

### 1) Machine Arithmetic:-

- Introduction
- Finite digit Arithmetic
- errors

### 2) Equations in one variable:-

- the bisection method
- fixed points
- fixed point iteration method
- Newton-Raphson method for root finding
- secant method for root finding
- Regula falsi, method of false position for root finding
- modified newton Raphson for root multiplicity
- Altken's  $\Delta^2$  method of accelerated convergence

### 3) Interpolation:-

- Lagrange interpolating polynomials.
- cumulative calculation of interpolating polynomials
- Neville's formula ... 
$$P = \frac{(x - x_j)P_j(x) - (x - x_i)P_i(x)}{x_i - x_j}$$
- Neville's table
- divided differences, its table
- Osculating polynomials
- Hermite polynomials
- Piecewise polynomial interpolation; Splining.
  - cubic spline, quadratic spline

### 4) Numerical Differentiation and Integration:-

- computing  $f'(x)$ .  
(by interpolation the function with polynomials)
  - (n+1) point formula
  - Three point formula
- Numerical Integration
  - Numerical quadrature
  - Trapezoidal & Simpson's
  - accuracy/precision
  - Newton-cotes formulae. ( $n=1, 2, 3, \dots$ )  
Open & close
  - Composite numerical integration = Composite trapezoid, simpsons, mblpoint.
  - Adaptive quadrature method
  - Gaussian Quadrature
  - Legendre polynomials → to compute Gaussian quadrature coefficients.
- multiple dimensions
  - multiple trapezoid, simpsons rule.

-- Improper integrals

$$\bullet \int_a^b \frac{g(x) - P_k(x)}{(x-a)^p} + \int_a^b \frac{P_k(x)}{(x-a)^p} dx.$$

### 5.) Ordinary Differential Equations:-

- Lipschitz condition
- Euler's method
- local truncation error
- Taylor of order 'n'
- Runge-Kutta methods of order 2
- multi-order runge-kutta
- multi-step methods
- Adams-Bashforth, Adams-Moulton
- predictor-corrector model

### 6.) Numerical Linear Algebra:-

- GEM-operation count
- Scaled partial pivoting
- LU decomposition
- PLU decomposition
- iterative methods
  - Norms on matrices
- eigen values & vectors
  - Jacobi method
  - Gauss-Seidel method
  - residual vector
  - condition number
- Gerschgorin theorem
- Power method

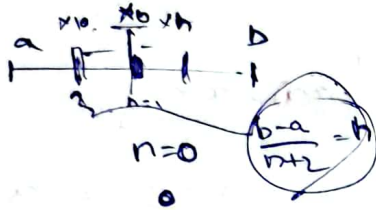
round-off error.  
truncation-error.

integrating  $\rightarrow$  numerical quadrature



$$\int_a^b f(x) dx = \sum_{i=0}^n A_i f(x_i)$$

basically  $\int_a^b L(x)$   $n=1$   
 Lagrange.  $\frac{1}{2}$



error is

$$\int_a^b (x-x_0)(x-x_1) \dots (x-x_n) \cdot \frac{f^{(n+1)}(\xi)}{(n+1)!} dx$$

$$\frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2)) = h^5$$

$$h^3 \quad 2+2 \quad 1+1 \rightarrow 2$$

### 1) normal integration

- trapezoid
- Simpson's rule
- Newton-cotes open  
close

### 2) Composite integration

\* round off error is same.  
 $\rightarrow$  problem  $\rightarrow$  Adaptive quadrature.

composite Simpson  
 $n \rightarrow$  even.

$$|S(a,b) - S(a, \frac{a+b}{2}) - S(\frac{a+b}{2}, b)| \leq 15E$$

$$\int_a^b f(x) dx = S(a, \frac{a+b}{2}) + S(\frac{a+b}{2}, b)$$

$$\frac{h}{3} [f(a) + 2 \sum_{j=1}^{n/2-1} f(x_{2j}) + 4 \sum_{j=1}^{n/2} f(x_{2j-1}) + f(b)]$$

### 3) Gaussian quadrature:-

$$\int_a^b f(x) dx = \sum_{i=1}^n A_i f(x_i)$$

$x_i$  in  $[a, b]$   
 choosel.

$$\int_{-1}^1 p(x) dx = \sum_{i=1}^n C_i p(x_i)$$

tabulated

$$C_i = \int_{-1}^1 \prod_{j=1, j \neq i}^n \frac{x - x_j}{x_i - x_j} dx$$

Standard:  $[-1, 1]$   
 - Legendre polynomials:-

$$P_0(x) = 1$$

$$P_1(x) = x$$

$$P_2(x) = x^2 - \frac{1}{2}$$

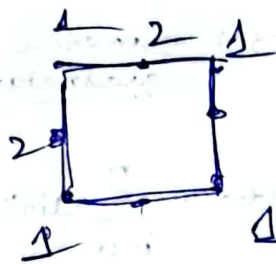
$$P_3(x) = x^3 - \frac{3}{2}x$$

roots, lie in  $[-1, 1]$



## 4) Multiple Integrals

$$\iint_R f(x,y) dx dy$$



$$g(a,b) = \frac{1}{3}(1+2+1) = \frac{4}{3}$$

## 5) Improper Integrals

$$\int \frac{g(x)}{(x-a)^p} \rightarrow \int \frac{g(x) - P_4(x)}{(x-a)^p} + \frac{P_4(x)}{(x-a)^p}$$

$\downarrow$   
 composite  
 Simpson's  
 rule.

$$= g(a) + \frac{(x-a)}{1} g'(a) + \frac{(x-a)^2}{2} g''(a) + \dots$$

## L29: Ordinary differential equations

### \* $f(t,y) \rightarrow$ Lipschitz Condition

$\rightarrow$  if  $f(t,y)$  satisfies Lipschitz on  $U$ ; initial value problem

$$y'(t) = f(t,y), y(a) = \alpha$$

has unique  $y$

$\rightarrow$  well-posed

universal

$$y' = f(t,y), y(a) = \alpha$$

methods:

### 1) Euler's method

$$h = \frac{b-a}{N}, t_0 = a, t_i = a + ih$$

$$w_{i+1} = w_i + h f(t_i, w_i)$$

error:

$$|y(t_i) - w_i| \leq \frac{hM}{2L} [e^{L(t_i-a)} - 1]$$

$L \rightarrow$  Lipschitz constant

$$|y''| \leq M$$

Local truncation error:

$$\text{say } w_{i+1} = w_i + h \phi(t_i, w_i)$$

$$\text{then } w_{i+1} = y(t_i) + h \phi(t_i, y(t_i))$$

$$\text{then } \frac{y(t_{i+1}) - w_{i+1}}{h} = \text{Local truncation error}$$

$$((1.000000 + 1.000000i) + (2.000000 + 2.000000i)) \frac{1}{2} + 1.000000 - 1.000000$$

$$LTE = \frac{y_{i+1} - y_i}{h} - f(t_i, y_i)$$

$$= \frac{h \cdot f(t_i, y_i)}{2} = \frac{h \cdot M}{2}$$

Euler: local truncation error  $O(h)$

$$h = \frac{0.1 - 0}{6}$$

2) Higher order Taylor method:-

$$y_{i+1} = y_i + f(t_i, y_i) \cdot h + \frac{h^2}{2} f'(t_i, y_i)$$

$$\therefore w_{i+1} = w_i + h \cdot T(t_i, w_i)$$

$$T(t_i, w_i) = f(t_i, w_i) + \frac{h}{2} f'(t_i, w_i) + \frac{h^2}{2} f''(t_i, w_i) + \dots$$

order 2

$$(1.000000 + 1.000000i) + (2.000000 + 2.000000i) = 3.000000 + 3.000000i$$

$n^{\text{th}}$  order Taylor: local truncation error  $O(h^n)$

3) Runge-Kutta method (Taylor's in 2-D)

to attain same error as higher Taylor, without  $f''$ ,  $f'''$ ...

determine values

$$\alpha_1, \alpha_2, \beta_1$$

so that

$$\alpha_1 f(t + \alpha_1, y + \beta_1)$$

$$\text{equals } f(t + y) + \frac{h}{2} f'(t, y)$$

$$\alpha_1 = 1$$

$$\alpha_2 = \frac{1}{2}h$$

$$\beta_1 = \frac{h}{2} f(t, y)$$

midpoint method!

$$\therefore w_{i+1} = w_i + f(t + \frac{h}{2}, w_i + \frac{h}{2} f(t, w_i))$$

like some midpoint...

## A modified Euler:

$$w_{i+1} = w_i + \frac{h}{2} [f(t_i, w_i) + f(t_{i+1}, w_i + hf(t_i, w_i))]$$

5) Higher order Runge-Kutta:-

$$T(t, y) = f(t, y) + \frac{h}{2} f'(t, y) + \frac{h^2}{6} f''(t, y)$$

↑ approximate this...

by

$$f(t + \alpha_1, y + \delta_1, f(t + \alpha_2, y + \delta_2, f(t, y))) \text{ with } O(h^3) \text{ error}$$

Heun's method.

Here



6) Order-4 Runge-Kutta:-

$$w_0 = \alpha.$$

Writing for convenience-

$$w_{i+1} = w_i + \frac{1}{6} (K_1 + 2K_2 + 2K_3 + K_4)$$

$$K_1 = hf(t_i, w_i)$$

$$K_2 = hf(t_i + \frac{h}{2}, w_i + \frac{K_1}{2})$$

$$K_3 = hf(t_i + \frac{h}{2}, w_i + \frac{1}{2}K_2)$$

local trunc.  
 $O(h^4)$

$$K_4 = hf(t_{i+1}, w_i + K_3)$$

multistep:

Adams-Bashforth: explicit

$$w_{i+1} = w_i + \begin{matrix} (i-1) \\ (i-2) \\ (i-3) \end{matrix}$$

-moulton: implicit