s = "long string is mod 1";
            break;
        case 2:
            s = "long string is mod 2";
            break;
        case 3:
            s = "long string is mod 3";
            break;
    }
}
```

- How can we make `s` `const` in this context?



# Don't Do More Work Than You Have To

Always `const` - Complex Initialization - *Use IIFE*

```
int main()
{
    const int i = std::rand();
    const std::string s = [&]() {
        switch (i % 4) {
            case 0:
                return "long string is mod 0";
            case 1:
                return "long string is mod 1";
            case 2:
                return "long string is mod 2";
            case 3:
                return "long string is mod 3";
        }
    }();
}
```

- ~31% more efficient

# Don't Do More Work Than You Have To

*Always Initialize When Const Isn't Practical*

```
struct Int
{
    Int(std::string t_s)
    {
        m_s = t_s;
    }

    int val() const {
        return std::atoi(m_s.c_str());
    }

    std::string m_s;
};
```

- Same issues as previous examples

# Don't Do More Work Than You Have To

## *Always Initialize When Const Isn't Practical*

```
struct Int
{
    Int(std::string t_s) : m_s(std::move(t_s))
    {
    }

    int val() const {
        return std::atoi(m_s.c_str());
    }

    std::string m_s;
};
```

- Same gains as const initializer
- What's wrong with this version now?
- val() parses string on each call

# Don't Do More Work Than You Have To

## *Don't Recalculate Values - Calculate on First Use*

```
struct Int
{
    Int(std::string t_s) : s(std::move(t_s))
    { }

    int val() const {
        if (!is_calculated) {
            value = std::atoi(s);
        }
        return value;
    }

    mutable bool is_calculated = false;
    mutable int value;
    std::string s;
};
```

- What's wrong now?
- C++ Core Guidelines state that const methods should be thread safe
- What else?
- `is_calculated` isn't being set

# Don't Do More Work Than You Have To

## *Don't Recalculate Values - Calculate On First Use*

```
struct Int
{
    Int(std::string t_s) : s(std::move(t_s))
    { }

    int val() const {
        if (!is_calculated) {
            value = std::atoi(s);
            is_calculated = true;
        }
        return value;
    }

    mutable std::atomic_bool is_calculated = false;
    mutable std::atomic_int value;
    std::string s;
};
```

- Branching is slower
- Atomics are slower

# Don't Do More Work Than You Have To

## *Don't Recalculate Values - Calculate At Construction*

```
struct Int
{
    Int(const std::string &t_s) : m_i(std::atoi(t_s.c_str()))
    { }

    int val() const {
        return m_i;
    }

    int m_i;
};
```

- No branching, no atomics, smaller runtime (int vs string)
- In the context of a large code base, this took ~2 years to find
- Resulted in 10% performance improvement across system
- *The simpler solution is almost always the best solution*

# Don't Do More Work Than You Have To

## Initialization Practices

- Always const
- Always initialize
- Using IIFE can help you initialize
- Don't recalculate values that can be calculated once

# Don't Do More Work Than You Have To

```
struct Base {  
    virtual ~Base() = default;  
    virtual void do_a_thing() = 0;  
};  
  
struct Derived : Base {  
    virtual ~Derived() = default;  
    void do_a_thing() override {}  
};
```

- What's wrong here?
- move construction / assignment is disabled (virtual destructor)
- `virtual ~Derived()` is unnecessary



# Don't Do More Work Than You Have To

*Don't Disable Move Operations / Use Rule of 0*

```
struct Base {  
    virtual ~Base() = default;  
    Base() = default;  
    Base(const Base &) = default; Base& operator=(const Base&) = default;  
    Base(Base &&) = default; Base& operator=(Base &&) = default;  
  
    virtual void do_a_thing() = 0;  
};  
  
struct Derived : Base {  
    virtual void do_a_thing() {}  
};
```

- 10% improvement with fixing this in just one commonly used class

# Don't Do More Work Than You Have To

## On The Topic Of Copying

```
#include <string>

struct S {
    S(std::string t_s) : s(std::move(t_s)) {}
    std::string s;
};

int main()
{
    for (int i = 0; i < 10000000; ++i) {
        std::string s = std::string("a not very short string") + "b";
        S o(s);
    }
}
```

- We all know that copying objects is bad
- So let's use `std::move`

# Don't Do More Work Than You Have To

## On The Topic Of Copying

```
#include <string>

struct S {
    S(std::string t_s) : s(std::move(t_s)) {}
    std::string s;
};

int main()
{
    for (int i = 0; i < 10000000; ++i) {
        std::string s = std::string("a not very short string") + "b";
        S o(std::move(s));
    }
}
```

- 29% more efficient
- 32% smaller binary
- Good! But what's better?

# Don't Do More Work Than You Have To

## *Avoid Named Temporaries*

```
#include <string>

struct S {
    S(std::string t_s) : s(std::move(t_s)) {}
    std::string s;
};

int main()
{
    for (int i = 0; i < 10000000; ++i) {
        S o(std::string("a not very short string") + "b");
    }
}
```

- 2% more efficient again
- Can lead to less readable code sometimes, but more maintainable than `std::move` calls
- This is taking the "don't declare a variable until you need it" philosophy to its ultimate conclusion

# Don't Do More Work Than You Have To

```
int use_a_base(std::shared_ptr<Base> p)
{
    return p->value();
}

int main()
{
    auto ptr = std::make_shared<Derived>();
    use_a_base(ptr);
}
```

- What's the problem here?
- Copies are being made of `shared_ptr<Base>`

# Don't Do More Work Than You Have To

## *Avoid (`shared_ptr`) Copies*

```
int use_a_base(const std::shared_ptr<Base> &p)
{
    return p->value();
}

int main()
{
    auto ptr = std::make_shared<Derived>();
    use_a_base(ptr);
}
```

- Fixed!
- Right?
- Wrong!

# Don't Do More Work Than You Have To

## *Avoid Automatic Conversions*

```
int use_a_base(const Base &p)
{
    return p.value();
}

int main()
{
    auto ptr = std::make_shared<Derived>();
    use_a_base(*ptr);
}
```

- This version is 2.5x faster than the last

# Don't Do More Work Than You Have To

`std::endl`

```
void println(ostream &os, const std::string &str)
{
    os << str << std::endl;
}
```

- What does `std::endl` do?
- it's equivalent to `'\n' << std::flush`
- Expect that flush to cost you at least 9x overhead in your IO



# Don't Do More Work Than You Have To

## Real World `std::endl` Anecdote

```
void write_file(std::ostream &os) {
    os << "a line of text" << std::endl;
    os << "another line of text" << std::endl;
    /* snip */
    os << "many more lines of text" << std::endl;
}

void write_file(const std::string &filename) {
    std::ofstream ofs(filename.c_str());
    write_file(ofs);
}

std::string get_file_as_string() {
    std::stringstream ss;
    write_file(ss);
    return ss.str();
}
```

# Don't Do More Work Than You Have To

*Avoid `std::endl`*

Prefer just using `'\n'`

```
void println(ostream &os, const std::string &str)
{
    os << str << '\n';
}
```

# Don't Do More Work Than You Have To

## Hidden Work Practices

- Calculate values once - at initialization time
- Obey the rule of 0
- If it looks simpler, it's probably faster
- Avoid object copying
- Avoid automatic conversions
  - Don't pass smart pointers
  - Make conversion operations explicit
- Avoid `std::endl`

# Don't Do More Work Than You Have To

## `shared_ptr` Instantiations

# Don't Do More Work Than You Have To

## `shared_ptr` Instantiations

```
int main() {  
    std::make_shared<int>(1);  
}
```

# Don't Do More Work Than You Have To

## `shared_ptr` Instantiations

```
std::_Sp_counted_ptr_inplace<int, std::allocator<int>, (__gnu_cxx::_Lock_policy)2>::~~_M
    rep ret
std::_Sp_counted_ptr_inplace<int, std::allocator<int>, (__gnu_cxx::_Lock_policy)2>::~_M
    rep ret
std::_Sp_counted_ptr_inplace<int, std::allocator<int>, (__gnu_cxx::_Lock_policy)2>::~_M
    movq    8(%rsi), %rsi
    movq    %rdi, %rdx
    cmpq    typeinfo name for std::_Sp_make_shared_tag, %rsi
    je      .L4
    xorl    %eax, %eax
    cmpb    $42, (%rsi)
    je      .L3
    movl    typeinfo name for std::_Sp_make_shared_tag, %edi
    movl    $24, %ecx
    repz    cmpsb
    jne     .L3
.L4:
    leaq    16(%rdx), %rax
```

# Don't Do More Work Than You Have To

## `shared_ptr` Instantiations

```
.L3:
    rep ret
std::_Sp_counted_ptr_inplace<int, std::allocator<int>, (__gnu_cxx::_Lock_policy)2>::~~_
    movl    $24, %esi
    jmp     operator delete(void*, unsigned long)
std::_Sp_counted_ptr_inplace<int, std::allocator<int>, (__gnu_cxx::_Lock_policy)2>::~_M
    jmp     operator delete(void*)
main:
    pushq   %rbx
    movl    $24, %edi
    call    operator new(unsigned long)
    movq    %rax, %rbx
    movl    $1, 8(%rax)
    movl    $1, 12(%rax)
    movq    vtable for std::_Sp_counted_ptr_inplace<int, std::allocator<int>, (__g
    movl    $0, 16(%rax)
    movl    __gthrw___pthread_key_create(unsigned int*, void (*)(void*)), %eax
    testq   %rax, %rax
    je      .L17
    leaq    8(%rbx), %rdi
    orl     $-1, %esi
    call    __gnu_cxx::__exchange_and_add(int volatile*, int)
    subl    $1, %eax
    je      .L26
```

# Don't Do More Work Than You Have To

## `shared_ptr` Instantiations

```
.L22:
    xorl    %eax, %eax
    popq    %rbx
    ret

.L17:
    movl    $0, 8(%rbx)
    movl    $0, 12(%rbx)

.L23:
    movq    (%rbx), %rax
    movq    %rbx, %rdi
    movq    24(%rax), %rax
    call    *%rax
    jmp     .L22

.L26:
    movq    (%rbx), %rax
    movq    %rbx, %rdi
    movq    16(%rax), %rax
    call    *%rax
    leaq    12(%rbx), %rdi
    orl     $-1, %esi
    call    __gnu_cxx::__exchange_and_add(int volatile*, int)
    subl    $1, %eax
    jne     .L22
    jmp     .L23
```



# Don't Do More Work Than You Have To

## `unique_ptr` Instantiations

# Don't Do More Work Than You Have To

## `unique_ptr` Instantiations

```
int main()
{
    std::make_unique<int>(0);
}
```

- What does this have to do?

# Don't Do More Work Than You Have To

## `unique_ptr` Instantiations

```
int main()
{
    std::make_unique<int>(0);
}
```

```
main:
    sub     rsp, 8
    mov     edi, 4
    call    operator new(unsigned long)
    mov     esi, 4
    mov     DWORD PTR [rax], 0
    mov     rdi, rax
    call    operator delete(void*, unsigned long)
    xor     eax, eax
    add     rsp, 8
    ret
```

# Don't Do More Work Than You Have To

## `unique_ptr` Compared To Manual Memory Management

```
int main()
{
    auto i = new int(0);
    delete i;
}
```

```
main:
    sub     rsp, 8
    mov     edi, 4
    call    operator new(unsigned long)
    mov     esi, 4
    mov     DWORD PTR [rax], 0
    mov     rdi, rax
    call    operator delete(void*, unsigned long)
    xor     eax, eax
    add     rsp, 8
    ret
```

Identical

# Part 1: Don't Do More Work Than You Have To - Summary

- Avoid `shared_ptr`
- Avoid `std::endl`
- Always `const`
- Always initialize with meaningful values
- Don't recalculate immutable results

# Part 1: Questions?

# Part 2: Smaller Code Is Faster Code

# Smaller Code Is Faster Code

```
struct B
{
    virtual ~B() = default; // plus the other default operations
    virtual std::vector<int> get_vec() const = 0;
};

template<typename T>
struct D : B
{
    std::vector<int> get_vec() const override { return m_v; }
    std::vector<int> m_v;
}
```

- With many template instantiations this code blows up in size quickly



# Smaller Code Is Faster Code

## DRY In Templates

```
struct B
{
    virtual ~B() = default; // plus the other default operations
    virtual std::vector<int> get_vec() const { return m_v; }
    std::vector<int> m_v;
};

template<typename T>
struct D : B
{
}
```

# Smaller Code Is Faster Code

## Factories

# Smaller Code Is Faster Code

## Factories

```
struct B {  
    virtual ~B() = default;  
};  
  
template<int T>  
struct D : B {  
};  
  
template<int T>  
std::shared_ptr<B> d_factory() {  
    return std::make_shared<D<T>>();  
}  
  
int main() {  
    std::vector<std::shared_ptr<B>> v{  
        d_factory<1>(), d_factory<2>(), /* ... */ , d_factory<29>(), d_factory<30>()  
    };  
}
```

- Prefer returning `unique_ptr<>` (Back To The Basics - Herb Sutter ~0:19)
- We already saw that `shared_ptr<>` is big - don't make more than you have to

# Smaller Code Is Faster Code

*Prefer return `unique_ptr<>` from factories*

```
struct B {  
    virtual ~B() = default;  
};  
  
template<int T>  
struct D : B {  
};  
  
template<int T>  
std::unique_ptr<B> d_factory() {  
    return std::make_unique<D<T>>();  
}  
  
int main() {  
    std::vector<std::shared_ptr<B>> v{  
        d_factory<1>(), d_factory<2>(), /* ... */ , d_factory<29>(), d_factory<30>()  
    };  
}
```

# Smaller Code Is Faster Code

*Prefer return `unique_ptr<>` from factories*

```
template<int T> std::unique_ptr<B> d_factory()  
{  
    return std::make_unique<D<T>>();  
}
```

1.30s compile, 30k exe, 149796k compile RAM

```
template<int T> std::shared_ptr<B> d_factory()  
{  
    return std::make_shared<D<T>>();  
}
```

2.24s compile, 70k exe, 164808k compile RAM

```
template<int T> std::shared_ptr<B> d_factory()  
{  
    return std::make_unique<D<T>>();  
}
```

2.43s compile, 91k exe, 190044k compile RAM

# Smaller Code Is Faster Code

*Prefer return `unique_ptr<>` from factories - ChaiScript Numbers*

```
std::unique_ptr<B> d_factory()
{
    return std::make_unique<D>();
}
```

4925k exe

```
std::shared_ptr<B> d_factory()
{
    return std::make_shared<D>();
}
```

7350k exe, ~6% slower

```
std::shared_ptr<B> d_factory()
{
    return std::make_unique<D>();
}
```

7573k exe, ~10% slower (very surprising when I found this bottleneck)

# Smaller Code Is Faster Code

*Prefer return `unique_ptr<>` from factories - A Note About Performance*

```
template<int T> std::shared_ptr<B> d_factory()  
{  
    return std::make_shared<D<T>>();  
}
```

- This `make_shared` version is faster in raw performance
- If you create many short-lived shared objects, the `make_shared` version is fastest
- If you create long-lived shared objects, use the `make_unique` version is fastest
- C++ Core Guidelines are surprisingly inconsistent in examples for factories

# Smaller Code Is Faster Code

```
std::string add(const std::string &lhs, const std::string &rhs) {  
    return lhs + rhs;  
}  
  
int main() {  
    const std::function<std::string (const std::string &)> f  
        = std::bind(add, "Hello ", std::placeholders::_1);  
    f("World");  
}
```



# Smaller Code Is Faster Code

*Avoid `std::function<>`*

```
std::string add(const std::string &lhs, const std::string &rhs) {  
    return lhs + rhs;  
}  
  
int main() {  
    const std::function<std::string (const std::string &)> f  
        = std::bind(add, "Hello ", std::placeholders::_1);  
    f("World");  
}
```

- 2.9x slower than bare function call
- 30% compile time overhead
- ~10% compile size overhead

# Smaller Code Is Faster Code

*Never. Ever. Ever. Use `std::bind`*

```
std::string add(const std::string &lhs, const std::string &rhs) {  
    return lhs + rhs;  
}  
  
int main() {  
    const auto f = std::bind(add, "Hello ", std::placeholders::_1);  
    f("World");  
}
```

- 1.9x slower than bare function call
- ~15% compile time overhead
- Effective Modern C++ #34
- Any talk on `std::function` from STL

# Smaller Code Is Faster Code

## *Use Lambdas*

```
std::string add(const std::string &lhs, const std::string &rhs) {  
    return lhs + rhs;  
}  
  
int main() {  
    const auto f = [](const std::string &b) {  
        return add("Hello ", b);  
    };  
    f("World");  
}
```

- 0 overhead compared to direct function call
- 0% compile time overhead

# Smaller Code Is Faster Code - Exceptions

```
size_t mycount(const std::vector<uint8_t> &s, uint8_t c)
{
    return std::count(std::begin(s), std::end(s), c);
}
```

# Smaller Code Is Faster Code - Exceptions

g++ pre 5.0

```
mycount(std::vector<unsigned char, std::allocator<unsigned char> > const&, unsigned ch
    mov     r8, QWORD PTR [rdi+8]
    mov     rdx, QWORD PTR [rdi]
    xor     eax, eax
    cmp     rdx, r8
    je      .L4
.L3:
    cmp     BYTE PTR [rdx], sil
    lea     rcx, [rax+1]
    cmov     rax, rcx
    add     rdx, 1
    cmp     rdx, r8
    jne     .L3
    rep ret
.L4:
    rep ret
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
mycount(std::vector<unsigned char, std::allocator<unsigned char> > const&, unsigned ch
    push    rbp
    push    rbx
    mov     r9, QWORD PTR [rdi+8]
    mov     rbx, QWORD PTR [rdi]
    cmp     r9, rbx
    je      .L13
    mov     r8, rbx
    mov     r11, r9
    lea     rbp, [rbx+1]
    neg     r8
    sub     r11, rbx
    and     r8d, 15
    cmp     r8, r11
    cmova   r8, r11
    cmp     r11, 19
    cmovbe  r8, r11
    test    r8, r8
    je      .L14
    lea     rcx, [rbx+r8]
    mov     r10d, esi
    mov     rdx, rbx
    xor     eax, eax
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
xor     edi, edi
cmp     r10b, BYTE PTR [rdx]
sete    dil
add     rdx, 1
add     rax, rdi
cmp     rdx, rcx
jne     .L5
cmp     r11, r8
je      .L2
.L4:
sub     r11, r8
mov     rdi, r9
lea     rdx, [r11-16]
sub     rdi, rbp
sub     rdi, r8
shr     rdx, 4
add     rdx, 1
mov     r10, rdx
sal     r10, 4
cmp     rdi, 14
jbe     .L7
mov     DWORD PTR [rsp-12], esi
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
pxor    xmm4, xmm4
movd    xmm0, DWORD PTR [rsp-12]
pxor    xmm9, xmm9
pxor    xmm8, xmm8
add     r8, rbx
punpcklbw    xmm0, xmm0
xor     edi, edi
pxor    xmm7, xmm7
movdqa  xmm10, XMMWORD PTR .LC0[rip]
punpcklwd    xmm0, xmm0
pshufd  xmm0, xmm0, 0
movdqa  xmm3, xmm0
```



# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
movdqa    xmm2, XMMWORD PTR [r8]
movdqa    xmm0, xmm9
add       rdi, 1
add       r8, 16
pcmpeqb   xmm2, xmm3
cmp       rdx, rdi
pand      xmm2, xmm10
pcmpgtb   xmm0, xmm2
movdqa    xmm1, xmm2
punpcklbw        xmm1, xmm0
punpckhbw        xmm2, xmm0
movdqa    xmm0, xmm8
movdqa    xmm6, xmm1
pcmpgtw   xmm0, xmm1
movdqa    xmm5, xmm2
movdqa    xmm11, xmm2
punpckhwd        xmm1, xmm0
punpcklwd        xmm6, xmm0
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
movdqa    xmm0, xmm8
pcmpgtw    xmm0, xmm2
movdqa    xmm2, xmm7
punpckhwd          xmm5, xmm0
pcmpgtd    xmm2, xmm6
punpcklwd          xmm11, xmm0
movdqa    xmm0, xmm5
movdqa    xmm5, xmm6
punpckhdq          xmm6, xmm2
punpckldq          xmm5, xmm2
movdqa    xmm2, xmm7
paddq      xmm4, xmm5
pcmpgtd    xmm2, xmm1
movdqa    xmm5, xmm1
paddq      xmm6, xmm4
movdqa    xmm4, xmm11
punpckldq          xmm5, xmm2
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
paddq    xmm5, xmm6
movdqa   xmm6, xmm1
movdqa   xmm1, xmm11
punpckhdq    xmm6, xmm2
movdqa   xmm2, xmm7
pcmpgtd  xmm2, xmm11
paddq    xmm5, xmm6
punpckhdq    xmm4, xmm2
punpckldq    xmm1, xmm2
movdqa   xmm2, xmm7
pcmpgtd  xmm2, xmm0
paddq    xmm1, xmm5
paddq    xmm1, xmm4
movdqa   xmm4, xmm0
punpckhdq    xmm0, xmm2
punpckldq    xmm4, xmm2
paddq    xmm4, xmm1
paddq    xmm4, xmm0
ja       .L8
movdqa   xmm0, xmm4
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
    add    rcx, r10
    psrldq xmm0, 8
    paddq  xmm4, xmm0
    movq   rdx, xmm4
    add    rax, rdx
    cmp    r11, r10
    je     .L2
.L7:
    xor     edx, edx
    cmp     sil, BYTE PTR [rcx]
    sete   dl
    add    rax, rdx
    lea    rdx, [rcx+1]
    cmp    r9, rdx
    je     .L2
    xor     edx, edx
    cmp     sil, BYTE PTR [rcx+1]
    sete   dl
    add    rax, rdx
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
lea    rdx, [rcx+2]
cmp    r9, rdx
je     .L2
xor    edx, edx
cmp    sil, BYTE PTR [rcx+2]
sete   dl
add    rax, rdx
lea    rdx, [rcx+3]
cmp    r9, rdx
je     .L2
xor    edx, edx
cmp    sil, BYTE PTR [rcx+3]
sete   dl
add    rax, rdx
lea    rdx, [rcx+4]
cmp    r9, rdx
je     .L2
xor    edx, edx
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
cmp     sil, BYTE PTR [rcx+4]
sete    dl
add     rax, rdx
lea     rdx, [rcx+5]
cmp     r9, rdx
je      .L2
xor     edx, edx
cmp     sil, BYTE PTR [rcx+5]
sete    dl
add     rax, rdx
lea     rdx, [rcx+6]
cmp     r9, rdx
je      .L2
xor     edx, edx
cmp     sil, BYTE PTR [rcx+6]
sete    dl
add     rax, rdx
lea     rdx, [rcx+7]
cmp     r9, rdx
je      .L2
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
xor     edx, edx
cmp     sil, BYTE PTR [rcx+7]
sete    dl
add     rax, rdx
lea     rdx, [rcx+8]
cmp     r9, rdx
je      .L2
xor     edx, edx
cmp     sil, BYTE PTR [rcx+8]
sete    dl
add     rax, rdx
lea     rdx, [rcx+9]
cmp     r9, rdx
je      .L2
xor     edx, edx
cmp     sil, BYTE PTR [rcx+9]
sete    dl
add     rax, rdx
lea     rdx, [rcx+10]
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
cmp    r9, rdx
je     .L2
xor     edx, edx
cmp     sil, BYTE PTR [rcx+10]
sete    dl
add     rax, rdx
lea     rdx, [rcx+11]
cmp     r9, rdx
je     .L2
xor     edx, edx
cmp     sil, BYTE PTR [rcx+11]
sete    dl
add     rax, rdx
lea     rdx, [rcx+12]
cmp     r9, rdx
je     .L2
xor     edx, edx
cmp     sil, BYTE PTR [rcx+12]
sete    dl
add     rax, rdx
lea     rdx, [rcx+13]
```



# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
    cmp     r9, rdx
    je      .L2
    xor     edx, edx
    cmp     sil, BYTE PTR [rcx+13]
    sete    dl
    add     rax, rdx
    lea     rdx, [rcx+14]
    cmp     r9, rdx
    je      .L2
    xor     edx, edx
    cmp     sil, BYTE PTR [rcx+14]
    sete    dl
    add     rax, rdx
.L2:
    pop     rbx
    pop     rbp
    ret
.L14:
    mov     rcx, rbx
    xor     eax, eax
    jmp     .L4
```

# Smaller Code Is Faster Code - Exceptions

g++ 5.1

```
.L13:
    xor     eax, eax
    jmp     .L2
.LC0:
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
    .byte   1
```

# Smaller Code Is Faster Code - Exceptions

- The compiler has unrolled and vectorized the loop for us
- So, you may see smaller/simpler code actually cause an increase in compile size
- Is this necessarily a good thing all the time?

# Part 2: Smaller Code Is Faster Code - Summary

- Don't repeat yourself in templates
- Avoid use of `shared_ptr`
- Avoid `std::function`
- Never use `std::bind`

# Part 2: Smaller Code Is Faster Code - Questions

# When I Break The Rules

# When I Break The Rules

`std::map`

- For very small, short lived key value pairs, `std::vector` can be faster
- Even if you are doing lots of querying of the keys

```
std::vector<std::pair<std::string, int>> data;
```

VS

```
std::map<std::string, int> data;
```

- This is similar to the `boost::flat_map`

# When I Break The Rules

## Factories

I take the factory issues one step further to avoid template instantiations, to make smaller code and have taken this:

```
std::unique_ptr<B> d_factory()  
{  
    return std::make_unique<D>();  
}
```

```
std::shared_ptr<Base> factory()  
{  
    return std::shared_ptr<Base>(static_cast<Base*>(new Derived<T>()));  
}
```

This prevents `std::shared_ptr<Derived>` or any part of it from ever being instantiated  
2% smaller executable size, 3% better runtime



# Bonus Slide - Avoid Non-Local Data

## Non-Locals Tend To

1. Be statics - which have a cost associated
2. Need some kind of mutex protection
3. Be in a container with on-trivial lookup costs (`std::map<>` for example)

# Summary

- First ask yourself: What am I asking the compiler to do here?

## Initialization Practices

- Always const
- Always initialize

## Hidden Work Practices

- Calculate values once - at initialization time
- Obey the rule of 0
- If it looks simpler, it's probably faster
- Avoid automatic conversions - use `explicit`
- avoid `std::endl`

# Summary (Continued)

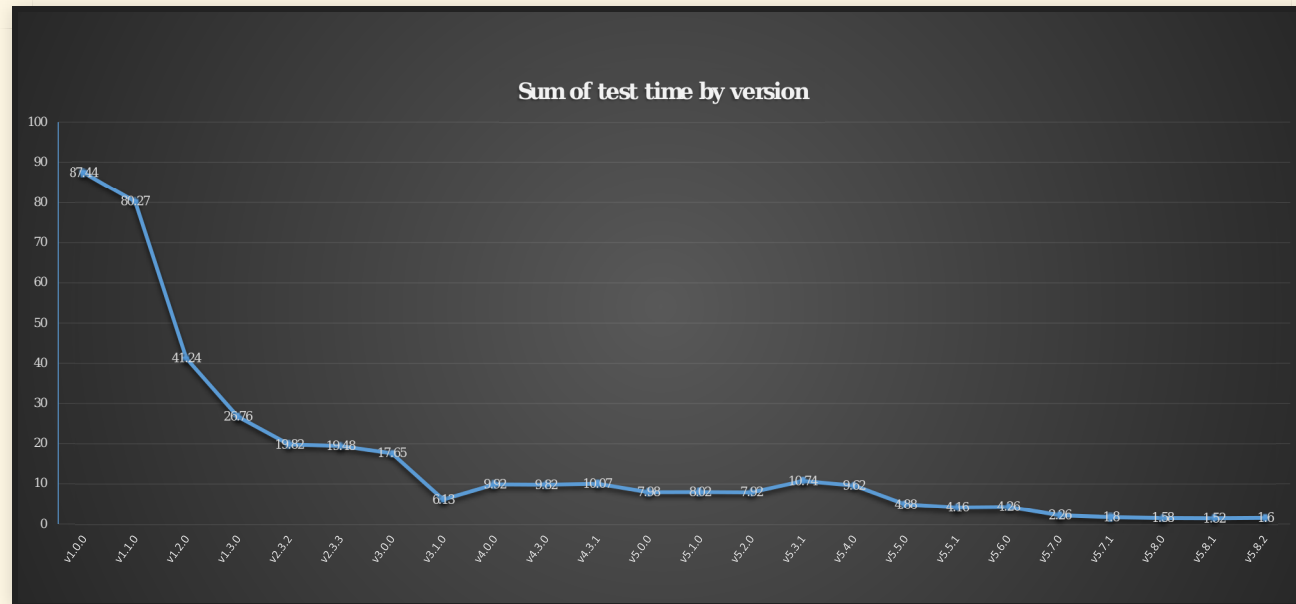
## Container Practices

- Always prefer `std::array`
- Then `std::vector`
- Then only differ if you need specific behavior
- Make sure you understand what the library has to do

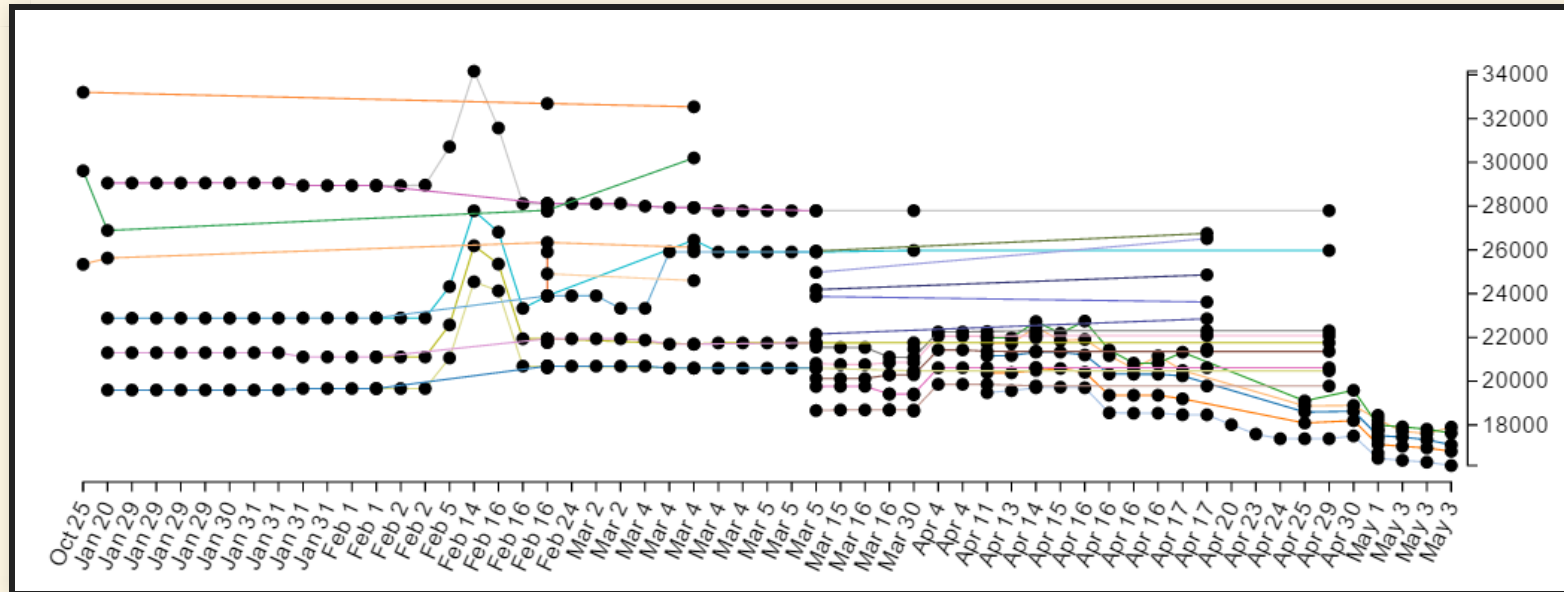
## Smaller Code Is Faster Code Practices

- Don't repeat yourself in templates
- Avoid use of `std::shared_ptr`
- Avoid `std::function`
- Never use `std::bind`

# Performance History



# Performance Monitoring



# What About constexpr?

# What About constexpr?

```
template<typename Itr>
constexpr bool is_sorted(Itr begin, const Itr &end)
{
    Itr start = begin;
    ++begin;
    while (begin != end) {
        if (!(*start < *begin)) { return false; }
        start = begin;
        ++begin;
    }
    return true;
}

template<typename T>
constexpr bool is_sorted(const std::initializer_list<T> &l) {
    return is_sorted(l.begin(), l.end());
}

int main()
{
    return is_sorted({1,2,3,4,5});
}
```

# What About constexpr?

```
main:                                     # @main
    mov     eax, 1
    ret
```



# What About *Not* constexpr?

```
template<typename Itr>
bool is_sorted(Itr begin, const Itr &end)
{
    Itr start = begin;
    ++begin;
    while (begin != end) {
        if (!(*start < *begin)) { return false; }
        start = begin;
        ++begin;
    }
    return true;
}

template<typename T>
bool is_sorted(const std::initializer_list<T> &l) {
    return is_sorted(l.begin(), l.end());
}

int main()
{
    return is_sorted({1,2,3,4,5});
}
```

- What does this compile to?

# What About *Not* constexpr? (with optimizations enabled)

```
main:                                # @main
    mov     eax, 1
    ret
```

# constexpr

- I use `constexpr` with care
- Full `constexpr` enabling of every data structure that can be can result in bigger code
- Bigger code is often slower code
- This is a profile and test scenario for me

# So Why Does This All Work?

# So Why Does This All Work?

## Branches and Predictions

- Code branches are expensive
- Simpler code has fewer branches
- (According to oprofile) ChaiScript v5.8.3 has 1.86x fewer branches than v5.1.0, and 3x the branch prediction success rate

# So Why Does This All Work?

## Cache Hits

- CPU cache is many (hundreds of) times faster than main memory
- Smaller code (and simpler code is smaller) is more likely to fit in to the CPU cache
- (According to oprofile) ChaiScript v5.8.3 hits the Last Level Cache 35x less often than v5.1.0, and has 1% better cache hits rates when it does

# So Why Does This All Work?

## Doing What The Compiler Author Expects

- Idiomatic C++ falls into certain patterns that compiler authors expect to find
- Well known patterns can be optimized better

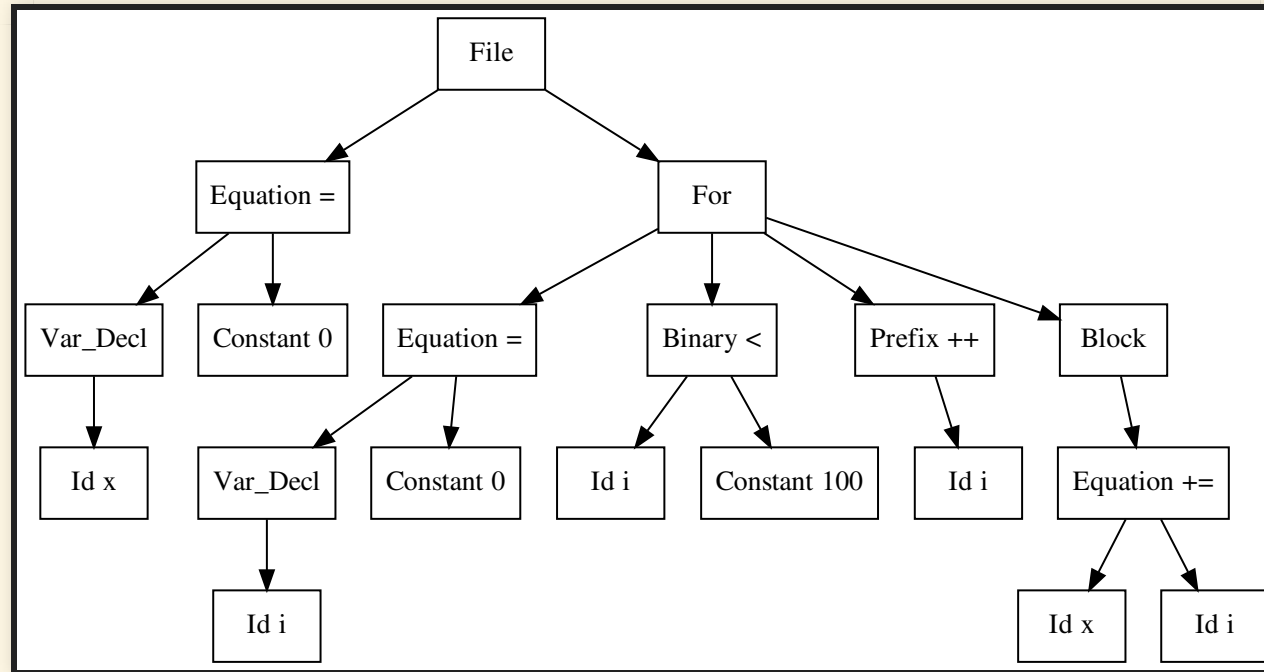
# What's Next?



# What's Next?

## Simplifying User Input - Before

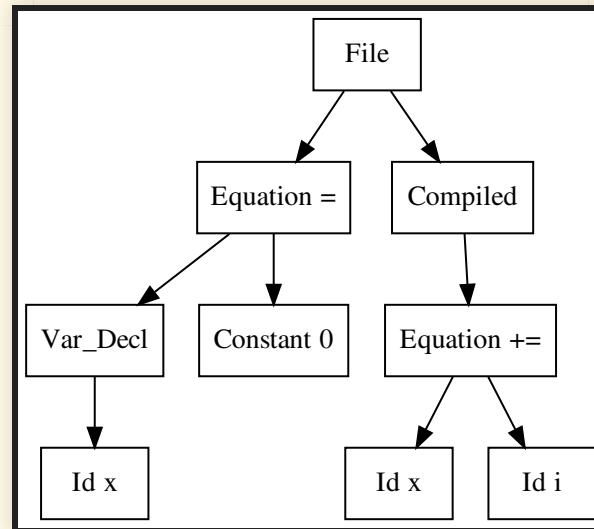
```
var x = 0;  
for (var i = 0; i < 100; ++i) {  
    x += i;  
}
```



# What's Next?

## Simplifying User Input - After

```
var x = 0;  
for (var i = 0; i < 100; ++i) {  
    x += i;  
}
```



# What's Next?

## Simplifying User Input

Nearly every project of significance relies on user input.

Are there ways you can simplify your user input to make the execution of your program faster?

# Questions?

Jason Turner

- <http://github.com/lefticus/presentations>
- <http://cppcast.com>
- <http://chaiscript.com>
- <http://cppbestpractices.com>
- C++ Weekly - YouTube
- @lefticus
- Independent Contractor