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DATA STRUCTURE USING IN C

UNIT – 1

Data structure

- Data Structure is a branch of Computer Science.
- A data structure is a storage that is used to store and organize all the data items.
- used for processing, retrieving, and storing data.

Why do we use data structure

- Necessary for designing efficient algorithms.
- It helps to organization of all data items within the memory.
- It requires less time.
- Easy access to the large database.

Classification/ Types of Data structure

- **Linear data structure** --allows data elements to be arranged in a sequential or linear fashion.
Example: arrays, linked lists, stack, and queue etc.
- **Non-Linear data structure** -- It is a form of data structure where the data elements do not stay arranged linearly or sequentially.
Example: Tree, graph etc.

Terminologies in Data structure

- **Data** -- Data are values or set of values.
- **Data Item** -- Data item refers to single unit of values.
- **Entity** -- An entity is that which contains certain attributes or properties, which may be assigned values.
- **Entity Set** -- Entities of similar attributes form an entity set.
- **Field** -- Field is a single elementary unit of information representing an attribute of an entity.
- **Record** -- Record is a collection of field values of a given entity.
- **File** -- File is a collection of records of the entities in a given entity set.

Datatypes in C programming

- **Primitive Data Types** -- It is the most basic data types that are used for representing simple values such as:
 - Integers – 23, 33432, 342342 etc.
 - Float – 23.2342, 232.00, 2342.0000, 323.323 etc.
 - Characters - '2', 'a', '\$', '@', 'g' etc.
 - Void – used to specify the type of functions which returns nothing.
- **Non-Primitive Data Types** -- It is derived from primitive data types.
 - Arrays
 - Linked-list
 - Queue
 - Stack etc.

Algorithm

- An algorithm is a step-by-step procedure of any problem.
- **Criteria of an algorithm** --
 1. Input
 2. Output
 3. Definiteness
 4. Finiteness
 5. Effectiveness

Way of analyzing an algorithm --

1. Best case
2. Average case
3. Worst case

Complexity of an algorithm --

- Complexity in algorithms refers to the amount of resources required to solve a problem or perform a task.
- Resources may be time and space.

Types of Complexities of an algorithm --

- **Time complexity** of an algorithm is the amount of time it needs to run to completion.
- **Space complexity** of an algorithm is the amount of space it needs to run to completion.

order of Complexity of an algorithm --

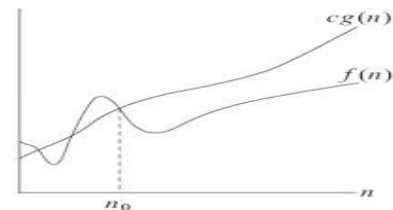
$$O(1) < O(\log n) < O(n) < O(n \log n) < O(n^2) < O(n^3) < O(2^n) < O(3^n) < O(n!)$$

Asymptotic Notation

It is used to write possible running time for an algorithm. It also referred to as 'best case' and 'worst case' scenarios respectively.

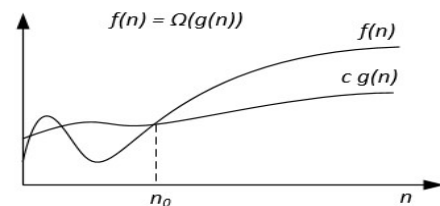
Big-oh notation:

- It is the method of expressing the upper bound of an algorithm's running time.
- It is the measure of the longest amount of time. The function $f(n) = O(g(n))$
- $f(n) \leq c \cdot g(n)$ where $n > n_0$
- Example: $3n+2 = O(n)$ as $3n+2 \leq 4n$ for all $n \geq 2$



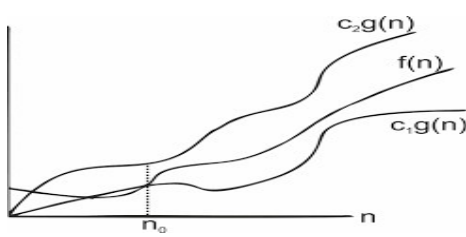
Big-Omega notation:

- It is the method of expressing the lower bound of an algorithm's running time.
- It is the measure of the smallest amount of time. The function $f(n) = \Omega(g(n))$
- $f(n) \geq c \cdot g(n)$ where $n > n_0$
- Example: $3n-3 = \Omega(n)$ as $3n-3 \geq 2n$ for all $n \geq 3$



Theta(Θ) notation:

- It is the method of expressing the both lower and upper bound of an algorithm's running time.
- It is the measure of the average amount of time. The function $f(n) = \Theta(g(n))$
- $c_1 \cdot g(n) \leq f(n) \leq c_2 \cdot g(n)$ where $n > n_0$
- Example: $3n-3 = O(n)$ as $2n \leq 3n-3 \leq 4n$ for all $n \geq 3$



- It is used to implement vectors, and lists in C++ STL.
- Arrays are used as the base of all sorting algorithms.
- It is used to implement other DS like stack, queue, etc.
- Used for implementing matrices.
- Graphs are also implemented as arrays in the form of an adjacency matrix etc.

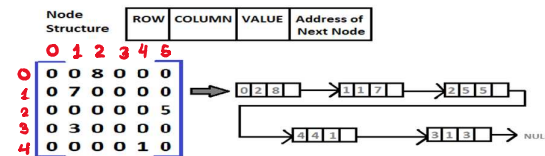
Sparse Matrix

- It is matrix in which most of the elements of the matrix have zero value .
- Only we stored non-zero elements with triples- (Row, Column, value).
- **Array representation of Sparse Matrix –**

	0	1	2	3	4	5
0	0	0	0	0	9	0
1	0	8	0	0	0	0
2	4	0	0	2	0	0
3	0	0	0	0	0	5
4	0	0	2	0	0	0

Rows	Columns	Values
5	6	6
0	4	9
1	1	8
2	0	4
2	3	2
3	5	5
4	2	2

- **Linked list representation of sparse matrix –**

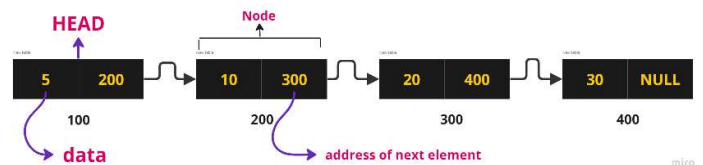


Linked List

- A linked list is a collection of “nodes” connected together via links.
- These nodes consist of the data to be stored and a pointer to the address of the next element .
- Linked list has multiple types:
 1. singly linked list
 2. Doubly linked list
 3. Circular linked list

Singly Linked List (SLL)

- It is a linear data structure in which the elements are not stored in contiguous memory locations .
- Each element is connected only to its next element using address.



- **Representation Node of SLL :**

```
struct node{
    int data; //data item for storing value of the node
    struct node *next; //address of the next node
};
```

- **create Node of SLL:**

```
struct Node* Node(int data){
    struct Node* newNode=(struct Node*)malloc(sizeof(struct Node ));

    newNode->data=data;
    newNode->next=NULL;
    return newNode;
}
```

Time-Space Trade-Off in Algorithms

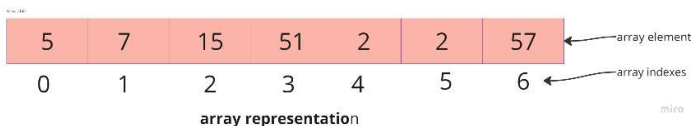
- It is a problem solving technique in which we solve the problem:
 - Either in less time and using more space, or
 - In very little space by spending more time.
- The best algorithm is that which helps to solve a problem that requires less space in memory as well as takes less time to generate the output.
- it is not always possible to achieve both of these conditions at the same time.

Abstract Data type (ADT)

- It is a type (or class) for objects whose behaviour is defined by a set of values and a set of operations.
- The definition of ADT only mentions what operations are to be performed but not how these operations will be implemented.
- Example : if we talk about LIST then here we can store multiple value and it has many built in function so that we will work on that data .
Function such as insert(), delete(), pop(), remove() etc.

Array

- An array is a collection of items stored at contiguous memory locations.
- Array is linear data structure. It is one of the simplest DS.
- The idea is to store multiple items of the same type together.
- **Syntax --** type variable_name [size];
- **Example –** int arr[10]; this is a array declaration of the array now here we can only store 10 integer values in this array
- Array has two type:



1. One dimensional
2. Multidimensional

- **One dimensional Array :**

- Array represented as one-one dimension such as row or column and that holds finite number of same type of data items is called 1D array .

- **Example --** int arr[10];

- **Multi-dimensional Array :**

- Array represented as more than one dimension . there are no restriction to number of dimensions that we can have.

- **Example --** int arr[2][4][5];

- **Application of Array :**

- Arrays can be storing data in tabular format

Operations on SLL

Insert At beginning :

```
struct Node * addAtBeg(int data, struct Node* head){
    struct Node* newNode=Node(data);
    if(head==NULL){
        return newNode;
    }
    newNode->next=head;
    return newNode;
}
```

Insert At End :

```
struct Node * addAtEnd(int data, struct Node* head){
    struct Node* newNode=Node(data);
    if(head==NULL){
        return newNode;
    }
    struct Node* temp=head;
    while ( temp->next !=NULL)
    {
        temp=temp->next;
    }
    temp->next=newNode;
    return head;
}
```

Insert At specific Position :

```
struct Node* addAtPos(int data , int pos , struct Node* head)
{
    if(pos==1){
        return addAtBeg(data,head); }
    struct Node* temp=head;
    for (int i = 1; i <=pos; i++)
    {
        if(i!=pos && temp==NULL){
            return head; //invalid position
        }
        if(i==pos-1){
            struct Node * newNode=Node(data);
            newNode->next=temp->next;
            temp->next=newNode;
            return head;
        }
        temp=temp->next;
    }
    return head;
}
```

Delete at beginning :

```
struct Node * deleteAtBeg( struct Node* head){
    if(head==NULL){
        return NULL;
    }
    return head->next;
}
```

Delete at End :

```
struct Node * deleteAtEnd( struct Node* head){
    if( head==NULL || head->next == NULL){
        return NULL;
    }
    struct Node* temp=head;
    while (temp->next->next !=NULL){
        temp=temp->next;
    }
    temp->next=NULL;
    return head;
}
```

Traverse Linked List:

```
void traverse(struct Node* head){
    while (head->next!=NULL){
        printf("%d ", head->data);
        head=head->next;
    }
}
```

Advantage & disadvantage of singly linked list

Advantages:

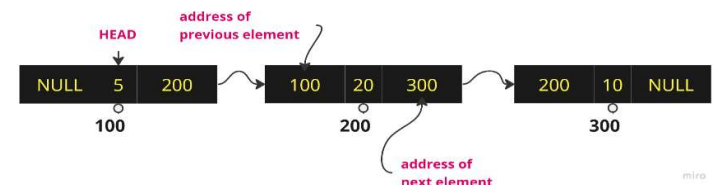
- very easier for the accessibility of a node in the forward direction.
- the insertion and deletion of a node are very easy.
- require less memory when compared to doubly, circular linked list.
- very easy data structure
- Insertion and deletion of elements don't need the movement of all the elements when compared to an array.

Disadvantages :

- Accessing the preceding node of a current node is not possible as there is no backward traversal.
- Accessing of a node is very time-consuming.

Doubly Linked List(DLL)

- A DLL is a complex version of a SLL .
- A DLL has each node pointed to next node as well as previous node.



Representation Node of DLL :

```
struct node
{
    int data; //data item for storing value of the node
    struct node *next; //address of the next node
    struct node *prev; //address of the previous node
};
```

create Node of DLL:

```
struct Node* Node(int data){
    struct Node* newNode=(struct Node*)malloc(sizeof(struct Node ));
    newNode->prev= NULL;
    newNode->data=data;
    newNode->next=NULL;
    return newNode;
}
```

Operations on DLL

Insert At beginning :

```
struct Node * addAtBeg(int data, struct Node* head){
    struct Node* newNode=Node(data);
    if(head==NULL){
        return newNode;
    }
    newNode->next=head;
    head->prev=newNode;
    return newNode;
}
```

Insert At End :

```
struct Node * addAtEnd(int data, struct Node* head){
    struct Node* newNode=Node(data);
    if(head==NULL){
        return newNode;
    }
    struct Node* temp=head;
    while ( temp->next !=NULL)
    {
        temp=temp->next;
    }
    temp->next=newNode;
    newNode->prev=temp;
    return head;
}
```

Delete At beginning:

```
struct Node * deleteAtBeg( struct Node* head){
    if(head==NULL || head->next==NULL){
        return NULL;
    }
    head->next->prev = NULL;
    return head->next;
}
```

delete At End :

```
struct Node * deleteAtEnd( struct Node* head){
    if( head==NULL || head->next == NULL){
        return NULL;
    }
    struct Node* temp=head;
    while (temp->next->next !=NULL){
        temp=temp->next;
    }
    temp->next=NULL;
    return head;
}
```

Traverse DLL :

```
void traverse(struct Node* head){
    while (head!=NULL){
        printf("%d ", head->data);
        head=head->next; } }
```

ReverseTraverse DLL:

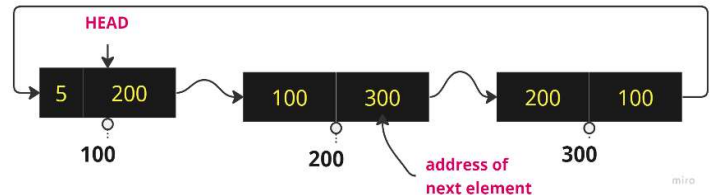
```
void traverseRev(struct Node* head){
    if(head==NULL)
        return;
    while (head->next!=NULL)
        head=head->next;
    while (head!=NULL){
        printf("%d ", head->data);
        head=head->prev;
    }
}
```

Advantage & disadvantage of DLL

- Advantages:**
 - It is bi-directional traversal
 - It is efficient deletion
 - Insertion and deletion at both ends in constant time
- Disadvantages :**
 - Increased memory usage
 - More complex implementation
 - It is slower traversal

Circular Linked List (CLL)

- All nodes are connected to form a circle.
- the first node and the last node are connected to each other which forms a circle.
- There is no NULL at the end.



Operations on CLL

- Insert at beginning
- Insert at specific Position
- Insert at end
- delete at beginning
- delete at specific position
- delete at end

Advantage & disadvantage of CLL

- Advantages:**
 - No need for a NULL pointer
 - Efficient insertion and deletion
 - Flexibility
- Disadvantages :**
 - Traversal can be more complex
 - Reversing of circular list is a complex as SLL.

Row major order & Column major order

```
int arr[2][3]=
{ {1,2,3},
  {4,5,6} } //2D array
```

```
//row major order
{1,2,3,4,5,6}
//column major order
{1,4,2,5,3,6}
```

Address of any element in 1D array

$$\text{Address of } A[I] = B + W * (I - LB)$$

I = element, B = Base address, LB = Lower Bound

W = size of element in any array(in byte),

Example: Given the base address of an array A[1300 1900] as 1020 and the size of each element is 2 bytes in the memory, find the address of A[1700].

Solution :

$$\text{Address of } A[I] = B + W * (I - LB)$$

$$\begin{aligned} \text{Address of } A[1700] &= 1020 + 2 * (1700 - 1300) \\ &= 1020 + 2 * (400) = 1020 + 800 = \underline{1820} \end{aligned}$$

Address of any element in 2D array

$$\text{Row major order : } A[I][J] = B + W * ((I - LR) * N + (J - LC))$$

I = Row element , j=column element , LR=lower limit of row

N = No. of column given in the matrix , LC=lower limit of column

Example: Given an array, arr[1.....10][1.....15] with base value 100 and the size of each element is 1 Byte in memory. Find the address of arr[8][6] with the help of row-major order.

Formula:

$$\text{Address of } A[I][J] = B + W * ((I - LR) * N + (J - LC))$$

Solution:

$$N = \text{Upper Bound column} - \text{Lower Bound column} + 1$$

$$\begin{aligned} A[8][6] &= 100 + 1 * ((8 - 1) * 15 + (6 - 1)) = 100 + 1 * ((7) * 15 + (5)) \\ &= 100 + 1 * (110) = \underline{\underline{210}} \end{aligned}$$

column major order :

$$A[I][J] = B + W * ((J - LC) * M + (I - LR))$$

N = No. of rows given in the matrix

Example: Given an array, arr[1.....10][1.....15] with base value 100 and the size of each element is 1 Byte in memory. Find the address of arr[8][6] with the help of row-major order.

Formula:

$$A[I][J] = B + W * ((J - LC) * M + (I - LR))$$

Solution:

$$M = \text{Upper Bound row} - \text{Lower Bound row} + 1$$

$$A[I][J] = B + W * ((J - LC) * M + (I - LR))$$

$$A[8][6] = 100 + 1 * ((6 - 1) * 10 + (8 - 1))$$

$$= 100 + 1 * ((5) * 10 + (7)) = 100 + 1 * (57) = \underline{\underline{157}}$$

Difference between Array and Linked List

Array	Linked List
It is stored in a contiguous memory location.	It can be stored randomly in the memory .
elements are independent of each other.	elements are dependent on each other
memory is allocated at compile-time.	memory is allocated at run time
Accessing any element in an array is faster	Accessing an element in a linked list is slower
Array takes more time while performing any operation like insertion, deletion, etc.	Linked list takes less time while performing any operation like insertion, deletion, etc.