Ravi Tej Akella

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Education

Carnegie Mellon University — School of Computer Science — Pittsburgh, PA
Master of Science in Robotics — GPA: 4.2/4.33 — *Aug 2021 - Aug 2023*

Indian Institute of Technology (IIT) Roorkee — Roorkee, India
Bachelor of Technology in Electronics & Communication Engineering — GPA: 8.129/10 — *Jul 2014 - May 2018*
Minors in Computer Science & Engineering

Selected Coursework: Computer Vision (16-720), Statistical Techniques in Robotics (16-831), Learning for 3D Vision (16-825), Optimal Control & Reinforcement Learning (16-745).

Experience

Tesla AI | AutoPilot — Palo Alto, CA

`Senior Machine Learning Scientist` — *Jun 2025 – Present*
`Machine Learning Scientist` — *Aug 2023 – Jun 2025*

- Train end-to-end self-driving neural networks for Tesla Full Self-Driving (FSD) Beta v12, v13 and v14.

Cruise Automation | Maneuver Planning — San Francisco, CA

`Machine Learning Engineer Intern` — *May 2022 - Aug 2022*

- Leveraged imitation learning to reduce the trajectory optimizer latency in the AV stack by 10%.
- Designed a neural network architecture that generates kinematically feasible trajectory proposals.
- Trained a conditional generative model that provides high-reward and diverse trajectory samples.

Carnegie Mellon University | School of Computer Science — Pittsburgh, PA

`Research Assistant (Russ Lab, Machine Learning Department)` — *Aug 2022 - July 2023*

- Developed a self-supervised learning method for goal-conditioned RL that exploits the Markov property in MDPs.
- Presented at ICML Learning, Control, and Dynamical Systems workshop.

`Research Assistant (Auton Lab, The Robotics Institute)` — *Sep 2021 - July 2023*

- Designed a hierarchical offline RL algorithm that uses latent diffusion for batch-constrained Q-learning.
- More stable and offers superior performance relative to prior offline RL works on the D4RL benchmark.

California Institute of Technology | Anima AI + Science Lab — Remote

`Researcher` — *Oct 2018 - Dec 2020*

- Developed a new policy gradient estimator that uses Bayesian quadrature for more accurate gradient estimation.
- Implemented kernel interpolation and fast-SVD to reduce the computational complexity from cubic to linear.
- Lead contributor on this collaborative project between Caltech and Google Research.

Publications

- Distributional Distance Classifiers for Goal-Conditioned Reinforcement Learning. *Ravi Tej Akella, B. Eysenbach, R. Salakhutdinov, J. Schneider.* **ICML Workshop** 2023. [Link]
- Reasoning with Latent Diffusion in Offline Reinforcement Learning. *S. Venkatraman*, S. Khaitan*, Ravi Tej Akella*, J. Dolan, J. Schneider, G. Berseth.* **ICLR** 2024. [Link]
- Deep Bayesian Quadrature Policy Optimization. *Ravi Tej Akella, K. Azizzadenesheli, M. Ghavamzadeh, A. Anandkumar, Y. Yue.* **AAAI** 2021, **NeurIPS Deep RL & Real-World RL Workshops** 2020. [Link]
- Enhancing Perceptual Loss with Adversarial Feature Matching for Super-Resolution. *Ravi Tej Akella, S. Halder, A. Shandilya, V. Pankajakshan.* International Joint Conference on Neural Networks (**IJCNN**) 2020. [Link]
- Reinforced Multi-task Approach for Multi-hop Question Generation. *D. Gupta, H. Chauhan, Ravi Tej Akella, A. Ekbal, P. Bhattacharyya.* International Conference on Computational Linguistics **(COLING)** 2020. [Link]
- Randomized Kernel-Based Secret Image Sharing (SIS) Scheme. ***Ravi Tej Akella**, R. Teja, V. Pankajakshan.* IEEE International Workshop on Information Forensics and Security (**WIFS**) 2018. [Link]

Technical Skills

Languages: Python, C, C++, Java, Shell, LaTeX, MATLAB and Simulink
Frameworks & Technologies: PyTorch, Jax, TensorFlow, Keras, Git, Linux