PV System Anomaly Detection

1. Objective and Problem Statement

The task is to develop an unsupervised machine learning solution to detect anomalies in a PV system using time-series data of actual (P) and expected (P_exp) MPPT power at 1-minute intervals. Key requirements:

- Define faulty vs. normal data points based on power deviation patterns.
- Select and justify an unsupervised model.
- Train without explicit labels.
- Identify and visualize anomalies in the dataset.

2. Solution Approach and Methodology

Data Preprocessing

• Data Cleaning:

Loaded and parsed datetime, handled missing values, and ensured 1-minute interval consistency.

• Feature Engineering:

Created four key features to capture anomalies:

- a. Delta $P = P \exp P$ (absolute deviation)
- b. Ratio P = P / P exp (relative deviation)
- c. P diff = P.diff() (rate of change of actual power)
- d. P_exp_diff = P_exp.diff() (rate of change of expected power)

These features quantify deviations in magnitude and trend consistency.

Model Selection: Isolation Forest

• Justification:

- O Unsupervised learning (no labels available).
- o Effective for detecting rare anomalies in high-dimensional data.
- o Computationally efficient with low memory requirements.
- Robust to outliers by design.

• Model Configuration:

IsolationForest(contamination=0.01, random state=42)

o contamination=0.01 assumes ~1% of points are anomalies (adjustable based on domain knowledge).

Training Process

1. Unsupervised Training:

- o The model learns the "normal" feature distribution.
- o Anomalies are points easily isolated (fewer splits required).

2. Anomaly Scoring:

o model.fit predict(features) flags anomalies as -1 (converted to 1 for clarity).

3. No Explicit Labels Needed:

 Relies on the assumption that anomalies are statistically rare and distinct from normal data.

3. Key Findings

1. Data Distribution and Fault Definition

• Data Distribution:

- Most points cluster where $P \approx P_{exp}$ (high Ratio_P, low Delta_P).
- Occasional large deviations indicate potential faults (e.g., shading, dust, hardware issues).

• Fault Definition:

A point is **faulty** if:

- O Delta P or |P diff P exp diff exceeds dynamic thresholds (learned by the model).
- o Ratio P is abnormally low (e.g., < 0.8) or volatile.

• Model Choice Justification:

Isolation Forest handles unlabeled data, ignores noise, and scales well for time-series.

2. Training Without Labels

• Strategy:

The model infers anomalies solely from feature space density. Dense regions = normal; sparse regions = anomalies.

Assumptions:

- \circ Anomalies are rare (< 1% of data).
- o Faults manifest as sudden drops in Ratio P or inconsistent power-change rates.

3. Anomaly Detection Results

• Visualization:

Actual vs. expected power with anomalies (red) highlighted.

• Key Observations:

- o Anomalies correlate with:
 - Sharp drops in P (e.g., from 900W to 300W while P_{exp} remains stable).
 - Sustained deviations (e.g., P consistently 20% below P_{exp}).
- Example: On $10/1/2023 \ 11:00$, $P_{exp} = 1803.9W$ but P = 1303.9W (Ratio_P ≈ 0.72).

4. Assumptions and Limitations

• Assumptions:

- Clear-sky conditions dominate; anomalies imply system faults.
- o No environmental data (irradiance/temperature) used.

• Limitations:

- o May flag rapid weather changes as false positives.
- o Cannot classify fault types (shading vs. inverter failure).

• Improvements:

- o Add rolling-window features (e.g., 10-min mean/std).
- o Incorporate weather data to reduce false positives.
- o Use clustering (e.g., DBSCAN) for anomaly type identification.

5. Conclusion

The Isolation Forest model successfully identifies PV system anomalies by leveraging featureengineered deviations in power data. This approach provides a scalable, unsupervised solution for real-time fault detection, enabling proactive maintenance.