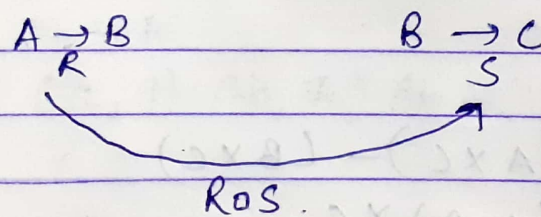


## COMPOSITION OF RELATION

If  $A, B, C$  are 3 non-empty sets and  $R$  &  $S$  the relations from  $A \xrightarrow{R} B$  and  $B \xrightarrow{S} C$  respectively, then we define ~~the~~ a relation from  $A \rightarrow C$ , denoted by  $R \circ S$



$R \circ S = \{ (x, z) : \text{there exist some } y \in B \text{ such that } (x, y) \in R \text{ and } (y, z) \in S \}$ .

↓  
Composition of

Note (a, b), (b, c)

if same

then (a, c)

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you have to write

## Q.1 Composition of Relation

let  $A = \{1, 2, 3\}$ ,  $B = \{P, Q, R\}$

$C = \{x, y, z\}$  and

relation  $R = \{(1, P), (1, Q), (2, Q), (3, R)\}$

relation  $S = \{(P, y), (Q, x), (R, z)\}$

then find  $R \circ S$

As we know  $R \circ S = \{(x, z)\}$

$(x, y) \in R$  &  $(y, z) \in S$

$(1, P) (P, y) \rightarrow$  So  $(1, y)$

Same

$(1, P) (Q, x)$  leave it

not same

$(1, P) (R, z)$  leave it hence

not same

we find only  $(1, y)$

Now we are trying by taking  $(1, Q)$

$(1, Q) (P, y)$  no

$(1, Q) (Q, x)$  no

$(1, Q) (R, z) (1, z)$

same

we find  $(1, z)$



Now we are trying  $(2, 2)$

$(2, 2) (1, y)$  no

$(2, 2) (2, x) (2, x)$   
same

$(2, 2) (1, z)$  no

So only  $(2, x)$  we have

Now last pair is  $(3, 2)$

$(3, 2) (1, y)$  no

$(3, 2) (2, x) (3, x)$   
same

$(3, 2), (1, z)$  no  
not

So in Composition of ROS we have

$$ROS = \{(1, y), (1, z); (2, x), (3, x)\}$$

Q.2 Find By Matrix method

Let  $A = \{3, 4, 5, 6\}$

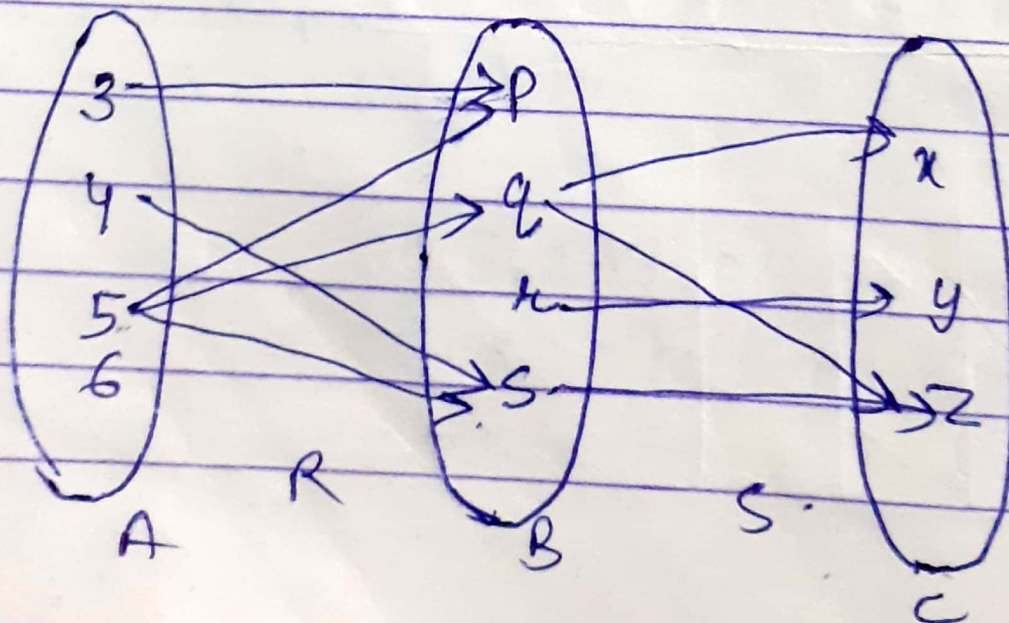
$B = \{p, q, r, s\}$

$C = \{x, y, z\}$

$R = \{(3, p), (4, s), (5, p), (5, q), (5, s)\}$

$S = \{(q, x), (q, z), (r, y), (s, z)\}$

$LoS = \{(4, z), (5, x), (5, z)\}$





## Matrix Method →

$$M_R = \begin{matrix} & \begin{matrix} p & q & r & s \end{matrix} \\ \begin{matrix} 3 \\ 4 \\ 5 \\ 6 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix} \quad 4 \times 4$$

$$M_S = \begin{matrix} & \begin{matrix} x & y & z \end{matrix} \\ \begin{matrix} p \\ q \\ r \\ s \end{matrix} & \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{matrix} \quad 4 \times 3$$

$$M_{ROS} = M_R \times M_S$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{matrix} & \begin{matrix} x & y & z \end{matrix} \\ \begin{matrix} 3 \\ 4 \\ 5 \\ 6 \end{matrix} & \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \end{matrix}$$

⇒ Related elements =  $\{(4, z) (5, x) (5, z)\}$

## Objective Problem

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Q. If  $R$  is a relation represented by

$$M_R = \begin{matrix} & \begin{matrix} x & y & z \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \end{matrix}$$

then find <sup>(i)</sup>  $M_R^c$  (Compliment)

(ii)  $M_R^{-1}$

(i) for Compliment replace 1 by 0  
& 0 by 1

$$\text{So } M_R^c = \begin{matrix} & \begin{matrix} x & y & z \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

(ii) To find  $M_R^{-1}$  we write transpose of  $M_R$

$$M_R^{-1} = \begin{matrix} & \begin{matrix} x & y & z \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \end{matrix}$$

$$\therefore R = \{ (1, x), (1, z), (2, x), (2, y), (3, z) \}$$