LP1 Assignment AIR A4

N-Queens using backtracking

Date - 19th October, 2020.

Assignment Number - AIR A4

Title

N-Queens using backtracking

Problem Definition

Implement backtracking for N-Queens

Learning Objectives

To learn and implement backtracking

Learning Outcomes

I will be able to learn and implement backtracking for N-Queens

Software Packages and Hardware Apparatus Used

- Operating System: 64-bit Ubuntu 18.04
- Programming Language: Python 3
- Jupyter Notebook Environment : Google Colaboratory

Programmers' Perspective

S = {s; e; X; Y; Fme; Ff; DD; NDD}

S = {s; e; X; Y; Fme; Ff; DD; NDD}

s = start state

- $s = \{n\}$
 - Where n is the number of queens

e = end state

• e = {2D Representation of the nxn Chess Board with all the queens placed}

 $X = {X1}$

• X1 = s

 $Y = \{Y1\}$

Y1 = e

Fme = $\{f0\}$

• f0 = function to perform backtracking

 $Ff = \{f1, f2, f3, f4, f5, f6\}$ where

- f1 = function for Agent : Perception
- f2 = function for Agent : Cognition
- f3 = function for Agent : Action
- f4 = function for Agent : Goal
- f5 = function to place a queen
- f6 = function to unplace a queen

DD = integer array of size n

NDD = No non deterministic data

Concepts related Theory

N Queens

- The N queens puzzle is the problem of placing N chess queens on an 8×8 chessboard so that no two queens threaten each other, where N is a natural number.
- Thus, a solution requires that no two queens share the same row, column, or diagonal.

Backtracking

 Backtracking is a general algorithm for finding all (or some) solutions to some computational problems, notably constraint satisfaction problems • It incrementally builds candidates to the solutions, and abandons a candidate ("backtracks") as soon as it determines that the candidate cannot possibly be completed to a valid solution.

Mathematical Model

for a given n, N-Queens has been defined as a Constraint Satisfaction Problem

N' is a set of Whole Numbers less than n

$$N' = \{x \mid x \in W \text{ and } x < n \}$$

Set of variable representing n Queens

$$X = \{Q_i\} \forall i \in N'$$

Set of Domain for each Queen

$$D = \{D_i \mid D_i \in N'\} \ \forall \ i \in N'$$

Set of Constraints Two types of constraints for any two queens Each queen is placed in a different column at the time of input itself, therefore we don't need to define a constraint for it explicitly.

$$C = \{C^1{}_i \mathbb{X}, \, C^2{}_i \mathbb{X}\} \, \, \forall \, \, i,j \, \Subset \, \, N'$$

Constraint C¹_i∅:

For two queens Q_i and Q_i , no two queens can be on the same row.

$$\begin{array}{cccc} \bullet & C^1{}_i \mathbb{X} = < t^1{}_i \mathbb{X}, \ R^1{}_i \mathbb{X}> \\ & \circ & t^1{}_i \mathbb{X} = \{Q_i, Q\mathbb{X}\} \\ & \circ & R^1{}_i \mathbb{X} = \{x \neq y \mid x = Q_i \ and \ y = Q\mathbb{X}\} \end{array}$$

Constraint C^2_i :

For two queens Q_i and $Q\mathbb{Z}$, no two queens can be on the same diagonal.

$$\begin{split} \bullet \quad & C^2{}_i \mathbb{X} = \langle t^2{}_i \mathbb{X}, \ R^2{}_i \mathbb{X} \rangle \\ & \circ \quad & t^2{}_i \mathbb{X} = \{i,j,Q_i,Q\mathbb{X}\} \\ & \circ \quad & R^2{}_i \mathbb{X} = \{\ |x-y| \neq |x'-y'| \ | \ x=i,\ x'=Q_i,\ x'=j,\ x'=Q\mathbb{X} \} \end{split}$$

Initial State

Given n.

Where n is the number of queens to be placed

Perception

Given n number of queens

- Consider an integer array of size n.
- Each element represents a queen
- Index of the element represents column of the queen
- Value of the element represents row of the queen
- If the queen is unplaced, value of the element is -1

Cognition

N Queens is being solved using backtracking

With each step we need to check for three constraints

- 1. If two Queens are in the same row
- 2. If two Queens are in the same normal diagonal
- 3. If two Queens are in the same backward diagonal

Since we are placing/unplacing a queen one column at a time, we need not check for it

To Lookup these constraints in real time, we use three boolean arrays

The size of the boolean array to look up row is n

The size of the other two is (2*n-1)

The index of the lookup of normal diagonal is (row+col)

The index of the lookup of backward diagonal is (row-col+n-1)

The value 'n-1' is to lookup of backward diagonal to facilitate zero-based indexing

Action

Algorithm for solving N queens using backtracking

Algorithm: N-Queen(j)

- n is the number of queens
- queens[] is an integer array which stores row number of a queen
- queens' indexes represent the column number of a queen
- j is the column in which we will be placing the queen, starting from 0
- rowLookUp is a boolean array which is True for rows in which a new queen cannot be placed

- diagonalNormalLookUp is a boolean array which is True for normal diagonal in which a new queen cannot be placed
- diagonalBackwardLookUp is a boolean array which is True for backward diagonals in which a new queen cannot be placed
- Possible(i,j) returns true if rowLookUp(i)=False and diagonalNormalLookUp(i+j)=False and diagonalBackwardLookUp(i-j+n-1)=False

Steps:

- 1. if j=n then
 - 1. return true
- 2. for i <- 1 to n do
 - 1. if Possible(i,j) then do
 - 1. queens[j] <- i
 - 2. rowLookUp[i] <- True
 - 3. diagonalNormalLookUp[i+j] <- True
 - 4. diagonalBackwardLookUp[i-j+n-1] <- True
 - 5. if N-Queen(j+1) then
 - 1. return true
 - 6. queens[i] <- -1
 - 7. rowLookUp[i] <- False
 - 8. diagonalNormalLookUp[i+j] <- False
 - 9. diagonalBackwardLookUp[i-j+n-1] <- False
- 3. return false

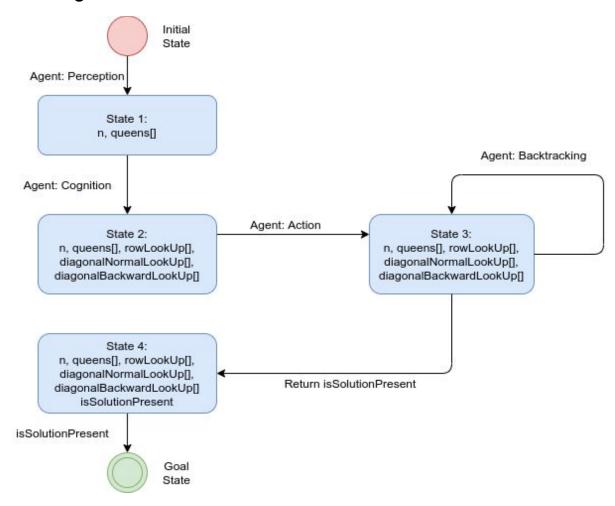
Goal State

- Boolean value isSolutionPresent
- 2D Representation of the nxn Chessboard

Class Diagram

N_Queens queens[] rowLookUp[] diagonalNormalLookUp[] diagonalBackwardLookUp[] _init__(n) __str() setRowLookUp(row) setDiagonalNormalLookUp(row,col) setDiagonalBackwardLookUp(row,col) unsetRowLookUp(row) unsetDiagonalNormalLookUp(row,col) unsetDiagonalBackwardLookUp(row,col) ifPossible(row,col) _solveRecursive(col) solve()

State Diagram



Source Code (Modified using PCAG)

```
"''CALLING THE FOUR STATES'''
#Parameterized Constructor

def __init__(self, n):
    self.perception(n)
    self.cognition(n)
    isSolutionPresent = self.action()
    self.goal(isSolutionPresent)
```

class N Queens PCAG:

```
'''PERCEPTION'''
def perception(self, n):
 self.n = n
 self.queens = [-1] * n
 print('\nBefore Solving : ',self)
 return n
'''COGNITION'''
def cognition(self, n):
 self.rowLookUp = [False] * n
  self.diagonalNormalLookUp = [False] * (n+n-1)
  self.diagonalBackwardLookUp = [False] * (n+n-1)
'''ACTION'''
def action(self):
 return self.backtrack(0)
'''BACKTRACKING FUNCTION'''
def backtrack(self, col):
  #Return True if N Queens have been placed
 if col == self.n:
      return True
  #For each cell in the current column
  for row in range(self.n):
    #If It is possible to place a Queen
    if self.ifPossible(row, col):
      #Place the Queen and Set the lookups
      self.placeQueen(row, col)
```

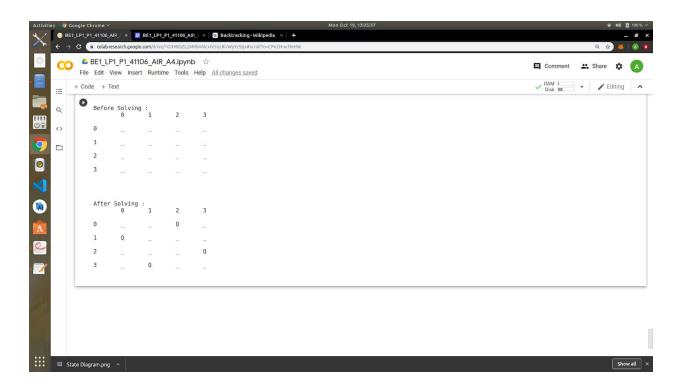
```
#Try to place the next queen in the next column
      if self.backtrack(col + 1) == True:
        return True
      #Unplace the Queen and unset the lookups
      self.unplaceQueen(row, col)
  #Return False if No queens were placed in the Column
  return False
'''GOAL'''
def goal(self, isSolutionPresent):
 if not isSolutionPresent:
   print('Solution is not present')
 print('\n\nAfter Solving : ',self)
'''STRING REPRESENTATION'''
#Print Object as a board
def str (self):
 res = ' n t'
 for num in range(self.n):
   res += (str(num) + "\t")
  res += '\n\n'
  board = [[ ' ' for j in range(self.n)] for i in range(self.n)]
  for col, row in enumerate(self.queens):
    if (row!=-1):
     board[row][col] = 'O'
  for index, i in enumerate(range(self.n)):
    res += str(index) + "\t"
    for j in range(self.n):
     res += (str(board[i][j]) + "\t")
    res += ' n n'
  return res
```

```
'''HELPER FUNCTIONS'''
#Set and Unset Functions for the Lookups
def setDiagonalNormalLookUp(self,row,col):
      self.diagonalNormalLookUp[row+col] = True
def unsetDiagonalNormalLookUp(self,row,col):
      self.diagonalNormalLookUp[row+col] = False
def setDiagonalBackwardLookUp(self,row,col):
      self.diagonalBackwardLookUp[row-col+self.n-1] = True
def unsetDiagonalBackwardLookUp(self,row,col):
      self.diagonalBackwardLookUp[row-col+self.n-1] = False
def setRowLookUp(self,row):
      self.rowLookUp[row] = True
def unsetRowLookUp(self,row):
      self.rowLookUp[row] = False
def ifPossible(self, row, col):
  return ( self.rowLookUp[row] == False and
          self.diagonalNormalLookUp[row+col] == False and
          self.diagonalBackwardLookUp[row-col+self.n-1] == False )
def placeQueen(self, row, col):
  self.queens[col] = row
  self.setRowLookUp(row)
  self.setDiagonalNormalLookUp(row,col)
  self.setDiagonalBackwardLookUp(row,col)
def unplaceQueen(self, row, col):
  self.queens[col] = -1
  self.unsetRowLookUp(row)
  self.unsetDiagonalNormalLookUp(row,col)
  self.unsetDiagonalBackwardLookUp(row,col)
```

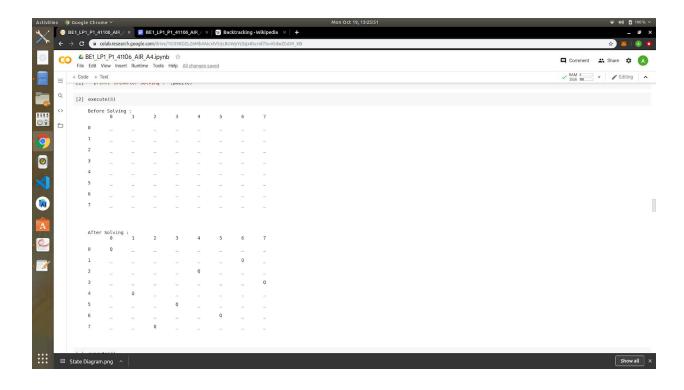
```
def execute(n):
   puzzle = N_Queens_PCAG(n)
execute(4)
```

Output Screenshots

Case 1: n=4

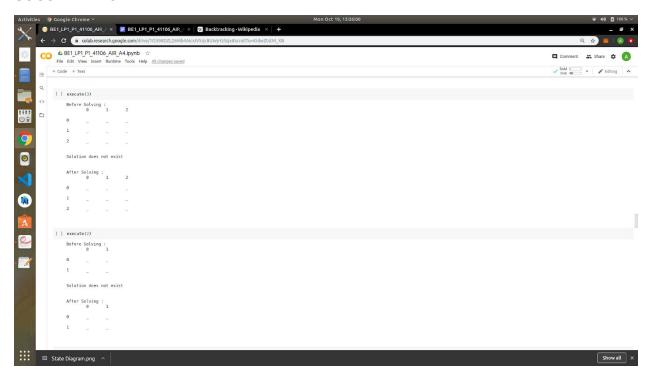


Case 2: n=8

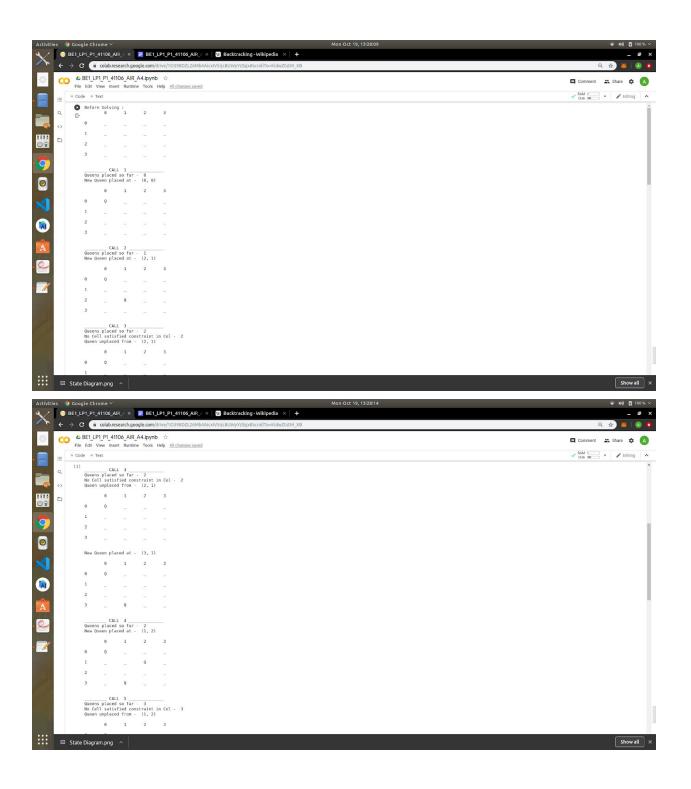


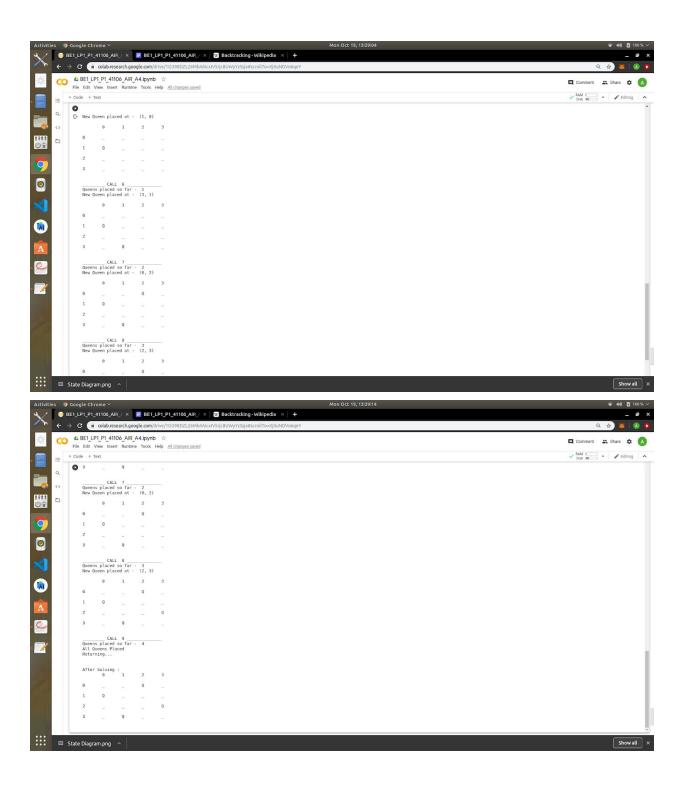
Case 3: n=2

Case 4: n=3



Case 4: n=4 (Showing all steps)





Conclusion

I have successfully designed and implemented backtracking for N_Queens using Agents Perception, Cognition, Action and Goal