### pySpark pictures

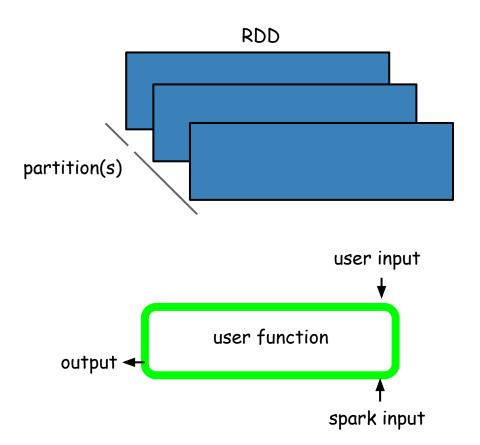
## legend

**RDD** Elements

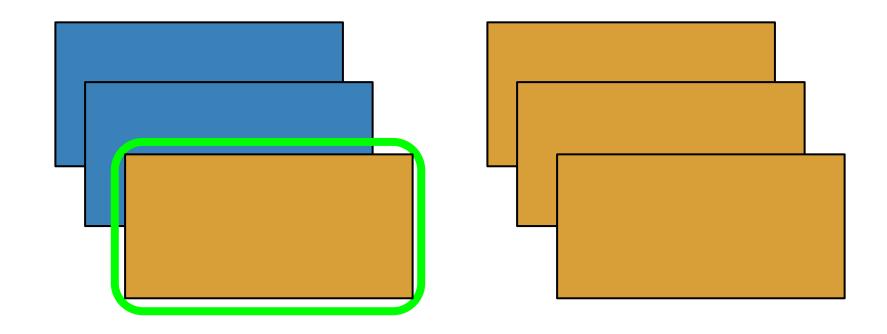
key original

transformed value

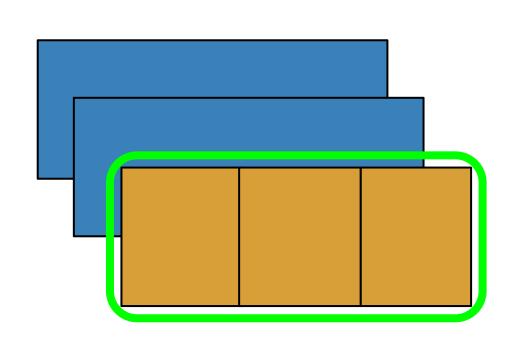
transformed type

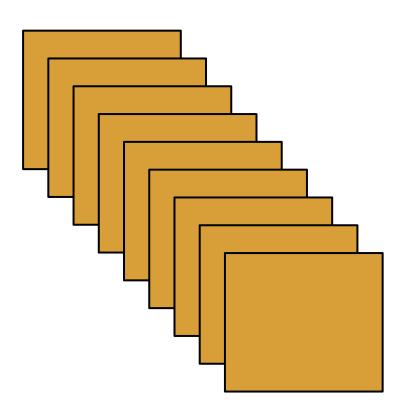


### map

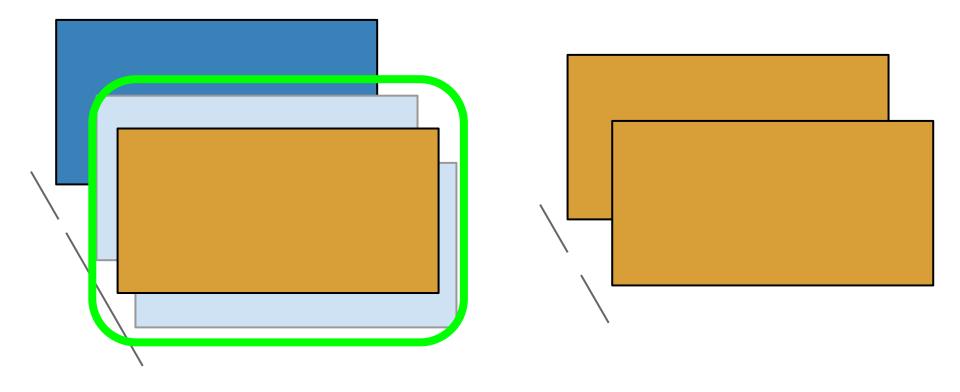


## flatMap

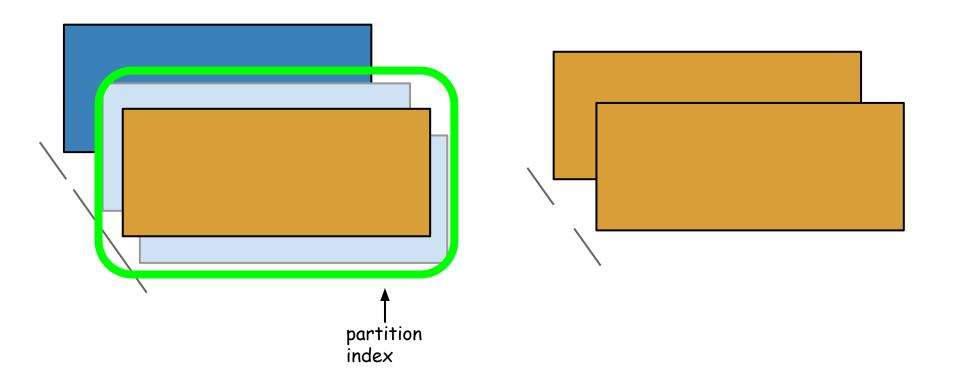




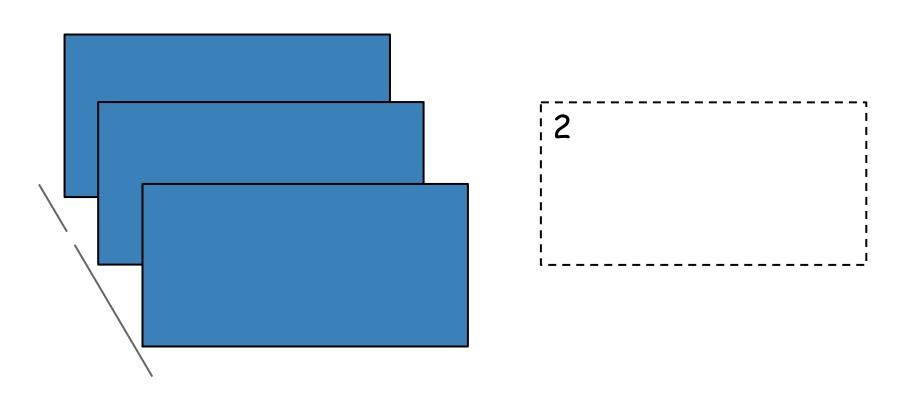
### mapPartitions



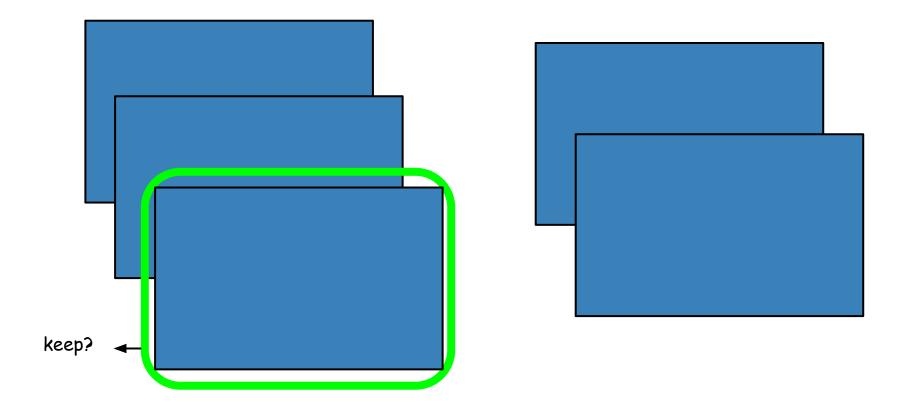
### mapPartitionsWithIndex



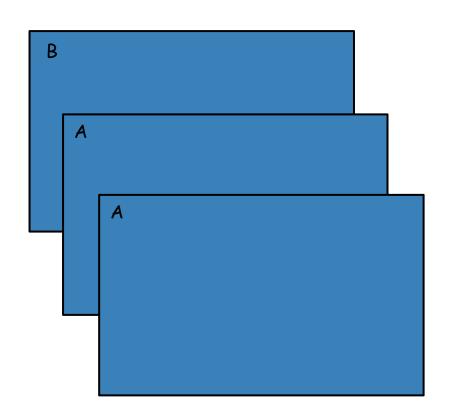
## getNumPartitions

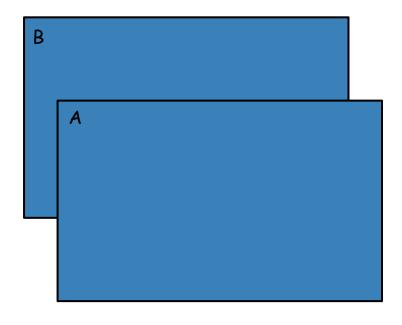


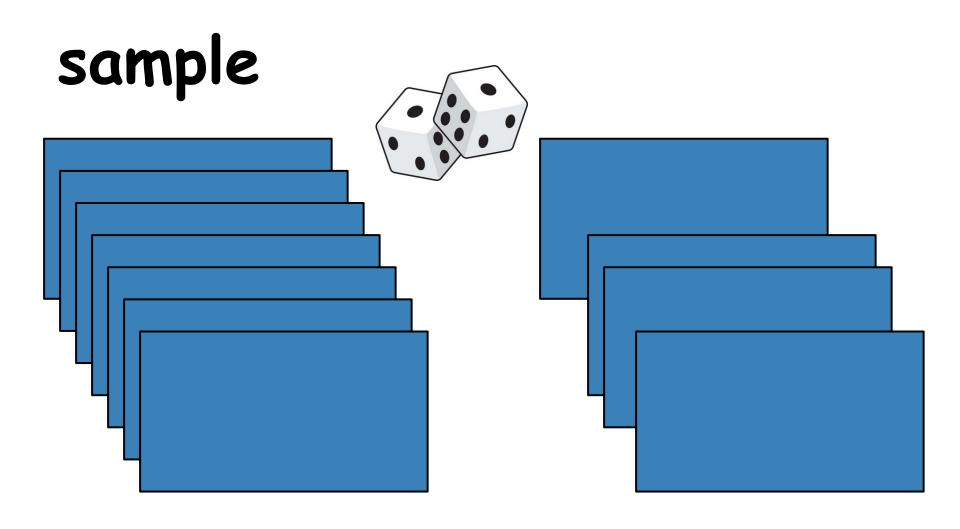
### filter



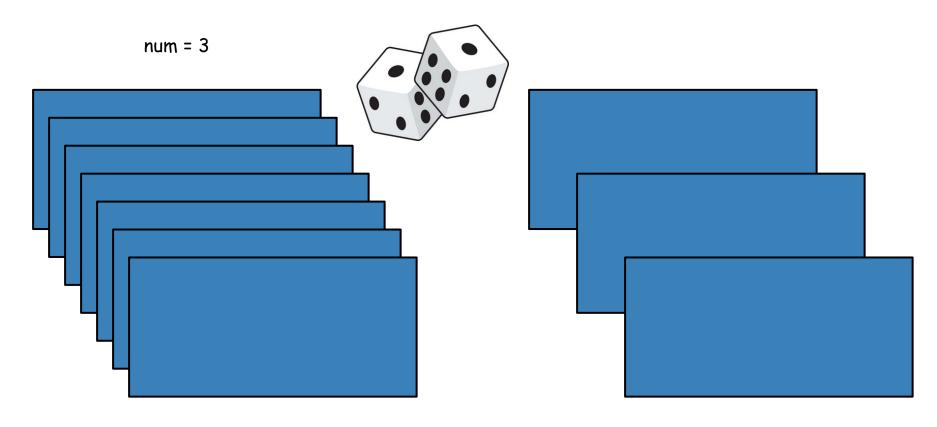
### distinct



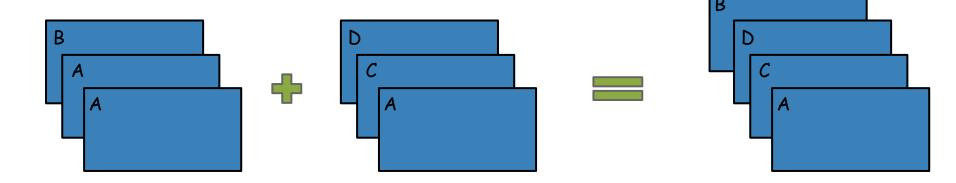




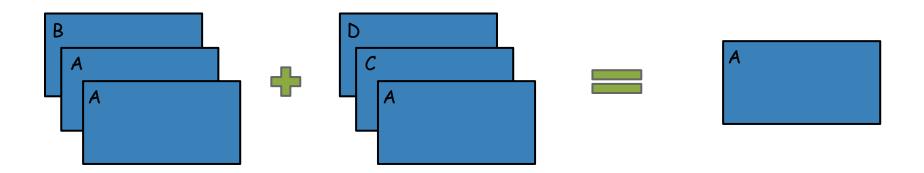
## takeSample



# union (+)

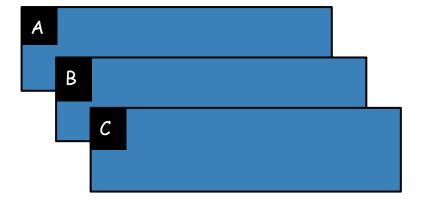


#### intersection

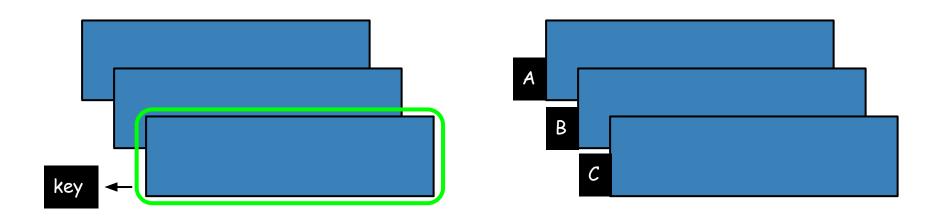


## sortByKey

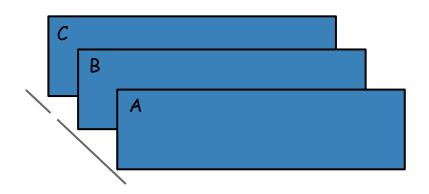


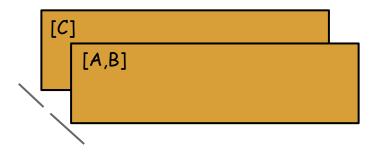


# sortBy

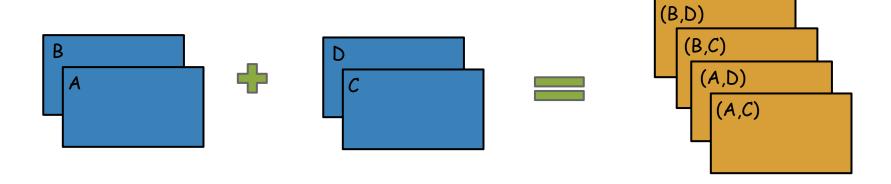


# glom

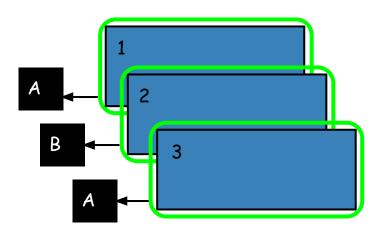




### cartesian

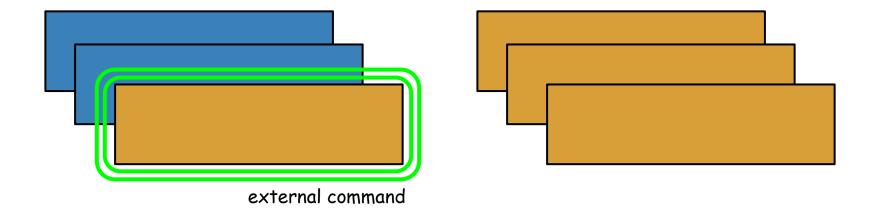


## groupBy

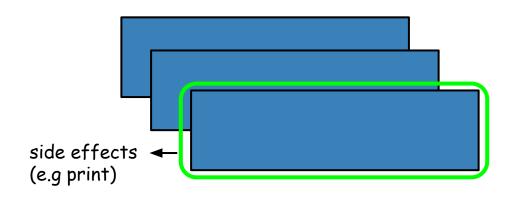




# pipe

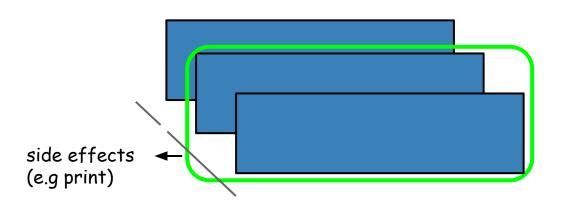


### foreach



\*no return value, original RDD unchanged

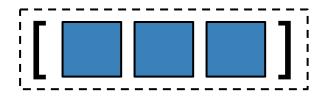
#### foreachPartition



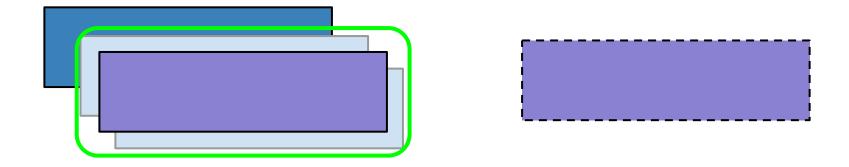
\*no return value, original RDD unchanged

### collect

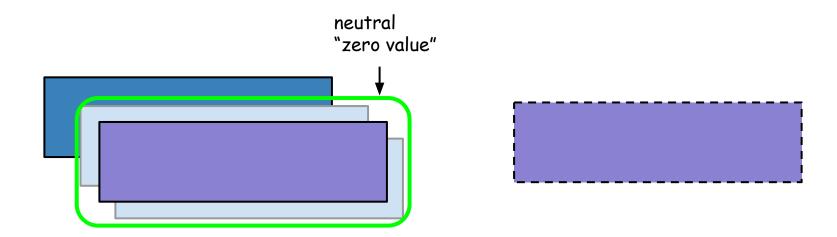




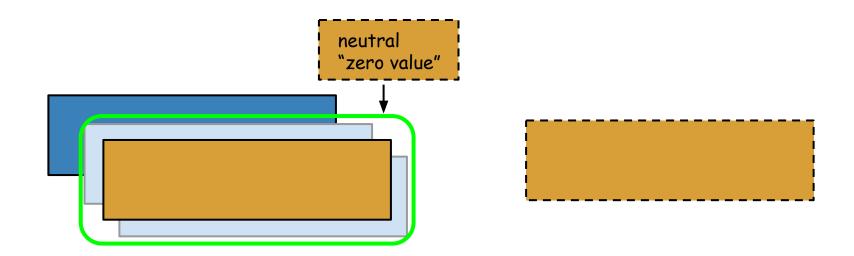
### reduce



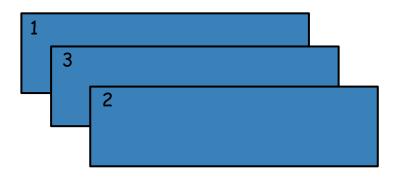
### fold



### aggregate

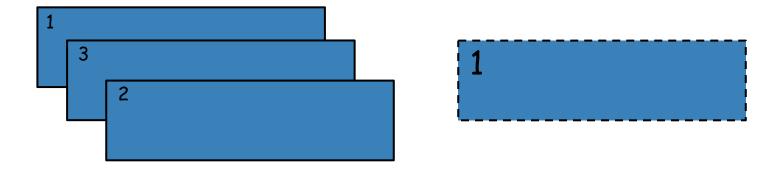


#### max





### min

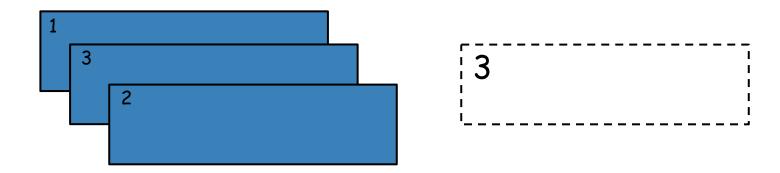


#### sum



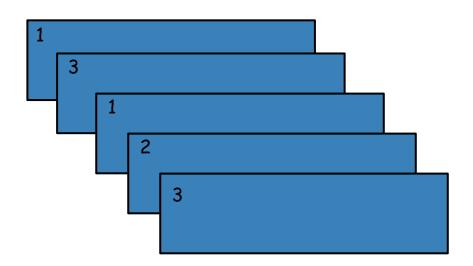


### count



## histogram

buckets = 2



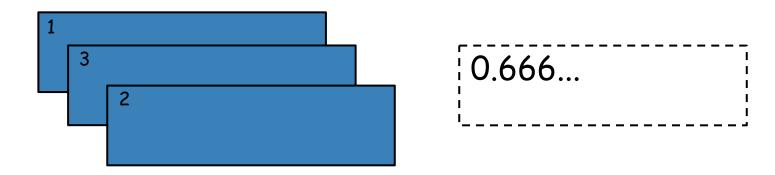
```
((1,2,3),[2,3])
```

#### mean

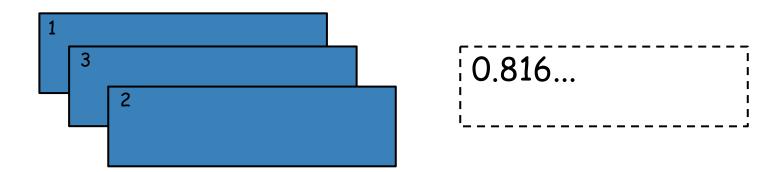




#### variance



### stdev



## sampleStdev



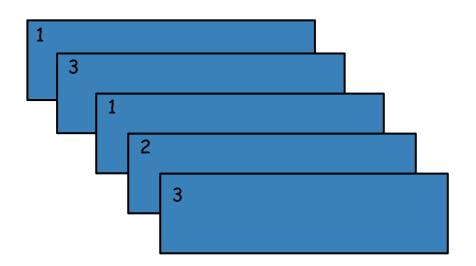
1.0

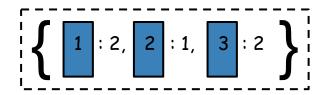
## sampleVariance



1.0

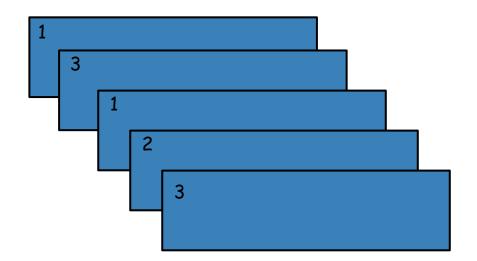
## countByValue

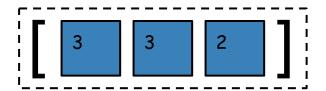




### top

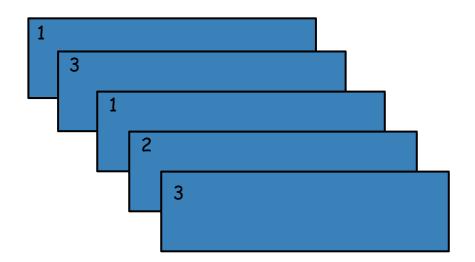
num = 3

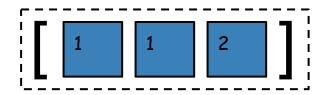




#### takeOrdered

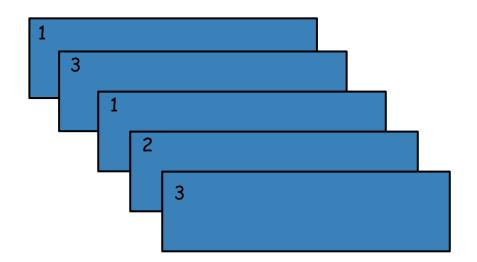
num = 3

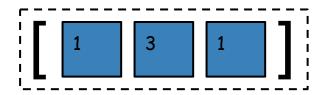




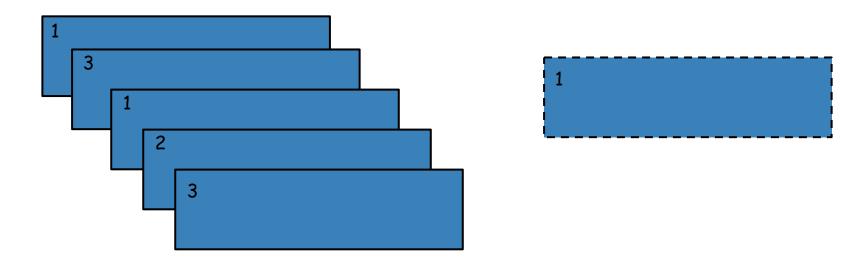
#### take

num = 3

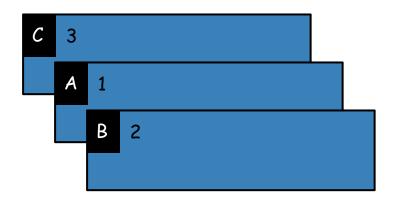


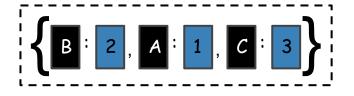


#### first

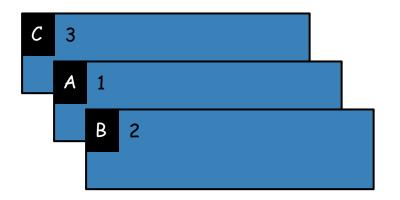


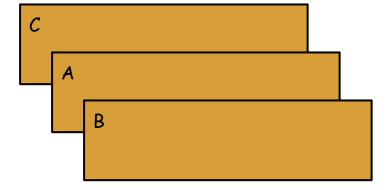
#### collectAsMap



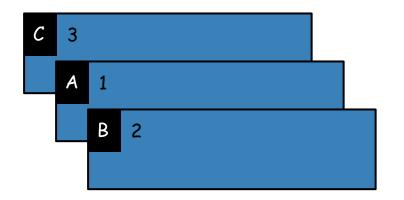


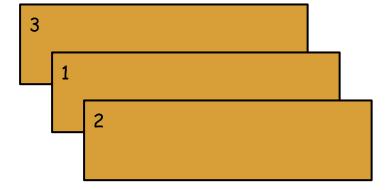
# keys



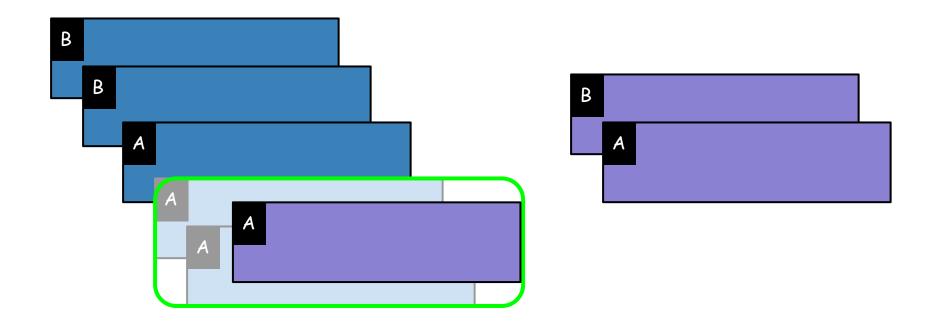


#### values

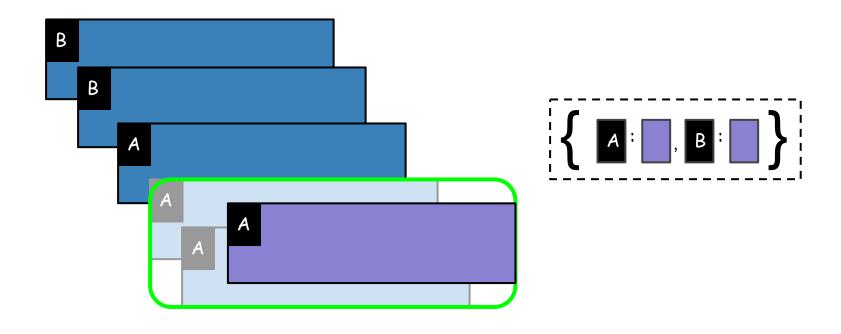




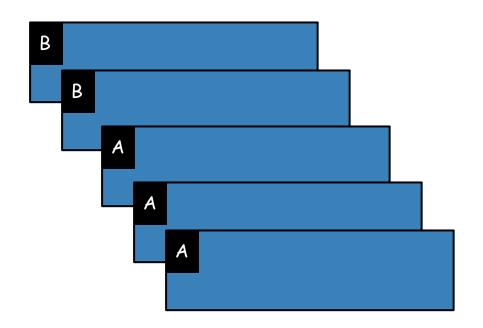
## reduceByKey

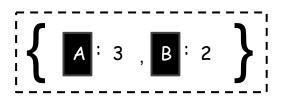


### reduceByKeyLocally

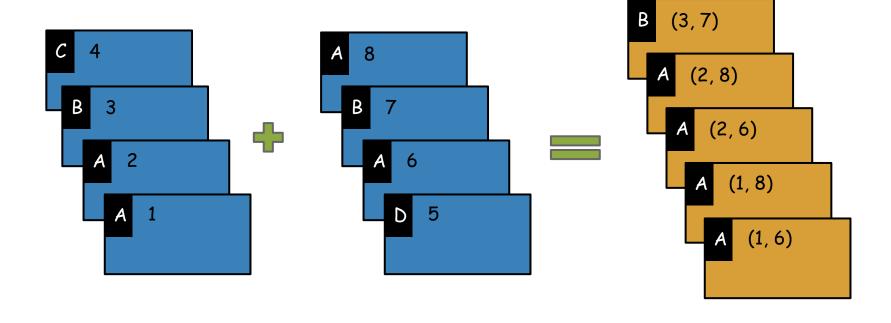


#### countByKey

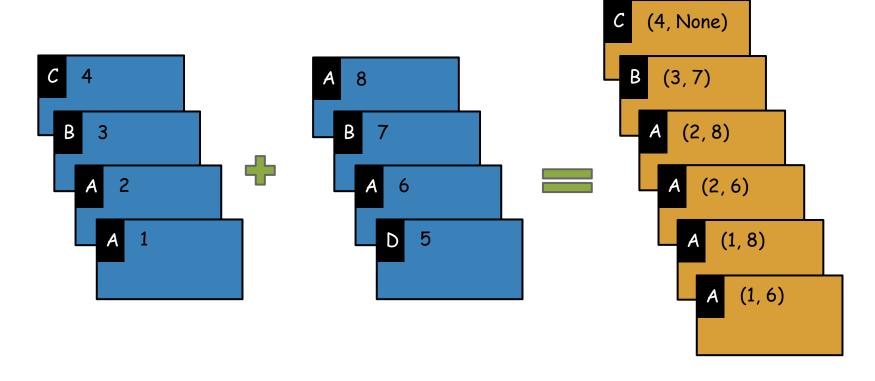




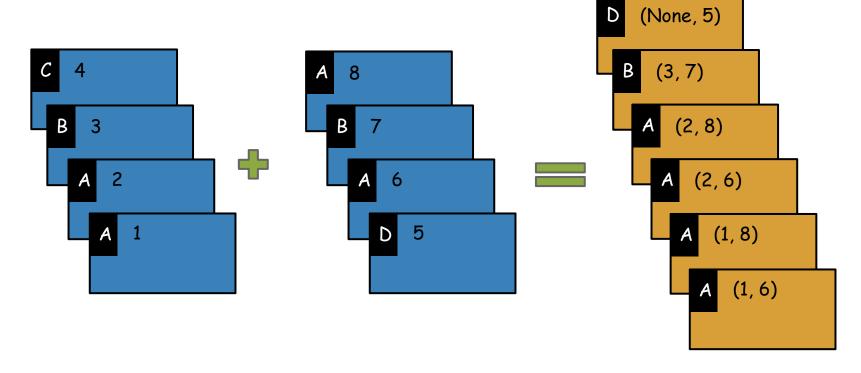
## join



#### leftOuterJoin

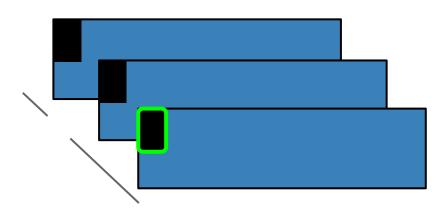


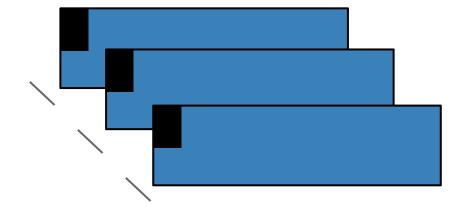
## rightOuterJoin



#### partitionBy

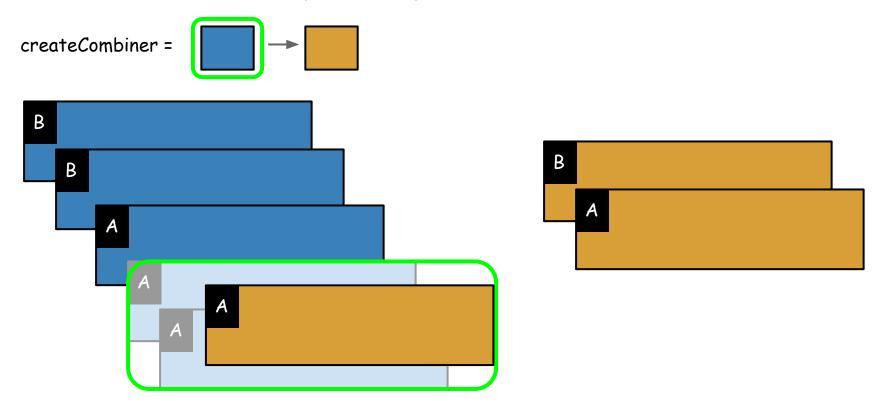
numPartitions = 3



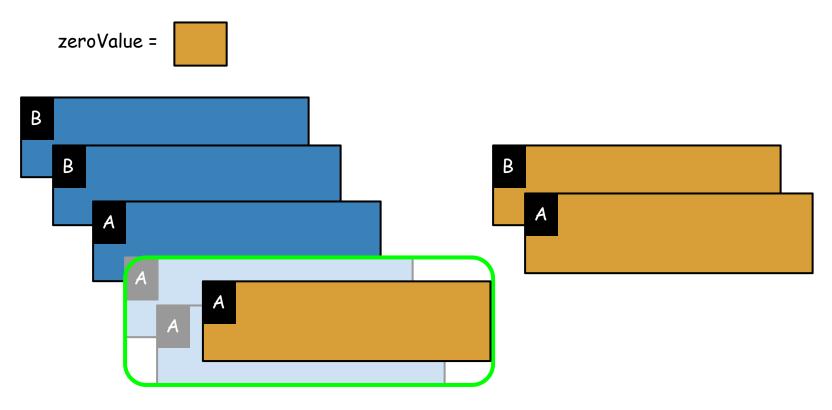


new partition ndex = f(key) % numPartitions

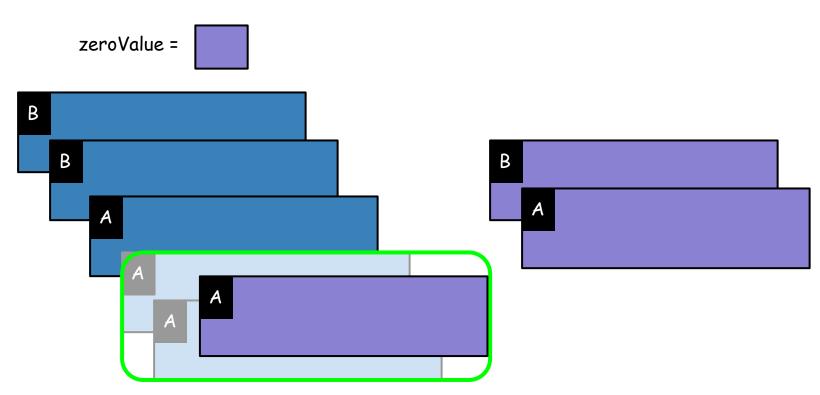
#### combineByKey



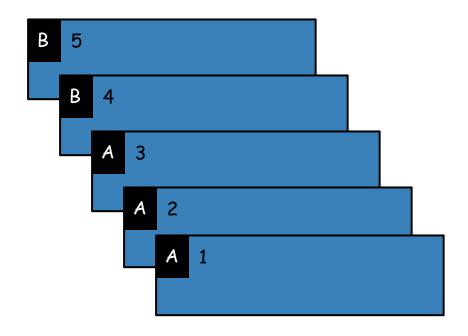
# aggregateByKey

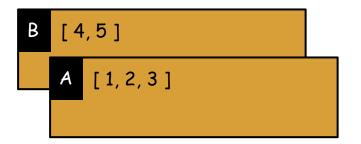


# foldByKey

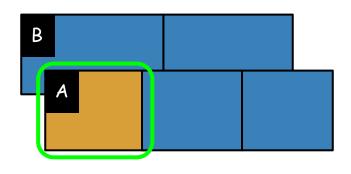


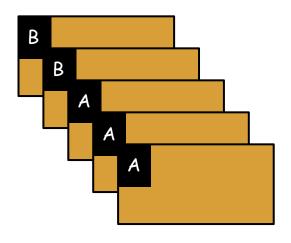
## groupByKey



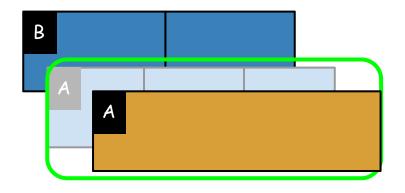


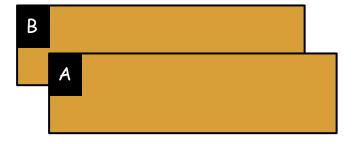
### flatMapValues



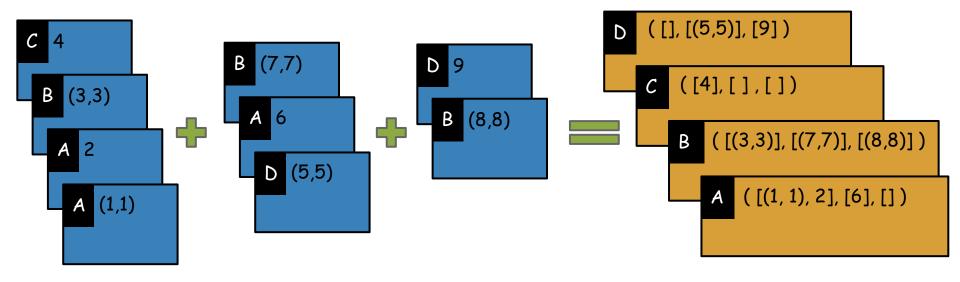


# mapValues

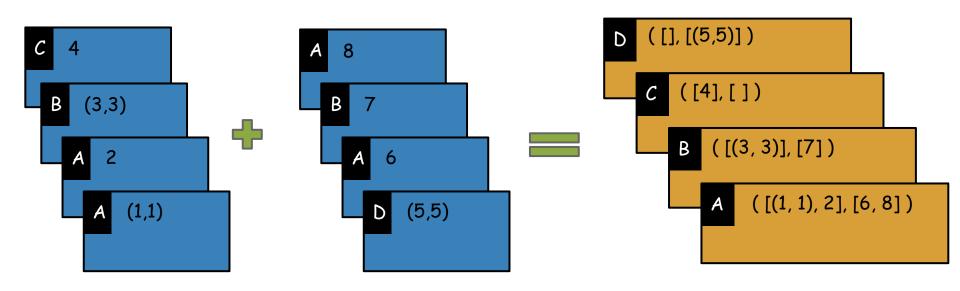




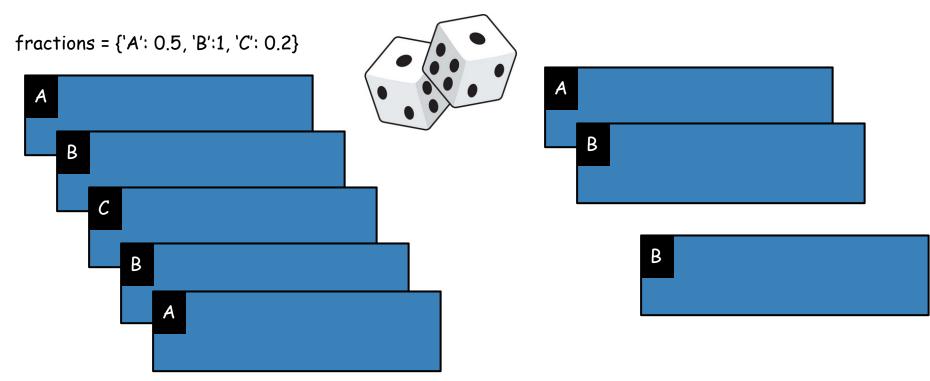
## groupWith



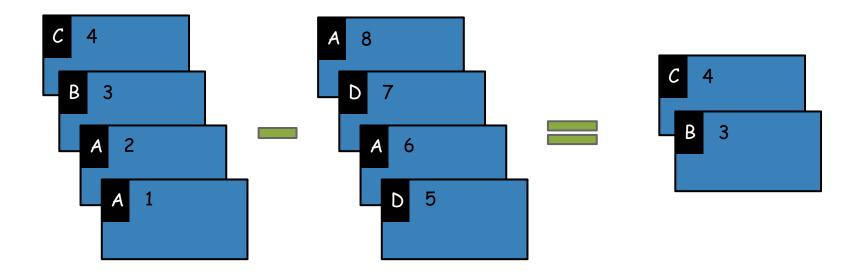
#### cogroup



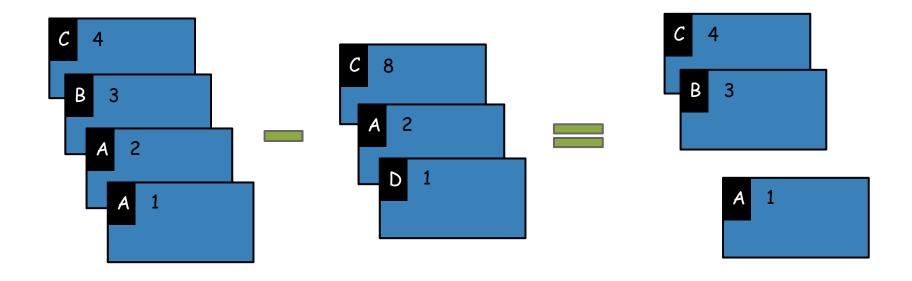
## sampleByKey



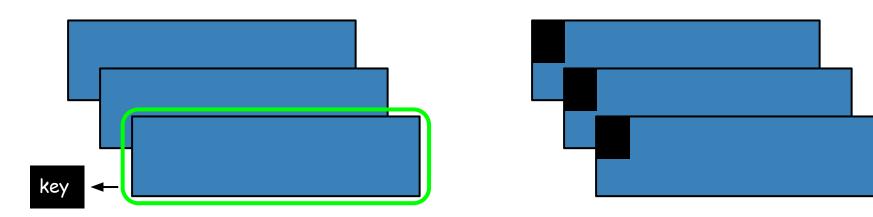
## subtractByKey



#### subtract

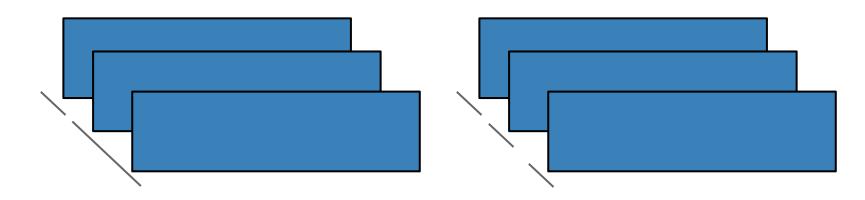


# keyBy



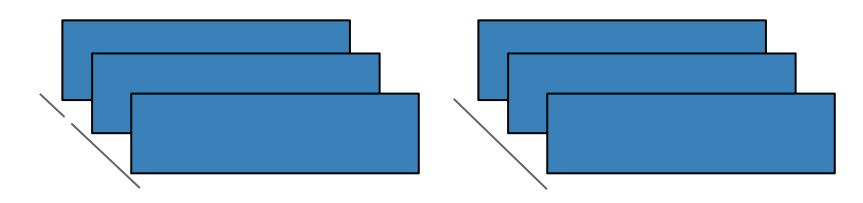
### repartition

numPartitions = 3

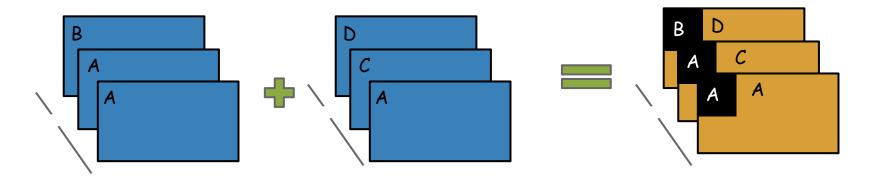


#### coalesce

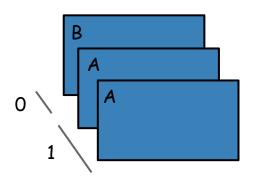
numPartitions = 1

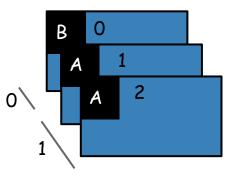


## zip

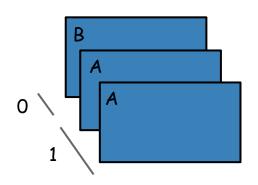


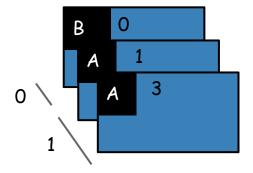
## zipWithIndex





#### zipWithUniqueId





uniqueId = element index \* #partitions + partition index