OS LAB: ASSIGNMENT 4 REPORT

Group number: 30

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Data Structures:

We have used two datastructures one is Action which is used for different actions, it has following data members:

int user_id, int action_id, int action_type, time_t action_time

Other structure used is adj_list it has following data members: int id,

int *neighbours (it contains the list of all neighbours (node id) of the current node)
int num_neighbours (it contains number of neighbours of the current number)
int count[3] (it is used to recognize type of action i.e {0: post, 1: comment, 2: like})
queue<Action> wall_queue (contains actions of this nodes)
queue<Action> feed_queue (contains actions of the neighbours of this node)
int reading_order (defines reading order i.e for priority 0 and for chronological 1)
pthread_mutex_t feed_lock (pthread_mutex_lock allows threads to acquire a
mutual exclusion lock, which is used to protect shared resources from concurrent
access.)

pthread_cond_t feed_cond (pthread_cond_t to allow threads to wait for a condition to be true before proceeding with their execution.)

Design decision for queue sizes:

For feed queue and wall queue we have used queue container from STL library. Queue is a container adapter that operates in a first-in, first-out (FIFO) order which helps in maintaining chronological order.

Design of how locks are used to ensure no race condition and concurrency:

Whenever there is a possibility that we are writing or reading to a data structure that is shared, we have used mutex locks there. Hence, we have used eight locks. A detailed Overview is as follows:

- UserSimulator:
 - 1. Before writing to the shared queue
- ReadPost:
 - 1. Before reading from the feed queue set
 - 2. Before reading from the feed queue for new actions
- PushUpdate:
 - 1. Reading from shared Queue
 - 2. Before writing to the feed queue of a node
 - 3. Before writing to the shared feed queue set
- Before writing to the terminal or the log file
- Before writing to the feed queue