

## ← Homework for Module 4 Part 1

Quiz, 15 questions

1  
point

1.

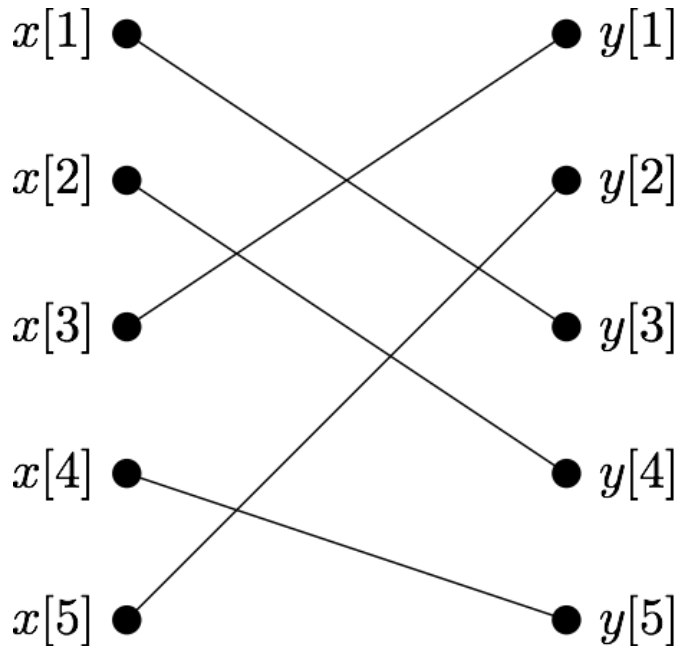
(Difficulty: ★) Among the choices below, select all the **linear** systems. (Please note that some of the choices use functions rather than discrete-time signals; the concept of linearity is identical in both cases).

☒ The DTFT, i.e. transform a sequence  $\mathbf{x}$  into  $\text{DTFT}\{\mathbf{x}\}$ .

☒ Second derivative, i.e.

$$y(t) = \frac{d^2}{dt^2} x(t)$$

☒ Scrambling, i.e. a permutation to the input sequence, e.g. :



☐ AM radio modulation, i.e. multiply a signal  $x[n]$  by a cosine at the carrier frequency :

$$y[n] = x[n] \cos(2\pi\omega_c n)$$

☐ Time-stretch, i.e.  $y(t) = x(\alpha t)$ , e.g. if you play an old LP-45 vinyl disc at 33 rpm, the time-stretch coefficient would be  $\alpha = 33/45$ .

☐ Clipping, i.e. enforce a maximum signal amplitude  $M$ , e.g.:

$$y[n] = \begin{cases} x[n] & , x[n] \leq M \\ M & , \text{otherwise} \end{cases}$$

☐ Envelope detection (via squaring), i.e.  $y[n] = |x[n]|^2 * h[n]$ , where  $h[n]$  is the impulse response of a *lowpass filter* such as the moving average filter.



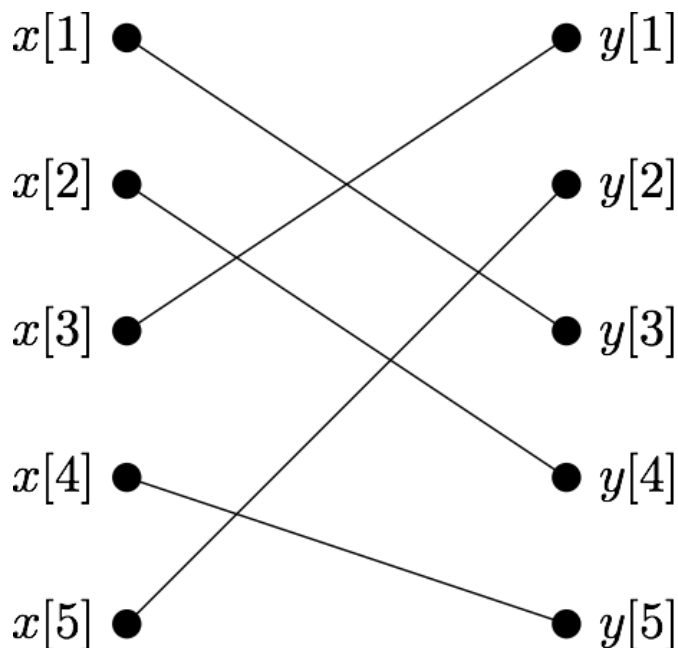
1  
point

## Homework for Module 4 Part 1

Quiz, 15 questions

(Difficulty: ★) Among the choices below, select all the **time-invariant** systems. (Please note that some of the choices use functions rather than discrete-time signals; the concept of time invariance is identical in both cases).

- ☐ Scrambling : apply a permutation to the input sequence, e.g. :



- ☒ Clipping, i.e. enforce a maximum signal amplitude  $M$ , e.g.:

$$y[n] = \begin{cases} x[n] & , x[n] \leq M \\ M & , \text{otherwise} \end{cases}$$

- ☒ Second derivative, i.e.

$$y(t) = \frac{d^2}{dt^2} x(t)$$

- ☐ The DTFT, i.e. transform a sequence  $\mathbf{x}$  into  $\text{DTFT}\{\mathbf{x}\}$ .

- ☐ Time-stretch, i.e.  $y(t) = x(\alpha t)$ , e.g. if you play an old LP-45 vinyl disc at 33 rpm, the time-stretch coefficient would be  $\alpha = 33/45$

- ☒ Envelope detection (via squaring), i.e.  $y[n] = |x[n]|^2 * h[n]$ , where  $h[n]$  is the impulse response of a *lowpass filter* such as the moving average filter.

- ☐ AM radio modulation, i.e. multiply a signal  $x[n]$  by a cosine at the carrier frequency :

$$y[n] = x[n] \cos(2\pi\omega_c n)$$

1  
point

3.

(Difficulty: ★) The impulse response of a room can be recorded by producing a sharp noise (impulsive sound source) in a silent room, thereby capturing the scattering of the sound produced by the walls.



## Homework for Module 4 Part 1

The impulse response  $h[n]$  of [Lausanne Cathedral](#) was measured by *Dokmanic et al.* by recording the sound of balloons being popped ([hear it!](#)).

The balloon is popped at time  $n = 0$  and after a number of samples  $N$ , the reverberations die out, i.e.  $h[n] = 0$  for  $n < 0$  or  $n > N$ .

The acoustic of this large space can then be artificially recreated by convolving any audio recording with the impulse response, e.g. this [cello recording](#) becomes [this](#).

What are the properties of  $h[n]$ ? (tick all the correct answers)

☐ Anticausal

☒ FIR

☒ BIBO stable

1  
point

4.

(Difficulty: ★) Let

$$h[n] = \delta[n] - \delta[n - 1]$$

$$x[n] = \begin{cases} 1 & , n \geq 0, \\ 0 & , \text{else.} \end{cases}$$

$$y[n] = x[n] * h[n].$$

Compute  $y[-1]$ ,  $y[0]$ ,  $y[1]$ ,  $y[2]$  and write the result as space-separated values. E.g.: If you find  $y[-1] = -2$ ,  $y[0] = -1$ ,  $y[1] = 0$ ,  $y[2] = 1$ , you should enter

1 -2 -1 0 1

0 1 0 0

1  
point

5.

(Difficulty: ★★) Consider the filter  $h[n] = \delta[n] - \delta[n - 1]$ ,



## Homework for Module 4 Part 1

the signal  $x[n] = \begin{cases} n, & n = 0, 1, 2, \\ 0, & \text{else.} \end{cases}$   
 Quiz, 15 questions

and the output  $y[n] = x[n] * h[n]$ .

Compute  $y[-1]$ ,  $y[0]$ ,  $y[1]$ ,  $y[2]$  and write the result as space-separated values. E.g.: If you find  $y[-1] = -2$ ,  $y[0] = -1$ ,  $y[1] = 0$ ,  $y[2] = 1$ , you should enter

1 -2 -1 0 1

0 0 1 1

1  
point

6.

(Difficulty: ★ ★ ★) Which of the following filters are BIBO-stable?

Assume  $N \in \mathbb{N}$  and  $0 < \omega_c < \pi$ .

☐

The ideal low pass filter with a cutoff frequency  $\omega_c$ :  $H(e^{j\omega}) = \begin{cases} 1 & |\omega| \leq \omega_c \\ 0 & \text{otherwise} \end{cases}$ .

☒

Any filter  $h[n]$  with finite support and bounded coefficients.

☐

The following smoothing filter:  $h[n] = \sum_{k=0}^{\infty} \frac{1}{k+1} \delta[n-k]$ .

☒

The moving average:  $h[n] = \frac{\delta[n] + \delta[n-1]}{2}$ .

1  
point

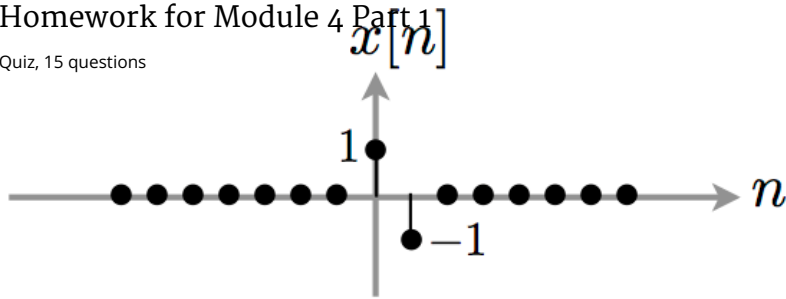
7.

(Difficulty: ★★) Consider an LTI system  $\mathcal{H}$ . When the input to  $\mathcal{H}$  is the following signal

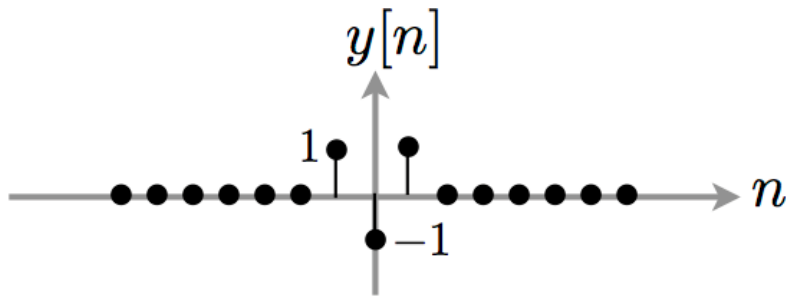


## Homework for Module 4 Part 1

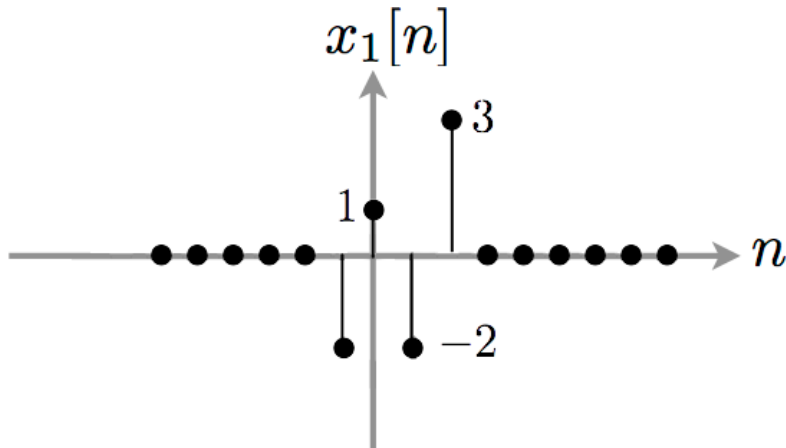
Quiz, 15 questions



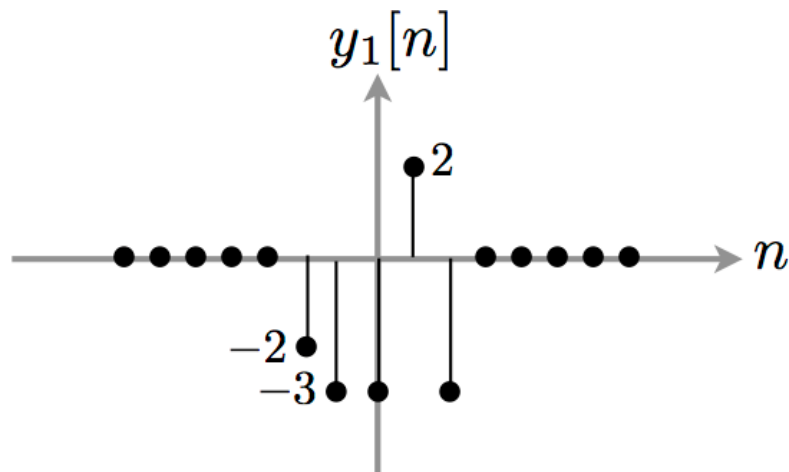
then the output is



Assume now the input to  $\mathcal{H}$  is the following signal

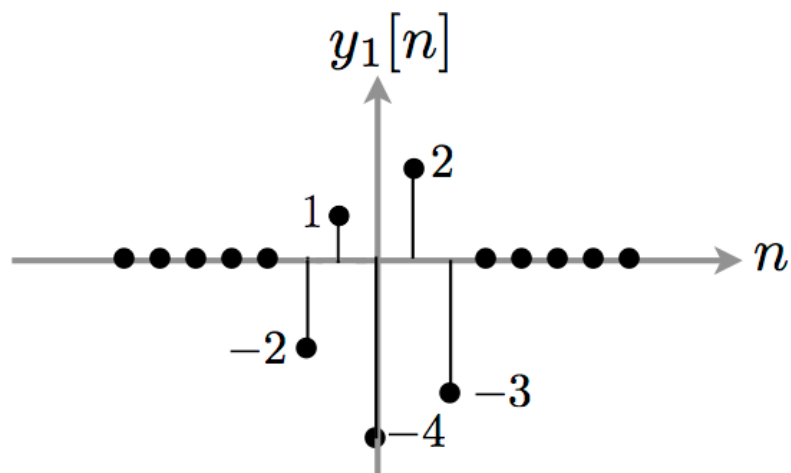
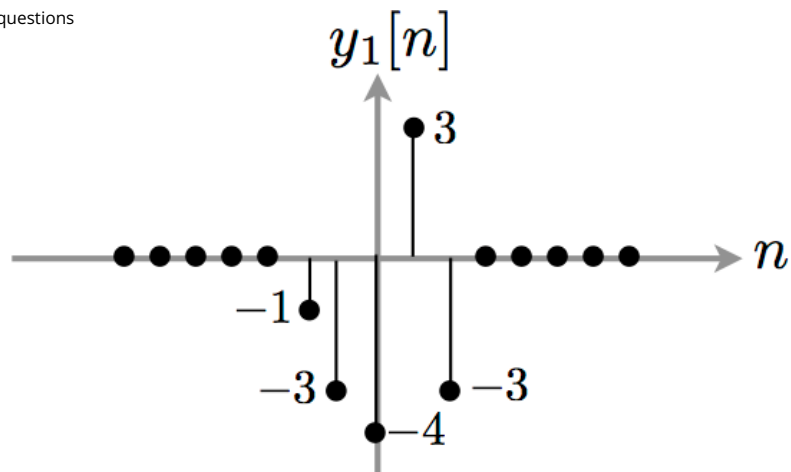


Which one of the following signals is the system's output?



# ← Homework for Module 4 Part 1

Quiz, 15 questions



1  
point

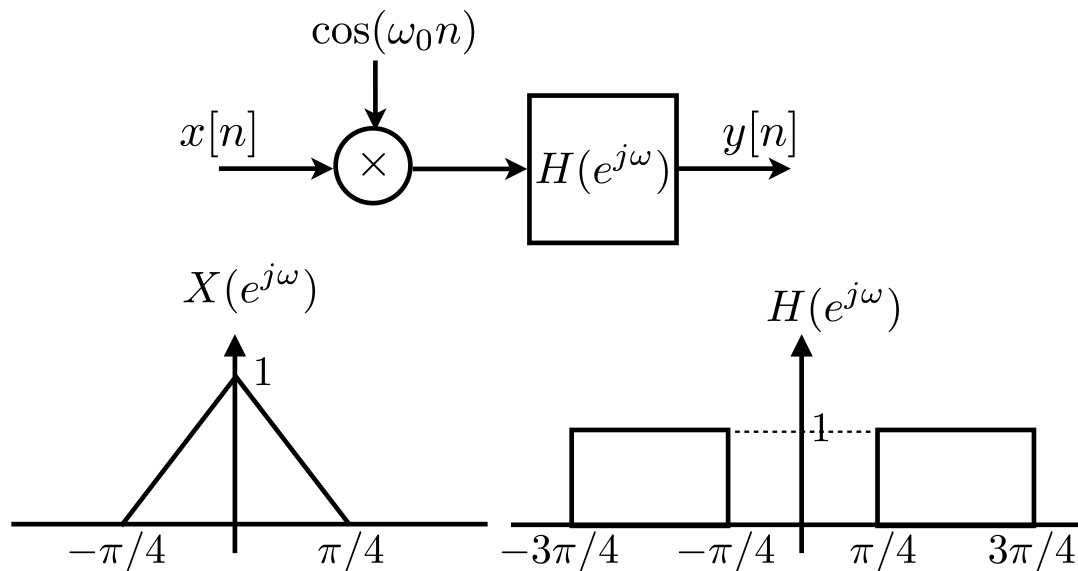
8.

(Difficulty: ★) Consider the system shown below, consisting of a cosine modulator at frequency  $\omega_0$  followed by an ideal bandpass filter  $h[n]$  whose frequency response is also shown in the figure; assume that the input to the system is the signal  $x[n]$ , whose spectrum is shown below.



## Homework for Module 4, Part 1

Quiz, 15 questions



Determine the value of  $\omega_0 \in [0, 2\pi]$  that maximizes the energy of the output  $y[n]$  when the input is  $x[n]$ .

Remember that  $\pi$  must be entered in the answer box as pi.

Preview

$$\frac{\pi}{2}$$

pi/2

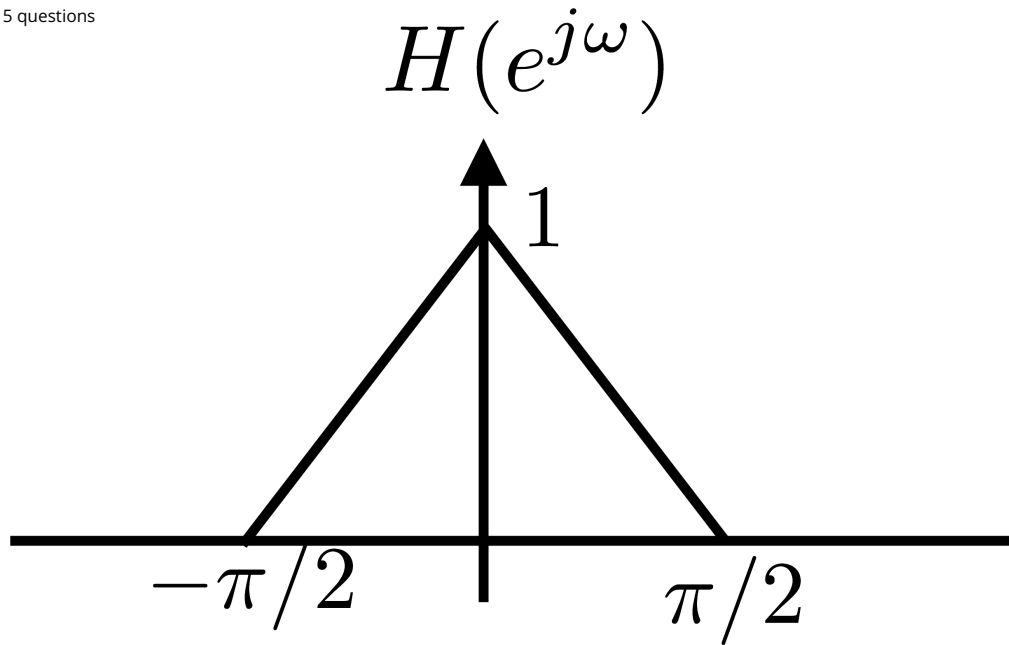
1  
point

9.

(Difficulty: ★) Consider a lowpass filter with the following frequency response.

## ← Homework for Module 4 Part 1

Quiz, 15 questions



What is the output  $y[n]$  when the input to this filter is  $x[n] = \cos(\frac{\pi}{5}n) + \sin(\frac{\pi}{4}n) + 0.5\cos(\frac{3\pi}{4}n)$ ?

Preview

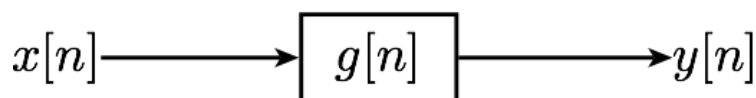
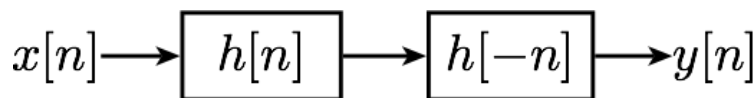
$$\frac{1}{2} \sin\left(\frac{\pi n}{4}\right) + \frac{3}{5} \cos\left(\frac{\pi n}{5}\right)$$

$$3/5 * \cos(\pi/5 * n) + 1/2 * \sin(\pi/4 * n)$$

1  
point

10.

(Difficulty: ★) Consider a filter with real-valued impulse response  $h[n]$ . The filter is cascaded with another filter whose impulse response is  $h'[n] = h[-n]$ , i.e. whose impulse response is the time-reversed version of  $h[n]$ :



The cascade system can be seen as a single filter with impulse response  $g[n]$ .

What is the phase of  $G(e^{j\omega})$ ?

Preview

0





## Homework for Module 4 Part 1

Quiz, 15 questions

1  
point

11.

(Difficulty: ★) Let  $x[n] = \cos(\frac{\pi}{2}n)$  and  $h[n] = \frac{1}{5}\text{sinc}(\frac{n}{5})$ . Compute the convolution  $y[n] = x[n] * h[n]$ , and write the value of  $y[5]$ .

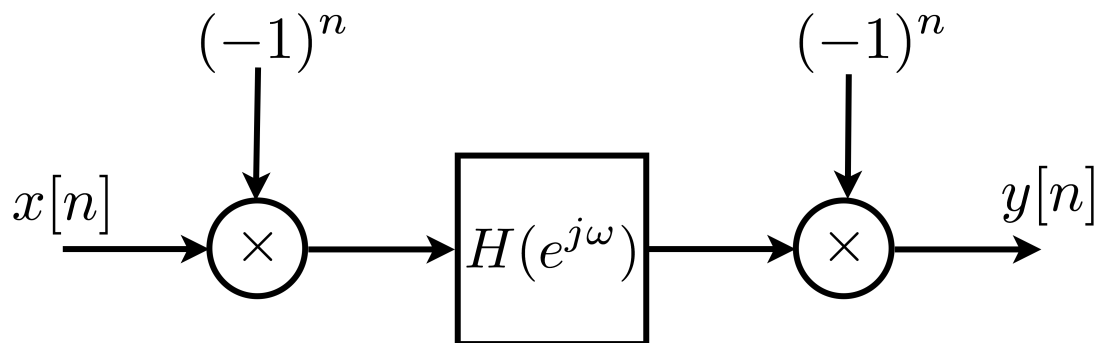
Hint: First find the convolution result in the frequency domain.

0

1  
point

12.

(Difficulty: ★★) Consider the system below, where  $H(e^{j\omega})$  is an ideal lowpass filter with cutoff frequency  $\omega_c = \pi/4$ :



Consider two input signals to the system:

- $x_1[n]$  is bandlimited to  $[-\pi/4, \pi/4]$
- $x_2[n]$  is band-limited to  $[-\pi, -3\pi/4] \cup [3\pi/4, \pi]$ .

Which of the following statements is correct?

- ☐ Both  $x_1[n]$  and  $x_2[n]$  are eliminated by the system.
- ☐ Both  $x_1[n]$  and  $x_2[n]$  are not modified by the system.
- ☐  $x_1[n]$  is not modified by the system while  $x_2[n]$  is eliminated.
- ☒  $x_2[n]$  is not modified by the system while  $x_1[n]$  is eliminated.

1  
point

13.

(Difficulty: ★)  $x[n]$  and  $y[n]$  are two square-summable signals in  $\ell_2(\mathbb{Z})$ ;  $X(e^{j\omega})$  and  $Y(e^{j\omega})$  are their corresponding DTFTs.



## Homework for Module 4 Part 1

We want to compute the value.

Quiz, 15 questions

$$\sum_{n=-\infty}^{\infty} x[n]y^*[n].$$

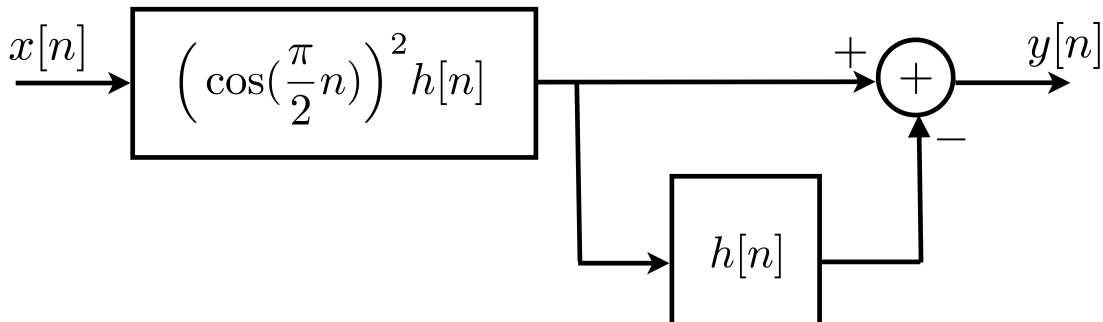
in terms of  $X(e^{j\omega})$  and  $Y(e^{j\omega})$ . Select the correct expression among the choices below.

- ☒  $\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})Y^*(e^{j\omega})d\omega$
- ☐  $\frac{1}{2\pi} X(e^{j\omega})Y^*(e^{j\omega})$
- ☐  $\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})Y(e^{-j\omega})d\omega$
- ☐  $X(e^{j\omega}) * Y(e^{-j\omega})$
- ☐  $\frac{1}{2\pi} X(e^{j\omega})Y(e^{-j\omega})$
- ☐  $X(e^{j\omega})Y(e^{-j\omega})$

1  
point

14.

(Difficulty: ★ ★ ★)  $h[n]$  is the impulse response of an ideal lowpass filter with cutoff frequency  $\omega_c < \frac{\pi}{2}$ . Select the correct description for the system represented in the following figure?



Hint: Use the trigonometric identity  $\cos(x)^2 = \frac{1}{2}(1 + \cos(2x))$ .

- ☐ A lowpass filter with gain  $\frac{1}{2}$  and cutoff frequency  $2\omega_c$ .
- ☐ A lowpass filter with gain 1 and cutoff frequency  $\omega_c/2$ .
- ☐ A lowpass filter with gain 1 and cutoff frequency  $\omega_c$ .
- ☒ A highpass filter with gain  $\frac{1}{2}$  and cutoff frequency  $\pi - \omega_c$ .
- ☐ A highpass filter with gain  $\frac{1}{4}$  and cutoff frequency  $\omega_c$ .
- ☐ A highpass filter with gain 1 and pass band  $[\omega_c, \pi - \omega_c]$ .

1  
point

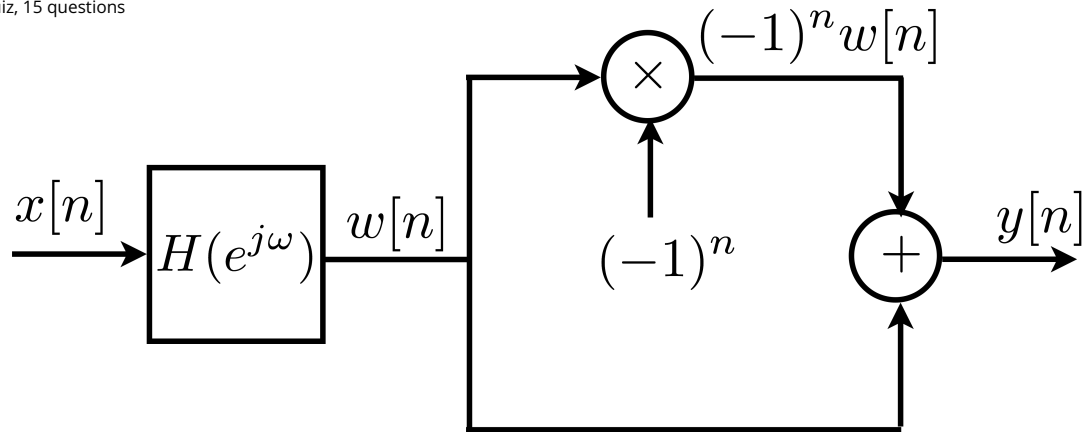
15.

(Difficulty: ★ ★ ★) Consider the following system, where  $H(e^{j\omega})$  is a half-band filter, i.e. an ideal lowpass with cutoff frequency  $\omega_c = \pi/2$ :



## Homework for Module 4 Part 1

Quiz, 15 questions



Assume the input to the system is  $x[n] = \delta[n]$ . Compute

$$\sum_{n=-\infty}^{\infty} y[n]$$

- Hint: Perform the derivations in the frequency domain.



I, **Mark R. Lytell**, understand that submitting work that isn't my own may result in permanent failure of this course or deactivation of my Coursera account.

[Learn more about Coursera's Honor Code](#)

