#### **SVM**

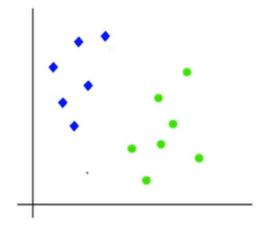
Module-3
Dr. Parimala M
SCORE, VIT

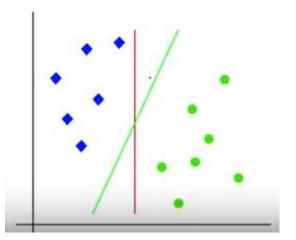
#### Introduction

- Supervised Learning
- Used for both classification and regression, mainly used for classification algorithms
- The goal of SVM is to create a best line or decision boundary that can segregate ndimensional space into classes.
- Best decision boundary is called the hyperplane

 There can be multiple lines to segregate the classes in n-dimensional space but we need to find the best decision boundary to classify the data points

Need to choose the best line that separates the two classes





- The dimensions of the hyperplane depend on the features present in the dataset,
   which means if there are 2 features (as shown in image), then hyperplane will be
   a straight line.
  - And if there are 3 features, then hyperplane will be a 2-dimension plane.
  - We always create a hyperplane that has a maximum margin, which means the maximum distance between the data points.

- The data points or vectors that are the closest to the hyperplane and which affect the position of the hyperplane are termed as Support Vector.
- Since these vectors support the hyperplane, hence called a Support vector.

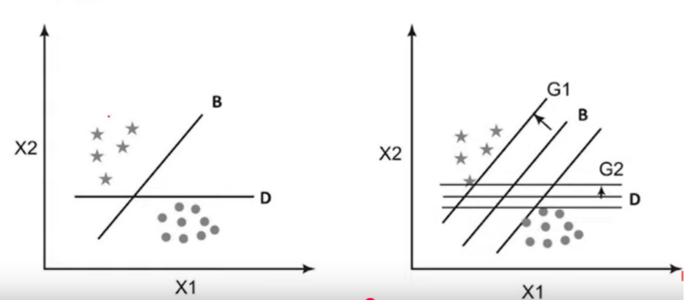
# Types of SVM

#### SVM can be of two types:

- 1. Linear SVM: Linear SVM is used for linearly separable data, which means if a dataset can be classified into two classes by using a single straight line, then such data is termed as linearly separable data, and classifier is used called as Linear SVM classifier.
- 2. Non-linear SVM: Non-Linear SVM is used for non-linearly separated data, which means if a dataset cannot be classified by using a straight line, then such data is termed as non-linear data and classifier used is called as Non-linear SVM classifier.

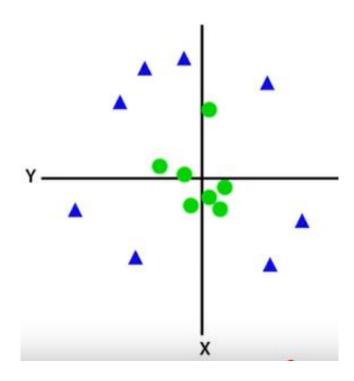
# Linear SVM



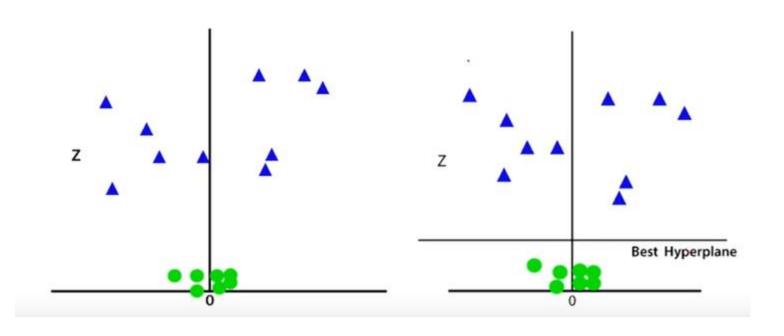


#### Non-Linear SVM

- If data is linearly arranged, then we can separate it by using a straight line, but for non-linear data, we cannot draw a single straight line.
- So to separate these data points, we need to add one more dimension.
- For linear data, we have used two dimensions x and y, so for non-linear data, we will add a third dimension z.
- It can be calculated as: Z=X<sup>2</sup> +y<sup>2</sup>



### Non-Linear SVM



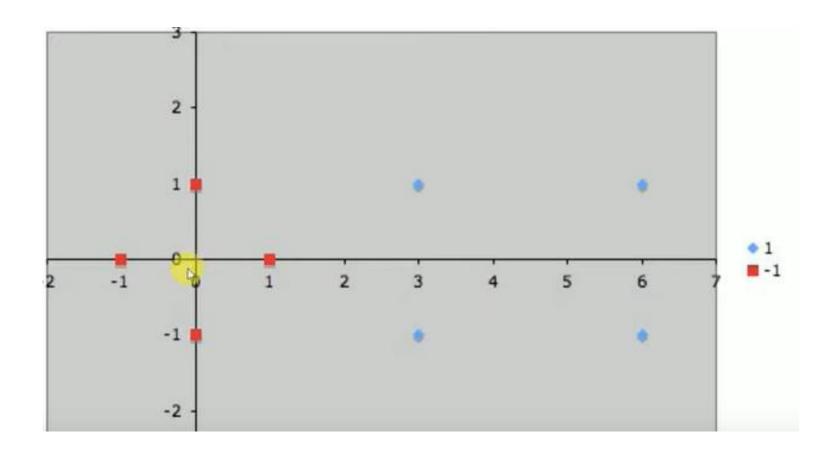
# Linear SVM-Solved example

Suppose we are given the following positively labeled data points,

$$\left\{ \left(\begin{array}{c} 3\\1 \end{array}\right), \left(\begin{array}{c} 3\\-1 \end{array}\right), \left(\begin{array}{c} 6\\1 \end{array}\right), \left(\begin{array}{c} 6\\-1 \end{array}\right) \right\}$$

and the following negatively labeled data points,

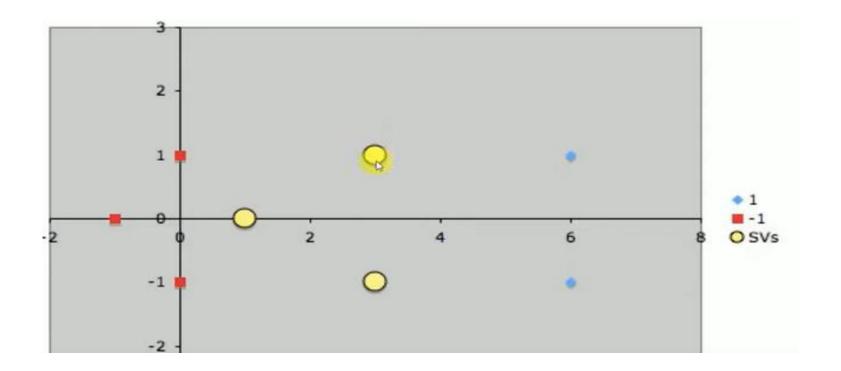
$$\left\{ \left(\begin{array}{c} 1 \\ 0 \end{array}\right), \left(\begin{array}{c} 0 \\ 1 \end{array}\right), \left(\begin{array}{c} 0 \\ -1 \end{array}\right), \left(\begin{array}{c} -1 \\ 0 \end{array}\right) \right\}$$



## Support vectors

· By inspection, it should be obvious that there are three support vectors,

$$\left\{s_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, s_2 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}, s_3 = \begin{pmatrix} 3 \\ -1 \end{pmatrix}\right\}$$



· Each vector is augmented with a 1 as a bias input

• So, 
$$s_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 then  $\widetilde{s_1} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ 

· Similarly,

• 
$$s_2 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$
, then  $\widetilde{s_2} = \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix}$  and  $s_3 = \begin{pmatrix} 3 \\ -1 \end{pmatrix}$ , then  $\widetilde{s_3} = \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix}$ 

$$\begin{array}{lll} \alpha_{1}\tilde{s_{1}}\cdot\tilde{s_{1}}+\alpha_{2}\tilde{s_{2}}\cdot\tilde{s_{1}}+\alpha_{3}\tilde{s_{3}}\cdot\tilde{s_{1}}&=&-1\\ \alpha_{1}\tilde{s_{1}}\cdot\tilde{s_{2}}+\alpha_{2}\tilde{s_{2}}\cdot\tilde{s_{2}}+\alpha_{3}\tilde{s_{3}}\cdot\tilde{s_{2}}&=&+1\\ \alpha_{1}\tilde{s_{1}}\cdot\tilde{s_{2}}+\alpha_{2}\tilde{s_{2}}\cdot\tilde{s_{2}}+\alpha_{3}\tilde{s_{3}}\cdot\tilde{s_{2}}&=&+1\\ \alpha_{1}\tilde{s_{1}}\cdot\tilde{s_{3}}+\alpha_{2}\tilde{s_{2}}\cdot\tilde{s_{3}}+\alpha_{3}\tilde{s_{3}}\cdot\tilde{s_{3}}&=&+1\\ &\alpha_{1}(3+0+1)+\alpha_{2}(9+1+1)+\alpha_{3}(9+1+1)&=&1\\ &\alpha_{1}(3+0+1)+\alpha_{2}(9-1+1)+\alpha_{3}(9+1+1)&=&1\\ \end{array}$$

$$\alpha_{1} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \alpha_{2} \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \alpha_{3} \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = -1$$

$$\alpha_{1} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} + \alpha_{2} \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} + \alpha_{3} \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} = 1$$

$$\alpha_{1} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} + \alpha_{2} \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} + \alpha_{3} \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} + \alpha_{3} \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} = 1$$

$$2\alpha_1 + 4\alpha_2 + 4\alpha_3 = -1$$

$$4\alpha_1 + 11\alpha_2 + 9\alpha_3 = 1$$

$$4\alpha_1 + 9\alpha_2 + 11\alpha_3 = 1$$

$$\alpha_1 = -3.5$$

$$\alpha_2 = 0.75$$

$$\alpha_3 \stackrel{\triangle}{=} 0.75$$

$$\tilde{w} = \sum_{i} \alpha_{i} \tilde{s}_{i}$$

$$= -3.5 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + 0.75 \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} + 0.75 \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix}$$

- Finally, remembering that our vectors are augmented with a bias.
- We can equate the last entry in  $\widetilde{w}$  as the hyperplane offset b and write the separating
- Hyperplane equation y = wx + b
- with  $w = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and b = -2.

