

1 HeavyDS

1.1 Iterative

```

struct Data{
};

Data op(const Data &a, const Data &b){
}

struct segtree{
    vector<Data> d;
    int _n, log, size;
    unsigned int bit.ceil(unsigned int n) {
        unsigned int x = 1;
        while (x < (unsigned int)(n)) x <= 1;
        return x;
    }
    segtree(int n): _n(n) {
        size = (int)bit.ceil((unsigned int)(n));
        log = __builtin_ctz((unsigned int)size);
        d.resize(2*size, Data());
    }
    void update(int k) { d[k] = op(d[2*k],
        ↳ d[2*k+1]); }
    void set(int p, Data x) {
        p += size;
        d[p] = x;
        for (int i = 1; i <= log; i++) update(p >>
            ↳ i);
    }
    Data prod(int l, int r) { // !!! q(l,r) return
        ↳ l to r-1
        if (l == r) return Data();
        l += size;
        r += size;
        Data sml = Data(), smr = Data();
        while (l < r) {
            if (l&1) sml = op(sml, d[l++]);
            if (r&1) smr = op(d[--r], smr);
            l >= 1;
            r >= 1;
        }
        return op(sml, smr);
    }
};

```

1.2 Lazy

```

struct Min{
    int x;
    Min(int x = inf) : x(x) {}
};

Min operator+(const Min& a, const Min& b){
    return std::min(a.x, b.x);
}

void apply(int &a, int b){
    a += b;
}

void apply(Min& a, int b){

```

```

    a.x += b;
}

// Always make a class for them and define basic
// overloads
template<class Node, class Lazy, class Merge =
    std::plus<Node>>
struct LazySegTree {
    const int _n;
    const Merge _merge;
    std::vector<Node> _segT;
    std::vector<Lazy> _lazy;
    LazySegTree(int n) : _n(n), _merge(Merge()),
        ↳ _segT(4 << std::__lg(n)), _lazy(4 <<
        ↳ std::__lg(n)) {}
    LazySegTree(std::vector<Node> init) :
        ↳ LazySegTree(init.size()) {
        std::function<void(int, int, int)> build =
            [&](int node, int st, int en){
                if(en - st == 1){
                    _segT[node] = init[st];
                    return;
                }
                int md = (st + en) >> 1;
                build(node << 1, st, md);
                build(node << 1 | 1, md, en);
                pull(node);
            };
        build(1, 0, _n);
    }
    void pull(int node){
        _segT[node] = _merge(_segT[node << 1],
            ↳ _segT[node << 1 | 1]);
    }
    void apply(int node, const Lazy& lazy){
        ::apply(_segT[node], lazy);
        ::apply(_lazy[node], lazy);
    }
    void push(int node){
        apply(node << 1, _lazy[node]);
        apply(node << 1 | 1, _lazy[node]);
        _lazy[node] = Lazy();
    }
    void update(int node, int st, int en, int idx,
        ↳ const Node& nodeVal){
        if(en - st == 1){
            _segT[node] = nodeVal;
            return;
        }
        push(node);
        int md = (st + en) >> 1;
        if(idx < md){
            update(node << 1, st, md, idx,
                ↳ nodeVal);
        }
        else{
            update(node << 1 | 1, md, en, idx,
                ↳ nodeVal);
        }
        pull(node);
    }
    void update(int idx, const Node& nodeVal){
        update(1, 0, _n, idx, nodeVal);
    }
}

```

```

}

Node rangeQuery(int node, int st, int en, int
→ ql, int qr){
    if(st >= qr || en <= ql){
        return Node();
    }
    if(st >= ql && en <= qr){
        return _segT[node];
    }
    push(node);
    int md = (st + en) >> 1;
    return _merge(rangeQuery(node << 1, st, md,
→ ql, qr), rangeQuery(node << 1 | 1, md,
→ en, ql, qr));
}

Node rangeQuery(int ql, int qr){
    return rangeQuery(1, 0, _n, ql, qr);
}

void rangeApply(int node, int st, int en, int
→ ql, int qr, const Lazy& lazy){
    if(st >= qr || en <= ql){
        return;
    }
    if(st >= ql && en <= qr){
        apply(node, lazy);
        return;
    }
    push(node);
    int md = (st + en) >> 1;
    rangeApply(node << 1, st, md, ql, qr,
→ lazy);
    rangeApply(node << 1 | 1, md, en, ql, qr,
→ lazy);
    pull(node);
}

void rangeApply(int ql, int qr, const Lazy&
→ lazy){
    rangeApply(1, 0, _n, ql, qr, lazy);
}
};

// LazySegTree<Min, int> seg(a);
// For range [i, j] use i, j + 1

```

1.3 PersistentSegmentTree

```

struct PST{
    struct Node{
        int sum = 0;
        int l = 0, r = 0;
    };
    const int n;
    vector<Node> tree;
    int timer = 1;
    PST(int n, int mx_nodes) : n(n), tree(mx_nodes)
→ {}
    Node merge(int l, int r){
        return Node({tree[l].sum + tree[r].sum, l,
→ r});
    }
    int build(int st, int en, const vector<int>
→ &init){

```

```

        if(st == en){
            tree[timer] = Node({init[st], 0, 0});
            return timer++;
        }
        int md = (st + en) >> 1;
        tree[timer] = merge(build(st, md, init),
→ build(md + 1, en, init));
        return timer++;
    }
    int update(int root, int idx, int val, int st,
→ int en){
        if(st == en){
            tree[timer] = Node({val, 0, 0});
            return timer++;
        }
        int md = (st + en) >> 1;
        if(idx <= md){
            tree[timer] =
                → merge(update(tree[root].l, idx,
                → val, st, md), tree[root].r);
        }
        else{
            tree[timer] = merge(tree[root].l,
                → update(tree[root].r, idx, val, md +
                → 1, en));
        }
        return timer++;
    }
    int query(int root, int l, int r, int st, int
→ en){
        if(r < st || en < l) return 0;
        if(l <= st && en <= r) return
            → tree[root].sum;
        int md = (st + en) >> 1;
        return query(tree[root].l, l, r, st, md) +
            → query(tree[root].r, l, r, md + 1, en);
    }
    int build(const vector<int> &init){
        return build(0, n - 1, init);
    }
    int update(int root, int idx, int val){
        return update(root, idx, val, 0, n - 1);
    }
    int query(int root, int l, int r){
        return query(root, l, r, 0, n - 1);
    }
};

```

1.4 Fenwick_sum

```

struct FenwickTree {
    vector<int> bit; // binary indexed tree
    int n;
    FenwickTree(int n) {
        this->n = n;
        bit.assign(n, 0);
    }
    FenwickTree(vector<int> const &a) :
        → FenwickTree(a.size()) {
            for (size_t i = 0; i < a.size(); i++)
                add(i, a[i]);
    }
    void add(int i, int val){
        for (int j = i; j < n; j += j & -j)
            bit[j] += val;
    }
    int query(int i){
        int sum = 0;
        for (int j = i; j >= 0; j -= j & -j)
            sum += bit[j];
        return sum;
    }
};

```

```

    }
    int sum(int r) {
        int ret = 0;
        for (; r >= 0; r = (r & (r + 1)) - 1)
            ret += bit[r];
        return ret;
    }
    int sum(int l, int r) {
        return sum(r) - sum(l - 1);
    }
    void add(int idx, int delta) {
        for (; idx < n; idx = idx | (idx + 1))
            bit[idx] += delta;
    }
};

```

1.5 SparseTable

```

int log_floor(int x){
    return x ? __builtin_clzll(1) -
    ↵ __builtin_clzll(x) : -1 ;
}
template<typename T , class F = function<T(const
→ T&,const T&)>>
struct SPARSE_TABLE{
    int n;
    vector<vector<T>> st;
    F fun;
    SPARSE_TABLE(const vector<T> &v , const F &f) :
    ↵ fun(f){
        n = static_cast<int>(v.size());
        int maxN = log_floor(n) + 1;

        st.resize(maxN);
        st[0] = v;

        for(int i = 1; i < maxN; i++){
            st[i].resize(n - (1 << i) + 1);

            for(int j = 0; j + (1 << i) <= n;
            ↵ j++){
                st[i][j] = fun(st[i - 1][j] , st[i
                ↵ - 1][j + (1 << (i - 1))]);
            }
        }
    }
    T get(int l, int r){
        int h = log_floor(r - l + 1);
        // works for idempotent functions only ykw
        return fun(st[h][l] , st[h][r - (1 << h) +
        ↵ 1]);
    }
};

```

1.6 MergeSortTree

```

template <typename T>
struct MergeSortTree {
    int n;
    vector<vector<T>> tree;

```

```

// Constructor: builds the tree from input
→ vector a
MergeSortTree(const vector<T>& a) {
    n = a.size();
    tree.resize(4 * n);
    build(1, 0, n - 1, a);
}

void build(int node, int start, int end, const
→ vector<T>& a) {
    if (start == end) {
        tree[node] = {a[start]};
        return;
    }
    int mid = (start + end) / 2;
    build(2 * node, start, mid, a);
    build(2 * node + 1, mid + 1, end, a);

    // Merge two sorted vectors
    merge(tree[2 * node].begin(), tree[2 *
    ↵ node].end(),
    ↵ tree[2 * node + 1].begin(), tree[2 *
    ↵ node + 1].end(),
    ↵ back_inserter(tree[node]));
}

// Internal query function for Lower Bound
→ (smallest value >= x)
T query_lb(int node, int start, int end, int l,
→ int r, T x) {
    if (start > end || start > r || end < l)
        return numeric_limits<T>::max(); // ← Return INF

    if (start >= l && end <= r) {
        auto it =
        ↵ lower_bound(tree[node].begin(),
        ↵ tree[node].end(), x);
        if (it != tree[node].end())
            return *it;
        return numeric_limits<T>::max();
    }

    int mid = (start + end) / 2;
    return min(query_lb(2 * node, start, mid,
    ↵ l, r, x),
    ↵ query_lb(2 * node + 1, mid + 1,
    ↵ end, l, r, x));
}

// Internal query function for Count (number
→ of elements <= x)
int query_count(int node, int start, int end,
→ int l, int r, T x) {
    if (start > end || start > r || end < l)
        return 0;

    if (start >= l && end <= r) {
        // upper_bound gives first element > x,
        ↵ so index gives count of elements
        ↵ <= x
    }
}
```

```

        return upper_bound(tree[node].begin(),
    ↵ tree[node].end(), x) -
    ↵ tree[node].begin();
}

int mid = (start + end) / 2;
return query_count(2 * node, start, mid, l,
    ↵ r, x) +
    ↵ query_count(2 * node + 1, mid + 1,
    ↵ end, l, r, x);
}

// Public Interface: Find smallest number >= x
// in range [l, r]
T lower_bound_val(int l, int r, T x) {
    return query_lb(1, 0, n - 1, l, r, x);
}

// Public Interface: Count numbers <= x in
// range [l, r]
int count_less_equal(int l, int r, T x) {
    return query_count(1, 0, n - 1, l, r, x);
}
};

```

1.7 PolyMul

```

namespace GetPrimitive{
    vi Divisors;
    vi Divisor(lli x){vi ans;
        for(lli i=2;i*i<=x;i++){
            ↵ if(x%i==0){ans.EB(i);while(x%i==0)x/=i;}
        }
        if(x>1)ans.EB(x);return ans;
    }
    bool check(int prim,int p,vi &divs){
        for(auto v:divs){
            if(binpow(prim,(p-1)/v,p)==1)return 0;
        }return 1;
    }
    int getRoot(int p){
        int ans=2;vi divs=Divisor(p-1);
        while(!check(ans,p,divs))ans++;
        return ans;
    }
};

//7340033      5
//998244353    3
const lli MAXB = 1 << 21;
using polybase = lli;
polybase A[MAXB], B[MAXB], C[MAXB];
template<lli NTTMOD,lli PRIMITIVE_ROOT> struct
    ↵ POLYMULT{
        lli modInv(lli a) { return a <= 1 ? a : (long
    ↵ long) (NTTMOD - NTTMOD / a) *
    ↵ modInv(NTTMOD % a) % NTTMOD; }
        void NTT(polybase P[], lli n, lli oper) {
            for(int i=1,j=0;i<n-1;i++){
                for(int s=n;j^=s>>=1,~j&s;){
                    if(i<j)swap(P[i],P[j]);
                }
            }
        }
        int upper_bound(polybase l, polybase r, lli
    ↵ start, lli end, lli x) {
            return query_count(2 * node, start, mid, l,
    ↵ r, x) -
    ↵ tree[node].begin();
        }
        int mid = (start + end) / 2;
        return query_count(2 * node, start, mid, l,
    ↵ r, x) +
    ↵ query_count(2 * node + 1, mid + 1,
    ↵ end, l, r, x);
    }

    // Public Interface: Find smallest number >= x
    // in range [l, r]
    T lower_bound_val(int l, int r, T x) {
        return query_lb(1, 0, n - 1, l, r, x);
    }

    // Public Interface: Count numbers <= x in
    // range [l, r]
    int count_less_equal(int l, int r, T x) {
        return query_count(1, 0, n - 1, l, r, x);
    }
};

```

```

for(int d=0;(1<<d)<n;d++){
    int m=1<<d,m2=m*2;
    lli
    ↵ unit_p0::=binpow(PRIMITIVE_ROOT,(NTTMOD-1));
    if(oper<0)unit_p0=modInv(unit_p0);
    for(int i=0;i<n;i+= m2) {
        polybase unit = 1;
        for (int j = 0; j < m; j++) {
            polybase &P1 = P[i + j + m], &P2 = P[i
    ↵ + j];
            polybase t = unit * P1 % NTTMOD;
            P1 = (P2 - t + NTTMOD) % NTTMOD; P2 =
    ↵ (P2 + t) % NTTMOD;
            unit = unit * unit_p0 % NTTMOD;
        }
    }
}
vector<polybase> mul(const vector<polybase> &a,
    ↵ const vector<polybase> &b) {
    vector<polybase> ret(max(0LL, (lli)
    ↵ a.size() + (lli)b.size() - 1), 0);
    int len = 1; while (len < (lli)ret.size())
    ↵ len <<= 1;
    for (int i = 0; i < len; i++) A[i] = i <
    ↵ (int)a.size() ? a[i] : 0;
    for (int i = 0; i < len; i++) B[i] = i <
    ↵ (int)b.size() ? b[i] : 0;
    NTT(A, len, 1); NTT(B, len, 1);
    for (lli i = 0; i < len; i++) C[i] =
    ↵ (polybase) A[i] * B[i] % NTTMOD;
    NTT(C, len, -1); for (lli i = 0, inv =
    ↵ modInv(len); i < (lli)ret.size(); i++)
    ↵ ret[i] = (long long) C[i] * inv %
    ↵ NTTMOD;
    return ret;
}
vi binpow(vi b,lli p){
    vi ans=vi(1,1);
    for(;p;p>>=1){
        if(p&1)ans=mul(ans,b);
        b=mul(b,b);
    }
    return ans;
}
vi calc(vi &arr,int l,int r){
    if(l==r){
        //base case;
        return {};
    }
    int mid=(l+r)>>1;
    vi x=calc(arr,l,mid),y=calc(arr,mid+1,r);
    return mul(x,y);
}
POLYMULT<998244353,3> ntt;

lli phi(lli x){// will be a power of 2 mostly.
    if(x==1)return 1;
    else return x/2;
}

```

```

vi arr[20];
void solve(){
    lli n,k,q;
    arr[1].assign(100001,0);
    cin>>n>>k;
    vi divs;
    lli cur=1;
    while(n%cur==0){
        divs.EB(cur);
        cur*=2;
    }
    fr(i,k){
        lli x;cin>>x;arr[1][x]++;
    }
    rep(i,2,19){
        arr[i]=ntt.mul(arr[i-1],arr[i-1]);
        if(arr[i].size()>100001)arr[i].resize(100001);
    }
    sort(all(divs));
    cin>>q;
    fr(_i,q){
        lli S;cin>>S;
        lli ans=0;
        for(int i=0;i<divs.size();i++){
            if(S%(n/divs[i])!=0)continue;
            ans=(ans+arr[i+1][S/(n/divs[i])]*phi(n/divs[i]))%MOD;
        }
        ans=ans*binpow(n,MOD-2,MOD)%MOD;
        cout<<ans<<endl;
    }
}

// youKnowWho's FFT
using cd = complex<double>;
const double PI = acos(-1);

void fft(vector<cd> & a, bool invert) {
    int n = a.size();
    for (int i = 1, j = 0; i < n; i++) {
        int bit = n >> 1;
        for (; j & bit; bit >>= 1) j ^= bit;
        if (i < j) swap(a[i], a[j]);
    }
    for (int len = 2; len <= n; len <= 1) {
        double ang = 2 * PI / len * (invert ? -1 : 1);
        cd wlen(cos(ang), sin(ang));
        for (int i = 0; i < n; i += len) {
            cd w(1);
            for (int j = 0; j < len / 2; j++) {
                cd u = a[i+j], v = a[i+j+len/2] *
                    w;
                a[i+j] = u + v;
                a[i+j+len/2] = u - v;
                w *= wlen;
            }
        }
    }
    if (invert) {
}
}

```

```

        for (cd & x : a) x /= n;
    }
}
vector<int> multiply(vector<int> const& a, int n)
{
    vector<cd> fa(n);
    for (int i = 0; i < (int)a.size(); i++) {
        fa[i] = a[i];
    }
    for (int i = a.size(); i < n; i++) {
        fa[i] = 0;
    }
    fft(fa, false);
    for (int i = 0; i < n; i++) {
        fa[i] *= fa[i];
    }
    fft(fa, true);

    vector<int> res(n);
    for (int i = 0; i < n; i++) {
        res[i] = round(fa[i].real());
    }
    return res;
}

vector<int> p(MAXN);
void solve(){
    int n; cin>>n;
    n=n%MOD, 1;
    vector<int> s(n + 1);
    for (int i = 1; i <= n; i++) {
        cin>>s[i];
        mx = max(mx, s[i]);
    }
    mx += 1000;
    for (int i = 1; i <= n; i++) {
        p[s[i]] = 1;
    }

    n = 1;
    while (n <= MAXN) {
        n <= 1;
    }
    vector<int> res = multiply(p, n);
    // dbg(res);

    int c = 0;
    for (int i = 2; i <= 2 * mx; i += 2) {
        int md = i / 2;
        if (p[md]){
            c += (res[i] - 1) / 2;
        }
    }
    cout<<c<<endl;
}

```

1.8 FWT

Given two arrays \$A\$ and \$B\$ of size \$n = 2^k\$,
 compute an array \$C\$ such that



```

C[x] = sum_{i} substack{j} A[i] B[j].
}

template <typename T>
struct FWT {

    // ===== XOR =====
    void fwt_xor(T a[], int n) {
        for (int d = 1; d < n; d <= 1) {
            for (int i = 0; i < n; i += (d << 1))
                for (int j = 0; j < d; j++) {
                    T x = a[i + j];
                    T y = a[i + j + d];
                    a[i + j] = x + y;
                    a[i + j + d] = x - y;
                }
        }
    }

    void ufwt_xor(T a[], int n) {
        for (int d = 1; d < n; d <= 1) {
            for (int i = 0; i < n; i += (d << 1))
                for (int j = 0; j < d; j++) {
                    T x = a[i + j];
                    T y = a[i + j + d];
                    a[i + j] = (x + y) >> 1;
                    a[i + j + d] = (x - y) >> 1;
                }
        }
    }

    // ===== AND =====
    void fwt_and(T a[], int n) {
        for (int d = 1; d < n; d <= 1) {
            for (int i = 0; i < n; i += (d << 1))
                for (int j = 0; j < d; j++)
                    a[i + j] += a[i + j + d];
        }
    }

    void ufwt_and(T a[], int n) {
        for (int d = 1; d < n; d <= 1) {
            for (int i = 0; i < n; i += (d << 1))
                for (int j = 0; j < d; j++)
                    a[i + j] -= a[i + j + d];
        }
    }

    // ===== OR =====
    void fwt_or(T a[], int n) {
        for (int d = 1; d < n; d <= 1) {
}

```

```

            for (int i = 0; i < n; i += (d << 1))
                for (int j = 0; j < d; j++)
                    a[i + j + d] += a[i + j];
        }
    }

    void ufwt_or(T a[], int n) {
        for (int d = 1; d < n; d <= 1) {
            for (int i = 0; i < n; i += (d << 1))
                for (int j = 0; j < d; j++)
                    a[i + j + d] -= a[i + j];
        }
    }

    // ===== CONVOLUTIONS =====
    void xor_convolution(T a[], T b[], int n) {
        fwt_xor(a, n);
        fwt_xor(b, n);
        for (int i = 0; i < n; i++) a[i] *= b[i];
        ufwt_xor(a, n);
    }

    void and_convolution(T a[], T b[], int n) {
        fwt_and(a, n);
        fwt_and(b, n);
        for (int i = 0; i < n; i++) a[i] *= b[i];
        ufwt_and(a, n);
    }

    void or_convolution(T a[], T b[], int n) {
        fwt_or(a, n);
        fwt_or(b, n);
        for (int i = 0; i < n; i++) a[i] *= b[i];
        ufwt_or(a, n);
    }
};

```

2 Graphs

2.1 Dinic

```

template<class T>
struct Flow {
    const int n;
    struct Edge {
        int to;
        T cap;
        Edge(int to, T cap) : to(to), cap(cap) {}
    };
    std::vector<Edge> e;
    std::vector<std::vector<int>> g;
    std::vector<int> cur, h;
    Flow(int n) : n(n), g(n) {}

    bool bfs(int s, int t) {
}

```

```

    h.assign(n, -1);
    std::queue<int> que;
    h[s] = 0;
    que.push(s);
    while (!que.empty()) {
        const int u = que.front();
        que.pop();
        for (int i : g[u]) {
            auto [v, c] = e[i];
            if (c > 0 && h[v] == -1) {
                h[v] = h[u] + 1;
                if (v == t) {
                    return true;
                }
                que.push(v);
            }
        }
    }
    return false;
}

T dfs(int u, int t, T f) {
    if (u == t) {
        return f;
    }
    auto r = f;
    for (int &i = cur[u]; i <
         (int)(g[u].size()); ++i) {
        const int j = g[u][i];
        auto [v, c] = e[j];
        if (c > 0 && h[v] == h[u] + 1) {
            auto a = dfs(v, t, std::min(r,
                c));
            e[j].cap -= a;
            e[j ^ 1].cap += a;
            r -= a;
            if (r == 0) {
                return f;
            }
        }
    }
    return f - r;
}
void addEdge(int u, int v, T c) {
    g[u].push_back(e.size());
    e.emplace_back(v, c);
    g[v].push_back(e.size());
    e.emplace_back(u, 0);
}
T maxFlow(int s, int t) {
    T ans = 0;
    while (bfs(s, t)) {
        cur.assign(n, 0);
        ans += dfs(s, t,
            std::numeric_limits<T>::max());
    }
    return ans;
}
void get(int end){
    vector<int> path;
    cur.assign(n, 0);
    int u = 1;
    while(u != end){
        path.push_back(u);
        dbg(path)
        for (int &i = cur[u]; i <
             (int)(g[u].size()); ++i) {
            const int j = g[u][i];
            auto [v, c] = e[j];
            dbg(u, v, c, j)
            if (j % 2 == 0 && c == 0) {
                e[j].cap = 1;
                u = v;
                break;
            }
        }
    }
    path.push_back(end);
    cout<<path.size()<<endl;
    for(int i : path) cout<<i<<" ";
    cout<<endl;
}
};

queue<int> q;
vector<bool> vis(n + 1, false);
q.push(1);
vis[1] = true;
while(!q.empty()){
    int u = q.front(); q.pop();
    for(auto i: mf.g[u]){
        auto [v, c] = mf.e[i];
        if(c > 0 && !vis[v]){
            vis[v] = true;
            q.push(v);
        }
    }
}
for(int i = 1; i <= n; i++){
    for(auto id : mf.g[i]){
        auto [v, c] = mf.e[id];
        if(v != s and c == 0){
            cout<<i<<" "<<v - n<<endl;
        }
    }
}
}

```

2.2 LCA

```

// LCA and Binary Lifting
void dfs(int v, int p){
    up[0][v] = p;
    for(int i = 1; i < 20; i++){
        up[i][v] = up[i - 1][up[i - 1][v]];
    }
    for(auto x : g[v]){
        if(x == p) continue;
        dst[x] = dst[v] + 1;
        dfs(x, v);
    }
}
auto lca = [&](int x, int y){
    if(dst[x] < dst[y]) swap(x, y);
    for(int i = 19; i >= 0; i --){

```

```

        if(dst[up[i][x]] >= dst[y]){
            x = up[i][x];
        }
    }
    if(x == y) return x;
    for(int i = 19; i >= 0; i --){
        if(up[i][x] != up[i][y]){
            x = up[i][x];
            y = up[i][y];
        }
    }
    return up[0][x];
}

```

2.3 CutPoint

```

vll g[NUM];
bool vis[NUM];
ll in[NUM];
ll low[NUM];
int timer = 0;

void CutPoints(ll src, ll parent = -1)
{
    vis[src] = true;
    in[src] = low[src] = timer;
    timer++;
    int children = 0;
    for (auto child : g[src])
    {
        if (child == parent)
            continue;
        if (vis[child])
        {
            low[src] = min(low[src], in[child]);
        }
        else
        {
            CutPoints(child, src);
            low[src] = min(low[src], low[child]);
            if (low[child] >= in[src] &&
                parent!=-1)
            {
                // Src is a cut point!
                // CAUTION: Might get called
                // multiple times due to
                // satisfiability of multiple
                // children
            }
            children++;
        }
    }
    if (parent== -1 && children>1){
        // Root is a cut point!
        // used children instead of size of adj
        // bcoz we dont use back edges
    }
}

```

2.4 CentroidDecomp

```

int nn;
void dfs1(int u, int p)
{
    sub[u] = 1;
    nn++;
    for (auto it = g[u].begin(); it != g[u].end();
        → it++)
        if (*it != p)
        {
            dfs1(*it, u);
            sub[u] += sub[*it];
        }
}
int dfs2(int u, int p)
{
    for (auto it = g[u].begin(); it != g[u].end();
        → it++)
        if (*it != p && sub[*it] > nn / 2)
            return dfs2(*it, u);
    return u;
}
void decompose(int root, int p)
{
    nn = 0;
    dfs1(root, root);
    int centroid = dfs2(root, root);
    if (p == -1)
        p = centroid;
    par[centroid] = p;
    for (auto it = g[centroid].begin(); it !=
        → g[centroid].end(); it++)
    {
        g[*it].erase(centroid);
        decompose(*it, centroid);
    }
    g[centroid].clear();
}

```

2.5 VirtualTree

```

const int MAXN = 200005;

// --- PREREQUISITES (LCA & DFS Times) ---
vector<int> adj[MAXN];
int tin[MAXN], tout[MAXN], timer;
int up[MAXN][20], depth[MAXN];

void dfs_lca(int u, int p, int d) {
    tin[u] = ++timer;
    depth[u] = d;
    up[u][0] = p;
    for (int i = 1; i < 20; i++)
        up[u][i] = up[up[u][i-1]][i-1];

    for (int v : adj[u]) {
        if (v != p) dfs_lca(v, u, d + 1);
    }
    tout[u] = timer;
}

```

```

bool is_ancestor(int u, int v) {
    return tin[u] <= tin[v] && tout[u] >= tout[v];
}

int lca(int u, int v) {
    if (is_ancestor(u, v)) return u;
    if (is_ancestor(v, u)) return v;
    for (int i = 19; i >= 0; i--) {
        if (!is_ancestor(up[u][i], v))
            u = up[u][i];
    }
    return up[u][0];
}

// --- VIRTUAL TREE TEMPLATE ---
vector<int> vt_adj[MAXN]; // Adjacency list for
// Virtual Tree

// Sorts nodes by DFS entry time (Critical for
// construction)
bool compare_tin(int a, int b) {
    return tin[a] < tin[b];
}

void build_virtual_tree(vector<int>& nodes) {
    // 1. Sort by DFS entry time
    sort(nodes.begin(), nodes.end(), compare_tin);

    // 2. Add LCAs of adjacent sorted nodes to the
    // set
    // This guarantees all necessary connecting
    // nodes are present
    int k = nodes.size();
    for (int i = 0; i < k - 1; i++) {
        nodes.push_back(lca(nodes[i],
        // nodes[i+1]));
    }

    // 3. Sort again and remove duplicates
    sort(nodes.begin(), nodes.end(), compare_tin);
    nodes.erase(unique(nodes.begin(), nodes.end()),
    // nodes.end());
}

// 4. Build edges using a stack
// Clear previous virtual tree edges for these
// specific nodes
for (int u : nodes) vt_adj[u].clear();

vector<int> stack;
stack.push_back(nodes[0]);

for (int i = 1; i < nodes.size(); i++) {
    int u = nodes[i];
    // Pop stack while the top is NOT an
    // ancestor of u
    // (This means we finished the subtree of
    // stack.back())
    while (stack.size() > 1 &&
    // !is_ancestor(stack.back(), u)) {
        stack.pop_back();
    }
    // Add edge from the current direct
    // ancestor to u
}

```

```

// Note: The graph is directed downwards
// usually, or undirected depending on
// need
vt_adj[stack.back()].push_back(u);
vt_adj[u].push_back(stack.back()); // Add
// this if undirected

stack.push_back(u);
}
}

```

2.6 Centroid

```

function<void(int, int)> dfs2 = [&](int v, int p){
    int mx = 0;
    for(auto u: g[v]){
        if(u == p || vis[u]) continue;
        mx = max(mx, sbt[u]);
    }
    mx = max(mx, n - sbt[v]);
    if(mx <= n / 2){
        centroid = v;
    }
    for(auto u: g[v]){
        if(u == p || vis[u]) continue;
        dfs2(u, v);
    }
};

```

2.7 Mcmf

```

using i64 = long long;
template<class T>
struct MinCostFlow {
    struct _Edge {
        int to;
        T cap;
        T cost;
        _Edge(int to_, T cap_, T cost_) : to(to_), 
        // cap(cap_), cost(cost_) {}
    };
    int n;
    std::vector<_Edge> e;
    std::vector<std::vector<int>> g;
    std::vector<T> h, dis;
    std::vector<int> pre;
    bool dijkstra(int s, int t) {
        dis.assign(n,
        // std::numeric_limits<T>::max());
        pre.assign(n, -1);
        std::priority_queue<std::pair<T, int>,
        // std::vector<std::pair<T, int>>,
        // std::greater<std::pair<T, int>>> que;
        dis[s] = 0;
        que.emplace(0, s);
        while (!que.empty()) {
            T d = que.top().first;
            int u = que.top().second;
            que.pop();
            if (dis[u] != d) {
                continue;
            }
            for (auto v: g[u]) {
                if (dis[v] >= dis[u] + v->cost) {
                    dis[v] = dis[u] + v->cost;
                    pre[v] = u;
                    que.emplace(dis[v], v);
                }
            }
        }
    }
};

```

```

    }
    for (int i : g[u]) {
        int v = e[i].to;
        T cap = e[i].cap;
        T cost = e[i].cost;
        if (cap > 0 && dis[v] > d + h[u] -
            → h[v] + cost) {
            dis[v] = d + h[u] - h[v] +
            → cost;
            pre[v] = i;
            que.emplace(dis[v], v);
        }
    }
}
return dis[t] !=
→ std::numeric_limits<T>::max();
}

MinCostFlow() {}
MinCostFlow(int n_) {
    init(n_);
}
void init(int n_) {
    n = n_;
    e.clear();
    g.assign(n, {});
}
void addEdge(int u, int v, T cap, T cost) {
    g[u].push_back(e.size());
    e.emplace_back(v, cap, cost);
    g[v].push_back(e.size());
    e.emplace_back(u, 0, -cost);
}
std::pair<T, T> flow(int s, int t) {
    T flow = 0;
    T cost = 0;
    h.assign(n, 0);
    while (dijkstra(s, t)) {
        for (int i = 0; i < n; ++i) {
            h[i] += dis[i];
        }
        T aug =
            → std::numeric_limits<int>::max();
        for (int i = t; i != s; i = e[pre[i] ^
            → 1].to) {
            aug = std::min(aug,
            → e[pre[i]].cap);
        }
        for (int i = t; i != s; i = e[pre[i] ^
            → 1].to) {
            e[pre[i]].cap -= aug;
            e[pre[i] ^ 1].cap += aug;
        }
        flow += aug;
        cost += aug * h[t];
    }
    return std::make_pair(flow, cost);
}

struct Edge {
    int from;
    int to;
    T cap;
    T cost;
    T flow;
}

```

```

    };
    std::vector<Edge> edges() {
        std::vector<Edge> a;
        for (int i = 0; i < e.size(); i += 2) {
            Edge x;
            x.from = e[i + 1].to;
            x.to = e[i].to;
            x.cap = e[i].cap + e[i + 1].cap;
            x.cost = e[i].cost;
            x.flow = e[i + 1].cap;
            a.push_back(x);
        }
        return a;
    }
};

```

2.8 Hld

```

struct hld {
    vector<vector<int>> g;
    vector<int> par, dpth, heavy, root, pos, subt,
    → inv;
    vector<vector<int>> up;
    segtree seg;
    int cur_pos = 0;
    hld(int n){
        g.resize(n + 1), par.resize(n + 1),
        → dpth.resize(n + 1);
        heavy.resize(n + 1, -1), root.resize(n +
        → 1), pos.resize(n + 1), inv.resize(n +
        → 1);
        subt.resize(n + 1, 1);
        up.resize(n + 1);
        for(int i = 0; i <= n; i ++){
            up[i].resize(20, 0);
        }
        seg = segtree(n + 1);
        cur_pos = 0;
    }
    void add_edge(int u, int v){
        g[u].push_back(v);
        g[v].push_back(u);
    }
    void run(int rt){
        dfs_sz(rt, 0);
        dfs_hld(rt, rt);
    }
    int dfs_sz(int v, int p){
        int sz = 1, mx_sz = 0;
        par[v] = p;
        up[v][0] = p;
        for(int i = 1; i < 20; i ++){
            up[v][i] = up[up[v][i - 1]][i - 1];
        }
        for(auto x : g[v]){
            if(x == p) continue;
            dpth[x] = dpth[v] + 1;
            int c_sz = dfs_sz(x, v);
            sz += c_sz;
            if(c_sz > mx_sz){
                mx_sz = c_sz;
            }
        }
    }
}
```

```

        heavy[v] = x;
    }
}
return subt[v] = sz;
}

void dfs_hld(int v, int h){
    root[v] = h;
    pos[v] = cur_pos, inv[cur_pos] = v;
    cur_pos++;
    if(heavy[v] != -1) dfs_hld(heavy[v], h);
    for(auto x : g[v]){
        if(x == par[v] || x == heavy[v])
            continue;
        dfs_hld(x, x);
    }
}

bool is_anc(int a, int b) {
    return pos[a] <= pos[b] && pos[b] < pos[a]
        + subt[a];
}

int kth(int v, int k) {
    for (int i = 0; i < 20; i++) {
        if (k & (1 << i)) {
            v = up[v][i];
        }
    }
    return v;
}

int hehe(int v, int u) {
    // u is ancestor of v
    int dif = dpth[v] - dpth[u] - 1;
    return kth(v, dif);
}

mint qry(int a, int b) {
    mint res = 0;
    for (; root[a] != root[b]; b =
        par[root[b]]) {
        if (dpth[root[a]] > dpth[root[b]])
            swap(a, b);
        mint cur_heavy_path_max =
            seg.prod(pos[root[b]], pos[b] +
            1).x;
        res += cur_heavy_path_max;
    }
    if (dpth[a] > dpth[b])
        swap(a, b);
    mint last_heavy_path_max = seg.prod(pos[a],
        pos[b] + 1).x;
    res += last_heavy_path_max;
    return res;
}
};

```

2.9 Euler

```

// Hierholzer's Algorithm undirected
// check remove the seen for directed
void dfs(int node) {
    while (!g[node].empty()) {
        auto [son, idx] = g[node].back();
        g[node].pop_back();
        if (seen[idx]) { continue; }

```

```

        seen[idx] = true;
        dfs(son);
    }
    path.push_back(node);
}
for (int node = 0; node < n; node++) {
    if (degree[node] % 2) {
        cout << "IMPOSSIBLE" << endl;
        return 0;
    }
}
dfs(0);
if (path.size() != m + 1) {
    cout << "IMPOSSIBLE";
}

```

2.10 Kosaraju

```

vector<int> g[n + 1], rg[n + 1];
for(auto [x, y, w] : edgs){
    g[x].push_back(y);
    rg[y].push_back(x);
}
vector<int> order;
vector<int> vis(n + 1, -1);
function<void(int)> dfs = [&](int v){
    vis[v] = 1;
    for(auto x : g[v]){
        if(vis[x] == -1) dfs(x);
    }
    order.push_back(v);
};
for(int i = 1; i <= n; i++) if(vis[i] == -1)
    dfs(i);
reverse(al(order));
int idx = 1;
for(int i = 1; i <= n; i++) vis[i] = -1;
function<void(int, vector<int>&)> dfs2 = [&](int v,
    vector<int>& cmp){
    vis[v] = 1;
    for(auto x : rg[v]){
        if(vis[x] == -1) dfs2(x, cmp);
    }
    cmp.push_back(v);
};
vector<int> dag(n + 1, -1);
for(auto x : order){
    if(vis[x] == -1){
        vector<int> cmp;
        dfs2(x, cmp);
        for(auto y : cmp) dag[y] = idx;
        idx++;
    }
}
set<int> ng[idx], idg(idx, 0);
for(int i = 1; i <= n; i++){
    for(auto x : g[i]){
        if(dag[x] != dag[i]){
            ng[dag[i]].insert(dag[x]);
        }
    }
}

```

```

}
for(int i = 1; i < idx; i ++){
    for(auto x : ng[i]) idg[x]++;
}
queue<int> q;
vector<int> dp(idx, 0);
for(int i = 1; i < idx; i ++){
    if(idg[i] == 0){
        q.push(i);
        dp[i] = 1;
    }
}
while(!q.empty()){
    auto v = q.front(); q.pop();
    for(auto x : ng[v]){
        idg[x]--;
        dp[x] = max(dp[x], dp[v] + 1);
        if(!idg[x]) q.push(x);
    }
}

```

2.11 Bridges

```

// Bridges
vector<int> tin(n + 1, -1), low(n + 1, -1), vis(n +
→ 1, 0);
int clk = 0;
vector<pair<int, int>> ans;
function<void(int, int)> dfs = [&](int v, int p){
    vis[v] = 1;
    tin[v] = low[v] = clk++;
    for(auto x : g[v]){
        if(x == p) continue;
        if(!vis[x]){
            dfs(x, v);
            low[v] = min(low[v], low[x]);
            if(low[x] > tin[v]){
                ans.push_back({v, x});
            }
        }
    }
};

for(int i = 1; i <= n; i ++){
    if(!vis[i]){
        dfs(i, -1);
    }
}

// Articulation Points
function<void(int, int)> dfs = [&](int v, int p){
    vis[v] = 1;
    tin[v] = low[v] = clk++;
    int c = 0;
    for(auto x : g[v]){
        if(x == p) continue;
        if(vis[x]){
            low[v] = min(low[v], tin[x]);
        } else{
            dfs(x, v);
            low[v] = min(low[v], low[x]);
            if(low[x] >= tin[v] && p != -1){

```

```

                ans.insert(v);
            }
            c++;
        }
    }
    if(c > 1 && p == -1){
        ans.insert(v);
    }
};

for(int i = 1; i <= n; i ++){
    if(!vis[i]){
        dfs(i, -1);
    }
}

```

2.12 Toposort

```

vector<int> topoSort(const vector<vector<int>>& gr)
→ {
vector<int> indeg(n), q;
for (auto& li : gr) for (int x : li) indeg[x]++;
rep(i, 0, n) if (indeg[i] == 0) q.push_back(i);
rep(j, 0, sz(q)) for (int x : gr[q[j]]) if (--indeg[x] == 0) q.push_back(x);
return q;
}

```

2.13 Distances

```

// Bellman Ford
vector<int> d(n, INF);
d[v] = 0;
for (int i = 0; i < n - 1; ++i)
    for (Edge e : edges)
        if (d[e.a] < INF)
            d[e.b] = min(d[e.b], d[e.a] +
→ e.cost);

// Dijkstra Algorithm
void dijkstra(int s, vector<int> & d, vector<int>
→ & p) {
    int n = adj.size();
    d.assign(n, INF);
    p.assign(n, -1);

    d[s] = 0;
    using pii = pair<int, int>;
    priority_queue<pii, vector<pii>, greater<pii>>
→ q;
    q.push({0, s});
    while (!q.empty()) {
        int v = q.top().second;
        int d_v = q.top().first;
        q.pop();
        if (d_v != d[v])
            continue;

        for (auto edge : adj[v]) {

```

```

        int to = edge.first;
        int len = edge.second;

        if (d[v] + len < d[to]) {
            d[to] = d[v] + len;
            p[to] = v;
            q.push({d[to], to});
        }
    }
}

// Floyd Warshall
for (int k = 0; k < n; ++k) {
    for (int i = 0; i < n; ++i) {
        for (int j = 0; j < n; ++j) {
            if (d[i][k] < INF && d[k][j] < INF)
                d[i][j] = min(d[i][j], d[i][k] +
                               d[k][j]);
        }
    }
}

```

3 Misc

3.1 Dsu_dynconn

```

struct dsu_state{
    int v, u, rnk_v, rnk_u;
    dsu_state() {}
    dsu_state(int v, int u, int rnk_v, int rnk_u)
        : v(v), u(u), rnk_v(rnk_v), rnk_u(rnk_u)
        {}
};

struct dsuRoll{
    vector<int> par, rnk;
    stack<dsu_state> st;
    int comps;
    dsuRoll() {}
    dsuRoll(int n){
        par.resize(n + 1), rnk.resize(n + 1, 0);
        for(int i = 1; i <= n; i ++){
            par[i] = i;
            rnk[i] = 0;
        }
        comps = n;
    }
    int find(int v){
        return (v == par[v]) ? v : find(par[v]);
    }
    bool unite(int x, int y){
        x = find(x), y = find(y);
        if(x == y) return false;
        if(rnk[x] > rnk[y]) swap(x, y);
        st.push(dsu_state(x, y, rnk[x], rnk[y]));
        par[x] = y;
        if(rnk[x] == rnk[y]) rnk[y]++;
        comps--;
        return true;
    }
}

```

```

void rollback(){
    if(st.empty()) return;
    auto cur = st.top(); st.pop();
    comps++;
    par[cur.v] = cur.v;
    par[cur.u] = cur.u;
    rnk[cur.v] = cur.rnk_v;
    rnk[cur.u] = cur.rnk_u;
}
};

struct qry{
    int v, u;
    bool f;
    qry() {}
    qry(int v, int u) : v(v), u(u) {}
};

struct dynCon{
    int n, sz;
    vector<vector<qry>> seg;
    dsuRoll dsu;
    dynCon(int _n, int _q) : n(_n), sz(_q) {
        dsu = dsuRoll(_n);
        seg.resize(4 * _q + 5);
    }
    void add(int idx, int st, int en, int ql, int qr, qry& q){
        if(st > qr || en < ql) return;
        if(st >= ql && en <= qr){
            seg[idx].push_back(q);
            return;
        }
        int md = (st + en) >> 1;
        add(idx << 1, st, md, ql, min(qr, md), q);
        add(idx << 1 | 1, md + 1, en, max(md + 1, qr), qr, q);
    }
    void add(int l, int r, qry q){
        add(1, 0, sz, l, r, q);
    }
    void run(int v, int l, int r, vector<int>& ans){
        for(auto &q : seg[v]) q.f = dsu.unite(q.v, q.u);
        if(l == r) /* do something */
        else{
            int md = (l + r) >> 1;
            run(v << 1, l, md, ans);
            run(v << 1 | 1, md + 1, r, ans);
        }
        for(auto &q : seg[v]) if(q.f)
            dsu.rollback();
    }
    vector<int> solve(){
        vector<int> ans(sz + 1);
        run(1, 0, sz, ans);
        return ans;
    }
};

int n, q;

```

```

fscanf(in, "%d %d", &n, &q);
map<pair<int, int>, int> mp;
vector<int> ans(q + 1);
dynCon dc(n, q);
for(int i = 0; i < q; i ++){
    char c; fscanf(in, " %c", &c);
    if(c == '?'){
        ans[i] = 1;
    }
    else{
        int v, u;
        fscanf(in, "%d %d", &v, &u);
        if(v > u) swap(v, u);
        if(c == '+'){
            mp[{v, u}] = i;
        }
        else{
            dc.add(mp[{v, u}], i - 1, qry(v, u));
            mp.erase({v, u});
        }
    }
}

for(auto [p, start] : mp){
    dc.add(start, q, qry(p.first, p.second));
}

auto f = dc.solve();

```

3.2 IntervalContainer

```

/* Description: Add and remove intervals from a
   ↵ set of disjoint intervals.
Will merge the added interval with any overlapping
   ↵ intervals in the set when
adding. Intervals are [inclusive, exclusive). */
set<pii>::iterator addInterval(set<pii>& is, int L,
   ↵ int R) {
    if (L == R) return is.end();
    auto it = is.lower_bound({L, R}), before = it;
    while (it != is.end() && it->first <= R) {
        R = max(R, it->second);
        before = it = is.erase(it);
    }
    if (it != is.begin() && (--it)->second >= L) {
        L = min(L, it->first);
        R = max(R, it->second);
        is.erase(it);
    }
    return is.insert(before, {L,R});
}
void removeInterval(set<pii>& is, int L, int R)
   ↵ {
    if (L == R) return;
    auto it = addInterval(is, L, R);
    auto r2 = it->second;
    if (it->first == L) is.erase(it);
    else (int&)it->second = L;
    if (R != r2) is.emplace(R, r2);
}

```

3.3 2SAT_Shrey

```

struct two_sat
{
    int n;
    vector<vector<int>> g, gr; // ← gr is the reversed graph
    vector<int> comp, topological_order, answer; // ← comp[v]: ID of the SCC containing node v
    vector<bool> vis;
    two_sat() {}

    two_sat(int _n) { init(_n); }

    void init(int _n)
    {
        n = _n;
        g.assign(2 * n, vector<int>());
        gr.assign(2 * n, vector<int>());
        comp.resize(2 * n);
        vis.resize(2 * n);
        answer.resize(2 * n);
    }

    void add_edge(int u, int v)
    {
        g[u].push_back(v);
        gr[v].push_back(u);
    }

    // For the following three functions
    // int x, bool val: if 'val' is true, we take
    // ← the variable to be x. Otherwise we take it
    // ← to be x's complement.

    // At least one of them is true
    void add_clause_or(int i, bool f, int j, bool
       ↵ g)
    {
        add_edge(i + (f ? n : 0), j + (g ? 0 :
           ↵ n));
        add_edge(j + (g ? n : 0), i + (f ? 0 :
           ↵ n));
    }

    // Only one of them is true
    void add_clause_xor(int i, bool f, int j, bool
       ↵ g)
    {
        add_clause_or(i, f, j, g);
        add_clause_or(i, !f, j, !g);
    }

    // Both of them have the same value
    void add_clause_and(int i, bool f, int j, bool
       ↵ g)
    {
        add_clause_xor(i, !f, j, g);
    }

    // Topological sort

```

```

void dfs(int u)
{
    vis[u] = true;

    for (const auto &v : g[u])
        if (!vis[v])
            dfs(v);

    topological_order.push_back(u);
}

// Extracting strongly connected components
void scc(int u, int id)
{
    vis[u] = true;
    comp[u] = id;

    for (const auto &v : gr[u])
        if (!vis[v])
            scc(v, id);
}

// Returns true if the given proposition is
// satisfiable and constructs a valid
// assignment
bool satisfiable()
{
    fill(vis.begin(), vis.end(), false);

    for (int i = 0; i < 2 * n; i++)
        if (!vis[i])
            dfs(i);

    fill(vis.begin(), vis.end(), false);
    reverse(topological_order.begin(),
    topological_order.end());

    int id = 0;
    for (const auto &v : topological_order)
        if (!vis[v])
            scc(v, id++);

    // Constructing the answer
    for (int i = 0; i < n; i++)
    {
        if (comp[i] == comp[i + n])
            return false;
        answer[i] = (comp[i] > comp[i + n] ? 1
        : 0);
    }

    return true;
}
};


```

```

void hungarian(vector<vector<long double>> &a, vll
    &ans)
{
    ll n = a.size();
    vector<ld> u(n + 1, 0), v(n + 1, 0);
    vll p(n + 1, 0), way(n + 1, 0);

    for (ll i = 1; i <= n; ++i)
    {
        vector<ld> minv(n + 1, INF);
        vector<bool> used(n + 1, false);
        ll j0 = 0;
        p[0] = i;
        do
        {
            used[j0] = true;
            ll i0 = p[j0], j1;
            long double delta = LDBL_MAX;
            for (ll j = 1; j <= n; ++j)
            {
                if (!used[j])
                {
                    long double cur = a[i0 - 1][j -
                    1] - u[i0] - v[j];
                    if (cur < minv[j])
                    {
                        minv[j] = cur;
                        way[j] = j0;
                    }
                    if (minv[j] < delta)
                    {
                        delta = minv[j];
                        j1 = j;
                    }
                }
            }
            for (ll j = 0; j <= n; ++j)
            {
                if (used[j])
                {
                    u[p[j]] += delta;
                    v[j] -= delta;
                }
                else
                {
                    minv[j] -= delta;
                }
            }
            j0 = j1;
        } while (p[j0] != 0);
        do
        {
            ll j1 = way[j0];
            p[j0] = p[j1];
            j0 = j1;
        } while (j0);
    }
}

for (ll j = 1; j <= n; ++j)
{
    ans[p[j] - 1] = j - 1;
}

```

3.4 Hungarian

```

// ans[i] = j means ith worker is assigned jth
// task
// O(n^3) time complexity
// It finds the assignment where the sum of costs
// is the lowest possible value.

```

```
}
```

3.5 OrderedSet

```
// Remember to change define int long long
#include "ext/pb_ds/assoc_container.hpp"
#include "ext/pb_ds/tree_policy.hpp"
using namespace __gnu_pbds;
template<class T>
using ordered_set = tree<T, null_type,less<T>,
→ rb_tree_tag, tree_order_statistics_node_update>
→ ;
template<class key, class value, class cmp =
→ std::less<key>>
using ordered_map = tree<key, value, cmp,
→ rb_tree_tag,
→ tree_order_statistics_node_update>;
// find_by_order(k) returns iterator to kth
→ element starting from 0;
// order_of_key(k) returns count of elements
→ strictly smaller than k;
template<class T>
using min_heap =
→ priority_queue<T,vector<T>,greater<T> >;
```

3.6 Fast

```
namespace fast {
    char B[1 << 18], *S = B,*T = B;
#define getc() (S == T && (T = (S = B) +
→ fread(B, 1, 1 << 18, stdin), S == T) ? 0 :
→ *S++)
    long long read() {
        long long ret = 0; char c;
        int f = 0;
        while (c = getc(), (c != '-') && (c < '0'
        → || c > '9'));
        for (; (c >= '0' && c <= '9') || c == '-';
        → c = getc()){
            if(c == '-') f = 1;
            else ret = ret * 10 + c - '0';
        }
        return f ? -ret : ret;
    }
}
```

3.7 Template

```
#include<bits/stdc++.h>
using namespace std;
#define int long long
#define endl "\n"
#define al(v) v.begin(), v.end()
#define set_bits __builtin_popcountll
const int N = 1e9 + 7;
//const int N = 998244353;
const int inf = 0x3f3f3f3f3f3f3f3f;
const int MAXN = 2e5 + 7;
mt19937_64 rng(chrono::steady_clock::now()
→ .time_since_epoch().count());
```

```
void solve(){}
int t = 1;
int32_t main(){
    ios::sync_with_stdio(0);
    cin.tie(0);
    int t; cin>>t;
    while(t --){
        solve();
    }
}
#pragma GCC optimize ("Ofast")
#pragma GCC target ("avx2")
```

3.8 Basis

```
struct basis{
    array<int, 20> b;
    int sz = 0;
    basis(){
        b.fill(0);
        sz = 0;
    }
    void insert(int x){
        for(int i = 19; i >= 0; i --){
            if((x >> i) & 1){
                if(!b[i]){
                    b[i] = x;
                    sz++;
                    return;
                }
                x ^= b[i];
            }
        }
    }
    bool query(int x){
        for(int i = 19; i >= 0; i --){
            if(x == 0) return true;
            if((x >> i) & 1){
                if(!b[i]) return false;
                x ^= b[i];
            }
        }
        return x == 0;
    }
};
```

3.9 ConvexHullTrick

```
template<class T>
using min_heap =
→ priority_queue<T,vector<T>,greater<T> >;
// When lines are added in increasing order of
→ slopes
// Queries minimum
struct CHT {
    struct Line {
        int m, c;
        Line () {}
        Line (int _m, int _c) : m(_m), c(_c) {}
```

```

double intersect(const Line &other) const
→ {
    return (double)(other.c - c) / (m -
→     other.m);
}

int operator()(int x) const {
    return m * x + c;
}

};

vector<double> points;
vector<Line> lines;
void init(Line l){
    points.push_back(-inf);
    lines.push_back(l);
}
void add_line(Line l){
    while(lines.size() >= 2 &&
→     l.intersect(lines[lines.size() - 2]) 
→     <= points.back()){
        points.pop_back();
        lines.pop_back();
    }
    if(!lines.empty()){
        points.push_back(l.intersect(
→         lines.back()));
    }
    if(!lines.empty() && lines.back().m ==
→     l.m){
        if(lines.back().c >= l.c) return;
        lines.pop_back();
        points.pop_back();
    }
    lines.push_back(l);
}
int query(int x){
    int idx = upper_bound(al(points), x) -
→     points.begin() - 1;
    return lines[idx](x);
}
void solve(){
    int n, c; cin>>n>>c;
    vector<int> a(n + 1), dp(n + 1);
    for(int i = 1; i <= n; i ++){
        cin>>a[i];
    }

    CHT cht;
    cht.init(CTH::Line(-2 * a[1], a[1] * a[1]));
    for(int i = 2; i <= n; i ++){
        dp[i] = cht.query(a[i]) + a[i] * a[i] + c;
        cht.add_line(CTH::Line(-2 * a[i], dp[i] +
→         a[i] * a[i]));
    }
    cout<<dp[n]<<endl;
}

// Anyhow works, Queries Maximum
struct Line {
    mutable int k, m, p;
}

```

```

bool operator<(const Line& o) const { return k
→     < o.k; }
bool operator<(int x) const { return p < x; }

};

struct CHT : multiset<Line, less<>> {
    // (for doubles, use inf = 1/.0, div(a,b) =
→     a/b)
    int div(int a, int b) { // floored division
        return a / b - ((a % b) < 0 && a % b); }
    bool isect(iterator x, iterator y) {
        if (y == end()) return x->p = inf, 0;
        if (x->k == y->k) x->p = x->m > y->m ? inf
→         : -inf;
        else x->p = div(y->m - x->m, x->k - y->k);
        return x->p >= y->p;
    }
    void add(int k, int m) {
        auto z = insert({k, m, 0}), y = z++, x =
→     y;
        while (isect(y, z)) z = erase(z);
        if (x != begin() && isect(--x, y)) isect(x,
→     y = erase(y));
        while ((y = x) != begin() && (--x)->p >=
→     y->p)
            isect(x, erase(y));
    }
    int query(int x) {
        assert(!empty());
        auto l = *lower_bound(x);
        return l.k * x + l.m;
    }
};

```

4 Strings

4.1 Hash

```

void go_hsh(string s){
    hsh[0] = s[0];
    ppow[0] = 1;
    for(int i = 1; i < s.size(); i ++){
        hsh[i] = (((hsh[i - 1] * p) % mod) + s[i])
→         % mod;
        ppow[i] = (ppow[i - 1] * p) % mod;
    }
}
int get(int l, int r){
    if(!l) return hsh[r];
    return (hsh[r] - (hsh[l - 1] * ppow[r - l + 1])
→         % mod + mod) % mod;
}

```

4.2 Manacher

```

// Finds all palindromic substrings in O(n) time
// Returns a vector where the ith element
→     represents the length of the longest
→     palindromic substring

```

```
// centered at index i (for odd-length palindromes)
// or between indices i and i+1 (for even-length
// palindromes)
vector<int> manacher_odd(string s){
    int n = s.size();
    s=('$' + s + '^');
    vector<int> ans(n + 2);
    int l = 1, r = 1;
    for(int i = 1; i <= n; i ++){
        ans[i] = max(0LL, min(r - i, ans[l + (r -
            i)]));
        while(s[i + ans[i]] == s[i - ans[i]]){
            ans[i]++;
        }
        if(i + ans[i] > r){
            l = i - ans[i];
            r = i + ans[i];
        }
    }
    vector<int> res;
    // we get answer as
    // even lengthed palindrome between i & i+1 as
    // (ans[i+1]-1)/2
    // odd centered at i as ans[i]/2
    return vector<int>(ans.begin() + 1, ans.end() - 1);
}

vector<int> manacher(string s){
    string t = "";
    for(auto x : s){
        t += "#";
        t += x;
    }
    t += "#";
    // cout<<t<<endl;
    auto res = manacher_odd(t);
    return vector<int>(res.begin() + 1, res.end() -
        1);
}
```

Manacher.h
Description: For each position in a string,
 computes $p[0][i]$ = half length
 of longest even palindrome around pos i , $p[1][i]$ =
 longest odd (half rounded
 down).

Time: O(N)
 e7ad79, 13 lines

```
array<vi, 2> manacher(const string& s) {
    int n = sz(s);
    array<vi, 2> p = {vi(n+1), vi(n)};
    rep(z, 0, 2) for (int i=0, l=0, r=0; i < n; i++) {
        int t = r-i+z;
        if (i < r) p[z][i] = min(t, p[z][l+t]);
        int L = i-p[z][i], R = i+p[z][i]-z;
        while (L>=1 && R+1<n && s[L-1] == s[R+1])
            p[z][i]++, L--, R++;
        if (R>r) l=L, r=R;
    }
    return p;
}
```

4.3 SuffixArray

```
struct SuffixArray {
    vector<int> sa, lcp;

    // Append 0 to s in case s is a vector
    SuffixArray(string &s, int lim = 256){
        int n = s.size() + 1, k = 0, a, b;
        vector<int> x(n), y(n), ws(max(n, lim)),
            rank(n);
        for(int i = 0; i < n - 1; i++) x[i] =
            s[i];
        sa = lcp = y, iota(sa.begin(), sa.end(),
            0);
        for(int j = 0, p = 0; p < n; j = max(1LL,
            j * 2), lim = p){
            p = j, iota(y.begin(), y.end(), n -
                j);
            for(int i = 0; i < n; i++) if (sa[i] -
                j) y[p++] = sa[i] - j;
            fill(ws.begin(), ws.end(), 0);
            for(int i = 0; i < n; i++)
                ws[x[i]]++;
            for(int i = 1; i < lim; i++) ws[i] +=
                ws[i - 1];
            for(int i = n; i --;)
                sa[--ws[x[y[i]]]] = y[i];
            swap(x, y), p = 1, x[sa[0]] = 0;
            for(int i = 1; i < n; i++) a = sa[i] -
                1, b = sa[i], x[b] =
                    (y[a] == y[b] && y[a + j] ==
                     y[b + j]) ? p - 1 :
                     p++;
        }
        for(int i = 1; i < n; i++) rank[sa[i]] =
            i;
        for(int i = 0, j; i < n - 1;
            lcp[rank[i++]] = k) {
            for(k && k--, j = sa[rank[i] - 1]; s[i +
                k] == s[j + k];
                k++);
        }
    }
};
```

4.4 Trie

```
const int MAXB = 30;
struct node{
    int cnt;
    int t[2];
    set<int> id;
    node () {
        cnt = 0;
        t[0] = t[1] = -1;
    }
};
struct btrie{
    vector<node> trie;
    btrie() {
        trie.resize(1);
    }
};
```

```

}

int new_node(){
    trie.push_back(node());
    return (int)trie.size() - 1;
}

void insert(int x, int id){
    int cur = 0;
    trie[cur].cnt++;
    for(int i = MAXB; i >= 0; i --){
        int b = (x >> i) & 1;
        if(trie[cur].t[b] == -1){
            trie[cur].t[b] = new_node();
        }
        cur = trie[cur].t[b];
        trie[cur].cnt++;
    }
    trie[cur].id.insert(id);
}

void remove(int x, int id){
    int cur = 0;
    trie[cur].cnt--;
    for(int i = MAXB; i >= 0; i --){
        int b = (x >> i) & 1;
        cur = trie[cur].t[b];
        trie[cur].cnt--;
    }
    assert(trie[cur].id.count(id));
    trie[cur].id.erase(id);
}

pair<int, int> min_xor(int x){
    int cur = 0, res = 0, idx = -1;
    for(int i = MAXB; i >= 0; i --){
        int b = ((x >> i) & 1);
        if(trie[cur].t[b] != -1 &&
           trie[trie[cur].t[b]].cnt > 0){
            cur = trie[cur].t[b];
        }
        else{
            res |= (1LL << i);
            cur = trie[cur].t[b ^ 1];
            if(cur == -1) return {res, -1};
        }
    }
    assert(!trie[cur].id.empty());
    idx = *trie[cur].id.begin();
    return {res, idx};
}

auto get = [&](int x){
    // I need y such that  $x \wedge y$  is maximum;
    // if x has 0 then find 1 then 0;
    // if x has 1 then find 0 then 1;
    int curr = 0;
    int ans = 0;
    for(int i = 29; i >= 0; i --){
        int bit = (x >> i) & 1;
        if(bit){
            if(trie[curr][0]){
                ans += (1 << i);
                curr = trie[curr][0];
            } else {
                curr = trie[curr][1];
            }
        }
    }
}

```

```

} else {
    if(trie[curr][1]){
        ans += (1 << i);
        curr = trie[curr][1];
    } else {
        curr = trie[curr][0];
    }
}
return ans;
}

```

4.5 Kmp

```

// p[i] = length of the longest proper prefix of
// s[0..i]
// which is also a suffix of s[0..i]
vector<int> prefix_function(string s) {
    int n = (int)s.length();
    vector<int> pi(n);
    for (int i = 1; i < n; i++) {
        int j = pi[i-1];
        while (j > 0 && s[i] != s[j])
            j = pi[j-1];
        if (s[i] == s[j])
            j++;
        pi[i] = j;
    }
    return pi;
}

```

5 Mathematics

5.1 Sieve

```

int low[MAXN];           // smallest prime factor
int phi[MAXN];           // Euler Totient Function
int mu[MAXN];            // Mobius function
vector<int> primes;
void sieve() {
    for (int i = 1; i < MAXN; i++) {
        phi[i] = i;
        mu[i] = 1;
    }
    for (int i = 2; i < MAXN; i++) {
        if (low[i] == 0) {                                // i is
            low[i] = i;
            primes.push_back(i);
            phi[i] = i - 1;
            mu[i] = -1;
        }
        for (int j = i; j < MAXN; j += i) {
            if (low[j] == 0) low[j] = i;
            phi[j] -= phi[j] / i;
            if ((j / i) % i == 0)
                mu[j] = 0;
            else
                mu[j] *= -1;
        }
    }
}

```

```

        }
    }
}

```

5.2 Vector

```

struct vec
{
    vector<ld> x;

    vec(ll n)
    {
        x.resize(n, 0);
    }

    vec operator+(const vec &other) const
    {
        vec res(x.size());
        rep(i, x.size())
        {
            res.x[i] = x[i] + other.x[i];
        }
        return res;
    }

    vec operator-(const vec &other) const
    {
        vec res(x.size());
        rep(i, x.size())
        {
            res.x[i] = x[i] - other.x[i];
        }
        return res;
    }

    vec operator*(const ld &other) const
    {
        vec res(x.size());
        rep(i, x.size())
        {
            res.x[i] = x[i] * other;
        }
        return res;
    }

    vec operator/(const ld &other) const
    {
        vec res(x.size());
        rep(i, x.size())
        {
            res.x[i] = x[i] / other;
        }
        return res;
    }

    ld dot(const vec &other) const
    {
        ld ans = 0;
        rep(i, x.size())
        {
            ans += x[i] * other.x[i];
        }
        return ans;
    }

    ld norm_sq() const
    {

```

```

        ld ans = 0;
        rep(i, x.size())
        {
            ans += x[i] * x[i];
        }
        return ans;
    }

    ld norm() const
    {
        return sqrt(norm_sq());
    }

    ld dist(vec &p, vec &a, vec &b)
    {
        vec ab = b - a;
        vec ap = p - a;
        ld seglensq = ab.norm_sq();
        if (seglensq < 1e-12)
        {
            return ap.norm();
        }
        ld t = ap.dot(ab) / seglensq;
        if (t < 0)
            t = 0;
        if (t > 1)
            t = 1;
        vec q = a + (ab * t);
        return (q - p).norm();
    }
}
```

5.3 SOSDp

```

int dpOr[MAXN], dpAnd[MAXN], A[MAXN];
for(int i = 0; i < n; i ++){
    dpOr[A[i]] ++, dpAnd[A[i]]++;
}
for(int bit = 0; bit < 20; bit ++){
    for(int msk = 0; msk < MAXN; msk ++){
        if((msk >> bit) & 1){
            dpOr[msk] += dpOr[msk ^ (1 << bit)];
        }
        else{
            dpAnd[msk] += dpAnd[msk | (1 << bit)];
        }
    }
}

```

5.4 PollardRho

```

// https://judge.yosupo.jp/problem/factorize
#include<bits/stdc++.h>
using namespace std;

using ll = long long;
namespace PollardRho {
    mt19937
        → rnd(chrono::steady_clock::now().time_since_epoch());
    const int P = 1e6 + 9;
    ll seq[P];
    int primes[P], spf[P];
}
```

```

inline ll add_mod(ll x, ll y, ll m) {
    return (x += y) < m ? x : x - m;
}

inline ll mul_mod(ll x, ll y, ll m) {
    ll res = __int128(x) * y % m;
    return res;
    // ll res = x * y - (ll)((long double)x * y /
    // → m + 0.5) * m;
    // return res < 0 ? res + m : res;
}

inline ll pow_mod(ll x, ll n, ll m) {
    ll res = 1 % m;
    for (; n; n >>= 1) {
        if (n & 1) res = mul_mod(res, x, m);
        x = mul_mod(x, x, m);
    }
    return res;
}

// O(it * (log n)^3), it = number of rounds
// → performed

inline bool miller_rabin(ll n) {
    if (n <= 2 || (n & 1 ^ 1)) return (n == 2);
    if (n < P) return spf[n] == n;
    ll c, d, s = 0, r = n - 1;
    for (; !(r & 1); r >>= 1, s++) {}
    // each iteration is a round
    for (int i = 0; primes[i] < n && primes[i] <
        32; i++) {
        c = pow_mod(primes[i], r, n);
        for (int j = 0; j < s; j++) {
            d = mul_mod(c, c, n);
            if (d == 1 && c != 1 && c != (n - 1))
                → return false;
            c = d;
        }
        if (c != 1) return false;
    }
    return true;
}

void init() {
    int cnt = 0;
    for (int i = 2; i < P; i++) {
        if (!spf[i]) primes[cnt++] = spf[i] = i;
        for (int j = 0, k; (k = i * primes[j]) < P;
            j++) {
            spf[k] = primes[j];
            if (spf[i] == spf[k]) break;
        }
    }
}

// returns O(n^(1/4))
ll pollard_rho(ll n) {
    while (1) {
        ll x = rnd() % n, y = x, c = rnd() % n, u =
        → 1, v, t = 0;
        ll *px = seq, *py = seq;
        while (1) {
            *py++ = y = add_mod(mul_mod(y, y, n), c,
            → n);
            *py++ = y = add_mod(mul_mod(y, y, n), c,
            → n);
            if ((x = *px++) == y) break;
            v = u;
        }
    }
}

```

```

u = mul_mod(u, abs(y - x), n);
if (!u) return __gcd(v, n);
if (++t == 32) {
    t = 0;
    if ((u = __gcd(u, n)) > 1 && u < n)
        → return u;
}
if (t && (u = __gcd(u, n)) > 1 && u < n)
    → return u;
}

vector<ll> factorize(ll n) {
    if (n == 1) return vector<ll>();
    if (miller_rabin(n)) return vector<ll>{n};
    vector<ll> v, w;
    while (n > 1 && n < P) {
        v.push_back(spf[n]);
        n /= spf[n];
    }
    if (n >= P) {
        ll x = pollard_rho(n);
        v = factorize(x);
        w = factorize(n / x);
        v.insert(v.end(), w.begin(), w.end());
    }
    return v;
}

void solve(){
    ll m, n, k; cin >> m >> n >> k;
    set<ll> st;
    for (ll i = 0; i < n; i++) {
        ll x; cin >> x;
        auto f = PollardRho::factorize(x);
        for (auto y : f) st.insert(y);
    }
    for (ll i = 0; i < k; i++) {
        ll a, b, c; cin >> a >> b >> c;
    }
    for (auto x : st) cout << x << " ";
    cout << endl;
}

int32_t main() {
    ios_base::sync_with_stdio(0);
    cin.tie(0);
    PollardRho::init();
    int t = 1;
    while (t--) {
        solve();
    }
    return 0;
}

```

5.5 Gaussian Elimination

```

void solve()
{
    ll p, f;
    cin >> p >> f;

```

```

vector<vll> adj(p);
vll deg(p, 0);
rep(i, f)
{
    ll a, b;
    cin >> a >> b;
    --a;
    --b;
    adj[a].pb(b);
    adj[b].pb(a);
    deg[a]++;
    deg[b]++;
}
}

vector<bitset<NUM + 1>> mat(p);
rep(v, p)
{
    for (auto u : adj[v])
        mat[v].set(u);
    if (deg[v] & 1)
        mat[v].set(v);
    else
        mat[v].set(p);
}

// The below code is taken from internet
// (Gaussian Elimination in GF(2))
ll row = 0;
for (ll col = 0; col < p && row < p; ++col)
{
    ll sel = -1;
    for (ll r = row; r < p; ++r)
    {
        if (mat[r].test(col))
        {
            sel = r;
            break;
        }
    }
    if (sel == -1)
        continue;
    if (sel != row)
        swap(mat[sel], mat[row]);
    for (ll r = 0; r < p; ++r)
    {
        if (r != row && mat[r].test(col))
        {
            mat[r] ^= mat[row];
        }
    }
    ++row;
}

for (ll r = 0; r < p; ++r)
{
    bool allzero = true;
    for (ll c = 0; c < p; ++c)
        if (mat[r].test(c))
        {
            allzero = false;
            break;
        }
    if (allzero && mat[r].test(p))
}

```

```

    {
        cout << 'N' << endl;
        return;
    }
}

cout << 'Y' << endl;
}

```

5.6 Crt

```

int extGcd(int a, int b, int &x, int &y){
    if(b == 0){
        x = 1; y = 0;
        return a;
    }
    int x1, y1;
    int d = extGcd(b, a % b, x1, y1);
    x = y1;
    y = x1 - (a / b) * y1;
    return d;
}

int modinv(int a, int m){
    int x, y;
    int g = extGcd(a, m, x, y);
    int inv = (x % m + m) % m;
    return inv;
}

// solves the two congruences and returns the
// minimum non-negative solution
int get(int a, int b, int c, int d, int n){
    // ax = -b mod n -> ax - kn = -b -> gcd(a, n)
    // / b
    // cx = -d mod n

    int g1 = gcd(a, n);
    if((-b) % g1 != 0) return -1;
    int m1 = n / g1;
    int r1 = ((-b / g1) % m1 + m1) % m1;
    int x1 = (modinv(a / g1, m1) * r1) % m1;

    int g2 = gcd(c, n);
    if((-d) % g2 != 0) return -1;
    int m2 = n / g2;
    int r2 = ((-d / g2) % m2 + m2) % m2;
    int x2 = (modinv(c / g2, m2) * r2) % m2;

    // x = x1 mod m1 and x = x2 mod m2
    int g = gcd(m1, m2);
    if((x2 - x1) % g != 0) return -1;
    int M = (m1 / g) * m2;
    int inv = modinv(m1 / g, m2 / g);
    int ans = (x1 + (((x2 - x1) / g * inv) % (m2 /
    g)) * m1) % M;
    ans = (ans + M) % M;
    return ans;
}

```

5.7 Bits

```

mask &= ~(1LL << i); // Clear i-th bit
mask &= (mask - 1); // Turn off lowest set bit
bool is_pow2 = (mask > 0 && (mask & (mask - 1)) == 0); // Is power of two
int leading_zeros = __builtin_clzll(mask); // Count leading zeros
int trailing_zeros = __builtin_ctzll(mask); // Count trailing zeros
int lsb = mask & (-mask); // Isolate least significant bit
mask &= (mask - 1); // Turn off least significant bit

// Iterate over all subsets of a bitmask
for(int sub = mask; sub; sub = (sub - 1) & mask){
    // sub is a non-empty subset
}

```

5.8 Euler_Totient

```

int phi(int n) { // O(sqrt(n))
    int result = n;
    for (int i = 2; i * i <= n; i++) {
        if (n % i == 0) {
            while (n % i == 0)
                n /= i;
            result -= result / i;
        }
    }
    if (n > 1)
        result -= result / n;
    return result;
}

void phi_1_to_n(int n) { // O(nloglogn)
    vector<int> phi(n + 1);
    for (int i = 0; i <= n; i++)
        phi[i] = i;

    for (int i = 2; i <= n; i++) {
        if (phi[i] == i) {
            for (int j = i; j <= n; j += i)
                phi[j] -= phi[j] / i;
        }
    }
}

```

5.9 NCr_Shrey

```

const ll MAXN = 1e7;
const ll MOD = 1e9 + 7;

vector<ll> fac(MAXN + 1);
vector<ll> inv(MAXN + 1);

/** Computes x^y modulo p in O(log p) time. */
ll exp(ll x, ll y, ll p)
{
    ll res = 1;

```

```

    x %= p;
    while (y)
    {
        if (y & 1)
        {
            res *= x;
            res %= p;
        }
        x *= x;
        x %= p;
        y >>= 1;
    }
    return res;
}

void factorial() {
    fac[0] = 1;
    for (ll i = 1; i <= MAXN; i++)
        fac[i] = (fac[i - 1] * i) % MOD;
}

void inverses() {
    inv[MAXN] = exp(fac[MAXN], MOD - 2, MOD);
    for (ll i = MAXN; i >= 1; i--)
        inv[i - 1] = (inv[i] * i) % MOD;
}

ll choose(int n, int r) {
    return fac[n] * inv[r] % MOD * inv[n - r] %
        MOD;
}

```

5.10 Matrix

```

template<typename T>
struct Matrix{
    vector<vector<T>> mat;
    int n, m;
    Matrix() {}
    Matrix(int _n, int _m, bool ident = false) {
        n = _n; m = _m;
        mat.assign(n, vector<T>(m, 0));
        if (ident) {
            for (int i = 0; i < n; i++)
                mat[i][i] = 1;
        }
    }
    Matrix(const vector<vector<T>> &v) {
        n = v.size();
        m = v[0].size();
        mat = v;
    }
    Matrix operator*(const Matrix &b) const {
        Matrix res(n, b.m);
        for (int i = 0; i < n; i++)
            for (int k = 0; k < m; k++)
                if (mat[i][k].val == 0) continue;
                for (int j = 0; j < b.m; j++)
                    res.mat[i][j] += mat[i][k] *
                        b.mat[k][j];
        return res;
    }
}

```

```

        }
    }
    return res;
}
};

template<typename T>
Matrix<T> mat_pow(Matrix<T> a, long long p) {
    Matrix<T> res(a.n, a.n, true);
    while (p) {
        if (p & 1) res = res * a;
        a = a * a;
        p >>= 1;
    }
    return res;
}

```

5.11 MillerRabin

```

using u64 = uint64_t;
using u128 = __uint128_t;

u64 binpower(u64 base, u64 e, u64 mod) {
    u64 result = 1;
    base %= mod;
    while (e) {
        if (e & 1)
            result = (u128)result * base % mod;
        base = (u128)base * base % mod;
        e >>= 1;
    }
    return result;
}

```

```

bool check_composite(u64 n, u64 a, u64 d, int s) {
    u64 x = binpower(a, d, n);
    if (x == 1 || x == n - 1)
        return false;
    for (int r = 1; r < s; r++) {
        x = (u128)x * x % n;
        if (x == n - 1)
            return false;
    }
    return true;
};

bool MillerRabin(u64 n) { // returns true if n is
    if (n < 2)
        return false;

    int r = 0;
    u64 d = n - 1;
    while ((d & 1) == 0) {
        d >>= 1;
        r++;
    }

    for (int a : {2, 3, 5, 7, 11, 13, 17, 19, 23,
    if (n == a)
        return true;
    if (check_composite(n, a, d, r))
        return false;
    }
    return true;
}

```

Combinatorial

Permutations

Cycles

Let $g_S(n)$ be the number of n -permutations whose cycle lengths all belong to the set S . Then

$$\sum_{n=0}^{\infty} g_S(n) \frac{x^n}{n!} = \exp \left(\sum_{n \in S} \frac{x^n}{n} \right)$$

Derangements

Permutations of a set such that none of the elements appear in their original position.

$$D(n) = (n-1)(D(n-1) + D(n-2)) = nD(n-1) + (-1)^n = \left\lfloor \frac{n!}{e} \right\rfloor$$

Burnside's lemma

Given a group G of symmetries and a set X , the number of elements of X up to symmetry equals

$$\frac{1}{|G|} \sum_{g \in G} |X^g|,$$

where X^g are the elements fixed by g ($g \cdot x = x$).

If $f(n)$ counts “configurations” (of some sort) of length n , we can ignore rotational symmetry using $G = \mathbb{Z}_n$ to get

$$g(n) = \frac{1}{n} \sum_{k=0}^{n-1} f(\gcd(n, k)) = \frac{1}{n} \sum_{k|n} f(k) \phi(n/k).$$

Partitions and subsets

Partition function

Number of ways of writing n as a sum of positive integers, disregarding the order of the summands.

$$p(0) = 1, p(n) = \sum_{k \in \mathbb{Z} \setminus \{0\}} (-1)^{k+1} p(n - k(3k-1)/2)$$

$$p(n) \sim 0.145/n \cdot \exp(2.56\sqrt{n})$$

n	0	1	2	3	4	5	6	7	8	9	20	50	100
$p(n)$	1	1	2	3	5	7	11	15	22	30	627	$\sim 2e5$	$\sim 2e8$

Lucas' Theorem

Let n, m be non-negative integers and p a prime. Write $n = n_k p^k + \dots + n_1 p + n_0$ and $m = m_k p^k + \dots + m_1 p + m_0$. Then $\binom{n}{m} \equiv \prod_{i=0}^k \binom{n_i}{m_i} \pmod{p}$.

General purpose numbers

Bernoulli numbers

EGF of Bernoulli numbers is $B(t) = \frac{t}{e^t - 1}$ (FFT-able). $B[0, \dots] = [1, -\frac{1}{2}, \frac{1}{6}, 0, -\frac{1}{30}, 0, \frac{1}{42}, \dots]$

Sums of powers:

$$\sum_{i=1}^n n^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k \cdot (n+1)^{m+1-k}$$

Euler-Maclaurin formula for infinite sums:

$$\begin{aligned} \sum_{i=m}^{\infty} f(i) &= \int_m^{\infty} f(x) dx - \sum_{k=1}^{\infty} \frac{B_k}{k!} f^{(k-1)}(m) \\ &\approx \int_m^{\infty} f(x) dx + \frac{f(m)}{2} - \frac{f'(m)}{12} + \frac{f'''(m)}{720} + O(f^{(5)}(m)) \end{aligned}$$

Stirling numbers of the first kind

Number of permutations on n items with k cycles.

$$\begin{aligned} c(n, k) &= c(n-1, k-1) + (n-1)c(n-1, k), \quad c(0, 0) = 1 \\ \sum_{k=0}^n c(n, k) x^k &= x(x+1) \dots (x+n-1) \end{aligned}$$

$$c(8, k) = 8, 0, 5040, 13068, 13132, 6769, 1960, 322, 28, 1$$

$$c(n, 2) = 0, 0, 1, 3, 11, 50, 274, 1764, 13068, 109584, \dots$$

Eulerian numbers

Number of permutations $\pi \in S_n$ in which exactly k elements are greater than the previous element. k j :s s.t. $\pi(j) > \pi(j+1)$, $k+1$ j :s s.t. $\pi(j) \geq j$, k j :s s.t. $\pi(j) > j$.

$$E(n, k) = (n-k)E(n-1, k-1) + (k+1)E(n-1, k)$$

$$E(n, 0) = E(n, n-1) = 1$$

$$E(n, k) = \sum_{j=0}^k (-1)^j \binom{n+1}{j} (k+1-j)^n$$

Stirling numbers of the second kind

Partitions of n distinct elements into exactly k groups.

$$S(n, k) = S(n-1, k-1) + kS(n-1, k)$$

$$S(n, 1) = S(n, n) = 1$$

$$S(n, k) = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$$

Bell numbers

Total number of partitions of n distinct elements. $B(n) = 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, \dots$ For p prime,

$$B(p^m + n) \equiv mB(n) + B(n+1) \pmod{p}$$

Labeled unrooted trees

on n vertices: n^{n-2}

on k existing trees of size n_i : $n_1 n_2 \dots n_k n^{k-2}$

with degrees d_i : $(n-2)! / ((d_1-1)! \dots (d_n-1)!)$

Catalan numbers

$$C_n = \frac{1}{n+1} \binom{2n}{n} = \binom{2n}{n} - \binom{2n}{n+1} = \frac{(2n)!}{(n+1)!n!}$$

$$C_0 = 1, C_{n+1} = \frac{2(2n+1)}{n+2} C_n, C_{n+1} = \sum C_i C_{n-i}$$

$$C_n = 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, \dots$$

- sub-diagonal monotone paths in an $n \times n$ grid.
- strings with n pairs of parenthesis, correctly nested.
- binary trees with $n+1$ leaves (0 or 2 children).
- ordered trees with $n+1$ vertices.
- ways a convex polygon with $n+2$ sides can be cut into triangles by connecting vertices with straight lines.
- permutations of $[n]$ with no 3-term increasing subseq.