Propeller Library

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1 Table of Contents

2 Pin Functions

To use the pin functions, include the <propeller/pins.h" header file.

2.1 pinInput

Prototype

```
void pinInput(int pin);
```

Parameters

[in]	pin	Pin number

Description

Sets a pin to an input. Pins are inputs by default but if a pin has been used as an output and you then want to use it as an input you should call this function first.

Returns

Nothing

2.2 pinOutput

Prototype

```
void pinOutput(int pin);
```

Parameters

[in]	pin	Pin number

Description

Sets a pin to an output. Since pins are inputs by default, this function must be called before you use it as an output.

Returns

Nothing

2.3 pinGetDirection

Prototype

```
int pinGetDirection(int pin);
```

Parameters

[in]	pin	Pin number

Description

Gets the direction of a pin. Returns 0 for input pins and 1 for output pins.

Returns

The pin direction.

2.4 pinSetDirection

Prototype

```
void pinSetDirection(int pin, int direction);
```

Parameters

[in]	pin	Pin number
[in]	direction	Pin direction

Description

Sets the direction of a pin. Set direction to 0 for input pins and 1 for output pins. Since pins are inputs by default, this function or pinOutput must be called to set a pin to be an output before you use it as an output.

Returns

The pin direction.

2.5 pinReverseDirection

Prototype

```
void pinReverseDirection(int pin);
```

Parameters

[in]	pin	Pin number

Description

Reverses the direction of a pin. If the pin was an output, it becomes an input. If it was an input, it becomes an output.

Returns

Nothing

2.6 pinGet

Prototype

```
int pinGet(int pin);
```

Parameters

[in]	pin	Pin number

Description

Gets the value of an input pin.

Returns

The pin value.

2.7 pinSet

Prototype

```
void pinSet(int pin, int value);
```

Parameters

[in]	pin	Pin number
[in]	value	The new pin value

Description

Sets the value of an output pin. Since pins are inputs by default, the pin should be set to an output using either pinOutput or pinSetDir prior to calling this function.

Returns

Nothing

2.8 pinGetField

Prototype

```
int pinGetField(int high, int low);
```

Parameters

[in]	high	High pin number
[in]	low	Low pin number

Description

Get the value of a group of pins starting with the high pin and ending with the low pin. For convenience, the high and low pin numbers can be swapped. This function allows a group of contiguous pins to be treated as a multi-bit field.

Returns

The value of the pins in the field.

2.9 pinSetField

Prototype

```
void pinSetField(int high, int low, int value);
```

Parameters

[in]	high	High pin number
[in]	low	Low pin number
[in]	value	Value to write to the field

Description

Set the value of a group of pins starting with the high pin and ending with the low pin. For convenience, the high and low pin numbers can be swapped. This function allows a group of contiguous pins to be treated as a multi-bit field.

Returns

Nothing

2.10 pinHigh

Prototype

```
void pinHigh(int pin);
```

Parameters

[in]	pin	Pin number

Description

Sets an output pin high. Since pins are inputs by default, the pin should be set to an output using either pinOutput or pinSetDir prior to calling this function.

Returns

Nothing

2.11 pinLow

Prototype

```
void pinLow(int pin);
```

Parameters

[in]	pin	Pin number

Description

Sets an output pin low. Since pins are inputs by default, the pin should be set to an output using either pinOutput or pinSetDir prior to calling this function.

Returns

Nothing

2.12 pinToggle

Prototype

```
void pinToggle(int pin);
```

Parameters

[in]	pin	Pin number

Description

Toggles an output pin. Since pins are inputs by default, the pin should be set to an output using either pinOutput or pinSetDir prior to calling this function.

Returns

Nothing

2.13 pinPulseIn

Prototype

```
void pinPulseIn(int pin, int state);
```

Parameters

[in]	pin	Pin number
[in]	state	Pin state to measure

Description

Measures a pulse on an input pin.
If state is 0, it measures a pulse starting immediately if the pin is already low or at the next high to low transition if it is high and ending at a low to high transition.

If state is 1, it measures a pulse starting immediately if the pin is already high or at the next low to high transition if it is low and ending at a high to low transition.

Returns

The duration of the pulse in clock ticks.

2.14 pinPulseOut

Prototype

```
void pinPulseOut(int pin, int duration);
```

Parameters

[in]	pin	Pin number
[in]	duration	Pulse duration in clock ticks

Description

Generates a pulse of the specified duration on an output pin. The pulse starts by toggling the state of the specified pin and ends by toggling it again. If the pin is low when this function is called, it will be set high for the specified duration and then back low again. If it is high when this function is called, it will be set low for the specified duration and then set high again.

Returns

Nothing

3 I2C Functions

To use the I2C functions, include the <propeller/i2c.h" header file.

3.1 i2cInit

Prototype

```
int i2cInit(
          I2C_STATE *dev,
          int scl,
          int sda,
          int frequency);
```

Parameters

[out]	dev	I2C state structure
[in]	scl	SCL pin number
[in]	sda	SDA pin number
[in]	frequency	I2C bus frequency

Description

Initializes an I2C device on the specified pins. The bus frequency can be set as high as 1mhz. This function must be called to initialize the I2C_STATE structure before any of the other I2C functions can be called. This function starts an I2C driver on another COG.

Returns

0	Success
-1	Failure

3.2 i2cTerm

Prototype

```
int i2cTerm(I2C_STATE *dev);
```

Parameters

[in]	dev	I2C state structure

Description

Terminates an I2C device and releases the COG that was running the I2C driver.

Returns

0	Success
-1	Failure

3.3 i2cSendBuf

Prototype

```
int i2cSendBuf(
          I2C_STATE *dev,
          int address,
          uint8_t *buffer,
          int count);
```

Parameters

[in]	dev	I2C state structure
[in]	address	I2C address
[in]	buffer	Buffer containing bytes to send
[in]	count	Count of bytes in the buffer

Description

Sends a buffer of data to the specified I2C address. The I2C_STATE structure must have been initialized by a call to i2cInit before calling this function.

Returns

0	Success
-1	Failure

3.4 i2cBegin

Prototype

```
int i2cBegin(I2C_STATE *dev, int address);
```

Parameters

[in]	dev	I2C state structure
[in]	address	I2C address

Description

Begins building a command to send to the I2C device at the specified address. Bytes can be added to the command using the i2cSend function. Once all of the necessary bytes are added to the command, the i2cEnd function is used to send the command to the I2C device. The I2C_STATE structure must have been initialized by a call to i2cInit before calling this function.

Returns

0	Success
-1	Failure

3.5 i2cAddByte

Prototype

```
int i2cAddByte(I2C_STATE *dev, int byte);
```

Parameters

[in]	dev	I2C state structure
[in]	byte	Byte to send

Description

Adds a byte to a command started by a call to i2cBegin. Up to 32 bytes can be added to a command. Once all of the necessary bytes are added to the command, the i2cEnd function is used to send the command to the I2C device.

Returns

0	Success
-1	Failure

3.6 i2cSend

Prototype

```
int i2cSend(I2C_STATE *dev);
```

Parameters

[in]	dev	I2C state structure
[in]	byte	Byte to send

Description

Sends the I2C command that was begun with a call to i2cBegin followed by calls to i2cAddByte.

Returns

0	Success
-1	Failure

3.7 i2cRequestBuf

Prototype

```
int i2cRequestBuf(
          I2C_STATE *dev,
          int address,
          uint8_t *buffer,
          int count);
```

Parameters

[in]	dev	I2C state structure
[in]	address	I2C address
[out]	buffer	Buffer for the bytes received
[in]	count	Count of bytes to receive

Description

Receives a buffer of data from the specified I2C address. The I2C_STATE structure must have been initialized by a call to i2cInit before calling this function.

Returns

0	Success
-1	Failure

3.8 i2cRequest

Prototype

```
int i2cRequest(
          I2C_STATE *dev,
          int address,
          int count);
```

Parameters

[in]	dev	I2C state structure
[in]	address	I2C address
[in]	count	Count of bytes to receive

Description

Receives and buffers data from the specified I2C address. After this function has been called, the i2cGetByte function can be called to get each byte from the received message. The I2C_STATE structure must have been initialized by a call to i2cInit before calling this function.

Returns

0	Success
-1	Failure

3.9 i2cGetByte

Prototype

```
int i2cGetByte(I2C_STATE *dev);
```

Parameters

[in]	dev	I2C state structure

Description

Gets a byte from the data that was retrieved with a call to i2cRequest. The i2cRequest function must have been called prior to calling this function and only the number of bytes requested can be fetched using i2cGetByte.

Returns

0	Success
-1	Failure