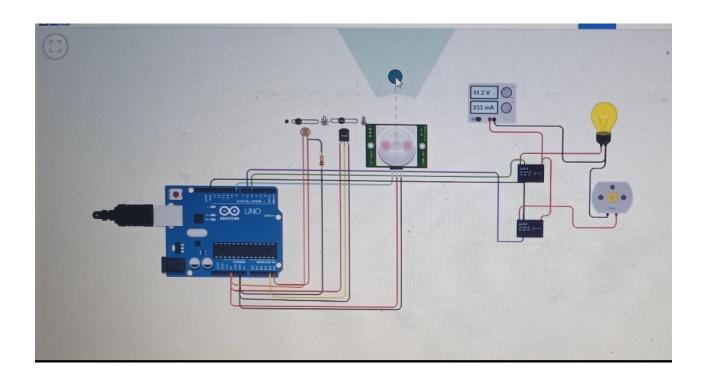
HOME AUTOMATION -ASSIGNMENT-1

```
float x, y, z, temp;
void setup()
  pinMode(8, INPUT);
  pinMode(5, OUTPUT);
  pinMode(6, OUTPUT);
  pinMode(A5, INPUT);
  pinMode (A4, INPUT);
Serial.begin(9600);
void loop()
  x = digitalRead(8);
  y = analogRead(A5);
  z= analogRead(A4);
  Serial.println(x);
  Serial.println(y);
  Serial.println(z);
  temp = (double)z / 1024;
  temp = temp * 5;
  temp = temp - 0.5;
  temp = temp * 100;
  if ((x>0))
    if ((y<550) && (temp>30))
      digitalWrite(5, HIGH);
      digitalWrite(6, HIGH);
    else if((y < 550)&&(temp<30))
      digitalWrite(5, HIGH);
      digitalWrite(6, LOW);
    else if((y>550) \&\& (temp>30))
      digitalWrite(5, LOW);
      digitalWrite(6, HIGH);
    else if((y>550) \&\& (temp<30))
      digitalWrite(5, LOW);
      digitalWrite(6, LOW);
    }
  }
  else
    digitalWrite(5, LOW);
    digitalWrite(6, LOW);
}
```

HOME AUTOMATION -ASSIGNMENT-1



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