Evaluation of Function

Numerical Methods for IT

Polynomials

Given a polynomial $P_n(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n$ and $v \in \mathbb{R}$.

Evaluation $P_n(v)$?

We have

$$\begin{split} P_n(v) &= a_0 + a_1 v + a_2 v^2 + \dots + a_{n-1} v^{n-1} + a_n v^n \\ &= a_0 + v(a_1 + a_2 v + \dots + a_{n-1} v^{n-2} + a_n v^{n-1}) \\ &= a_0 + v * P_{n-1}(v), \text{ where} \\ P_{n-1}(v) &= b_0 + b_1 v + \dots + b_{n-2} v^{n-2} + b_{n-1} v^{n-1}, b_i = a_{i+1}, i = 0, \dots, n-2 \end{split}$$

Let $P(n) = a[0 \dots n]$ is a 1-dimensional array that represents the computer representation of the polynomial $P_n(x)$. Given a value v. To evaluate $P_n(v)$, we can represent the recursive form as follows:

$$P(i,v) = \begin{cases} a[0], & i = 0 \\ a[0] + v * P(i,v), & i \ge 1 \end{cases}$$

Rational functions

To evaluate a rational function like:

$$R(x) = \frac{P_{\mu}(x)}{Q_{\nu}(x)} = \frac{p_0 + p_1 x + \dots + p_{\mu} x^{\mu}}{q_0 + q_1 x + \dots + q_{\nu} x^{\nu}}.$$

Given w, to evaluate R(w), we can use the polynomial evaluation routine to:

- (1) $num \leftarrow P(\mu, w)$
- (2) $dom \leftarrow Q(v, w)$
- (3) Return num/dom

Evaluation of Continued Fractions

Continued fractions are often powerful ways of evaluating functions that occur in scientific applications.

A continued fraction looks like:

$$f(x) = b_0 + \frac{a_1}{b_1 + \frac{a_2}{b_2 + \frac{a_3}{b_3 + \cdots}}} \equiv b_0 + \frac{a_1}{b_1 + \frac{a_2}{b_2 + \frac{a_3}{b_3 + \cdots}}} \dots$$

For example, the continued fraction representation of tangent function is: $\tan x = \frac{x}{1-} \frac{x^2}{3-} \frac{x^2}{5-} \frac{x^2}{7-} \dots$ Let f_n denote the result of f(x) with coefficients through a_n and b_n . Then

$$f_n = \frac{A_n}{B_n}$$

where A_n , B_n are given by the following recurrence:

$$A_{-1}\equiv 1\;;B_{-1}\equiv 0\;$$

$$A_0 \equiv b_0$$
; $B_0 \equiv 1$

$$A_j = b_j A_{j-1} + a_j A_{j-2}$$
; $B_j = b_j B_{j-1} + a_j B_{j-2}$; $j = 1, 2, ..., n$.

Steed's method.

. Set
$$f_0 = b_0$$
. If $b_0 = 0$, set $f_0 = \epsilon$.

. Set
$$C_0 = f_0$$
, $D_0 = 0$.

. For
$$j = 1, 2, ...$$
:

$$. \operatorname{Set} D_i = b_i + a_i D_{i-1}$$

. If
$$D_i = 0$$
, set $D_i = \epsilon$

. Set
$$C_i = b_i + a_i / C_{i-1}$$
.

. If
$$C_i = 0$$
, set $C_i = \epsilon$.

. Set
$$D_j = 1/D_j$$
, $\Delta = C_j D_j$, $f_j = f_{j-1} \Delta_j$.

. If
$$|\Delta_j - 1| < \epsilon_0$$
, then exit.

Chebyshev Approximation

The Chebyshev polynomial of degree n is denoted $T_n(x) = \cos(n \arccos x)$.

It can be combined with trigonometric identities to yield explicit expression for $T_n(x)$:

$$T_0(x) = 1$$
; $T_1(x) = x$; $T_2(x) = 2x^2 - 1$; $T_3(x) = 4x^3 - 3x^2$; $T_4(x) = 8x^4 - 8x^2 + 1...$
 $T_{n+1}(x) = 2xT_n(x) - T_{n-1}(x)$, $\forall n \ge 1$ (*).

Suppose N is so large. We consider the truncated approximation:

$$f(x) \approx \left[\Sigma_{k=0}^{m-1} c_k T_k(x) \right] - \frac{1}{2} c_0 \ (^{\star\star}) \ \text{where} \ c_j = \frac{2}{N} \Sigma_{k=0}^{N-1} f \left[\cos \left(\frac{\pi \left(k + \frac{1}{2} \right)}{N} \right) \right] \cos \left(\frac{\pi j \left(k + \frac{1}{2} \right)}{N} \right).$$

Now that we have the Chebyshev coefficients, how to evaluate the approximation?

We can use the above recurrence relation (*) to generate values for $T_k(x)$ from $T_0 = 1$, $T_1 = x$, while also accumulating the sum of (**).

It is better to use Clenshaw's recurrence formula:

$$\begin{aligned} d_{m+1} &\equiv d_m \equiv 0 \\ d_j &= 2xd_{j+1} - d_{j+2} + c_j, j = m - 1, m - 2, ..., 1 \\ f(x) &\equiv d_0 = xd_1 - d_2 + \frac{1}{2}c_0. \end{aligned}$$

Polynomial Approximation from Cheb. Coeff. Convert the c_k 's into actual polynomial coefficients in the original variable x and have an

Convert the c_k 's into actual polynomial coefficients in the original variable x and have an approximation of the following form:

$$f(x) \approx \sum_{k=0}^{m-1} g_k x^k$$
, $a \le x \le b$.

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Given a coefficients c[0..n-1], this routine returns
d[0..n-1]: \sum_{k=0}^{n-1} d_k y^k = \sum_{k=0}^{n-1} c_k T_k(y) - c_0/2.
Int k,i;
Doub sv;
VecDoub d(m), dd(m);
For (i=0;i< m;i++): d[0]=c[m-1];
For (j=m-2;j>0;j--):
          for (k=m-2;k>0;k--):
                     sv=d[k];
                     d[k]=2.0*d[k-1]-dd[k];
                     dd[k]=sv;
          sv=d[0];
          d[0]=-dd[0]+c[i]
          dd[0]=sv
For (j=m-2;j>0;j--): d[j]=d[j-1]-dd[j];
d[0]=-dd[0]+0.5*c[0];
Return d
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Given a coefficients c[0..n-1], this routine returns g[0..n-1]: \Sigma_{k=0}^{n-1}d_ky^k=\Sigma_{k=0}^{n-1}g_kx^k-c_0/2. The interval -1<y<1 is mapped to the interval a<x<b. Int k,j,n=d.size(); Doub cnst=2.0/(b-a), fac=cnst; VecDoub d(m), dd(m); For (j=0;j<n;j++): d[j] *= fac fac *= cnst cnst = 0.5*(a+b) For (j=0; j< n-2; j++): for (k=n-2; k>=j; k--): d[k] -= cnst*d[k+1]
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