

Transformations

* The need for transformation

- 1) Linearity of the regression - diagnosis: a plot of e_i against y_i reveals a trend (linear, logarithmic, exponential, etc.)
- 2) Normality of the residuals - outliers or skewness / heavy tails of y_i . Transformation on y may do the trick.
- 3) Variance stabilization

* Our hope is to settle all of these issues at once, but we may not be able to. Either way, we'll try.

* Variance stabilization transformations

* Suppose we have a sequence of random variables Y_1, \dots, Y_n w/ $E[Y_i] = \mu_i$ and $\text{Var}(Y_i) = \sigma_i^2$

* Suppose in particular that σ_i^2 is a function of μ_i :

$$\sigma_i^2 = g(\mu_i)$$

$$\text{ex: } Y_i \sim \text{Po}(\lambda) \Rightarrow \sigma^2 = \mu \Rightarrow g(\mu) = \mu$$

- * Aim: find a function $h(Y_i)$ whose variance is constant.
- * To do this, we use a Taylor approximation for $h(Y_i)$:

$$h(Y_i) - h(\mu_i) \approx (y_i - \mu_i) h'(\mu_i)$$

$$\Rightarrow \text{Var}(h(Y_i)) \approx (h'(\mu_i))^2 \sigma_i^2 \quad (*)$$

Note that the RHS(*) will be constant if

$$(h'(\mu))^2 g(\mu) = \text{constant} \quad (**)$$

- * Point: If we know $g(\mu)$, we can exactly determine the function / transformation h of Y_i that gives a constant variance by solving (**).

- * For many distributions, we can solve (**) and hence come up w/ a variance stabilizing transformation.

- * Example: $Y_i \sim \text{Po}(\lambda_i)$

$$\text{Then, } \sigma_i^2 = \lambda_i \Rightarrow g(\lambda_i) = \lambda_i$$

Solving (**) gives $h(\lambda_i) = \sqrt{\lambda_i}$ and in fact

$$\begin{aligned}(h'(\lambda_i))^2 \lambda_i &= \left(\frac{1}{2} \lambda_i^{-\frac{1}{2}}\right)^2 \lambda_i \\ &= \frac{1}{4}\end{aligned}$$

So, the $\sqrt{Y_i}$ is a variance stabilizing transform for Poisson (count) data, and in so doing we expect $\text{Var}(Y_i) \equiv \frac{1}{4}$.

* Box-Cox Families of Transformations

- * Many transformations we can take can be embedded into a power law family. This class, known as Box-Cox transformations can be written as:

$$h(y) = \frac{y^\lambda - 1}{\lambda} \quad (\text{Box-Cox})$$

where λ can take on any real number. For $\lambda = 0$, we have $h(y) = \ln(y)$.

* Choosing λ

- * The general approach for choosing from a possible Box-Cox transformation is to calculate λ through maximum likelihood estimation.
- * I forego the details here but show the example of how to do this from page 111 of Faraway.

- * The `boxcox()` function will return a confidence interval for λ for which you choose the most interpretable value.
- * Notably: if $\lambda = 1$ is in the CI, we have no good reason to perform a transformation.
- * Important Point about Inference after a Transformation: Any inference that you make will now be about the linear effect of x on $h(y)$. You have to think carefully about how to bring CIs on β for this model back to CIs for β for x on y .

Example: $h(y) = x\beta + \varepsilon$

$$\Rightarrow y = h^{-1}(x\beta + \varepsilon)$$