

%% Report %%

Settings:

data_dir: logs
data_file: figure8
info_dir: info
info_file: infofigure8.yaml
event_name: ['fixedFrequency', 'estPosition']
output_dir: reports
start_time: None
end_time: None

Parameters:

experiment: figure8
trajectory: figure8.csv
timescale: 3.0
motors: standard motors (CF)
propellers: standard propellers (CF)

%% Report %%

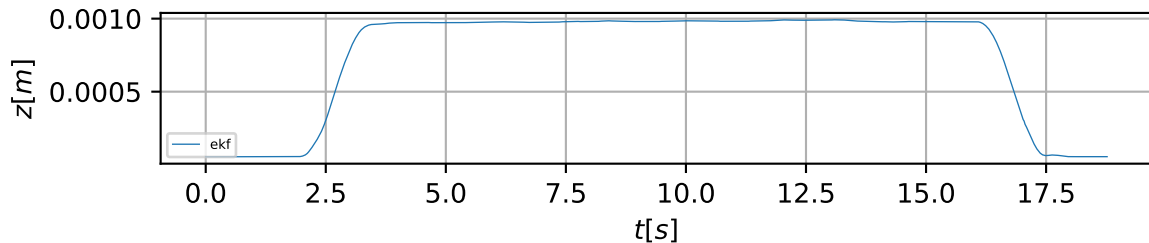
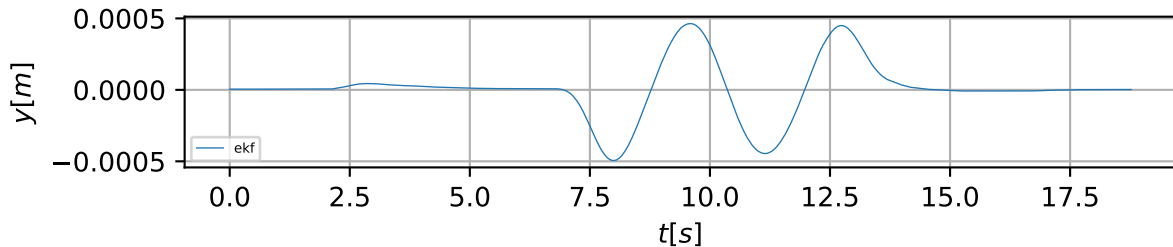
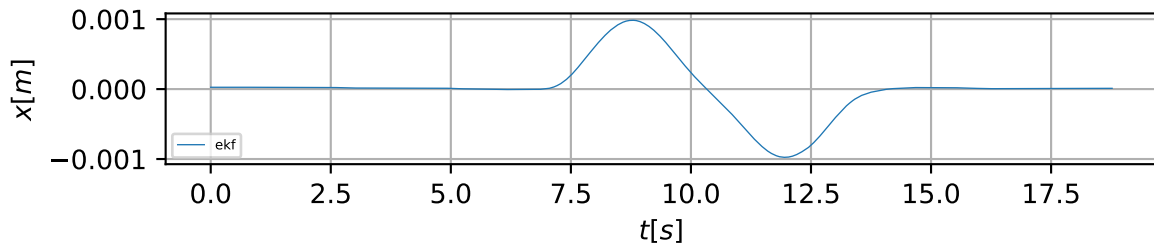
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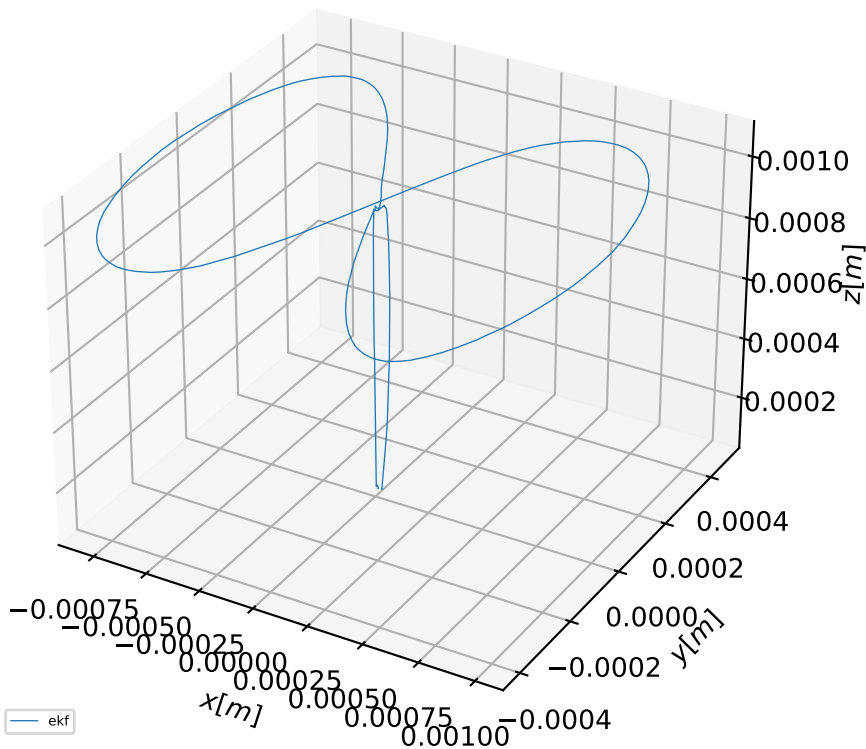
Parameters:

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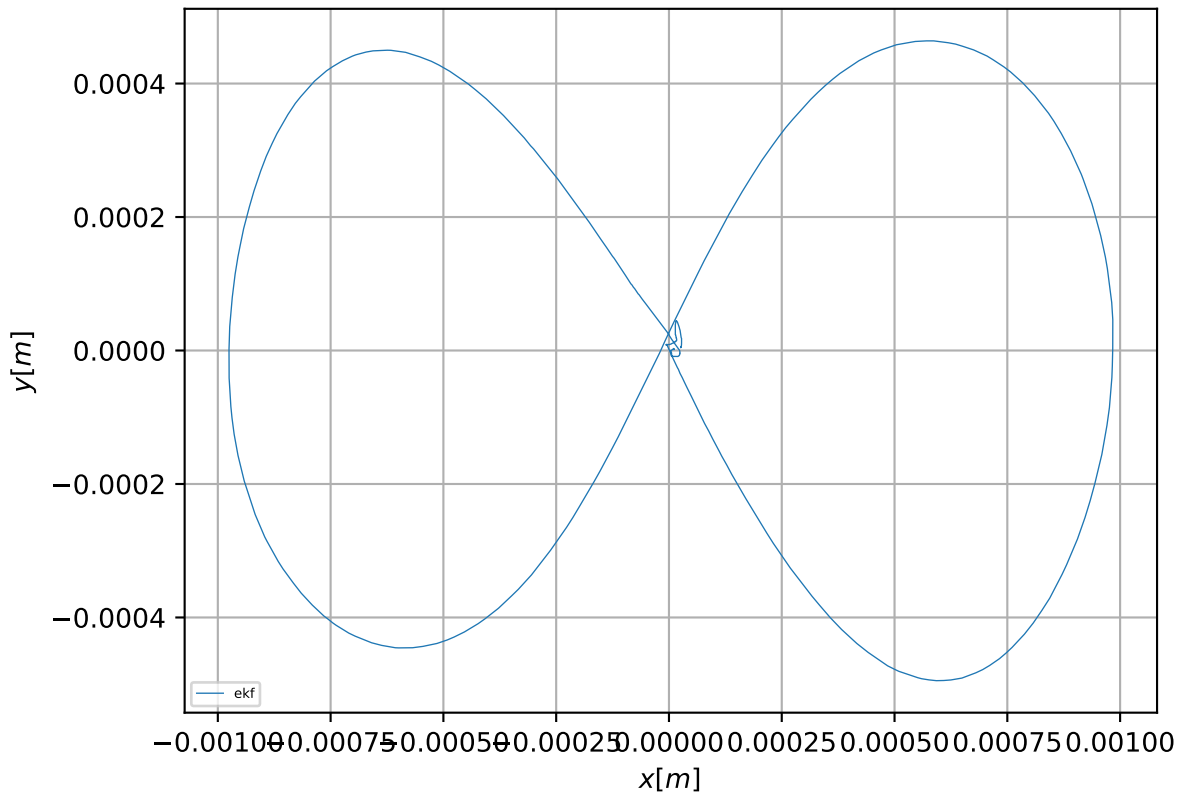
UAV Positions



3D Trajectory



2D Trajectory



%% Report %%

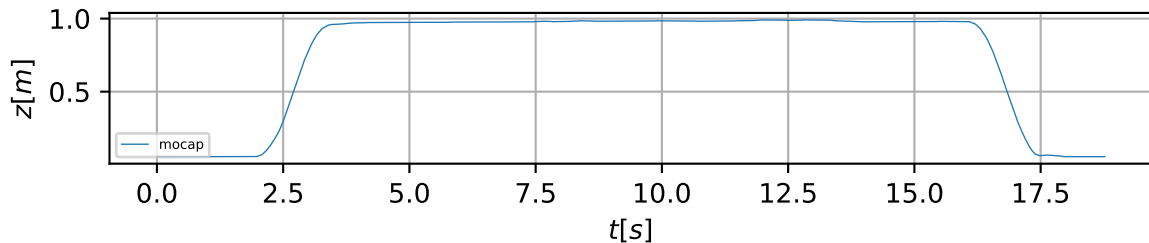
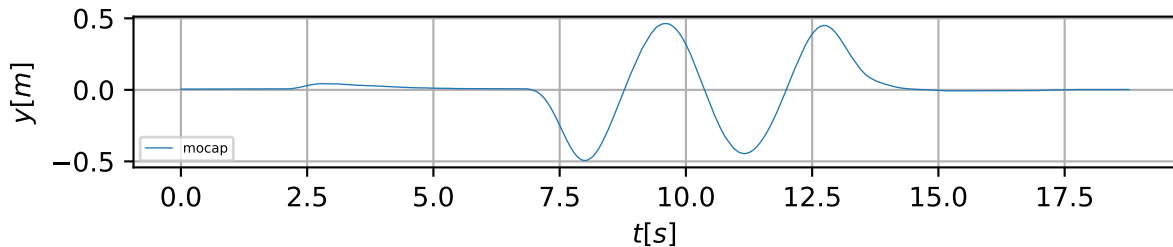
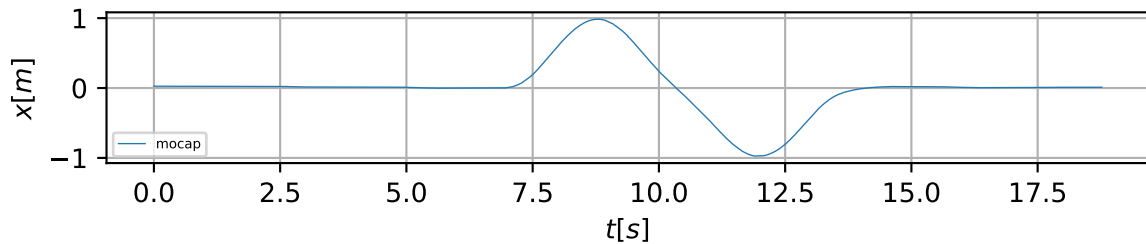
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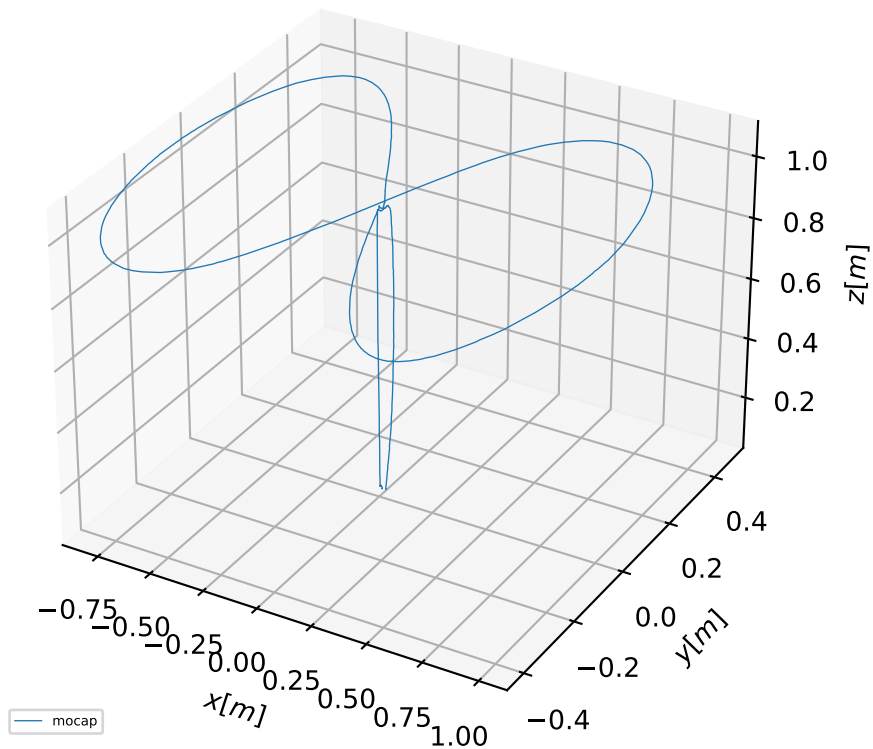
Parameters:

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timescale: 3.0
motors: standard motors (CF)
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UAV Positions



3D Trajectory



2D Trajectory

