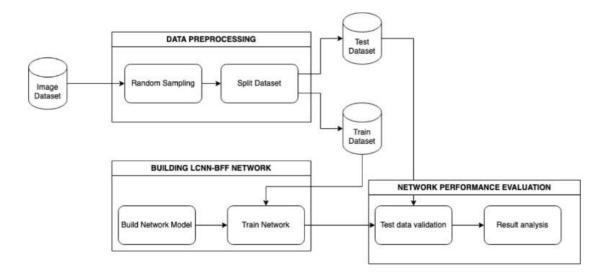
	_
CS6005	
DEEP LEARNING TECHNIQUES	
DELF LEARINING TECHNIQUES	
DDOLECT TITLE. Broads Footows Fooiss Composition Nationals for	
PROJECT TITLE: Branch Feature Fusion Convolution Network for	
Remote Sensing Scene Classification	
TEARA RATRADEDO	
TEAM MEMBERS:	
AJITESH M (2019103503)	
VISHNUPRIYA N (2019103599)	

ABSTRACT

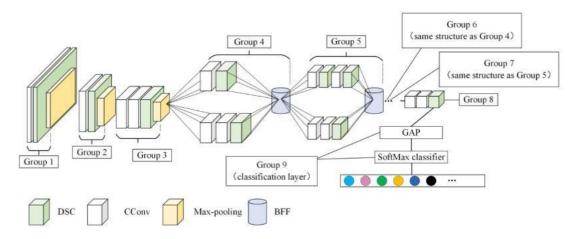
In the classification of remote sensing scenes, Convolutional Neural Networks (CNNs) have out-standing advantages. Deep CNN models with better classification performance typically have high complexity, whereas shallow CNN models with low complexity rarely achieve good classification performance for remote sensing images with complex spatial structures. A new lightweight CNN classification method based on branch feature fusion (LCNN-BFF) for remote sensing scene classification can be used for attaining these results. In contrast to a conventional single linear convolution structure, this model has a bilinear feature extraction structure. The BFF method is used to fuse the feature information extracted from the two branches, which improved the classification accuracy. In addition, combining depth wise separable convolution and conventional convolution to extract image features greatly reduced the complexity of the model on the premise of ensuring the accuracy of classification. We tested the method on four standard datasets. The experimental results showed that, compared with recent classification methods, the number of weight parameters of the proposed method only accounted for less than 5% of the other methods; however, the classification accuracy was equivalent to or even superior to certain high-performance classification methods.

NETWORK ARCHITECTURE

The following is the network architecture:



The following is the overall structure of the proposed LCNN-BFF method. DSC and conventional convolution (CConv).



The proposed LCNN-BFF network was composed of nine parts (Groups 1–9). According to the structure of the first three modules in the VGG16 network and the strategy of reducing model complexity introduced in this article, Groups 1–3 were defined.

- In Groups 1–3, the maximum pooling layer was used to down sample the remote sensing images, to reduce the spatial dimensions of the images, retain the main features of the images, and avoid the problem of overfitting.
- Groups 4–8 were mainly defined to extract representative features.
- Groups 4–7 used a bilinear convolution structure to extract more abundant feature information.

According to the bilinear convolution structure, the BFF method was proposed. BFF fuses the feature information extracted from the two branches to obtain more effective feature information.

Group 9 was defined for classification, to convert the extracted feature information into the probability of each scene class. In the feature extraction structure (Groups 1–8), lightweight convolution DSC and CConv were combined to extract image features, which greatly reduced the complexity of the model.

Batch normalization (BN) was used to normalize the output of each volume accumulation layer, and then the rectified linear unit function was used to activate the neurons. After BN processing, the learning speed of the model could be accelerated and converged quickly. To a certain extent, this can avoid the problem of the gradient disappearing with the deepening of the network, and improve the generalization ability of the model. In addition, due to the small number of images in the divided training set, this may cause the problem of overfitting in the process of network training.

Therefore, an L2 regularization penalty was added to the weight of the convolution layer, and the penalty coefficient was 0.0005.

In Group 9, the global average pooling (GAP) was used instead of the flatten layer, which can reduce the model size and overfitting.

DATASET SPLITING AND RANDOM SAMPLING

```
In [1]: 1 import os
           2 import random
            3 import shutil
           6 original_data_path = 'original_data/NWPU45/'
           7 data = os.listdir(original data path)
           8 image_path = {}
           9 for class_name in data:
                path_a = original_data_path + class_name + '/'
image_file = os.listdir(path_a)
                 x = []
for name in image file:
                    image_filepath = path_a + name
          15
                       x.append(image_filepath)
         train_data = random.sample(image, int(len(image)*train_percent))
          20
21
                   test_data = []
                 for i in image:
    if i not in train_data:
                           test data.append(i)
                for j in train_data:
          24
25
                 save_path_1 = 'data/train/' + j[14:]
save_path_2 = 'data/train/new_data/'
if not os.path.exists(save_path_1):
          26
27
                                                                + class_name + '/'
          28
29
30
31
                           os.makedirs(save_path_1)
                       shutil.copy(j, save_path_1)
                for k in test_data:
                  save_path_1 = 'data/test/' + k[14:]
save_path_2 = 'data/test/new_data/'
          32
33
                                                                + class_name + '/'
                     if not os.path.exists(save_path_1):
                            os.makedirs(save_path_1)
                 shutil.copy(k, save path 1)
```

To train and test our model, we split the data through random sampling for training and testing. Here we have used 0.8 training percent; the data is split in 80:20 ration i.e., 80% of the data will be used for training the model while 20% will be used for testing the model that is built out of it.

CHECKING AVAILABILITY OF GPU AND CUDA

GPUs can perform multiple, simultaneous computations. This enables the distribution of training processes and can significantly speed machine learning operations. We can accumulate many cores that use fewer resources without sacrificing efficiency or power.

CUDA is a toolkit that includes various libraries and components. These provide support for debugging and optimization, compiling, documentation, runtimes, signal processing, and parallel algorithms. CUDA Toolkit libraries support all NVIDIA GPUs.

We check the availability of GPU and CUDA with the following code:

```
In [1]:
    import sys
    import tensorflow.keras
    import numpy as np

    print(tf.__version__)
    print(sys.version)

    gpu = len(tf.config.list_physical_devices('GPU'))>0
    print("GPU is", "available" if gpu else "NOT AVAILABLE")

2    import tensorflow.keras
    __version__)
    print("GPU is", "available" if gpu else "NOT AVAILABLE")

2    import tensorflow.keras
    __version__)
    print("GPU is", "available" if gpu else "NOT AVAILABLE")

2    import tensorflow.keras
    __version__)
    print("GPU is", "available" if gpu else "NOT AVAILABLE")

2    import tensorflow.keras
    import tensor
```

IMPORTING REQUIRED PACKAGES

We import the following packages that are used later in the model from keras

```
In [2]:

1 from keras import backend as K, initializers, regularizers, constraints
from keras.backend import image_data_format
from keras.backend import _preprocess_conv2d_input, _preprocess_padding
from tensorflow.keras.layers import InputSpec
import tensorflow as tf
from keras.layers import Conv2D
from keras.layers import conv_utils

In [3]:

1 from keras.layers import Conv2D, DepthwiseConv2D, Dense, GlobalAveragePooling2D, MaxPooling2D, Input, BatchNormalization, \
add, Activation
from keras.regularizers import 12
from keras.models import Model

In [5]:

1 from keras.preprocessing.image import ImageDataGenerator
2 from keras.callbacks import ModelCheckpoint, ReduceLROnPlateau, TensorBoard, CSVLogger
from keras.optimizers import RMSprop, Adam, SGD
```

The following is the implementation of the model:

```
In [4]: 1 def LCNN_BFF(input_shape, num_classes):
                     input_0 = Input(shape=input_shape)
# Group 1 256*256
                     x = \text{Conv2D}(32, (3, 3), \text{ padding='same'}, \text{ strides=1, kernel\_regularizer=12(5e-4), use\_bias=False})(\text{input\_0})
x = \text{BatchNormalization}()(x)
                    x = Activation('relu')(x)
x = Conv2D(32, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
x = BatchNormalization()(x)
           10
                     x = MaxPooling2D(pool_size=(2, 2), strides=2, padding='same')(x)
           12
13
14
                    # Group 2 128*128
                    x = Activation('relu')(x)
           16
17
18
                    x = Conv2D(64, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
x = BatchNormalization()(x)
                     x = Activation('relu')(x)
           19
                    x = MaxPooling2D(pool_size=(2, 2), strides=2, padding='same')(x)
           20
21
                     x = Conv2D(128, (1, 1), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
                     x = BatchNormalization()(x)
x = Activation('relu')(x)
x = Conv2D(128, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
           24
                    x = Conv2D(120, (3, 3), padding= same , Strides=1, kernel_regularizer=12(5e-4), use_blas=False)(x)
x = BatchNormalization()(x)
x = Conv2D(128, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_blas=False)(x)
x = BatchNormalization()(x)
           26
27
           28
           30
                     x = Activation('relu')(x)
                     a = MaxPooling2D(pool_size=(2, 2), strides=2, padding='same')(x)
```

```
# Group 4 32*32
 33
34
          x = Conv2D(128, (1, 1), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(a)
          x = BatchNormalization()(x)
          36
  38
         q = BatchNormalization()(x)
  39
  40
         x = Conv2D(128, (1, 1), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(a)
x = BatchNormalization()(x)
 41
         x = Activation('relu')(x)
x = Conv2D(128, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
x = BatchNormalization()(x)
 43
 44
  45
         x = Activation('relu')(x)'

x = Conv2D(128, (3, 3), padding='same', strides=2, kernel_regularizer=12(5e-4), use_bias=False)(x)
 46
 48
         w = BatchNormalization()(x)
  49
          x = add([q, w])
          e = Activation('relu')(x)
          # Group 5 16*16
          x = \text{Conv2D}(256, (1, 1), \text{padding='same'}, \text{strides=1}, \text{kernel\_regularizer=12}(5e-4), \text{use\_bias=False})(e)
x = \text{BatchNormalization}()(x)
  54
          x = Activation('relu')(x)
x = Conv2D(256, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
x = BatchNormalization()(x)
         x = Activation('relu')(x)
x = Conv2D(256, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
 60
  61
          x = BatchNormalization()(x)
         62
 64
          r = BatchNormalization()(x)
 65
66
        x = Conv2D(256, (1, 1), padding='same', strides=1, kernel\_regularizer=12(5e-4), use\_bias=False)(e)
67
        x = BatchNormalization()(x)
68
       x = Activation('relu')(x)
x = Conv2D(256, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
69
70
        x = BatchNormalization()(x)
71
72
       x = Activation('relu')(x)
x = Conv2D(256, (3, 3), padding='same', strides=2, kernel_regularizer=12(5e-4), use_bias=False)(x)
73
74
75
       t = BatchNormalization()(x)
       x = add([r, t])
76
77
78
        e = Activation('relu')(x)
       # Group 6 8*8
79
80
       x = Conv2D(256, (1, 1), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(e)
       x = BatchNormalization()(x)
81
       x = Activation('relu')(x)
82
       x = Conv2D(256, (3, 3), padding='same', strides=2, kernel\_regularizer=12(5e-4), use\_bias=False)(x)
83
       q = BatchNormalization()(x)
84
85
       x = Conv2D(256, (1, 1), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(e)
86
       x = BatchNormalization()(x)
87
       x = Activation('relu')(x)
88
       x = Conv2D(256, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
89
       x = BatchNormalization()(x)
       x = Activation('relu')(x)
x = Conv2D(256, (3, 3), padding='same', strides=2, kernel_regularizer=12(5e-4), use_bias=False)(x)
90
91
92
       w = BatchNormalization()(x)
93
94
        x = add([a, w])
95
        e = Activation('relu')(x)
96
```

```
97
           x = Conv2D(256, (1, 1), padding='same', strides=1, kernel\_regularizer=12(5e-4), use\_bias=False)(e) 
 98
          x = BatchNormalization()(x)
100
          x = Activation('relu')(x)

x = Conv2D(256, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
101
          x = BatchNormalization()(x)
102
           \begin{array}{l} x = \operatorname{Activation('relu')(x)} \\ x = \operatorname{Conv2D(256, (3, 3), padding='same', strides=1, kernel\_regularizer=12(5e-4), use\_bias=False)(x)} \\ x = \operatorname{BatchNormalization()(x)} \\ \end{array} 
104
          106
107
108
          r = BatchNormalization()(x)
109
         110
111
           \begin{array}{l} x = \operatorname{Activation('relu')(x)} \\ x = \operatorname{Conv2D(256, (3, 3), padding='same', strides=1, kernel\_regularizer=12(5e-4), use\_bias=False)(x)} \\ x = \operatorname{BatchNormalization()(x)} \end{array} 
112
113
          x = Activation('relu')(x)
116
117
          x = Conv2D(256, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x) t = BatchNormalization()(x)
118
119
120
121
          x = add([r, t])
          e = Activation('relu')(x)
122
123
          # Group 8 4*4
          x = Conv2D(512, (1, 1), padding='same', strides=1, kernel\_regularizer=12(5e-4), use\_bias=False)(e)
124
          x = BatchNormalization()(x)
          126
127
          x = Activation('relu')(x)
x = Activation('relu')(x)
x = Conv2D(512, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)
x = BatchNormalization()(x)
                                                                                                                                                Activate V
         x = Activation('relu')(x)
120
          e = Activation('relu')(x)
121
122
123
          # Group 8 4*4
          x = Conv2D(512, (1, 1), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(e)
          x = Conv2D(312, (1, 1), padding= same , Strides=1, kernel_regularizer=12(5e-4), use_blas=False)(e)
x = BatchNormalization()(x)
x = Conv2D(512, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_blas=False)(x)
x = BatchNormalization()(x)
124
125
126
127
128
          x = Activation('relu')(x)
          x = \text{Conv2D(512, (3, 3), padding='same', strides=1, kernel_regularizer=12(5e-4), use_bias=False)(x)}
x = \text{BatchNormalization()(x)}
129
130
          x = Activation('relu')(x)
          # Group 9 full connection
          x = GlobalAveragePooling2D()(x)
135
136
          x = Dense(num_classes, activation='softmax')(x)
model = Model(input_0, x)
          return model
```

TRAINING THE NETWORK

HYPERPARAMETERS

Hyperparameters are parameters whose values control the learning process and determine the values of model parameters that a learning algorithm ends up learning.

- Learning Rate The learning rate is a tuning parameter in an optimization algorithm
 that determines the step size at each iteration while moving toward a minimum of a
 loss function. Here we have used a learning rate of 1e-2, i.e., 0.01 (1 percent)
- **Number of Epochs** The number of epochs is the number of complete passes through the training dataset. Here we have set num epochs to 1000.
- Momentum Momentum is an extension to the gradient descent optimization algorithm that allows the search to build inertia in a direction in the search space and overcome the oscillations of noisy gradients and coast across flat spots of the search space. We have set the momentum to 0.9.
- **Batch Size** The size of a batch refers to the number of training examples utilized in one iteration. We have taken a batch size of 16.

OPTIMISERS

In deep learning, optimizers are used to adjust the parameters for a model. The purpose of an optimizer is to adjust model weights to maximize a loss function.

The optimizers we have used are SGD and ReduceLROnPlateau.

1. SGD (Stochastic Gradient Descent)

Gradient descent is the preferred way to optimize neural networks and many other machine learning algorithms but is often used as a black box. Stochastic gradient descent (SGD) performs a parameter update for *each* training example $x^{(i)}$ and label $y^{(i)}$:

$$\theta = \theta - \eta \cdot \nabla_{\theta} J(\theta; x^{(i)}; y^{(i)}).$$

SGD handles redundancy by performing one update at a time. It is therefore usually much faster and performs frequent updates with a high variance that cause the objective function to fluctuate heavily.

2. ReduceLROnPlateau

As the name suggests, it reduces learning rate when a metric has stopped improving. Models often benefit from reducing the learning rate by a factor of 2-10 once learning stagnates. This scheduler reads a metrics quantity and if no improvement is seen for a 'patience' number of epochs, the learning rate is reduced.

It has certain arguments:

- monitor: quantity to be monitored.
- **factor:** factor by which the learning rate will be reduced. new Ir = Ir * factor.
- **patience:** number of epochs with no improvement after which learning rate will be reduced.
- verbose: int. 0: quiet, 1: update messages.

Here we monitor the value lost (val loss) with a factor 0.1, patience 32 and verbose 1.

LOSS FUNCTION

The loss function is used as a way to measure how well the model is performing. It maps an event or values of one or more variables onto a real number intuitively representing some "cost" associated with the event. An optimization problem seeks to minimize a loss function.

Here we use **categorical cross** entropy loss function. It computes the categorical cross entropy loss.

Arguments

- **y_true:** Tensor of one-hot true targets.
- y_pred: Tensor of predicted targets.
- **from_logits:** Whether y_pred is expected to be a logits tensor. By default, we assume that y_pred encodes a probability distribution.
- label_smoothing: Float in [0, 1]. If > 0 then smooth the labels. For example, if 0.1, use 0.1 / num_classes for non-target labels and 0.9 + 0.1 / num_classes for target labels.
- axis: Defaults to -1. The dimension along which the entropy is computed.

Returns

Categorical cross entropy loss value.

The implementation for training the network:

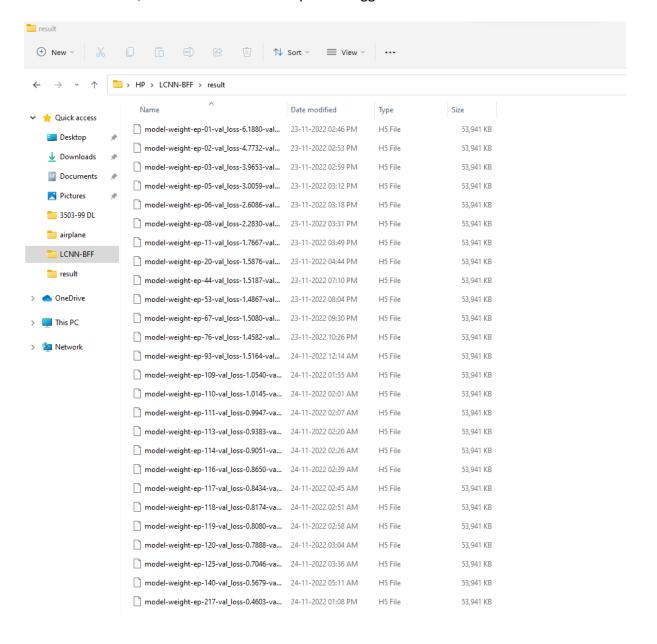
```
In [6]: 1 trainset_dir = 'data/train/NWPU45/'
2 valset_dir = 'data/test/NWPU45/'
3 num_classes = 45
            4 learning rate = 1e-2
               momentum = 0.9
            6 batch_size = 16
            7 input_shape = (256, 256, 3)
            9 train_datagen = ImageDataGenerator(
                          rescale = 1./255,
rotation_range = 60,
                          width_shift_range = 0.2,
                          height_shift_range = 0.2,
                         horizontal_flip = True,
vertical_flip = True,
                         fill_mode='nearest')
           18 val_datagen = ImageDataGenerator(rescale=1. / 255)
           20 train_generator = train_datagen.flow_from_directory(
                     trainset_dir,
                     target_size=(input_shape[0], input_shape[1]),
batch_size=batch_size,
                    class_mode='categorical')
           26 val_generator = val_datagen.flow_from_directory(
                   valset_dir,
target_size=(input_shape[0], input_shape[1]),
           28
                    batch_size=batch_size,
class_mode='categorical')
           32 optim = SGD(learning_rate=learning_rate, momentum=momentum)
          Found 25200 images belonging to 45 classes. Found 6300 images belonging to 45 classes.
```

```
Epoch 1/1000
Epoch 1: val_acc improved from -inf to 0.15635, saving model to ./result\model-weight-ep-01-val_loss-6.1880-val_acc-0.1563.h5
3 - 1r: 0.0100
Epoch 2/1000
1575/1575 [==
           -----] - ETA: 0s - loss: 4.9706 - acc: 0.2867
Epoch 2: val_acc improved from 0.15635 to 0.29206, saving model to ./result\model-weight-ep-02-val_loss-4.7732-val_acc-0.292
1.h5
1575/1575 [=
        1 - lr: 0.0100
Epoch 3/1000
1575/1575 [============= ] - ETA: 0s - loss: 4.0519 - acc: 0.3813
Epoch 3: val_acc improved from 0.29206 to 0.38016, saving model to ./result\model-weight-ep-03-val_loss-3.9653-val_acc-0.380
1575/1575 [==========] - 376s 238ms/step - loss: 4.0519 - acc: 0.3813 - val loss: 3.9653 - val acc: 0.380
2 - 1r: 0.0100
Epoch 4/1000
1575/1575 [========] - ETA: 0s - loss: 3.4146 - acc: 0.4468
Epoch 426/1000
Epoch 426: val_acc did not improve from 0.95397
6 - lr: 1.0000e-04
Epoch 427/1000
1575/1575 [======] - ETA: 0s - loss: 0.1556 - acc: 0.9960
Epoch 427: val acc did not improve from 0.95397
5 - lr: 1.0000e-04
Epoch 428/1000
1575/1575 [===========] - ETA: Os - loss: 0.1572 - acc: 0.9958
Epoch 428: val_acc did not improve from 0.95397
1 - 1r: 1.0000e-04
Epoch 429/1000
633/1575 [====
           ====>.....] - ETA: 3:37 - loss: 0.1545 - acc: 0.9959
0 - 1r: 1.0000e-15
Epoch 998/1000
1575/1575 [=============] - ETA: 0s - loss: 0.0985 - acc: 0.9989
Epoch 998: val acc did not improve from 0.95508
1575/1575 [===========] - 375s 238ms/step - loss: 0.0985 - acc: 0.9989 - val loss: 0.3083 - val acc: 0.953
3 - 1r: 1.0000e-16
Epoch 999/1000
1575/1575 [====
          -----] - ETA: 0s - loss: 0.0982 - acc: 0.9990
Epoch 999: val_acc did not improve from 0.95508
3 - lr: 1.0000e-16
Epoch 1000/1000
Epoch 1000: val_acc did not improve from 0.95508
```

Out[8]: <keras.callbacks.History at 0x17325bcda30>

5 - lr: 1.0000e-16

As the result of the training phase, the checkpoints of the model which produce the best results are stored, and the result of each epoch is logged in a CSV file.



4	A	В	. C	. D	. E	F
	epoch	acc	loss		val_acc	val_loss
2	0	0.147142857	6.386368275	0.01		6.187966347
3	1	0.286666662	4.97062397	0.01	0.292063504	4.773155212
4	2	0.381269842	4.051910877	0.01	0.380158722	3.965269804
5	3	0.446825385	3.414633751	0.01	0.336507946	4.06895113
6	4	0.492301583	2.951452017	0.01	0.481269836	3.005936146
7	5	0.52853173	2.615357876	0.01	0.524285734	2.608601093
8	6	0.56793648	2.355299711	0.01	0.5	2.692030907
9	7	0.59646827	2.16795826	0.01	0.563650787	2.282987118
10	8	0.617579341	2.022328377	0.01	0.516825378	2.522854805
11	9	0.635515869	1.925899029	0.01	0.442857146	3.151806593
12	10	0.654722214	1.833289266	0.01	0.673809528	1.766739726
13	11	0.660039663	1.791373968	0.01	0.610000014	2.19128561
14	12	0.679047644	1.71813643	0.01	0.523492038	2.651289463
15	13	0.682420611	1.701263309	0.01	0.482539684	2.8050313
L6	14	0.694841266	1.658886194	0.01	0.621269822	2.055324554
.7	15	0.697182536	1.636088967	0.01	0.645238101	1.954268932
8	16	0.709206343	1.612376451	0.01	0.626825392	1.932261586
L9	17	0.713095248	1.593413115	0.01	0.606031775	2.170803785
20	18	0.718293667	1.577822447	0.01	0.558888912	2.437092543
21	19	0.723452389	1.558637023	0.01	0.728412688	1.5875597
22	20	0.724880934	1.551594257	0.01	0.600952387	2.161413908
23	21	0.727103174	1.543855667	0.01	0.633333325	1.981584311
24	22	0.73146826	1.533724785	0.01	0.500476182	2.94591403
25	23	0.74023807	1.51911366	0.01	0.582063496	2.273865223
26	24	0.738412678	1.524551511	0.01	0.688571453	1.791189671
27	25	0.744920611	1.51406157	0.01	0.666507959	1.890483141
28	26	0.741706371	1.525231481	0.01	0.65031749	1.886744738
29	27	0.747182548	1.509722114	0.01	0.432222217	3.56233716
30	28	0.749603152	1.507339597	0.01	0.571746051	2.391289473
1	29	0.750396848	1.496598363	0.01	0.707460344	1.718337059
32	30	0.755992055	1.493844271	0.01	0.644920647	2.073897123
3	31	0.759206355	1.482271791	0.01	0.690634906	1.843597293
34	32	0.756984115	1.490798116	0.01	0.701587319	1.705972075
35	33	0.758015871	1.489545703	0.01	0.699523807	1.771898985
36	34	0.759801567	1.480996847	0.01	0.612857163	2.147623301
37	35	0.762182534	1.477557302	0.01	0.666349232	2.027133703
38	36	0.763809502	1.476256371	0.01	0.638730168	2.198781013
39	37	0.769206345	1.480588913	0.01	0,707460344	1.654153466

4	Α	В	С	D	E	F
964	962	0.999246061	0.097780928	1.00E-14	0.953968227	0.30768767
965	963	0.998730183	0.098671004	1.00E-14	0.953492045	0.307808697
966	964	0.998531759	0.098584868	1.00E-14	0.953968227	0.308814228
967	965	0.998412669	0.099772863	1.00E-15	0.953650773	0.309095919
968	966	0.998809516	0.098168276	1.00E-15	0.953492045	0.30682978
969	967	0.998531759	0.098538041	1.00E-15	0.952222228	0.307858914
70	968	0.99888891	0.097869359	1.00E-15	0.953492045	0.308778763
71	969	0.998849213	0.097924158	1.00E-15	0.953968227	0.307554841
72	970	0.999166667	0.097739652	1.00E-15	0.9538095	0.308715433
73	971	0.998730183	0.098740652	1.00E-15	0.953650773	0.30799821
74	972	0.999047637	0.098325357	1.00E-15	0.953492045	0.307983667
75	973	0.99900794	0.097968079	1.00E-15	0.953650773	0.306668133
76	974	0.99876982	0.098210491	1.00E-15	0.9538095	0.308372289
77	975	0.99888891	0.098624259	1.00E-15	0.954285741	0.308852822
78	976	0.998730183	0.098655395	1.00E-15	0.953174591	0.308404982
79	977	0.998492062	0.099209487	1.00E-15	0.95269841	0.309502693
80	978	0.99900794	0.097895093	1.00E-15	0.953015864	0.308343768
81	979	0.998730183	0.098573282	1.00E-15	0.953650773	0.307612093
82	980	0.99888891	0.098140888	1.00E-15	0.953492045	0.308877349
983	981	0.998968244	0.098139688	1.00E-15	0.953174591	0.306780964
84	982	0.998809516	0.098379031	1.00E-15	0.95269841	0.308407247
985	983	0.998571455	0.09838286	1.00E-15	0.953650773	0.308450669
86	984	0.998690486	0.098686211	1.00E-15	0.953650773	0.307598114
87	985	0.99888891	0.097968899	1.00E-15	0.953492045	0.309482992
88	986	0.99888891	0.098178819	1.00E-15	0.953174591	0.308006283
89	987	0.998928547	0.098460898	1.00E-15	0.953492045	0.306745261
90	988	0.998928547	0.098273516	1.00E-15	0.955079377	0.307262629
91	989	0.99876982	0.098252237	1.00E-15	0.954127014	0.305784583
92	990	0.999166667	0.097354397	1.00E-15	0.952857137	0.309331357
93	991	0.999285698	0.097405173	1.00E-15	0.953333318	0.309233248
94	992	0.999206364	0.097772308	1.00E-15	0.95269841	0.308266789
95	993	0.999365091	0.097521529	1.00E-15	0.953492045	0.307845384
96	994	0.998531759	0.098684363	1.00E-15	0.952222228	0.31036567
97	995	0.998968244	0.098678723	1.00E-15	0.952539682	0.30852139
98	996	0.99900794	0.098208249	1.00E-15	0.953968227	0.309860289
999	997	0.998928547	0.098453395	1.00E-16	0.953333318	0.308338404
000	998	0.998968244	0.098233476	1.00E-16	0.953333318	0.307960123
001	999	0.998531759	0.099014692	1.00E-16	0.953492045	0.307375163

TESTING THE NETWORK

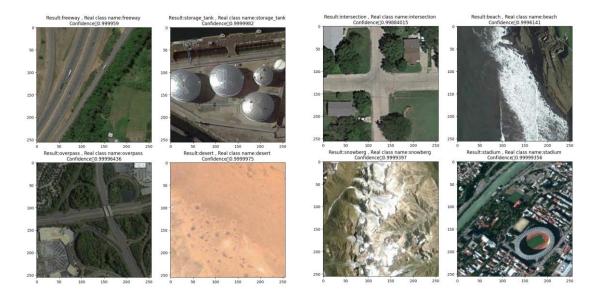
In the testing the network, random images are taken from the available test dataset and is passed to the model.

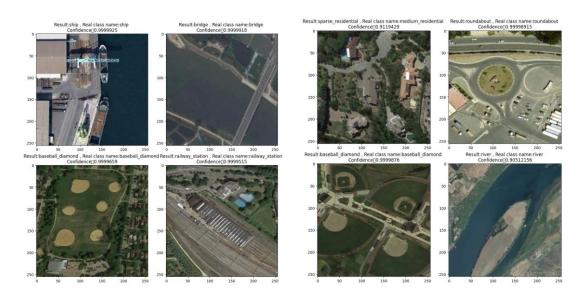
Test

```
In [27]:
                 1 import os
                      import numpy as np
                       import cv2
                  4 from keras import backend as K
                      from keras.models import load_model
                  6 from matplotlib import pyplot as plt
                       from keras.preprocessing.image import ImageDataGenerator
                  8 from tensorflow.keras.utils import img_to_array, load_img
                 10 def img_test(img_path, model, labels):
                             img_test(img_path, model, labels):
img_array = load_img(img_path, target_size=(256, 256))
img_array = [img_to_array(img_array)]
x_test = np.array(img_array, dtype='float') / 255.0
test_pred = np.argmax(model.predict(x_test), axis=1)
score = np.amax(model.predict(x_test), axis=1)
plt.title('Result:%s \nConfidence: %s' % (labels[test_pred[0]], score[0]))
plt.imshow(x_test[0])
                             plt.imshow(x_test[0])
                 18
                             plt.show()
                 def random_img_test(model, labels, testset_dir):
                             test_datagen = ImageDataGenerator(rescale=1. / 255)
test_generator = test_datagen.flow_from_directory(
                 22
23
                 24
25
                                    testset_dir,
target_size=(256, 256),
                 26
27
                                   batch_size=4,
class_mode='categorical')
                             x_test, y_test = test_generator.__getitem__(0)
preds = model.predict(x_test)
                 28
29
                 30
31
                             plt.figure(figsize=(10, 10))
                             plt.tigure(Tigsize=(10, 10))
for i in range(4):
    plt.subplot(2, 2, i+1)
    plt.title('Result:%s , Real class name:%s \nConfidence: %s' % (labels[np.argmax(preds[i])], labels[np.argmax(y_test[:
    plt.tight_layout(pad=0.4, w_pad=0.6, h_pad=0.6)
                                    plt.imshow(x_test[i])
                 36
37
                             plt.show()
                      4
```

 The result obtained contains the actual class, predicted class and confidence level for each image.







RESULT ANALYSIS

FEATURE MAP GENERATION

Feature map is the result of the convolution operation. Upon passing the input image over the convolution layers, the original image is converted into a feature image, which is then passed to a classification layer.

```
10 10 10
```

```
Feature Map
In [26]: 1 import numpy as np
                   3 import matplotlib.pvplot as plt
                   from keras.models import Model
                  6 from keras.preprocessing.image import ImageDataGenerator
7 from tensorflow.keras.utils import img_to_array, load_img
                9 input_shape = (256, 256, 3)
10 num_classes = 45
11 batch_size = 64
12 data_path = 'original_data/NWPU45/'
13 class_names = os.listdir(data_path)
                class_names = os.listdir(data_path)

# print(class_names)

image_paths = []

for c_name in class_names:

class_path = data_path + c_name + '/'

image_name = os.listdir(class_path)

for i in range(len(image_name)):

image_name[i] = class_path + image_name[i]

# print(image_paths.append(image_name[i])

# print(image_paths)

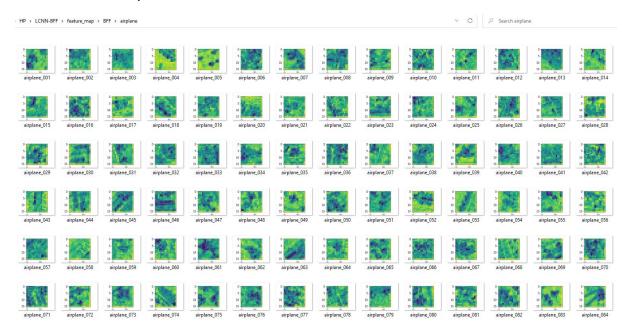
for c_name in class_names:

save = 'feature_map/BFF/' + c_name + '/'

if not os.path.exists(save):

os.makedirs(save)
                                   os.makedirs(save)
                22 weights_path = 'result/model-weight-ep-625-val_loss-0.3092-val_acc-0.9551.h5'
29 model = LCNN_BFF(input_shape, num_classes)
                30 model load_weights(weights_path)
31 #The fourth group, the first branch-36, the second branch-37, bff-38, channel = 128
22 conv_layer = Model(inputs=model.inputs, outputs=model.get_layer(index-38).output)
33
                334
4 test_datagen = ImageDataGenerator(rescale=1. / 255)
35 test_generator = test_datagen.flow_from_directory(
                             data_path,
                             target_size=(input_shape[0], input_shape[1]),
                            batch_size=batch_size,
class_mode='categorical',
shuffle=False)
                 39
40
               53
54
55
                                  plt.imshow(total_feature_map)
                                    save_path = 'feature_map/BFF/' + image_paths[c][21:-3] + 'png'
                                   plt.savefig(save_path)
c = c + 1
                Found 31500 images belonging to 45 classes.
               2/2 [=====] - 0s 177ms/step
2/2 [=====] - 0s 132ms/step
                2/2 [======] - 0s 48ms/step
               2/2 [-----] - 0s 52ms/step
```

After training the network, feature map is generated for every image in the dataset. These are the feature maps.



PREDICTION AND CLASSIFICATION

Random samples are taken from the test set and passed to the model for prediction and stored in **predict.csv** file.

predict.csv



We compute classification metrics: accuracy score, confusion matrix, plot accuracy and plot loss.

Classification

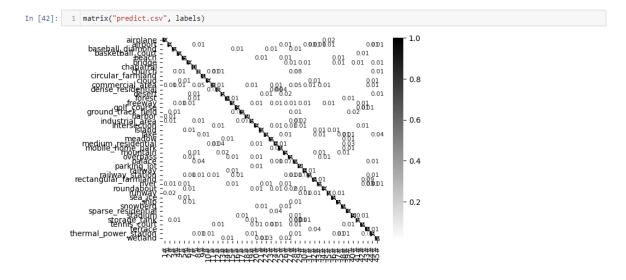
```
In [38]: 1 import pandas as pd
                   2 import seaborn as sn
3 import numpy as np
                  import os from sklearn.metrics import accuracy_score, classification_report, confusion_matrix
                  6 from matplotlib import pyplot as plt
                  8 def acc score(csv name):
                          r_c = pd.read_csv(csv_name)
true_labels = r_c['true_labels']
pred_labels = r_c['pred_labels']
                10
                11
                             acc = accuracy_score(true_labels, pred_labels)
                             return acc
                def report(csv_name, labels):
    r_c = pd.read_csv (csv_name)
    true_labels = r_c['true_labels']
    pred_labels = r_c['pred_labels']
                              r = classification_report(true_labels, pred_labels, digits=4, target_names=labels)
                             return
                def matrix(csv_name, labels):
    r_c = pd.read_csv( csv_name)
true_labels = r_c['true_labels']
pred_labels = r_c['pred_labels']
                           mat = confusion_matrix(true_labels, pred_labels)
mat_2 = np.ndarray((len(labels), len(labels)))
names = []
for n in range(1, len(labels)+1):
    name = str(n) + '#'
                 31
32
                 33
34
                             for i in range(len(labels)):
    for k in range(len(labels)):
                                    mat_2[i][k] = mat[i][k] / np.sum(mat[i])
                 35
36
```

```
mac_2[1][K] - mac[1][K] / hp.3am(mac[1])
           mat_2 = np.round(mat_2, decimals=2)
           mact_a = np.round(mat_a, detimals=2/)
sn.heatmap(mat_2, annot=frue, fmt='.2f', cmap='gray_r', xticklabels=names, yticklabels=labels,
mask=mat_2<0.001, annot_kws={'size':8})</pre>
38
39
40
             plt.yticks(rotation=360)
41
             plt.show()
plt.grid()
plt.show()
55 def plt_loss(csv_name2):
            plt_loss(csv_name2):
    r_c = pd.read_csv(csv_name2)
    loss = r_c['loss']
    val loss = r_c('val_loss')
    epochs = range(1, len(loss) + 1)
    plt.plot(epochs, loss, 'blue', label='train_loss', marker='', linestyle='-')
    plt.plot(epochs, val_loss, 'red', label='test_loss', marker='.', linestyle='-')
    plt.title('Train and Test Loss')
    ll lagrad()
61
62
63
64
65
             plt.legend()
             plt.grid()
             plt.show()
```

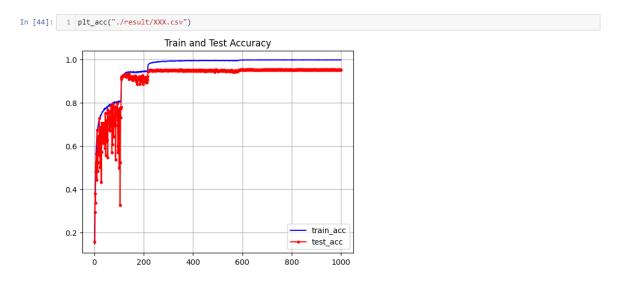
Accuracy score: Accuracy score is used to measure the model performance in terms
of measuring the ratio of sum of true positive and true negatives out of all the
predictions made.

0.9550									
	793650793651								
1 re	port("predict.csv", la	bels)							
100	prec	ision re	call f1-	score suppo	ort\n\n	airplane	1.0000	0.9786	0.9892
40\n	airport	0.9496	0.9429	0.9462	140\n	baseball_diamond	0.9856	0.9786	0.9821
140\n	basketball_court	0.9789	0.9929	0.9858	140\n	beach	0.9714	0.9714	0.9714
140\n	bridge	0.9504	0.9571	0.9537	140\n	chaparral	0.9722	1.0000	0.9859
140\n	church	0.8857	0.8857	0.8857	140\n	circular_farmland	0.9929	1.0000	0.9964
140\n	cloud	0.9928	0.9786	0.9856	140\n	commercial_area	0.9593	0.8429	0.8973
140\n	dense_residential	0.9254	0.8857	0.9051	140\n	desert	0.9781	0.9571	0.9675
140\n	forest	0.9783	0.9643	0.9712	140\n	freeway	0.9635	0.9429	0.9531
140\n	golf_course	0.9787	0.9857	0.9822	140\n	ground_track_field	0.9853	0.9571	0.9710
140\n	harbor	1.0000	0.9929	0.9964	140\n	industrial_area	0.9706	0.9429	0.9565
140\n	intersection	0.9568	0.9500	0.9534	140\n	island	0.9714	0.9714	0.9714
140\n	lake	0.9485	0.9214	0.9348	140\n	meadow	0.9855	0.9714	0.9784
140\n	medium_residential	0.8533	0.9143	0.8828	140\n	mobile_home_park	0.9517	0.9857	0.9684
140\n	mountain	0.9116	0.9571	0.9338	140\n	overpass	0.9441	0.9643	0.9541
140\n	palace	0.8239	0.9357	0.8763	140\n	parking_lot	0.9586	0.9929	0.9754
140\n	railway	0.9379	0.9714	0.9544	140\n	railway_station	0.9697	0.9143	0.9412
140\n ≀	rectangular_farmland	0.9403	0.9000	0.9197	140\n	river	0.9549	0.9071	0.9304
140\n	roundabout	0.9852	0.9500	0.9673	140\n	runway	0.9640	0.9571	0.9606
140\n	sea_ice	0.9858	0.9929	0.9893	140\n	ship	0.9718	0.9857	0.9787
140\n	snowberg	0.9718	0.9857	0.9787	140\n	sparse_residential	0.9247	0.9643	0.9441
140\n	stadium	0.9786	0.9786	0.9786	140\n	storage_tank	0.9926	0.9571	0.9745
140\n	tennis_court	0.9571	0.9571	0.9571	140\n	terrace	0.8816	0.9571	0.9178
	hermal_power_station	0.9496	0.9429	0.9462	140\n	wetland	0.9291	0.9357	0.9324
140\n\ı	n accuracy			0.9551	6300\n	macro avg	0.9566	0.9551	0.955

• **Confusion matrix:** A confusion matrix is a table that is used to define the performance of a classification algorithm. A confusion matrix visualizes and summarizes the performance of a classification algorithm.



• **Plot accuracy:** We pick up the training data accuracy ("acc") and the validation data accuracy ("val_acc") for plotting. As you can see in the diagram, the accuracy increases rapidly in the first 100 epochs, indicating that the network is learning fast.



• **Plot loss:** Plots the loss function of an object containing the results of a gradient descent object implementation. To prevent overfitting, we can make use of the loaded function plot_loss() to plot training loss against validation loss.

