May 15th 2024 MTH214 - Introduction to Operations Research Definition of Operation Research Operation revearch is concerned with scientifi-- cally desiding how to best design and Operate man-made systems. Osazusa Emmanuel Osabbioman

Clasifications of Operations Research Models 1. I conic Models 2. Hnalog Model 3. Symbolic Model 1- Tonic Model: This represents the real system by something that looks like what is being represented. Example are Photographs, alobes and 3D models etc. An advantage of their conic model is that it is welful for studying Condition which prevail at a given time. How ever iconic models are not particularly useful for the study of dynamic situations, or helpful in discovering relationships between the variables in a system. 2. Anollog Model: This is a model that establishes a relationship between a variable in a system and an analogow variable in the model. Examples are graphs, maps, flow charts and building Osazuwa Emmanuel Osabioman

plans. Unlike iconic models analog models are useful for the study of dynamic situations.

One disadvantage of the analog model is that it may over simplify the real life system.

3 Symbolic Model:

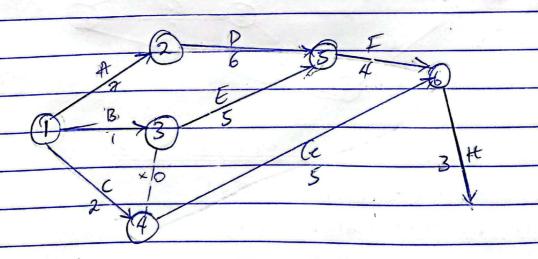
This is a model that replaces components or variable in a real life system with symbolo, and the systems are generally related mathematically and is therefore often called mathematical models

Leave 4 pages.

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## Network Analysis and Project Management

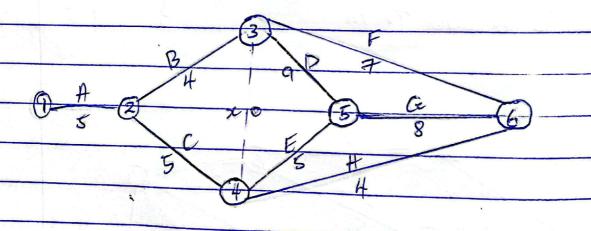
			1- 1.10
TA	no (see)	(days)	Immediate
J.D	Activity	(8493)	
A	Type-set Manuscript	7	None
· B	Procure Plates	1	None
(	Procure Papers	2	None
		0	<i>(</i> 0
Q	Parte and film	6	A-
E	Plate	5	B
F	Run Impression	4	DandE
Ge	Produce Cover	5	Bande
CE		3	
H	Bind and Trim		Fand G



Network 1.

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T.D	Activity	Duration (Days)	Immediate Predecessors
Δ		5	None
B		H	At .
C		5	A.
0		9	B
E		5	C
F		7	GB
Ge	/ /	8 .	D, E
+		4	
	, ,		



Title: Network2

Project Management Method Critical Path Method (CPM):

An activity is soid to be critical it a delay in it starts will cause a delay in the completion date of the entire project.

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The time between the earliest start and the latest completion date of a non-critical activity is longer than its actual duration. Hence a non-critical activity is said to have slack or float time. A critical path defines a chain of activities that connect the start and end event of the network. To determine the critical part of a project, we must: 1. Calculate the parliest possible times Ti(E) for each event. 2. Calculate the latest allowable times Ti(1) for each event. Determine the slack times for event i (8i) as Si = Ti(L) - Ti(E) The event which has O slack times are one the critical paths. farliest Time. (farliest Possible Start time) The earliest time of an event i denoted by Ti(E) is the earliest time at which event i can occur and is given by: Ti(E) = Max (Ti(E) + tiss Osazursa Emmanuel Oscilotion an

	•
	Where tis are the completion times of job is
	An i ranges over all nodes to which is
	Bist.
	Not: 1. The earliest time of the first node (event)
	is always set to be O. Ti (F) = D
. 2	Ladiest Time of the Last event in the project
	network gives the earliest time of completing
	the project.
	the state of the s
	The Latest Time (Latest Albibable Start Time)
11	The latest time of event i denoted by Till)
	is the latest time at which event i con occur
	without delaying the completion of the project. To
	atest time of a in the
(i)	each present n, proceed back was a through
AND THE RESERVE OF THE PARTY OF	The total a PNP of
(i)	Det the latest allows the
	Create legical to the
	Completion time. i.e Ta(1) = Tn(E).
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	Osa zuwa Emmanuel Osabotio m an

(ii) To compute the latest time for any event i (i In). Consider all activities leading from event i. The latest time is obtained by using Ji(L) = SMINSTICH - tis for 12i ×n-1 Consider this project netsork and calculate The parliest possible time. The latest possible time. Critical path [Using Nebsorks Diagram, Pg. 193 Using the formula: Tj (E) = Max of T; (E) + tij & T, (E) = 0 fwill always be 0] T, (E) = T, (E) + t, = 0+7 = 7 TRCE) = TI(E) + t1,3 = 0+1=1 T4 (E) = Max (T, (E) + T,4, T2 (E) + T34) = Max (0+2, 1+0) = 2 To(E) = Max (To(E) + to, 5, To(E) + tos = Max (7+6, 1+5) = 13(13,6) = 13 To(E) = Max (Ty(E) + ty,6, Ts(E) + ts,6) = Max (2+5, 13+4) = (7,12) = 17 Osazura Emmarel Osabboran

May 15th 2024 198. T2(E) = T(E) + t6,2 = 17 + 3 = 20Till) = Min(Till) - tis) Tn(D = Tn(E) => J(L) = 20 T6(1) = T2(1) - t67 = 20-3=17 To (4) = To(4) - to = 17-4 = 13 Ty(L) = Ts(L) - ty = 17-5 = 12 T2(4) = Min (T4(4) - +2,4, T5(4) - +2,5) = Min(12-0, 13-5) = Mix(12,8) = 8 Ta(1) = To(1) - t25 = 13-6=7 T, (4) = Min (T2(4) - t12, T3(4) - t13, T4(4) - t14) = Min(7-7, 8-1, 12-2) = Min(0, 7, 10) T, (4) = 0

frents	TI(E)	T; (4)	S, = T; (L) - T; (E)	Remark
	0	0	0	Critical
2	7	7	0	Critical
3	1	8	7	Non-Gibical
4	2	12	10	Non-Cribical
5	13	13	O	Critical
6	17	17	0	Critical
7	20	20	6	Critical

C	ntical	Path					
=	1-A	- 2 -	D 5	#	6	#	7

What is the total completion time: : A+D+F+H.

Practice Assignments Part of CA]

Ita Construct the network diagram

Job Predecessors Ruration

Rays

A None

B A 8

C A 8

P B; C 3

F A 10

200 May 15th 2024 140 Farliet possible time. (11) Latest allowable times (11) (ritical Path (IV) Total Completion Time Osazusa Immanuel Osalotioman