

%% Report %%

Settings:

data_dir: logs
data_file: cf231_
info_dir: info
info_file: info_cf231_.yaml
event_name: ['fixedFrequency', 'estPosition']
output_dir: reports
start_time: None
end_time: None

Parameters:

experiment: 184
trajectory: figure8.csv
timescale: 3.0
motors: standard motors (CF)
propellers: standard propellers (CF)

%% Report %%

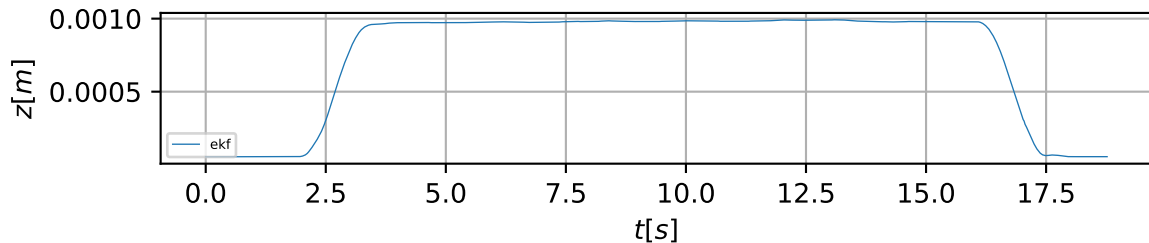
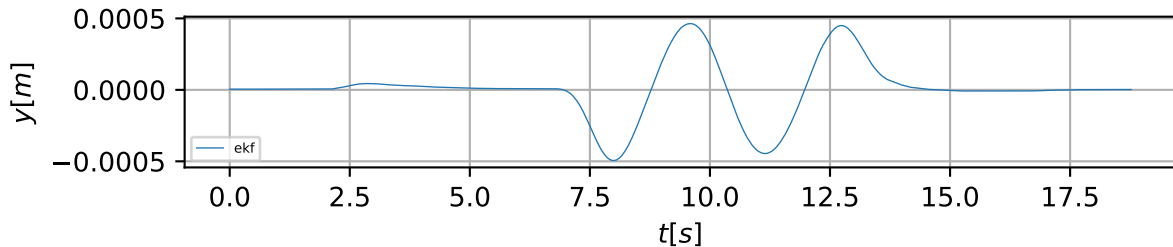
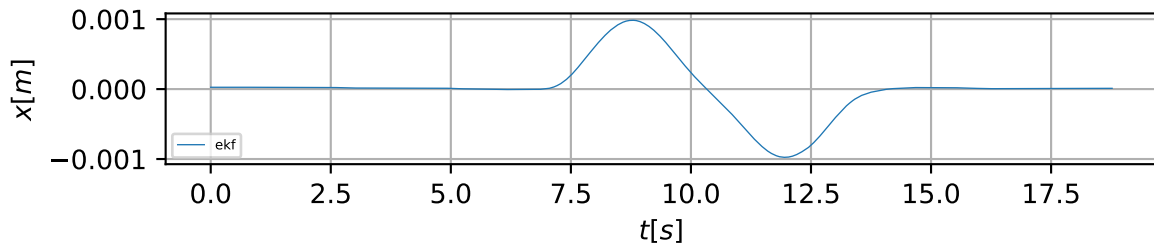
Settings:

data_dir: logs
data_file: cf231_
info_dir: info
info_file: info_cf231_.yaml
event_name: ['fixedFrequency', 'estPosition']
output_dir: reports
start_time: None
end_time: None

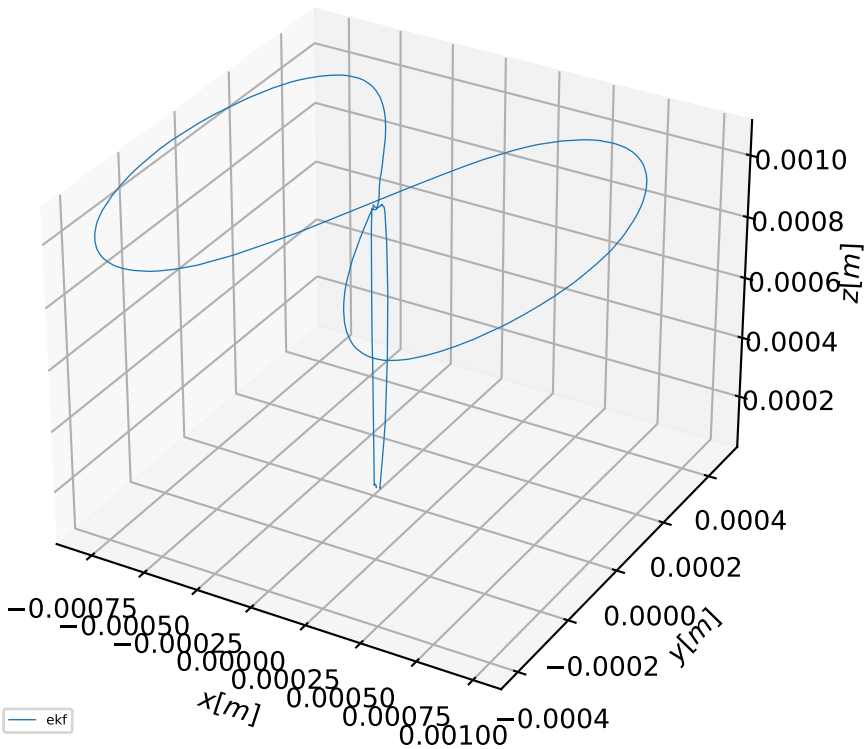
Parameters:

experiment: 184
trajectory: figure8.csv
timescale: 3.0
motors: standard motors (CF)
propellers: standard propellers (CF)

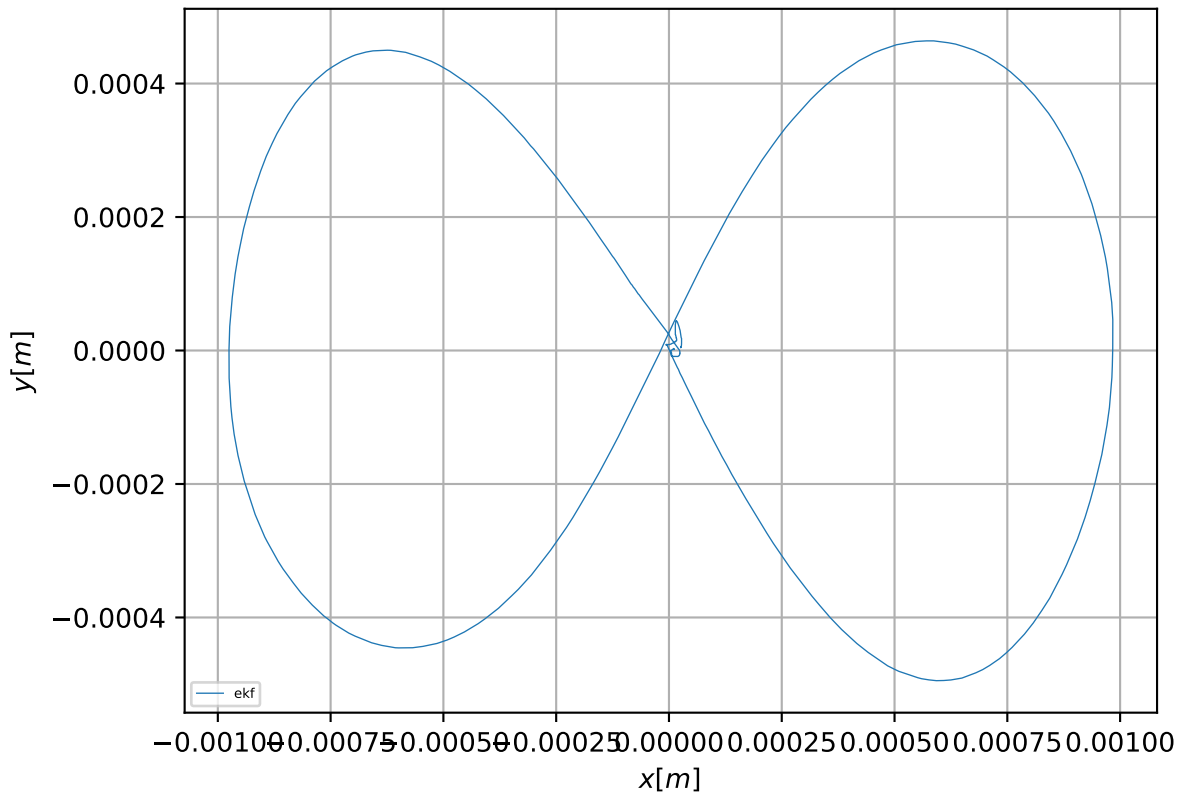
UAV Positions



3D Trajectory



2D Trajectory



%% Report %%

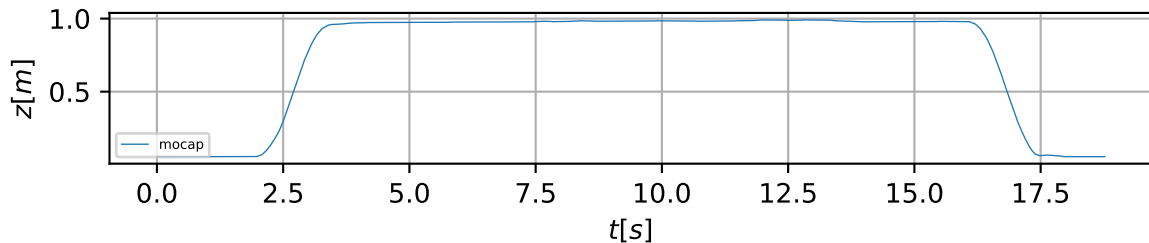
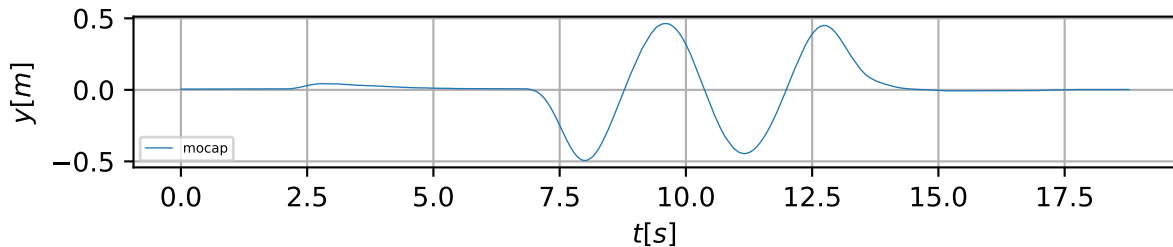
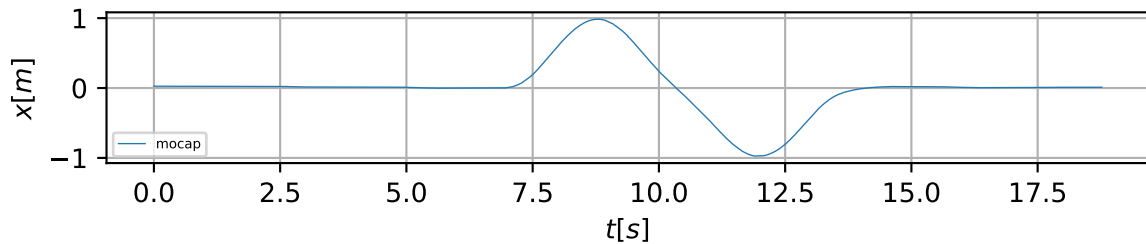
Settings:

data_dir: logs
data_file: cf231_
info_dir: info
info_file: info_cf231_.yaml
event_name: ['fixedFrequency', 'estPosition']
output_dir: reports
start_time: None
end_time: None

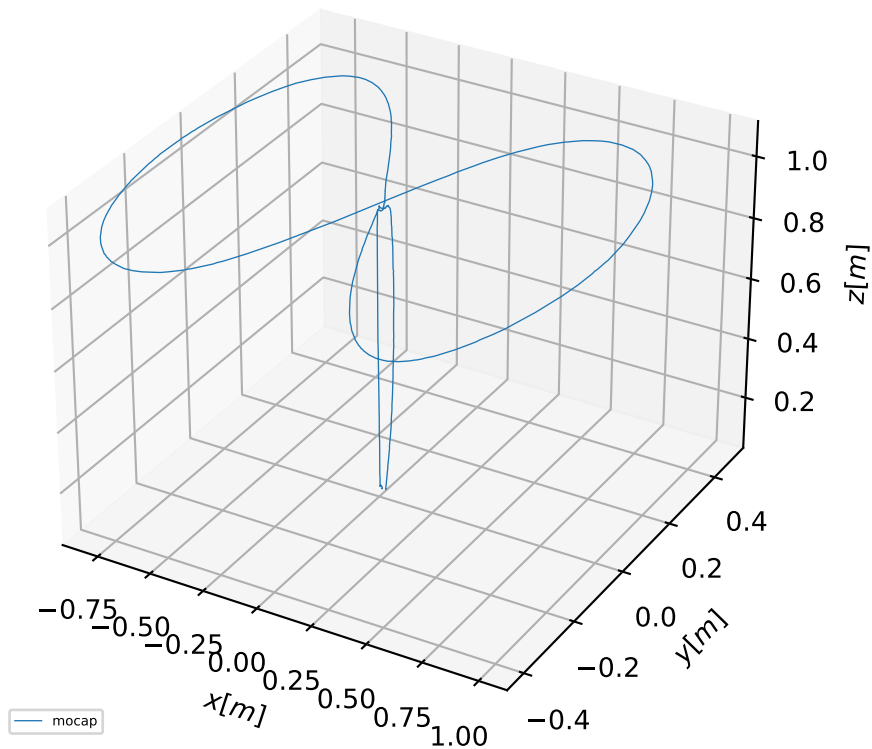
Parameters:

experiment: 184
trajectory: figure8.csv
timescale: 3.0
motors: standard motors (CF)
propellers: standard propellers (CF)

UAV Positions



3D Trajectory



2D Trajectory

