

# MNPoolWithRenshawCells

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## Input #1

```
import sys
sys.path.insert(0, '..')
import time
import matplotlib.pyplot as plt
%matplotlib inline
from IPython.display import set_matplotlib_formats
set_matplotlib_formats('pdf', 'png')
plt.rcParams['savefig.dpi'] = 75

plt.rcParams['figure.autolayout'] = False
plt.rcParams['figure.figsize'] = 10, 6
plt.rcParams['axes.labelsize'] = 18
plt.rcParams['axes.titlesize'] = 20
plt.rcParams['font.size'] = 16
plt.rcParams['lines.linewidth'] = 2.0
plt.rcParams['lines.markersize'] = 8
plt.rcParams['legend.fontsize'] = 14

plt.rcParams['text.usetex'] = True
plt.rcParams['font.family'] = "serif"
plt.rcParams['font.serif'] = "cm"
plt.rcParams['text.latex.preamble'] = "\usepackage{subdepth}, \usepackage{type1cm}"

import numpy as np

from Configuration import Configuration
from MotorUnitPool import MotorUnitPool
from InterneuronPool import InterneuronPool
from NeuralTract import NeuralTract
from SynapsesFactory import SynapsesFactory
```

## Input #2

```
conf = Configuration('confMNPoolWithRenshawCells.rmto')
conf.simDuration_ms = 5000 # Here I change simulation duration without changing the Configur
```

## Input #3

```
# Time vector for the simulation
t = np.arange(0.0, conf.simDuration_ms, conf.timeStep_ms)

membPotential = np.zeros_like(t, dtype = 'd')
```

## Input #4

```

pools = dict()
pools[0] = MotorUnitPool(conf, 'SOL')
pools[1] = NeuralTract(conf, 'CMExt')
pools[2] = InterneuronPool(conf, 'RC')

```

```
Syn = SynapsesFactory(conf, pools)
```

#### Output #4

```

Motor Unit Pool SOL built
Descending Command CMExt built
Interneuron Pool of RC built
Synaptic Noise on RC built
All the 124633 synapses were built

```

#### Input #5

```

tic = time.clock()
for i in xrange(0, len(t)-1):
    pools[1].atualizePool(t[i]) # NeuralTract
    pools[0].atualizeMotorUnitPool(t[i]) # MN pool
    pools[3].atualizePool(t[i]) # RC synaptic Noise
    pools[2].atualizeInterneuronPool(t[i]) # RC pool
toc = time.clock()
print str(toc - tic) + ' seconds'

```

#### Output #5

```
13950.211544 seconds
```

#### Input #6

```

pools[0].listSpikes()
pools[1].listSpikes()
pools[2].listSpikes()

```

#### Input #7

```

plt.figure()
plt.plot(pools[1].poolTerminalSpikes[:, 0],
         pools[1].poolTerminalSpikes[:, 1]+1, '.')
plt.xlabel('t (ms)')
plt.ylabel('Descending Command index')

```

#### Output #7

```
Out[7]: <matplotlib.text.Text at 0x7f8acffe98d0>
```

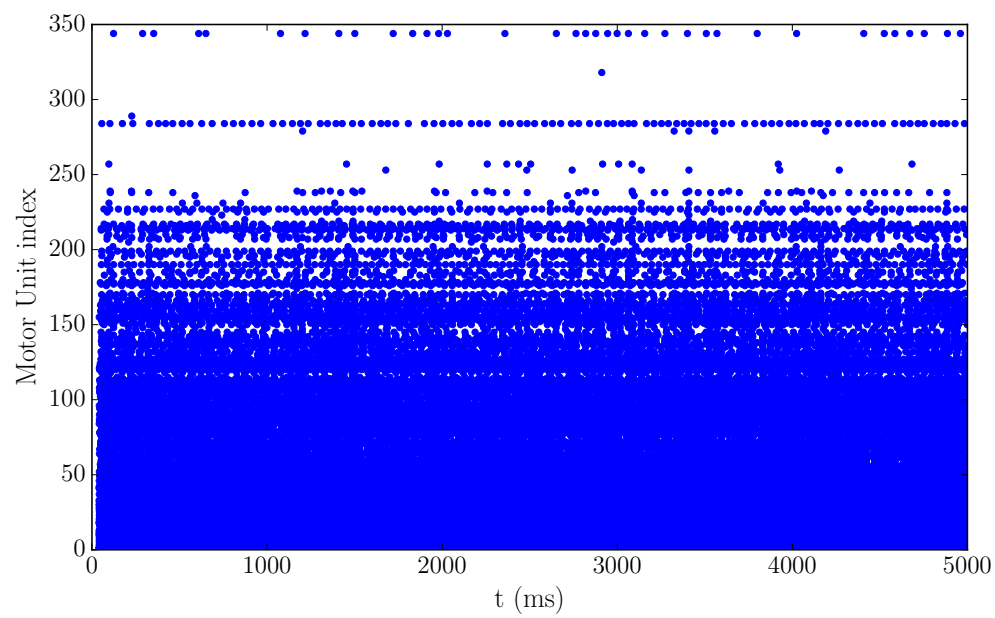
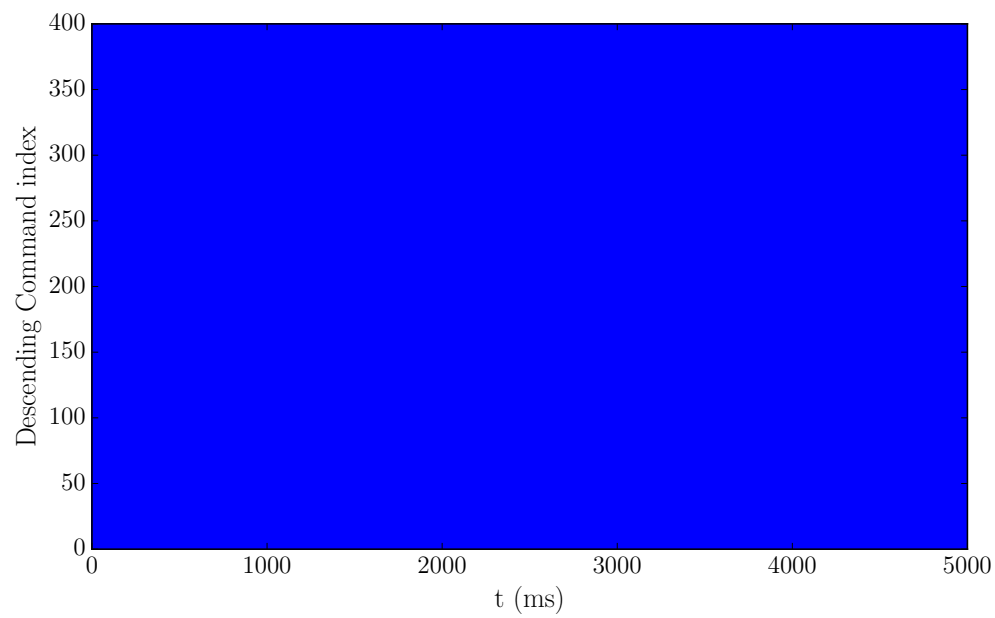
#### Input #8

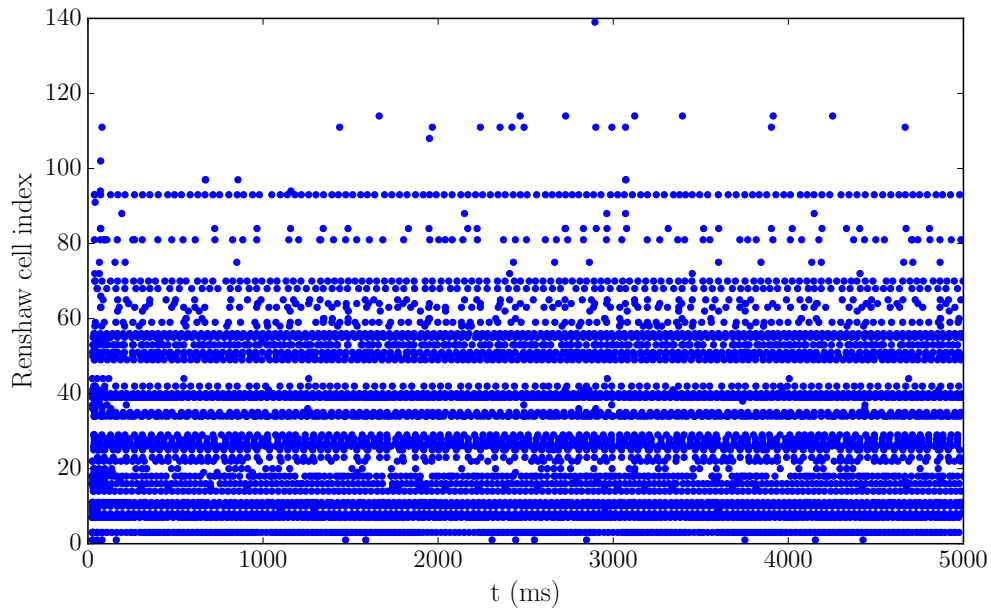
```

plt.figure()
plt.plot(pools[0].poolTerminalSpikes[:, 0],
         pools[0].poolTerminalSpikes[:, 1]+1, '.')
plt.xlabel('t (ms)')
plt.ylabel('Motor Unit index')

```

#### Output #8





Out[8]: <matplotlib.text.Text at 0x7f8ac7405e50>

#### Input #9

```
plt.figure()
plt.plot(pools[2].poolSomaSpikes[:, 0],
         pools[2].poolSomaSpikes[:, 1]+1, '.')
plt.xlabel('t (ms)')
plt.ylabel('Renshaw cell index')
```

#### Output #9

Out[9]: <matplotlib.text.Text at 0x7f8acd423e50>

#### Input #10

```
plt.figure()
plt.plot(t, pools[0].Muscle.force, '-')
plt.xlabel('t (ms)')
plt.ylabel('Muscle force (N)')
```

#### Output #10

Out[10]: <matplotlib.text.Text at 0x7f8aba60ba50>

#### Input #None

