Experiment 4

<u>Aim</u>: Find out the Minimum Cost Spanning Tree using Kruskal's Algorithm with the help of the Greedy Approach.

4.1CO Attained: CO2 and CO4

4.2 Objective:

Kruskal's algorithm: Kruskal's algorithm finds the minimum spanning tree for a weighted connected graph G=(V,E) to get an acyclic sub graph with |V|-1 edges for which the sum of edge weights is the smallest.

4.3 Resources: Turbo c/Dev C++

4.4 Program Logic:

A minimum spanning tree (MST) or minimum weight spanning tree is a subset of the edges of a connected, edge-weighted undirected graph that connects all the vertices together, without any cycles and with the minimum possible total edge weight.

```
1 Algorithm Kruskal(E, cost, n,t)
2 // E is the set of edges in G.G has n vertices. cost [u, v] is the
3 // cost of edge (u,v). t is the set of edges in the minimum-cost
4 // spanning tree. The final cost is returned.
6 Construct a heap out of the edge costs using Heapify;
7 for i := 1 to n do parent[i]:=-1;
8 // Each vertex is in a different set.
9 i :=0: mincost:=0.0:
10 while ((i< n-1) and (heap not empty)) do
12 Delete a minimum cost edge(u,v) from the heap
13 and reheapify using Adjust;
14 j :=Find(u); k :=Find(w);
15 if (i != k) then
16 {
17 i: =i+1;
18 t [i, 1]:=u; t [i, 2]:=v;
19 mincost:=mincost+ cost[u, v];
20 Union(j,k);
21 }
22 }
23 if (i!=n -1) then write ("No spanning tree");
24 else return mincost;
```

4.5 **Procedure:**

1. Create: Open Dev C++/C and write a program after that save the program with the .c extension.

2. Compile: Alt + F9
3. Execute: Ctrl + F10

4.6 Program Code:

```
#include <stdio.h>
#include <conio.h>
#include <stdlib.h>
int i, j, k, a, b, u, v, n, ne = 1;
int min, mincost = 0, cost[9][9], parent[9];
int find(int);
int uni(int, int);
void main()
printf("Enter the no. of vertices:\n");
scanf("%d", &n);
printf("\nEnter the cost adjacency matrix:\n");
for (i = 1; i \le n; i++)
for (j = 1; j \le n; j++)
scanf("%d", &cost[i][j]);
   if (cost[i][j] == 0)
cost[i][j] = 999;
  }
printf("The edges of Minimum Cost Spanning Tree are\n");
```

```
while (ne < n)
  for (i = 1, min = 999; i \le n; i++)
   for (j = 1; j \le n; j++)
    if (cost[i][j] < min)
      min = cost[i][j];
      a = u = i;
      b = v = j;
     }}
  u = find(u);
  v = find(v);
  if (uni(u, v))
  {
printf("%d edge (%d,%d) =%d\n", ne++, a, b, min);
mincost += min;
  }
  cost[a][b] = cost[b][a] = 999;
printf("\nMinimum cost = %d\n", mincost);
getch();
int find(int i)
while (parent[i])
i = parent[i];
return i;
```

```
int uni(int i, int j)

{
    if (i != j)
    {
       parent[j] = i;
    return 1;
    }
    return 0;
}
```

4.7 Conclusion:

```
Implementation of Kruskal's algorithm
```

```
Enter the no. of vertices:7
Enter the cost adjacency matrix:
0 28 0 0 0 10 0
28 0 16 0 0 0 14
0 16 0 12 0 0 0
0 0 12 0 22 0 18
0 0 0 22 0 25 24
10 0 0 0 25 0 0
0 14 0 0 24 0 0
The edges of Minimum Cost Spanning Tree are
1 \text{ edge } (1,6) = 10
2 \text{ edge } (3,4) = 12
3 \text{ edge } (2,7) = 14
4 \text{ edge } (2,3) = 16
5 edge (4,5) =22
6 edge (5,6) =25
         Minimum cost = 99
```

4.8 Analysis:

The time complexity of Kruskal's Algorithm = O(ElogV) or O(ElogE). where e is the number of edges and v is the number of vertices.

4.9 <u>Lab Viva Questions:</u>

- 1. What is the time complexity of Kruskal's algorithm.
- 2. Define spanning tree.
- 3. Define minimum cost spanning tree.