CS-226 Course Project

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Department of Computer Science Indian Institute of Technology, Bombay - Powai

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Team:

Akash Reddy G 190050038

D Chandrasekhar 190050031

M Satwik 190050107

K Vishwanth 190050131

FSM States

States:-

S1:
$$IR_{II-q} \longrightarrow RF_A1$$
 $IR_{8-6} \longrightarrow RF_A2$
 $t_2 \cdot \omega r$
 $RF_D1 \longrightarrow t_1$
 $RF_D2 \longrightarrow t_2$
 $t_3 \cdot \omega v$

$$52$$
:
 $t_1 \rightarrow ALUQ$ $t_3.Wr$
 $t_2 \rightarrow ALUb$
 $ALUC \rightarrow t_3$

$$52^{1}$$
:
 $t_{1} \rightarrow ALUA$ $t_{3} \cdot WY$
 $t_{2} \rightarrow ALUB$ $ALU_{0} \cdot nand$
 $ALUC \rightarrow t_{3}$

$$\frac{S_3}{t_3}$$
 $\rightarrow RF_D_3$ RF_wr $IR_{5-3} \rightarrow RF_A_3$

$$SE:$$
 $Imm9e16(IR_{8-0}) \rightarrow RF_D3$
 $RF.WY$
 $IR_{11-9} \rightarrow RF_A3$

Se:
$$t_2 \rightarrow \text{mem_addr}$$

$$\text{mem_D} \rightarrow t_3$$

$$t_3 \cdot \text{wr}$$

S12:

$$t_2 \longrightarrow RF-D_3$$
 $t_3 \longrightarrow RF-A_3$
 $t_3 \longrightarrow ALUa$
 $t_4 \longrightarrow ALUb$
 $t_4 \longrightarrow ALUb$

519:

S13:

$$t_1 \rightarrow \text{mem-ddol}r$$
 $t_2 \cdot \omega r$ $t_3 \rightarrow \text{ALUa}$ $t_3 \cdot \omega r$ $t_1 \rightarrow \text{ALUb}$ $t_2 \cdot \omega r$ $t_3 \rightarrow \text{RF-A1}$ $t_3 \rightarrow \text{RF-A1}$

S14:

$$t1 \longrightarrow ALUA$$
 $+1 \longrightarrow ALUb$
 $ALUC \longrightarrow t1$
 $t1 \longrightarrow mem-addr$
 $t2 \longrightarrow mem-in$

Sis:

S16:

$$\begin{array}{c} IR \longrightarrow RF-A3 \\ PC \longrightarrow RF-D3 \\ IR \longrightarrow 6 \longrightarrow RF-A2 \\ RF-D2 \longrightarrow t_2 \end{array}$$

S17:

S18:

Instruction-State Transition

Instructions: State transitions:

50 —
$$S_1 - S_2 - S_3 - S_4 - S_0$$

2) ADC:-
$$S_0 \longrightarrow S_1 \xrightarrow{C=1} S_2 \longrightarrow S_3 \longrightarrow S_{\times} --- S_0$$

$$S_0 - S_1 - S_{11}$$

$$S_{12} - S_{11}$$

$$S_{13} - S_{11}$$

$$S_{14} - S_{11}$$

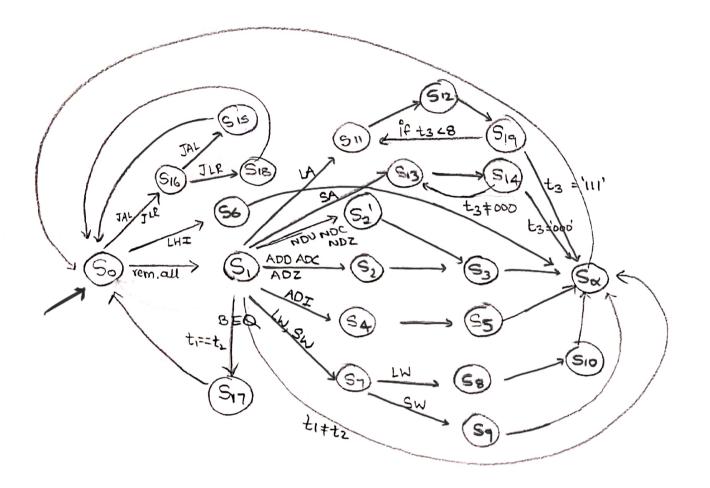
$$S_{15} - S_{11}$$

$$S_{17} - S_{11}$$

12)
$$SA:-$$

$$So -S_1 - S_1 \xrightarrow{23+"000"} S_1 \xrightarrow{3="000"} S_2 --- S_0$$

FSM Diagram



Total 21 States

Sa, S1-519,52

State diagram:

These states have been implemented via one-not encoding.

Control Signals

Column1	w1	w2	w3	w4	w5	w6	w7	m1	m12	m21	m20	m31	m30	m4	m51	m50	m61	m60	m71	m70	m8	m92	m91	m90	m101	m100	wc	wz	mz	alu_op
sa	1							0														0	1	1	0	1				
s0			1							0	1																			
s1					1	1	1							0			0	1	0	1	0									
s2					1												1	0				0	1	0	1	0	1	1		0
s2'					1												1	0				0	1	0	1	0	0	1		1
s3				1								1	0		1	1														
s4					1												1	0				0	0	1	1	0	1	1		
s5				1								0	1		1	1														
s6				1								0	0		0	1														
s7						1													1	0		0	0	1	1	1				
s8					1					0	0						0	0												
s9		1							0	0	0																			
s10				1								0	0		1	1											1	1	1	
s11						1				1	1								1	1										
s12				1	1							1	1		1	0	1	0				0	1	1	0	0				
s13					1	1								1			1	0	0	0		0	1	1	0	0				
s14		1					1		1	1	1										1	0	1	1	1	0				
s15	1							0														0	0	0	0	1				
s16				1		1						0	0		0	0			0	1										
s17	1							0														0	0	1	0	1				
s18	1							1																						
s19							1														1	0	1	1	1	0				

w = 1 means active/enable write.

default w is 0 (disabled)
In w's coloum, empty implies 0

m's are mux selectors

In m's column, empty implies don't care.

RTL circuit

