

## Rotate Image

You are given an  $n \times n$  2D matrix representing an image.

Rotate the image by 90 degrees (clockwise).

Follow up:

Could you do this in-place?

## Solution 1

here give a common method to solve the image rotation problems.

```
/*
 * clockwise rotate
 * first reverse up to down, then swap the symmetry
 * 1 2 3      7 8 9      7 4 1
 * 4 5 6  => 4 5 6  => 8 5 2
 * 7 8 9      1 2 3      9 6 3
 */
void rotate(vector<vector<int> > &matrix) {
    reverse(matrix.begin(), matrix.end());
    for (int i = 0; i < matrix.size(); ++i) {
        for (int j = i + 1; j < matrix[i].size(); ++j)
            swap(matrix[i][j], matrix[j][i]);
    }
}

/*
 * anticlockwise rotate
 * first reverse left to right, then swap the symmetry
 * 1 2 3      3 2 1      3 6 9
 * 4 5 6  => 6 5 4  => 2 5 8
 * 7 8 9      9 8 7      1 4 7
 */
void anti_rotate(vector<vector<int> > &matrix) {
    for (auto vi : matrix) reverse(vi.begin(), vi.end());
    for (int i = 0; i < matrix.size(); ++i) {
        for (int j = i + 1; j < matrix[i].size(); ++j)
            swap(matrix[i][j], matrix[j][i]);
    }
}
```

written by [shichaotan](#) original link [here](#)

## Solution 2

While these solutions are Python, I think they're understandable/interesting for non-Python coders as well. But before I begin: No mathematician would call a matrix `matrix`, so I'll use the usual `A`. Also, btw, the 40 ms reached by two of the solutions is I think the fastest achieved by Python solutions so far.

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### Most Pythonic - `[::-1]` and `zip` - 44 ms

The most pythonic solution is a simple one-liner using `[::-1]` to flip the matrix upside down and then `zip` to transpose it. It assigns the result back into `A`, so it's "in-place" in a sense and the OJ accepts it as such, though some people might not.

```
class Solution:
    def rotate(self, A):
        A[:] = zip(*A[::-1])
```

### Most Direct - 52 ms

A 100% in-place solution. It even reads and writes each matrix element only once and doesn't even use an extra temporary variable to hold them. It walks over the "top-left quadrant" of the matrix and directly rotates each element with the three corresponding elements in the other three quadrants. Note that I'm moving the four elements in parallel and that `[~i]` is way nicer than `[n-1-i]`.

```
class Solution:
    def rotate(self, A):
        n = len(A)
        for i in range(n/2):
            for j in range(n-n/2):
                A[i][j], A[~j][i], A[~i][~j], A[j][~i] = \
                    A[~j][i], A[~i][~j], A[j][~i], A[i][j]
```

### Clean Most Pythonic - 56 ms

While the OJ accepts the above solution, the the result rows are actually tuples, not lists, so it's a bit dirty. To fix this, we can just apply `list` to every row:

```
class Solution:
    def rotate(self, A):
        A[:] = map(list, zip(*A[::-1]))
```

### List Comprehension - 60 ms

If you don't like `zip`, you can use a nested list comprehension instead:

```
class Solution:
    def rotate(self, A):
        A[:] = [[row[i] for row in A[::-1]] for i in range(len(A))]
```

---

## Almost as Direct - 40 ms

If you don't like the little repetitive code of the above "Most Direct" solution, we can instead do each four-cycle of elements by using three swaps of just two elements.

```
class Solution:
    def rotate(self, A):
        n = len(A)
        for i in range(n/2):
            for j in range(n-n/2):
                for _ in '123':
                    A[i][j], A[~j][i], i, j = A[~j][i], A[i][j], ~j, ~i
                i = ~j
```

---

## Flip Flip - 40 ms

Basically the same as the first solution, but using `reverse` instead of `[::-1]` and transposing the matrix with loops instead of `zip`. It's 100% in-place, just instead of only moving elements around, it also moves the rows around.

```
class Solution:
    def rotate(self, A):
        A.reverse()
        for i in range(len(A)):
            for j in range(i):
                A[i][j], A[j][i] = A[j][i], A[i][j]
```

---

## Flip Flip, all by myself - 48 ms

Similar again, but I first transpose and then flip left-right instead of upside-down, and do it all by myself in loops. This one is 100% in-place again in the sense of just moving the elements.

```
class Solution:
    def rotate(self, A):
        n = len(A)
        for i in range(n):
            for j in range(i):
                A[i][j], A[j][i] = A[j][i], A[i][j]
        for row in A:
            for j in range(n/2):
                row[j], row[~j] = row[~j], row[j]
```

written by [StefanPochmann](#) original link [here](#)

## Solution 3

The idea was firstly transpose the matrix and then flip it symmetrically. For instance,

```
1  2  3
4  5  6
7  8  9
```

after transpose, it will be `swap(matrix[i][j], matrix[j][i])`

```
1  4  7
2  5  8
3  6  9
```

Then flip the matrix horizontally. (`swap(matrix[i][j], matrix[i][matrix.length-1-j])`)

```
7  4  1
8  5  2
9  6  3
```

Hope this helps.

```
public class Solution {
    public void rotate(int[][] matrix) {
        for(int i = 0; i<matrix.length; i++){
            for(int j = i; j<matrix[0].length; j++){
                int temp = 0;
                temp = matrix[i][j];
                matrix[i][j] = matrix[j][i];
                matrix[j][i] = temp;
            }
        }
        for(int i = 0; i<matrix.length; i++){
            for(int j = 0; j<matrix.length/2; j++){
                int temp = 0;
                temp = matrix[i][j];
                matrix[i][j] = matrix[i][matrix.length-1-j];
                matrix[i][matrix.length-1-j] = temp;
            }
        }
    }
}
```

written by [LuckyIdiot](#) original link [here](#)

From [LeetCoder](#).