```
import numpy as np
import pandas as pd
# import file utilities
import os
import glob
import random
# import charting
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation, ArtistAnimation
%matplotlib inline
from IPython.display import HTML
# import computer vision
import cv2
from google.colab import drive
drive.mount('/content/drive')
→ Mounted at /content/drive
realdata = "/content/drive/MyDrive/celebs/real"
fakedata = "/content/drive/MyDrive/celebs/fake"
def save_frames_from_video(video_path, output_folder):
   # Open the video file
   cap = cv2.VideoCapture(video_path)
   if not cap.isOpened():
        print(f"Error opening video file: {video_path}")
   # Create the output folder if it doesn't exist
   os.makedirs(output_folder, exist_ok=True)
   # Read and save frames from the video
   frame_count = 0
   while True:
       ret, frame = cap.read()
        if not ret:
           hreak
        # Save the frame as an image
        frame_path = os.path.join(output_folder, f"frame_{frame_count}.jpg")
        cv2.imwrite(frame_path, frame)
        frame_count += 1
   # Release the video capture object
   cap.release()
# Output folders for saving frames
real_output_folder = "real_frames"
fake_output_folder = "fake_frames"
# Save frames from one video in realdata folder
save_frames_from_video(os.path.join(realdata, os.listdir(realdata)[0]), real_output_folder)
# Save frames from one video in fakedata folder
save_frames_from_video(os.path.join(fakedata, os.listdir(fakedata)[0]), fake_output_folder)
import os
import shutil
from sklearn.model_selection import train_test_split
# Define your input folders
real_folder = "real_frames"
fake_folder = "fake_frames"
combined_folder = "combined_data"
# Create the combined folder if it doesn't exist
if not os.path.exists(combined_folder):
   os.makedirs(combined_folder)
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# Move real images to the combined folder
for filename in os.listdir(real folder):
   src_path = os.path.join(real_folder, filename)
   dst_path = os.path.join(combined_folder, filename)
    shutil.copy(src_path, dst_path)
# Move fake images to the combined folder
for filename in os.listdir(fake_folder):
   src_path = os.path.join(fake_folder, filename)
   dst_path = os.path.join(combined_folder, filename)
   shutil.copy(src_path, dst_path)
# Split the combined data into train and test sets
all images = os.listdir(combined folder)
train_images, test_images = train_test_split(all_images, test_size=0.2, random_state=42)
# Create train and test folders
train_folder = "train_data"
test_folder = "test_data"
os.makedirs(train_folder, exist_ok=True)
os.makedirs(test_folder, exist_ok=True)
# Move train images
for filename in train_images:
   src_path = os.path.join(combined_folder, filename)
   dst_path = os.path.join(train_folder, filename)
   shutil.copy(src_path, dst_path)
# Move test images
for filename in test_images:
   src_path = os.path.join(combined_folder, filename)
   dst path = os.path.join(test folder, filename)
   shutil.copy(src_path, dst_path)
print("Data split successfully!")
→ Data split successfully!
import os
import shutil
import random
# Define your input folders
real_folder = "real_frames"
fake_folder = "fake_frames"
# Define output folders
train folder = "train"
test_folder = "test"
# Create output directories
os.makedirs(os.path.join(train_folder, "real"), exist_ok=True)
os.makedirs(os.path.join(train_folder, "fake"), exist_ok=True)
os.makedirs(os.path.join(test_folder, "real"), exist_ok=True)
os.makedirs(os.path.join(test_folder, "fake"), exist_ok=True)
# Function to split files into train and test sets
def split_data(source_folder, train_subfolder, test_subfolder, test_size=0.2):
   files = os.listdir(source_folder)
   random.shuffle(files) # Shuffle files to ensure randomness
    split_index = int(len(files) * (1 - test_size)) # Calculate index for train-test split
   train files = files[:split index]
   test_files = files[split_index:]
   # Move files to the respective folders
   for file in train_files:
        shutil.copy(os.path.join(source_folder, file), os.path.join(train_subfolder, file))
   for file in test files:
        shutil.copy(os.path.join(source_folder, file), os.path.join(test_subfolder, file))
# Split the real and fake frames
split_data(real_folder, os.path.join(train_folder, "real"), os.path.join(test_folder, "real"))
split_data(fake_folder, os.path.join(train_folder, "fake"), os.path.join(test_folder, "fake"))
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print("Data organization completed!") → Data organization completed! Start coding or generate with AI. import os import shutil import random import numpy as np import tensorflow as tf from tensorflow.keras.applications import MobileNetV2 from tensorflow.keras.layers import Dense, GlobalAveragePooling2D, Dropout from tensorflow.keras.models import Model from tensorflow.keras.optimizers import Adam from tensorflow.keras.preprocessing.image import ImageDataGenerator from tensorflow.keras.callbacks import EarlyStopping, ModelCheckpoint import cv2 def save\_frames\_from\_video(video\_path, output\_folder): cap = cv2.VideoCapture(video\_path) if not cap.isOpened(): print(f"Error opening video file: {video\_path}") os.makedirs(output\_folder, exist\_ok=True) frame count = 0 while True: ret, frame = cap.read() if not ret: break frame\_path = os.path.join(output\_folder, f"frame\_{frame\_count}.jpg") cv2.imwrite(frame\_path, frame) frame\_count += 1 cap.release() def split\_data(source\_folder, train\_subfolder, test\_subfolder, test\_size=0.2): files = os.listdir(source\_folder) random.shuffle(files) split\_index = int(len(files) \* (1 - test\_size)) train\_files = files[:split\_index] test\_files = files[split\_index:] for file in train\_files: shutil.copy(os.path.join(source\_folder, file), os.path.join(train\_subfolder, file)) for file in test files: shutil.copy(os.path.join(source\_folder, file), os.path.join(test\_subfolder, file)) class DeepfakeDetector: def \_\_init\_\_(self, input\_shape=(224, 224, 3), learning\_rate=0.00001): self.input\_shape = input\_shape self.learning\_rate = learning\_rate self.model = self.\_build\_model() def build model(self): base\_model = MobileNetV2(input\_shape=self.input\_shape, include\_top=False, weights='imagenet') base\_model.trainable = False x = base\_model.output x = GlobalAveragePooling2D()(x) $x = Dense(256, activation='relu', kernel_regularizer=tf.keras.regularizers.l2(0.01))(x)$ x = Dropout(0.5)(x) # Increased dropoutpredictions = Dense(1, activation='sigmoid')(x)model = Model(inputs=base\_model.input, outputs=predictions) model.compile(optimizer=Adam(learning\_rate=self.learning\_rate), loss='binary\_crossentropy', metrics=['accuracy']) return model def train(self, train\_dir, valid\_dir, batch\_size=32, epochs=10): train\_datagen = ImageDataGenerator( rescale=1./255, rotation\_range=40,

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width_shift_range=0.2,
           height_shift_range=0.2,
           shear_range=0.2,
           zoom_range=0.2,
           brightness_range=[0.8, 1.2],
           horizontal_flip=True,
           fill mode='nearest',
           channel_shift_range=20.0
       )
       valid_datagen = ImageDataGenerator(rescale=1./255)
       train_generator = train_datagen.flow_from_directory(train_folder, target_size=(224, 224),
                                                          batch_size=32, class_mode='binary')
       valid_generator = valid_datagen.flow_from_directory(test_folder, target_size=(224, 224),
                                                          batch size=32, class mode='binary')
        # Callbacks
       early_stopping = EarlyStopping(monitor='val_loss', patience=5, restore_best_weights=True)
       checkpoint = ModelCheckpoint('best_model.keras', monitor='val_loss', save_best_only=True)
       lr_scheduler = tf.keras.callbacks.LearningRateScheduler(lambda epoch: 1e-4 * 0.1**(epoch // 5))
           history = self.model.fit(train_generator,
                                      steps_per_epoch=train_generator.samples // batch_size,
                                      validation data=valid generator,
                                      validation_steps=valid_generator.samples // batch_size,
                                      epochs=epochs,
                                      callbacks=[early stopping, checkpoint],
                                      verbose=1)
       except Exception as e:
           print(f"Error during training: {e}")
       return history
   def predict(self, image):
       if len(image.shape) == 3:
           image = np.expand_dims(image, axis=0)
       return self.model.predict(image)
   def save_model(self, path):
       self.model.save(path)
   @classmethod
   def load_model(cls, path):
       model = tf.keras.models.load_model(path)
       detector = cls()
       detector.model = model
       return detector
def extract_faces_from_frame(frame, face_detector):
   faces = face_detector.detect_faces(frame) # Assuming face_detector is implemented elsewhere
   if len(faces) > 0:
       x, y, w, h = faces[0]['box']
       face = frame[y:y+h, x:x+w]
       x = Dropout(0.5)(x)
       face = cv2.resize(face, (224, 224))
       return face
   return None
def extract_frames(video_path, face_detector, num_frames=30):
   cap = cv2.VideoCapture(video_path)
   frames = []
   frame_count = 0
   while cap.isOpened() and frame_count < num_frames:</pre>
       ret, frame = cap.read()
       if not ret:
           break
       face = extract_faces_from_frame(frame, face_detector)
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if face is not None:
            frames.append(face)
            frame_count += 1
    cap.release()
    return frames
detector = DeepfakeDetector()
history=detector.train(os.path.join(train_folder), os.path.join(test_folder), batch_size=32, epochs=10)
    Found 617 images belonging to 2 classes.
     Found 155 images belonging to 2 classes.
     Epoch 1/10
     19/19 -
                              - 54s 2s/step - accuracy: 0.5503 - loss: 5.1279 - val_accuracy: 0.7969 - val_loss: 4.8155
     Epoch 2/10
     19/19 -
                              – 5s 211ms/step - accuracy: 0.4688 - loss: 5.1498 - val_accuracy: 0.7407 - val_loss: 4.8412
     Epoch 3/10
     19/19 -
                              - 70s 2s/step - accuracy: 0.6245 - loss: 4.9625 - val accuracy: 0.8672 - val loss: 4.6713
     Epoch 4/10
     19/19 -
                              – 4s 158ms/step - accuracy: 0.6562 - loss: 4.8876 - val_accuracy: 0.8889 - val_loss: 4.6781
     Epoch 5/10
     19/19 -
                              - 82s 2s/step - accuracy: 0.6894 - loss: 4.7949 - val accuracy: 0.9219 - val loss: 4.5627
     Epoch 6/10
     19/19 -
                              — 3s 85ms/step - accuracy: 0.7188 - loss: 4.7737 - val_accuracy: 0.9630 - val_loss: 4.5289
     Epoch 7/10
     19/19 -
                              — 74s 2s/step - accuracy: 0.8259 - loss: 4.6361 - val_accuracy: 0.9766 - val_loss: 4.4740
     Epoch 8/10
     19/19
                              — 4s 149ms/step - accuracy: 0.7812 - loss: 4.7009 - val_accuracy: 1.0000 - val_loss: 4.4401
     Epoch 9/10
     19/19 -
                              — 81s 2s/step - accuracy: 0.8244 - loss: 4.5725 - val_accuracy: 1.0000 - val_loss: 4.3990
     Epoch 10/10
                              - 3s 91ms/step - accuracy: 0.8750 - loss: 4.5150 - val accuracy: 0.9630 - val loss: 4.3935
     19/19 -
import matplotlib.pyplot as plt
# Assuming 'history' is the variable storing the training history
# Plotting training and validation accuracy
plt.figure(figsize=(12, 6))
plt.plot(history.history['accuracy'], label='Training Accuracy')
plt.plot(history.history['val_accuracy'], label='Validation Accuracy')
plt.title('Training and Validation Accuracy')
plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.legend()
plt.grid(True)
plt.show()
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## Training and Validation Accuracy

