```
import numpy as np
import pandas as pd
# import file utilities
import os
import glob
import random
# import charting
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation, ArtistAnimation
%matplotlib inline
from IPython.display import HTML
# import computer vision
import cv2
from google.colab import drive
drive.mount('/content/drive')
→ Mounted at /content/drive
realdata = "/content/drive/MyDrive/deepfakes/FF++/real"
fakedata = "/content/drive/MyDrive/deepfakes/FF++/fake"
def save_frames_from_video(video_path, output_folder):
    # Open the video file
   cap = cv2.VideoCapture(video_path)
   if not cap.isOpened():
        print(f"Error opening video file: {video_path}")
   # Create the output folder if it doesn't exist
   os.makedirs(output_folder, exist_ok=True)
   # Read and save frames from the video
   frame_count = 0
   while True:
       ret, frame = cap.read()
        if not ret:
           hreak
        # Save the frame as an image
        frame_path = os.path.join(output_folder, f"frame_{frame_count}.jpg")
        cv2.imwrite(frame_path, frame)
        frame_count += 1
   # Release the video capture object
   cap.release()
# Output folders for saving frames
real_output_folder = "real_frames"
fake_output_folder = "fake_frames"
# Save frames from one video in realdata folder
save_frames_from_video(os.path.join(realdata, os.listdir(realdata)[0]), real_output_folder)
# Save frames from one video in fakedata folder
save_frames_from_video(os.path.join(fakedata, os.listdir(fakedata)[0]), fake_output_folder)
import os
import shutil
from sklearn.model_selection import train_test_split
# Define your input folders
real_folder = "real_frames"
fake_folder = "fake_frames"
combined_folder = "combined_data"
# Create the combined folder if it doesn't exist
if not os.path.exists(combined_folder):
   os.makedirs(combined_folder)
```

```
# Move real images to the combined folder
for filename in os.listdir(real folder):
   src_path = os.path.join(real_folder, filename)
   dst_path = os.path.join(combined_folder, filename)
    shutil.copy(src_path, dst_path)
# Move fake images to the combined folder
for filename in os.listdir(fake_folder):
   src_path = os.path.join(fake_folder, filename)
    dst_path = os.path.join(combined_folder, filename)
   shutil.copy(src_path, dst_path)
# Split the combined data into train and test sets
all images = os.listdir(combined_folder)
train_images, test_images = train_test_split(all_images, test_size=0.2, random_state=42)
# Create train and test folders
train_folder = "train_data"
test_folder = "test_data"
os.makedirs(train_folder, exist_ok=True)
os.makedirs(test_folder, exist_ok=True)
# Move train images
for filename in train_images:
   src_path = os.path.join(combined_folder, filename)
   dst_path = os.path.join(train_folder, filename)
   shutil.copy(src_path, dst_path)
# Move test images
for filename in test_images:
   src_path = os.path.join(combined_folder, filename)
   dst path = os.path.join(test folder, filename)
   shutil.copy(src_path, dst_path)
print("Data split successfully!")
→ Data split successfully!
import os
import shutil
import random
# Define your input folders
real_folder = "real_frames"
fake_folder = "fake_frames"
# Define output folders
train folder = "train"
test_folder = "test"
# Create output directories
os.makedirs(os.path.join(train_folder, "real"), exist_ok=True)
os.makedirs(os.path.join(train folder, "fake"), exist ok=True)
os.makedirs(os.path.join(test_folder, "real"), exist_ok=True)
os.makedirs(os.path.join(test_folder, "fake"), exist_ok=True)
# Function to split files into train and test sets
def split_data(source_folder, train_subfolder, test_subfolder, test_size=0.2):
   files = os.listdir(source_folder)
   random.shuffle(files) # Shuffle files to ensure randomness
    split_index = int(len(files) * (1 - test_size)) # Calculate index for train-test split
   train files = files[:split index]
   test_files = files[split_index:]
    # Move files to the respective folders
   for file in train_files:
        shutil.copy(os.path.join(source_folder, file), os.path.join(train_subfolder, file))
   for file in test files:
        shutil.copy(os.path.join(source_folder, file), os.path.join(test_subfolder, file))
# Split the real and fake frames
split_data(real_folder, os.path.join(train_folder, "real"), os.path.join(test_folder, "real"))
split_data(fake_folder, os.path.join(train_folder, "fake"), os.path.join(test_folder, "fake"))
```

- DFDC - FFPP

```
print("Data organization completed!")
Data organization completed!
Start coding or generate with AI.
Start coding or generate with AI.
!git clone https://github.com/polimi-ispl/icpr2020dfdc
!pip install efficientnet-pytorch
!pip install -U git+https://github.com/albu/albumentations > /dev/null
%cd icpr2020dfdc/notebook

→ Cloning into 'icpr2020dfdc'...

     remote: Enumerating objects: 656, done.
     remote: Counting objects: 100% (119/119), done.
     remote: Compressing objects: 100% (36/36), done.
     remote: Total 656 (delta 101), reused 87 (delta 83), pack-reused 537 (from 1)
     Receiving objects: 100% (656/656), 99.64 MiB \mid 16.29 MiB/s, done.
     Resolving deltas: 100% (341/341), done.
     Collecting efficientnet-pytorch
       Downloading efficientnet_pytorch-0.7.1.tar.gz (21 kB)
       Preparing metadata (setup.py) ... done
     Requirement already satisfied: torch in /usr/local/lib/python3.10/dist-packages (from efficientnet-pytorch) (2.5.0+cu121)
     Requirement already satisfied: filelock in /usr/local/lib/python3.10/dist-packages (from torch->efficientnet-pytorch) (3.16.1)
     Requirement already satisfied: typing-extensions>=4.8.0 in /usr/local/lib/python3.10/dist-packages (from torch->efficientnet-pytorch) (4
     Requirement already satisfied: networkx in /usr/local/lib/python3.10/dist-packages (from torch->efficientnet-pytorch) (3.4.2)
     Requirement already satisfied: jinja2 in /usr/local/lib/python3.10/dist-packages (from torch->efficientnet-pytorch) (3.1.4)
     Requirement already satisfied: fsspec in /usr/local/lib/python3.10/dist-packages (from torch->efficientnet-pytorch) (2024.6.1)
     Requirement already satisfied: sympy==1.13.1 in /usr/local/lib/python3.10/dist-packages (from torch->efficientnet-pytorch) (1.13.1)
     Requirement already satisfied: mpmath<1.4,>=1.1.0 in /usr/local/lib/python3.10/dist-packages (from sympy==1.13.1->torch->efficientnet-py
     Requirement already satisfied: MarkupSafe>=2.0 in /usr/local/lib/python3.10/dist-packages (from jinja2->torch->efficientnet-pytorch) (3.
     Building wheels for collected packages: efficientnet-pytorch
       Building wheel for efficientnet-pytorch (setup.py) ... done
       Created wheel for efficientnet-pytorch: filename=efficientnet_pytorch-0.7.1-py3-none-any.whl size=16424 sha256=61d3f298668e32eaa02f2f3
       Stored in directory: /root/.cache/pip/wheels/03/3f/e9/911b1bc46869644912bda90a56bcf7b960f20b5187feea3baf
     Successfully built efficientnet-pytorch
     Installing collected packages: efficientnet-pytorch
     Successfully installed efficientnet-pytorch-0.7.1
       Running command git clone --filter=blob:none --quiet <a href="https://github.com/albu/albumentations">https://github.com/albu/albumentations</a> /tmp/pip-req-build-3iqh6jfz
     ERROR: pip's dependency resolver does not currently take into account all the packages that are installed. This behaviour is the source
     albumentations 1.4.20 requires albucore==0.0.19, but you have albucore 0.0.20 which is incompatible.
     /content/icpr2020dfdc/notebook
import torch
from torch.utils.model zoo import load url
import matplotlib.pyplot as plt
from scipy.special import expit
import sys
sys.path.append('..')
from blazeface import FaceExtractor, BlazeFace, VideoReader
from architectures import fornet, weights
from isplutils import utils
   Parameters
Choose an architecture between
- EfficientNetB4
- EfficientNetB4ST
- EfficientNetAutoAttB4
- EfficientNetAutoAttB4ST
- Xception
.....
net_model = 'EfficientNetAutoAttB4ST'
Choose a training dataset between
```

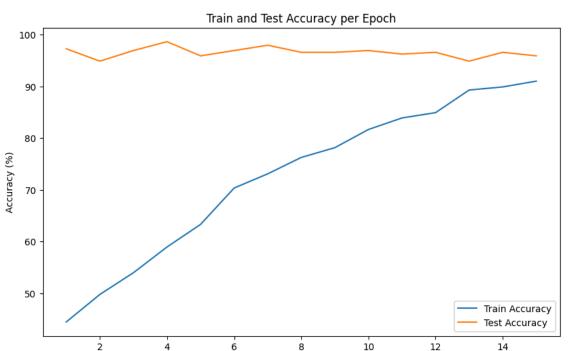
```
train db = 'FFPP'
os.environ['CUDA_LAUNCH_BLOCKING'] = '1'
device = torch.device('cpu')
face_policy = 'scale'
face_size = 224
frames_per_video = 32
Initialization
model_url = weights.weight_url['{:s}_{:s}'.format(net_model,train_db)]
net = getattr(fornet, net_model)()
os.environ['CUDA_LAUNCH_BLOCKING'] = '1'
# Try moving a single parameter to the GPU for debugging
try:
    # Get a single parameter from the model
    param = next(net.parameters())
    # Move the parameter to the GPU
    param.data = param.data.to(device)
except RuntimeError as e:
    print(f"Error moving parameter to GPU: {e}")
    # If this fails, it might indicate a problem with the model architecture or data type.
# Move the entire model to the GPU after the single parameter test
net = net.eval().to(device)
net.load_state_dict(load_url(model_url, map_location=device, check_hash=True))
Downloading: "https://github.com/lukemelas/EfficientNet-PyTorch/releases/download/1.0/efficientnet-b4-6ed6700e.pth" to /root/.cache/torc
                 74.4M/74.4M [00:03<00:00, 19.8MB/s]
     100%
     Loaded pretrained weights for efficientnet-b4
     Downloading: "https://f002.backblazeb2.com/file/icpr2020/EfficientNetAutoAttB4ST_FFPP_bestval-ddb357503b9b902e1b925c2550415604c4252b9b9e
     100%| 33.9M/33.9M [00:03<00:00, 10.7MB/s]
     <All keys matched successfully>
transf = utils.get_transformer(face_policy, face_size, net.get_normalizer(), train=False)
facedet = BlazeFace().to(device)
facedet.load_weights("../blazeface/blazeface.pth")
facedet.load_anchors("../blazeface/anchors.npy")
videoreader = VideoReader(verbose=False)
video_read_fn = lambda x: videoreader.read_frames(x, num_frames=frames_per_video)
face_extractor = FaceExtractor(video_read_fn=video_read_fn,facedet=facedet)
🚁 /content/icpr2020dfdc/notebook/../blazeface/blazeface.py:164: FutureWarning: You are using `torch.load` with `weights_only=False` (the c
       self.load_state_dict(torch.load(path))
import os
import cv2
import torch
from torch.utils.data import Dataset, DataLoader
from torchvision import transforms
class DeepFakeDataset(Dataset):
    def __init__(self, directory, transform=None):
        self.directory = directory
        self.transform = transform
        self.images = [] # Initialize an empty list to store image paths
        # Recursively search for images in subdirectories
        for root, _, files in os.walk(directory):
            for file in files:
               if file.endswith('.jpg'):
                    self.images.append(os.path.join(root, file))
    def __len__(self):
        return len(self.images)
```

```
def __getitem__(self, idx):
        img_path = self.images[idx]
        image = cv2.imread(img_path)
        image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB) # Convert BGR to RGB
        if self.transform:
            image = self.transform(image)
        label = 1 if "fake" in img_path else 0 # Assuming fake images have "fake" in the filename
        return image, label
transform = transforms.Compose([
    transforms.ToPILImage(),
    transforms.Resize((224, 224)),
    transforms.RandomHorizontalFlip(),
    transforms.RandomRotation(15),
    transforms.RandomAffine(0, shear=10, scale=(0.8, 1.2)),
    transforms.ColorJitter(brightness=0.3, contrast=0.3, saturation=0.3, hue=0.1),
    transforms.ToTensor(),
])
train_dataset = DeepFakeDataset('/content/train', transform=transform) # Using DeepFakeDataset class to create the dataset
test_dataset = DeepFakeDataset('/content/test', transform=transform) # Using DeepFakeDataset class to create the dataset
print(f"Train dataset size: {len(train_dataset)}")
print(f"Test dataset size: {len(test_dataset)}")
train_loader = DataLoader(train_dataset, batch_size=32, shuffle=True)
test_loader = DataLoader(test_dataset, batch_size=32, shuffle=False)
    Train dataset size: 1166
     Test dataset size: 292
import os
import cv2
import torch
import numpy as np
from torch.utils.data import Dataset, DataLoader
from torchvision import transforms, models
import torch.nn as nn
import torch.optim as optim
import time
# Custom Dataset Definition
class DeepFakeDataset(Dataset):
    def __init__(self, directory, transform=None):
        self.directory = directory
        self.transform = transform
        self.images = [os.path.join(root, file)
                       for root, _, files in os.walk(directory)
                       for file in files if file.endswith('.jpg')]
    def __len__(self):
        return len(self.images)
    def __getitem__(self, idx):
        img_path = self.images[idx]
        image = cv2.imread(img_path)
        image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
        if self.transform:
            image = self.transform(image)
        label = 1 if "fake" in img_path else 0
        return image, label
# Data Augmentation Transform
transform = transforms.Compose([
    transforms.ToPILImage(),
    transforms.Resize((224, 224)),
    transforms.RandomHorizontalFlip(),
    transforms.RandomRotation(20).
    transforms.ColorJitter(brightness=0.3, contrast=0.3, saturation=0.3, hue=0.2),
    transforms.RandomAffine(degrees=0, translate=(0.1, 0.1)),
    transforms.RandomGrayscale(p=0.2),
    transforms.ToTensor(),
```

1)

```
# Initialize Dataset and DataLoader
train_dataset = DeepFakeDataset('/content/train', transform=transform)
train_loader = DataLoader(train_dataset, batch_size=32, shuffle=True)
# Set up model, loss, and optimizer
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
net = models.efficientnet_b4(weights=models.EfficientNet_B4_Weights.IMAGENET1K_V1)
# Freeze early layers
for param in net.features.parameters():
    param.requires_grad = False
# Update the classifier for binary classification
num_ftrs = net.classifier[1].in_features
net.classifier = nn.Sequential(
    nn.Dropout(0.5),
    nn.Linear(num_ftrs, 1)
)
net.to(device)
# Define loss function and optimizer
criterion = nn.BCEWithLogitsLoss()
optimizer = optim.Adam(net.parameters(), 1r=1e-5)
scheduler = optim.lr_scheduler.ReduceLROnPlateau(optimizer, mode='min', factor=0.5, patience=3, verbose=True)
# Training loop
train_accuracies = [] # List to store training accuracies for each epoch
num_epochs = 15
for epoch in range(num_epochs):
    net.train()
    running_loss, correct, total = 0.0, 0, 0
    start time = time.time()
    for images, labels in train_loader:
        images, labels = images.to(device), labels.to(device)
        optimizer.zero_grad()
        outputs = net(images)
        loss = criterion(outputs.squeeze(1), labels.float())
        loss.backward()
        optimizer.step()
        running_loss += loss.item()
        preds = torch.round(torch.sigmoid(outputs.squeeze(1)))
        correct += (preds == labels).sum().item()
        total += labels.size(0)
    train_loss = running_loss / len(train_loader)
    train_accuracy = 100 * correct / total
    train accuracies.append(train accuracy) # Append training accuracy for this epoch
    # Learning Rate Adjustment
    scheduler.step(train_loss)
    # Print training results
    print(f"Epoch [{epoch+1}/{num_epochs}], "
          f"Train Loss: {train_loss:.4f}, Train Acc: {train_accuracy:.2f}%, "
          f"Time: {time.time() - start_time:.2f}s")
Epoch [1/15], Train Loss: 0.7022, Train Acc: 44.43%, Time: 40.85s
     Epoch [2/15], Train Loss: 0.6948, Train Acc: 49.74%, Time: 42.44s
     Epoch [3/15], Train Loss: 0.6889, Train Acc: 53.95%, Time: 41.47s
     Epoch [4/15], Train Loss: 0.6840, Train Acc: 58.92%, Time: 41.04s
     Epoch [5/15], Train Loss: 0.6766, Train Acc: 63.29%, Time: 39.91s
     Epoch [6/15], Train Loss: 0.6685, Train Acc: 70.33%, Time: 41.34s
     Epoch [7/15], Train Loss: 0.6631, Train Acc: 73.07%, Time: 41.25s
Epoch [8/15], Train Loss: 0.6572, Train Acc: 76.24%, Time: 43.22s
     Epoch [9/15], Train Loss: 0.6538, Train Acc: 78.13%, Time: 41.14s
     Epoch [10/15], Train Loss: 0.6452, Train Acc: 81.65%, Time: 39.86s
     Epoch [11/15], Train Loss: 0.6404, Train Acc: 83.88%, Time: 41.15s
     Epoch [12/15], Train Loss: 0.6341, Train Acc: 84.91%, Time: 41.33s
     Epoch [13/15], Train Loss: 0.6255, Train Acc: 89.28%, Time: 41.22s
     Epoch [14/15], Train Loss: 0.6199, Train Acc: 89.88%, Time: 42.65s
     Epoch [15/15], Train Loss: 0.6149, Train Acc: 90.99%, Time: 39.06s
```

```
num\_epochs = 15
test accuracies=[]
for epoch in range(num_epochs):
   net.eval() # Set the model to evaluation mode
   test_correct, test_total = 0, 0 # Initialize counters for correct predictions and total samples
   with torch.no_grad(): # Disable gradient calculation during evaluation
        for images, labels in test_loader: # Iterate over the test data loader
            images, labels = images.to(device), labels.to(device) # Move data to the device (GPU if available)
            outputs = net(images) # Get model predictions
            preds = torch.round(torch.sigmoid(outputs.squeeze(1)))  # Apply sigmoid and round to get binary predictions
            test_total += labels.size(0) # Update total samples count
            test_correct += (preds == labels).sum().item() # Update correct predictions count
   test accuracy = 100 * test correct / test total # Calculate test accuracy
   test_accuracies.append(test_accuracy) # Append test accuracy for this epoch
   # Print test accuracy for each epoch
   print(f"Epoch [{epoch+1}/{num_epochs}], Test Accuracy: {test_accuracy:.2f}%")
₹ Epoch [1/15], Test Accuracy: 97.26%
     Epoch [2/15], Test Accuracy: 94.86%
     Epoch [3/15], Test Accuracy: 96.92%
    Epoch [4/15], Test Accuracy: 98.63%
Epoch [5/15], Test Accuracy: 95.89%
     Epoch [6/15], Test Accuracy: 96.92%
     Epoch [7/15], Test Accuracy: 97.95%
     Epoch [8/15], Test Accuracy: 96.58%
     Epoch [9/15], Test Accuracy: 96.58%
     Epoch [10/15], Test Accuracy: 96.92%
     Epoch [11/15], Test Accuracy: 96.23%
     Epoch [12/15], Test Accuracy: 96.58%
     Epoch [13/15], Test Accuracy: 94.86%
     Epoch [14/15], Test Accuracy: 96.58%
     Epoch [15/15], Test Accuracy: 95.89%
# Plot the train and test accuracy curves
plt.figure(figsize=(10, 6))
plt.plot(range(1, num_epochs + 1), train_accuracies, label="Train Accuracy")
plt.plot(range(1, num_epochs + 1), test_accuracies, label="Test Accuracy")
plt.xlabel("Epoch")
plt.ylabel("Accuracy (%)")
plt.title("Train and Test Accuracy per Epoch")
plt.legend()
plt.show()
<del>_</del>__
                                              Train and Test Accuracy per Epoch
         100
```



import cv2
import torc

Epoch

```
import numpy as np
from torchvision import transforms
from scipy.special import expit # For sigmoid on logits
from torch.utils.data import DataLoader
from torch.utils.data import Dataset
import os
# Frame extraction function
def extract_frames(video_path, num_frames=32):
   cap = cv2.VideoCapture(video_path)
   frame_count = int(cap.get(cv2.CAP_PROP_FRAME_COUNT))
   frame_indices = np.linspace(0, frame_count - 1, num_frames, dtype=int)
   frames = []
    for idx in frame_indices:
        cap.set(cv2.CAP_PROP_POS_FRAMES, idx)
        ret, frame = cap.read()
        if ret:
           frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
           frames.append(frame)
   cap.release()
   return frames
# Prediction function for a single video
def predict_video(video_path, model, transform, device, num_frames=32):
   frames = extract_frames(video_path, num_frames=num_frames)
   frame_preds = []
   model.eval() # Ensure the model is in evaluation mode
   with torch.no_grad():
       for frame in frames:
            frame = transform(frame)
            frame = frame.unsqueeze(0).to(device) # Add batch dimension
            output = model(frame)
            prob = expit(output.item()) # Convert logits to probability
            frame_preds.append(prob)
   # Average prediction probabilities over all frames
   avg pred = np.mean(frame_preds)
   label = "Fake" if avg_pred >= 0.5 else "Real"
   print(f"Prediction: {label} (Confidence: {avg_pred:.2f})")
   return label, avg_pred
# Define frame transform (should match training transforms)
frame_transform = transforms.Compose([
   transforms.ToPILImage(),
   transforms.Resize((224, 224)),
   transforms.ToTensor(),
])
# Path to the video for prediction
video_path = '/content/fvideo_1.mp4'
label, confidence = predict_video(video_path, net, frame_transform, device)
→ Prediction: Fake (Confidence: 0.50)
import os
import cv2
import torch
import numpy as np
from torchvision import transforms
from scipy.special import expit # For sigmoid on logits
# Frame extraction function
def extract_frames(video_path, num_frames=32):
   cap = cv2.VideoCapture(video_path)
   frame count = int(cap.get(cv2.CAP PROP FRAME COUNT))
   frame_indices = np.linspace(0, frame_count - 1, num_frames, dtype=int)
   frames = []
   for idx in frame_indices:
       cap.set(cv2.CAP_PROP_POS_FRAMES, idx)
        ret, frame = cap.read()
```

```
frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
            frames.append(frame)
    cap.release()
   return frames
# Prediction function for a single video
def predict video(video path, model, transform, device, num frames=32):
    frames = extract_frames(video_path, num_frames=num_frames)
   frame_preds = []
   model.eval() # Ensure the model is in evaluation mode
   with torch.no_grad():
        for frame in frames:
           frame = transform(frame)
           frame = frame.unsqueeze(0).to(device) # Add batch dimension
           output = model(frame)
            prob = expit(output.item()) # Convert logits to probability
            frame_preds.append(prob)
   # Average prediction probabilities over all frames
   avg_pred = np.mean(frame_preds)
   label = "Fake" if avg_pred >= 0.5 else "Real"
   return label, avg_pred
# Batch prediction function for multiple videos in a folder
def predict_videos_in_folder(folder_path, model, transform, device, num_frames=32):
   results = {}
   video_files = [f for f in os.listdir(folder_path) if f.endswith(('.mp4', '.avi', '.mov'))]
    for video_file in video_files:
        video_path = os.path.join(folder_path, video_file)
        label, confidence = predict_video(video_path, model, transform, device, num_frames)
        results[video_file] = {"Label": label, "Confidence": confidence}
       print(f"Video: {video_file} - Prediction: {label}, Confidence: {confidence:.2f}")
    return results
# Define frame transform (should match training transforms)
frame_transform = transforms.Compose([
   transforms.ToPILImage(),
   transforms.Resize((224, 224)),
   transforms.ToTensor(),
])
# Path to the folder containing multiple videos
folder_path = '/content/drive/MyDrive/new_videos'
results = predict videos in folder(folder path, net, frame transform, device)
→ Video: video_3.mp4 - Prediction: Real, Confidence: 0.50
     Video: video_2.mp4 - Prediction: Real, Confidence: 0.48
     Video: video 1.mp4 - Prediction: Real, Confidence: 0.47
import os
import cv2
import torch
import numpy as np
from torchvision import transforms
from scipy.special import expit # For sigmoid on logits
# Frame extraction function
def extract_frames(video_path, num_frames=32):
   cap = cv2.VideoCapture(video_path)
   frame_count = int(cap.get(cv2.CAP_PROP_FRAME_COUNT))
   frame_indices = np.linspace(0, frame_count - 1, num_frames, dtype=int)
   frames = []
    for idx in frame_indices:
       cap.set(cv2.CAP_PROP_POS_FRAMES, idx)
        ret, frame = cap.read()
        if ret:
           frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
           frames.append(frame)
   cap.release()
   return frames
# Prediction function for a single video
```

```
def predict_video(video_path, model, transform, device, num_frames=32):
   frames = extract_frames(video_path, num_frames=num_frames)
   frame_preds = []
   model.eval() # Ensure the model is in evaluation mode
   with torch.no_grad():
        for frame in frames:
           frame = transform(frame)
           frame = frame.unsqueeze(0).to(device) # Add batch dimension
           output = model(frame)
           prob = expit(output.item()) # Convert logits to probability
           frame_preds.append(prob)
   # Average prediction probabilities over all frames
   avg_pred = np.mean(frame_preds)
   label = "Fake" if avg_pred >= 0.5 else "Real"
   return label, avg_pred
# Batch prediction function for multiple videos in a folder
def predict_videos_in_folder(folder_path, model, transform, device, num_frames=32):
   results = {}
   video_files = [f for f in os.listdir(folder_path) if f.endswith(('.mp4', '.avi', '.mov'))]
   for video_file in video_files:
        video_path = os.path.join(folder_path, video_file)
        label, confidence = predict_video(video_path, model, transform, device, num_frames)
       results[video_file] = {"Label": label, "Confidence": confidence}
        print(f"Video: {video_file} - Prediction: {label}, Confidence: {confidence:.2f}")
   return results
# Define frame transform (should match training transforms)
frame transform = transforms.Compose([
   transforms.ToPILImage(),
   transforms.Resize((224, 224)),
   transforms.ToTensor(),
1)
# Path to the folder containing multiple videos
folder_path = '/content/drive/MyDrive/new_videos'
results = predict_videos_in_folder(folder_path, net, frame_transform, device)
```